# Clocks in Kahn Process Networks

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> MPRI Course notes October 2025

# **Deterministic Parallel Programming**

What is the semantics of a set of parallel processes (possibly running on different machines) and communicating through FIFO (First-in-First-out) queues?

Represent thoses processes as a set of equations :

$$z,t = Q(y)$$

$$y = P(x,r)$$

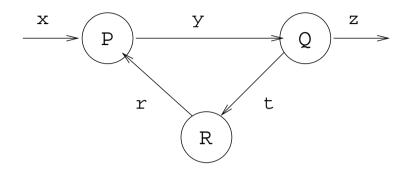
$$r = M(t)$$

What is the meaning of  $z, t, y, r, x, \dots$ ? of Q, P, M? Is this set of equations equivalent to a process F with :

$$z = F(x)$$

# Kahn Process Networks [Kahn'74, Kahn & MacQueen '77]

In 1974, G. Kahn show that the semantics of a deterministic parallel process that communicate through (possibly) unbounded buffers is a stream function.



- A set of sequential deterministic processes (i.e., sequential programs)
   written in an imperative language : P, Q, M,...
- They communicate **asynchronously** via **message passing** into FIFOs (buffers) using two primitives get/put with the following assumptions:
  - Read is blocking on the empty FIFO; sending is non blocking.
  - Channels are supposed reliable (communication delays are bounded).
  - Read (waiting) on a single channel only, i.e., the program :

if (a is not empty) or (b is not empty) then ... is FORBIDDEN

# **Concretely:**

- A buffer channel is defined by two primitives, get, to wait (pop) a value from a buffer and put, to send (push) a value.
- Parallel composition can either be implemented with regular processes ("fork") or lightweight processes ("threads").
- Historic note: Gilles Kahn was interested in the semantics of Unix pipes and Unix processes communicating through FIFOs.

#### E.g., take OCaml:

```
type 'a buff = { put: 'a -> unit; get: unit -> 'a }
val buffer : unit -> 'a buff
```

buffer () creates a buffer associated to a read and write functions.

Either unbounded size (using lists) or statically bounded size. Add a possible status bit: IsEmptyBuffer and IsFullBuffer.

# **Implementation**

Here is a possible implementation of the previous set of processes (kahn.ml).

```
(* Process P *)
                                     (* Process Q *)
                                     let q y t z () =
let p \times r y () =
 y.put 0; (* init *)
                                       while true do
 let memo = ref 0 in
                                         let v = y.get () in
 while true do
                                        t.put v;
   let v = x.get () in
                                        z.put v
   let w = r.get () in
                                       done
   memo := if v then 0 else !memo + w;
   y.put !memo
 done
(* Process M *)
                         (* Put them in parallel. *)
let m t r () =
                         let main x z () =
 while true do
                           let r = buffer () in let y = buffer () in
                           let t = buffer () in
   let v = t.get () in
   r.put (v + 1)
                           Thread.create (p x r y) ();
 done
                           Thread.create (q y t z) ();
                           Thread.create (m t r) ()
```

#### Exercise:

— Implement the function buffer in OCaml (using modules Thread, Mutex, or Unix and Sys).

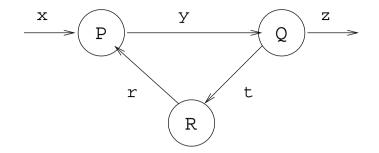
#### **Questions:**

- What is the semantics of p, q, m and main?
- What does it change to remove line (\* init \*)?
- Would you be able to define and prove that the program main is non blocking, i.e, if x.get () never blocks then z.put () never blocks?
- Is there a statically computable bound for the size of buffers without leading to blocking?
- Would it be possible to statically schedule this set of processes, that is, to generate an equivalent sequential program?

These are all undecidable questions in the general case (see [Thomas Park's PhD. thesis, 1995], among others).

Kahn Process Networks and variants have been and are still very popular, both practically, and theoretically because it conciliates **parallelism** and **determinacy**.

