

Semantic Equivalence

Semantics and applications to verification

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Reasoning on program equivalence

Properties considered in the previous lectures:

- Sets of **states**: absence of runtime errors...
- Sets of **traces**: termination
- Sets of **sets or traces**: security, dependences

In all these cases, **only one program is considered**.

Today: reasoning about several programs

Kinds of questions we will consider:

- Does P and Q have the same behaviors ?
- Does P have more behaviors than Q ?

A short introduction to these properties and **the verification of a micro-compiler** with Coq

Program transformations

Informal definition: program transformation

- A **program transformation** is a **partial function**, mapping a program P into another program $\mathcal{T}(P)$
- It should **preserve some semantic properties** of programs

- **Compilation:**
the target code behaviors should match those of the source code
- **Optimization:** the target code may differ strongly from the source, yet “produce the same observation”
- **Slicing:** the target code should perform the same actions over the “slicing criterion”

A first (and naive) definition of correctness

Correctness by semantic equivalence

Correctness of transformation \mathcal{T} writes down as an equivalence of semantics:

$$\llbracket \mathcal{T}(P) \rrbracket = \llbracket P \rrbracket$$

Why is it naïve ?

- P and $\mathcal{T}(P)$ may not be expressed in the same language, and thus have “comparable” semantics
- e.g., if we consider compilation, $\mathcal{T}(P)$ is much lower level (machine language, with registers, etc) than P

Limitations (1)

Example: compilation of a simple imperative language

- Variables
- Syntax:

$$\begin{aligned} e &::= v \mid e + e \mid \dots \\ i &::= x := e; \\ &\quad \mid \text{if}(e \leq 0) \text{ b else b} \\ &\quad \mid \text{while}(e \leq 0) \text{ b} \\ b &::= \{i; \dots; i;\} \end{aligned}$$

- Variables + registers
- Program counter
- Instructions:

$$\begin{aligned} i &::= \text{add } r_d, r_{s0}, r_{s1} \mid \text{li } r_d, r_{s0} V \\ &\quad \mid \text{b } dst \mid \text{blt } r_{s0}, r_{s1}, dst \\ &\quad \mid \text{ld } [s], r_d \mid \text{st } [d], r_s \end{aligned}$$

Translation of a simple code fragment

$$\left. \begin{array}{l} \ell_0 : x = 7; \\ \ell_1 : y = 8 + x; \\ \ell_2 : \dots \end{array} \right\} \xrightarrow{\mathcal{T}} \left\{ \begin{array}{ll} 0 : \text{li } r_0, 7 & 3 : \text{ld } [x], r_1 \\ 1 : \text{st } [x], r_0 & 4 : \text{add } r_1, r_0, r_1 \\ 2 : \text{li } r_0, 8 & 5 : \text{st } [y], r_1 \end{array} \right.$$

Limitations (1)

Translation of a simple code fragment:

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$$\left. \begin{array}{l} \ell_0 : x = 7; \\ \ell_1 : y = 8 + x; \\ \ell_2 : \dots \end{array} \right\} \xrightarrow{\mathcal{T}} \left\{ \begin{array}{ll} 0 : \text{li } r_0, 7 & 3 : \text{ld } [x], r_1 \\ 1 : \text{st } [x], r_0 & 4 : \text{add } r_1, r_0, r_1 \\ 2 : \text{li } r_0, 8 & 5 : \text{st } [y], r_1 \end{array} \right.$$

If we attempt at comparing traces point by point:

- **intermediate assembly points** 1, 3, 4 have **no counterpart in the source**
- **registers** r_0, r_1 have **no counterpart in the source**

A semantic equality is **too tight**.

A second definition of correctness

Fix: apply an **observation function** to traces

Correctness up to observation

Correctness up to observation \mathcal{O} of transformation \mathcal{T} writes down as an equivalence of semantics, after applying \mathcal{O} to the semantics:

$$\mathcal{O}[\mathcal{T}(P)] = \llbracket P \rrbracket$$

Example:

- \mathcal{O} ignores 1, 3, 4 and registers
- \mathcal{O} maps 0 to l_0 ; 2 to l_1 and 5 to l_2

Limitations (2)

Floating point computations:

- source semantics: allows **any IEEE-754 compliant rounding mode**
- target machine semantics: may choose **a specific rounding mode** (e.g., before running the program)
- all target program behavior are admissible in the source
- but **not all source behavior occur in the target program**

Execution order:

- **unspecified** in the C semantics
- **chosen** by the compiler (different compilers may make different choices)

A semantic equality is **too strong**

A third definition of correctness

Fix: weaken the previous statement to an inclusion

Correctness as an inclusion

Correctness up to observation \mathcal{O} of transformation \mathcal{T} writes down as an inclusion of semantics, after applying \mathcal{O} to the semantics:

$$\mathcal{O}[\mathcal{T}(P)] \subseteq [P]$$

In both examples, only an inclusion holds

Summary

- **Correctness** relies on **comparing executions**
- This comparison is usually **not tight**:
 - ▶ **up-to observation** (abstraction)
intricate aspects of the execution of initial and transformed programs typically do not match
 - ▶ **inclusion** (one-way only)
transformed programs often **refine** the initial one