#### Kahn Process Networks



- message communication into FIFOs (send/wait)
- reliable channels, bounded communication delay
- blocking wait on a channel. The following program is forbidden if (A is present) or (B is present) then ...

The Kahn Principle: a channel is a sequence (or stream); a deterministic process is a continuous stream function  $(V^{\infty})^n \to (V'^{\infty})^m$ .

#### Lustre:

- Lustre do have a Kahn semantics (no test of absence)
- A dedicated type system (clock calculus) to guaranty the existence of an execution with no buffer (no synchronization)

#### Kahn Process Networks

(+): Simple semantics: a process defines a function (determinism); composition is function composition

(+): Modularity: a network is a continuous function

(+): Asynchronous distributed execution: easy; no centralized scheduler

(+/-): **Time invariance**: no explicit timing; but impossible to state that two events happen at the same time.

(-): Ressources: KPN can run with unbounded memory or have deadlock. The parallel composition of two bounded memory/deadlock free KPN may be unbounded/deadlock.

x	=	$x_0$	$x_1$		$x_2$	$x_3$	$x_4$	$x_5$		•••
f(x)	=	$y_0$	$y_1$		$y_2$	$y_3$	$y_4$	$y_5$		•••
f(x)	=	$y_0$		$y_1$	$y_2$		$y_3$	$y_{\scriptscriptstyle L}$	$y_5$	•••

#### Kahn Process Networks

Some restrictions must be imposed for KPN to be used for real-time/embedded applications where ressources (time and memory) matter.

KPNs were quite successful to model for video apps (TV boxes): Sally (Philips NatLabs), StreamIt (MIT), Xstream (ST-micro) with various "synchronous" restriction à la SDF (Edward Lee)

More generally, we are interested here in stream programming:

- A stream models a time evolving value;
- The time line is the set of natural numbers;
- A system is a stream function, that is, a function from streams to streams.

#### A small dataflow kernel

Expression (e), constants (i), functions applied pointwise  $(op(e_1, ..., e_n))$ , data-flow primitives.

$$e \quad ::= \quad e \text{ fby } e \mid op(e,...,e) \mid x \mid v$$
 
$$\mid \text{merge } e \mid e \mid e \mid e \text{ when } e$$
 
$$op \quad ::= \quad + \mid - \mid \text{not} \mid ...$$

Definition of stream functions, equations:

$$\begin{array}{ll} d & ::= & \operatorname{node} f(p) = p \ \operatorname{with} \ D \\ \\ p & ::= & x, ..., x \mid x \\ \\ D & ::= & x = e \mid D \ \mathrm{and} \ D \mid \operatorname{var} x \ \operatorname{in} \ D \end{array}$$

## **Dataflow Primitives**

x	$x_0$	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$
y	$y_0$	$y_1$	$y_2$	$y_3$	$y_4$	$y_5$
x+y	$x_0 + y_0$	$x_1 + y_1$	$x_2 + y_2$	$x_3 + y_3$	$x_4 + y_4$	$x_5 + y_5$
$x  ext{ fby } y$	$x_0$	$y_0$	$y_1$	$y_2$	$y_3$	$y_4$
h	1	0	1	0	1	0
$x' = x  \mathrm{when}  h$	$x_0$		$x_2$		$x_4$	
$\overline{z}$		$z_0$		$z_1$		$z_2$
	$x_0$	$z_0$	$x_2$	$z_1$	$x_4$	$z_2$

# **Sampling:**

- ightharpoonup if h is a boolean sequence, x when h produces a sub-sequence of x
- ightharpoonup merge  $h \ x \ z$  combines two sub-sequences

## **Kahn Semantics**

- If V is a set,  $V^n$  is the set of sequences of length n made by concatenating elements from V.  $V^\star = \cup_{n=0}^\infty V^n$  is the Kleene star operation.
- $V^{\infty} = V^* \cup V^{\omega}$  is the set of finite and infinite sequences.
- $\epsilon$  is the empty sequence.
- v.s is a sequence whose first element is v and tail is s.
- The set  $(V^{\infty}, \leq, \epsilon)$ , with  $\leq$  the prefix order between sequences,  $\epsilon$  the minimum element, is a complete partial order (cpo). <sup>a</sup>
- The Kleene theorem applies : if  $f: V^{\infty} \to V^{\infty}$  is a continuous function, the equation x = f(x) has a least fix-point  $x^{\infty} = \lim_{n \to \infty} (f^n(\epsilon))$ .

Every operator is interpreted as a stream. If  $x \mapsto s_1$  and  $y \mapsto s_2$  then the value of x + y is  $lift^2(+)(s_1, s_2)$ 

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12/74

#### Kahn Semantics

$$lift^{0}(v) = v.lift^{0}(v)$$

$$lift^{1}(op)(v.s) = op(v).lift^{1}(op)(s)$$

$$lift^{1}(op)(\epsilon) = \epsilon$$

$$lift^{2}(op)(v_{1}.s_{1}, v_{2}.s_{2}) = op(v_{1}, v_{2}).lift^{2}(op)(s_{1}, s_{2})$$

$$lift^{2}(op)(s_{1}, s_{2}) = \epsilon \text{ if } s_{1} = \epsilon \text{ or } s_{2} = \epsilon$$

$$fby(s_{1})(s_{2}) = \epsilon \text{ if } s_{1} = \epsilon$$

$$fby(v_{1}.s_{1})(s_{2}) = v_{1}.s_{2}$$

## **Kahn Semantics**

All those functions are continuous [2].

# Denotational semantics (source language)

Function application, abstraction and fix-points are interpreted denotationally, as in purely functional programming languages [12].

Stream operations are interpreted as defined above.

Let  $Names = \{x_1, ...\}$  a numerable set of symbols (variable names).

Let  $\rho: Names \to V^{\infty}$  denotes an environment.

 $\rho_1 + \rho_2$  is the union of  $\rho_1$  and  $\rho_2$  provided defined names are disjoint.  $\rho|_x$  removes x from  $\rho$ .

The semantics  $[\![e]\!]_{\rho}:V^{\infty}$  of an expression e in environment  $\rho$ .

The semantics  $[\![D]\!]_{\rho}:Names\to V^{\infty}$  of an equation E in environment  $\rho.$ 

# An other formulation - sequences

Represent a sequence as a function from an initial segment of  $\mathbb N$  to V.

**Initial segment :**  $I \subseteq \mathbb{N}$  is an initial segment when :

$$\forall n, m \in \mathbb{N}. (n \in I) \land (m \le n) \Rightarrow (m \in I)$$

E.g.,  $\emptyset$ ,  $\{0, 1, 2\}$  are initial segment;  $\{0, 42\}$  is not.

**Lemma :** For any subset A of  $\mathbb{N}$ , there exists a strictly increasing, one-to-one function  $\phi_A$  between an initial segment  $I_A$  of  $\mathbb{N}$  and A.

A signal u is a sequence  $(u_n)_{n\in N}$ , finite or not, indexed on an initial segment N.

$$lift^{0}(v) = (u)_{n \in \mathbb{N}} \quad with \quad \forall n \in \mathbb{N}. u_{n} = v$$

$$lift^{1}(op)((u_{n})_{n \in \mathbb{N}}) = (v_{n})_{n \in \mathbb{N}} \quad with \quad \forall n \in \mathbb{N}. v_{n} = op(v_{n})$$

$$lift^{2}(op)((u_{n})_{n \in \mathbb{N}}, (v_{n})_{n \in \mathbb{N}}) = (w_{n})_{n \in \mathbb{N}} \quad with \quad \forall n \in \mathbb{N}. w_{n} = op(u_{n}, v_{n})$$

$$fby((u_{n})_{n \in \mathbb{N}})((v_{n})_{n \in \mathbb{N}}) = (w_{n})_{n \in \mathbb{N}} \quad with \quad w_{0} = u_{0}$$

$$and \quad \forall n \in \mathbb{N} \setminus \{0\}. w_{n} = v_{n-1}$$

If  $(h_n)_{n \in \mathbb{N}}$  is a boolean sequence, define :

$$N_h = \{k \in N \mid h_k = 1\}$$

and

$$N_{\overline{h}} = \{ k \in N \mid h_k = 0 \}$$

 $N_h$  with  $N_{\overline{h}}$  form a partition of N.

$$when((u_{n})_{n \in N}, (h_{n})_{n \in N}) = (v_{n})_{n \in I_{N_{h}}} \quad with \quad v_{n} = u_{\phi_{N_{h}}(n)}$$

$$merge((h_{n})_{n \in N}, (u_{n})_{n \in I_{N_{h}}}, (v_{n})_{n \in I_{N_{\overline{h}}}}) = (w_{n})_{n \in N} \quad with \quad w_{n} = u_{n} \text{ if } n \in N_{h}$$

$$and \quad w_{n} = v_{n} \text{ if } n \in N_{\overline{h}}$$

The base clock is the constant sequence base such that  $\forall n \in \mathbb{N}, base_n = 1$ .

# An encoding in Haskell

```
constant v n = v
lift1 op x n = op(x(n))
notl x = lift1 not
lift2 op x y n = op (x(n)) (y(n))
lift3 op x y z n = op (x(n)) (y(n)) (z(n))
x fby y 0 = x(0)
x fby y n = y(n-1)
x when h n = x(I(h)(n+1))
merge h x y n = if h(n) then x(O(h)(n)) else y(O(notl h)(n)
where I and O are (respectively) the index and cumulative functions.
```

#### The index and cumulative functions

I and O functions If h is a boolean stream, O(h)(n) is the sum of 1 till index n; I(h)(n) is the index of the n-th 1 in h.

$$O(h)(n) = \sum_{i=0}^{n} h(i) \quad I(h)(n) = \min\{k \in \mathbb{N} \mid O_h(k) = n\}$$

$$O(h)(n) = h(n) + (\text{if } n = 0 \text{ then } 0 \text{ else } 0(h)(n-1))$$

$$I(h)(n) = I'(h)(0)(n)$$

$$I'(h)(i)(n) = \text{if } h(i) \text{ then if } n = 1 \text{ then i}$$

$$\text{else } I'(h)(i+1)(n-1)$$

$$\text{else } I'(h)(i+1)(n)$$

It is very possible that I(n) be undefined (no value in  $\mathbb{N}$ ). E.g., (x when (constant false))(n). The domain of a signal x (values of n for which x(n) exists) is an initial section.

# An encoding of sequences in Ocaml (see companion file)

```
type 'a sequence = int -> 'a
let const v n = v
let extend f x n = (f(n)) (x(n))
let lift1 f x = extend (const f) x
let lift2 f x y = extend (extend (const f) x) y
let lift3 f x y z = extend (extend (extend (const f) x) y) z
let notl x = lift1 (fun x \rightarrow not x) x
let plusl x y = lift2 (+) x y
let minusl x y = lift2 (-) x y
let and x y = lift2 (\&\&) x y
let eql x y = lift2 (=) x y
(* The [if/then/else] of Lustre *)
let mux x y z = lift3 (fun x y z -> if x then y else z) x y z
```

# Cont. (unit delay) let pre v x n = if n = 0 then v else x(n-1)let fby x y n = if n = 0 then x 0 else y(n-1)let next x n = x (n+1)

```
Cont. (index/cumulative functions)
(* cumulative and index functions *)
(* [cumul(h)(n)] returns the sum of ones in h up to index n *)
let rec cumul(h)(n) = (if h(n) then 1 else 0) +
                      (if n = 0 then 0 else cumul(h)(n-1))
(* [index(h)(n)] returns the index of the n-th one in h *)
let rec index(h)(n) = index aux(h)(0)(n)
and index aux(h)(i)(n) =
 if h(i) then if n = 1 then i else index_aux(h)(i+1)(n-1)
 else index aux(h)(i+1)(n)
(* reset. [reset(h)(n)] returns the greatest *)
(* index i in [0..n] where h(i) = true; if there is no, returns 0 *)
let reset(h)(n) =
 let rec o n = if n = 0 then 0 else if h n then n else o(n-1) in
 o(n)
```

```
Cont. (filtering/merging - when/merge)
(* filtering and merge *)
let whenc x h n = x(index(h)(n+1))
let when notc x h n = x(index(notl h)(n+1))
let merge h \times y = if h(n) then x(cumul(h)(n)) else y(cumul(notl h)(n))
(* Fixpoint operator over sequences *)
let fix : ('a sequence -> 'a sequence) -> 'a sequence =
 fun f n -> let rec o n = f o n in o n
(* the bottom element [eps ()] *)
let rec eps n = eps n
```

```
Cont. (examples)
(* Examples *)
let half () = let rec half n = pre false (notl half) n in half
let from v =
 let rec f n = pre 0 (plusl f (const 1)) n in f
let incr v x n = pre v (plusl x (const 1)) n
let from v = fix (incr (v(0)))
let sum x =
  (* [The concrete syntax in Zelus is: let rec y = (0 \text{ fby } y) + x \text{ in } y] *)
 fix (fun y -> plusl (pre 0 y) x)
```

# Cont. examples

```
(* Deadlock / infinite loop *)
(* to test, type [deadlock 42] *)
let id x n = x n
let deadlock n = fix id n
(* to test, type [deadlock 42] *)
let deadlock n =
 let x = const true in
 whenc x (const false) n
(* non synchronous *)
let unbounded =
 let x = const true in
 let h = half () in
 andl (whenc x h) x
```

## Cont. examples

```
(* semantics of a simple language with a control structure and a reset *)
(* model a conditional that activate one block when a condition is true;
 *- activate the other when the condition is false *)
let cond_act c f g x =
  (* cond_act c f g x = merge c (f (x when c)) (g (x whenot c))) *)
 fun n -> merge c (f (whenc x c)) (g (when_notc x c))
(* after. [after x k] returns the sub-sequence of x that starts at index k *)
let after x k = fun n \rightarrow x (n+k)
(* model a modular reset.
*- take a system [f] and input [x];
*- run f x; every time [c] is true, restart [f] with the remaining inputs *)
let reset act f x c = fun n \rightarrow let k = reset c n in f (after x k)(n-k)
```

#### Comments

A denotational semantics and reference interpreter in a few lines of OCaml (or any general purpose language).

Yet, it is totally useless in practice.

Think of the (exponential) time (and memory) to compute Fibonacci :

```
let rec fibo(n) = if n <= 1 then 1 else fibo(n-1) + fibo(n-2)
```

whereas it denotes a simple stream equation (written in  $Z\acute{\rm ELUS}$ ) which can be implemented with two registers and run in constant time.

```
let rec pfibo = 1 fby (fibo + pfibo)
and fibo = 1 fby pfibo in fibo
```

Rmq: (1) it cannot be defined in Coq (unless using a trick, e.g., "fuel"); (2) yet, it can be used for a relational semantics; anwering questions like (3) is this program deadlocks? (4) is this program be implemented in bounded time and space? are difficult.

# An Implementation in Haskell using a Lazy Data-structure

module Streams where

```
data ST a = Cons a (ST a) deriving Show
-- lifting constants
constant x = Cons x (constant x)
-- pointwise application
extend (Cons f fs) (Cons x xs) = Cons (f x) (extend fs xs)
-- delays
(Cons x xs) 'fby' y = Cons x y
pre x y = Cons x y
-- sampling
(Cons x xs) 'when' (Cons True cs) = (Cons x (xs 'when' cs))
(Cons x xs) 'when' (Cons False cs) = xs 'when' cs
merge (Cons True c) (Cons x xs) y = Cons x (merge c xs y)
merge (Cons False c) x (Cons y ys) = Cons y (merge c x ys)
```

# An embedding in Haskell

function definition/applications are the regular ones; mutually recursive definitions of streams are represented as mutually recursive definitions of values.

We can write many usefull examples and benefit from features of the host language.

```
lift2 f x y = extend (extend (constant f) x) y
plusl x y = lift2 (+) x y
-- integers greaters than n
from n =
  let nat = n 'fby' (plusl nat (constant 1)) in nat
-- resetable counter
reset_counter res input =
  let output = ifthenelse res (constant 0) v
      v = ifthenelse input
                     (pre 0 (plusl output (constant 1)))
                     (pre 0 output)
  in output
```

# Multi-periodic systems

```
every n =
  let o = reset_counter (pre 0 o = n - 1)
                        (constant True)
  in o
filter n top = top when (every n)
hour_minute_second top =
  let second = filter (constant 10) top in
  let minute = filter (constant 60) second in
  let hour = filter (constant 60) minute in
 hour, minute, second
```

# Over-sampling (with fixed step)

```
Compute the sequence (o_n)_{n\in\mathbb{N}} such that o_{2n}=x_n and o_{2n+1}=x_n.
-- the half clock
half = (constant True) 'fby' notl half
-- double its input
stutter x =
  o = merge half x ((pre 0 o) when notl half) in o
   — over-sampling : the internal rate is faster than the rate of inputs
   — this is still a real-time program
   — why is it rejected in LUSTRE?
```

# Over-sampling with variable step

Compute the root of an input x (using Newton method)

```
u_n = u_{n-1}/2 + x/2u_{n-1}
u_1 = x
\text{eps = constant 0.001}
\text{root input =}
\text{let ic = merge ok input (pre 0 ic) when notl ok)}
\text{uc = (pre 0 uc) / 2 + (ic / 2 * pre 0 uc)}
\text{ok = true -> uc - pre 0 uc <= eps}
\text{output = uc when ok}
\text{in output}
```

This example mimics an internal while loop (example due to Paul Le Guernic)

#### Where are the monsters?

A stream is represented as a lazy data-structure. Nonetheless, lazyness allows streams to be build in a strange manner.

#### Structural (Scott) order:

```
\perp \leq_{struct} v, (v:w) \leq_{struct} (v':w') iff v \leq_{struct} v' and w \leq_{struct} w'.
```

The following programs are perfectly correct in Haskell (with a unique non-empty solution)

```
hd (x:y) = x

tl (x:y) = y

incr (x:y) = (x+1): incr y

one = 1: one

x = (if hd(tl(tl(tl(x)))) = 5 then 3 else 4) : 1: 2: 3: one

output = (hd(tl(tl(tl(x))))): (hd(tl(tl(x)))): (hd(x)): output

The values are:

-x = 4: 1: 2: 3: 1: ...

-output = 3: 2: 4: 3: 2: 4: ...
```

These stream may be constructed lazilly:

- $-x^0 = \bot, x^1 = \bot : 1 : 2 : 3 : un, x^2 = 4 : 1 : 2 : 3 : one.$
- $-output^0 = \bot, output^1 = 3:2:4:...$

An other example (due to Paul Caspi) :

```
nat = zero 'fby' (incr nat)

ifn n x y = if n <= 9 then hd(x) : ifn (n+1) (tl(x)) (tl(y)) else y

if9 x y = ifn 0 x y
```

$$x = if9 (incr (tl x)) nat$$

We have x = 20, 19, 18, 17, 16, 15, 14, 13, 12, 11, 10, 11, 12, 13, 14, 15, ....

Are they reasonnable programs? Streams are constructed in a reverse manner from the future to the past. We say that they are not "causal".

This is because the structural order between streams allows to fill the holes in any order, e.g. :

$$(\bot:\bot) \le (\bot:\bot:\bot:\bot) \le (\bot:\bot:2:\bot) \le (\bot:1:2:\bot) \le (0:1:2:\bot)$$

It is also possible to build streams with intermediate holes (undefined values in the middle) through the final program is correct:

$$half = 0. \perp .0. \perp ...$$

```
fail = fail
half = 0:fail:half
fill x = (hd(x)) : fill (tl(tl x))
ok = fill half
```

We need to model causality, that is, stream should be produced in a sequential order. We take the prefix order introduced by Kahn:

#### Prefix order:

 $x \leq y$  if x is a prefix of y, that is :  $\bot \leq x$  and  $v.x \leq v.y$  if  $x \leq y$ 

#### Causal function:

A function is causal when it is monotonous for the prefix order :

$$x \le y \Rightarrow f(x) \le f(y)$$

All the previous program will get the value  $\perp$  in the Kahn semantics.

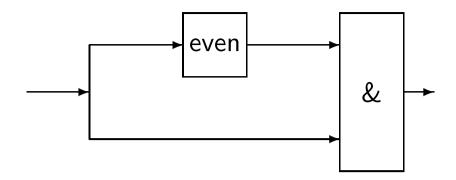
### Kahn Semantics in Haskell

It is possible to remove possible non causal streams by forbidding values of the form  $\perp x$ . In Haskell, the annotation !a states that the value with type a is strict  $(\neq \bot)$ .

```
module SStreams where
-- only consider streams where the head is always a value (not bot)
data ST a = Cons !a (ST a) deriving Show
constant x = Cons x (constant x)
extend (Cons f fs) (Cons x xs) = Cons (f x) (extend fs xs)
(Cons x xs) 'fby' y = Cons x y
(Cons x xs) 'when' (Cons True cs) = (Cons x (xs 'when' cs))
(Cons x xs) 'when' (Cons False cs) = xs 'when' cs
merge (Cons True c) (Cons x xs) y = Cons x (merge c xs y)
merge (Cons False c) x (Cons y ys) = Cons y (merge c x ys)
```

This time, all the previous non causal programs have value  $\perp$  (stack overflow).

## Some "synchrony" monsters



If  $x = (x_i)_{i \in I\!\!N}$  then  $even(x) = (x_{2i})_{i \in I\!\!N}$  and  $x \& even(x) = (x_i \& x_{2i})_{i \in I\!\!N}$ .

#### **Unbounded FIFOs!**

- must be rejected statically
- every operator is finite memory through the composition is not : all the complexity (synchronization) is hidden in communication channels
- ► the Kahn semantics does not model time, i.e., impossible to state that two event arrive at the same time

# Synchronous (Clocked) streams

Complete streams with an explicit representation of absence (abs).

$$x: (V^{abs})^{\infty}$$

**Clock**: the clock of x is a boolean sequence

$$I\!\!B = \{0,1\}$$
 $\mathcal{CLOCK} = I\!\!B^{\infty}$ 
 $\operatorname{clock} \epsilon = \epsilon$ 
 $\operatorname{clock} (abs.x) = 0.\operatorname{clock} x$ 
 $\operatorname{clock} (v.x) = 1.\operatorname{clock} x$ 

### **Synchronous streams:**

$$ClStream(V, cl) = \{s/s \in (V^{abs})^{\infty} \land \mathtt{clock}\ s \leq_{prefix} cl\}$$

An other possible encoding :  $x : (V \times I\!\!N)^\infty$ 

### **Dataflow Primitives**

#### **Constant:**

$$i^{\#}(\epsilon) = \epsilon$$
 $i^{\#}(1.cl) = i.i^{\#}(cl)$ 
 $i^{\#}(0.cl) = abs.i^{\#}(cl)$ 

### **Point-wise application:**

Synchronous arguments must be constant, i.e., having the same clock

$$+^{\#}(s_1, s_2)$$
 =  $\epsilon$  if  $s_i = \epsilon$   
 $+^{\#}(abs.s_1, abs.s_2)$  =  $abs.+^{\#}(s_1, s_2)$   
 $+^{\#}(v_1.s_1, v_2.s_2)$  =  $(v_1 + v_2).+^{\#}(s_1, s_2)$ 

#### **Partial definitions**

What happens when one element is present and the other is absent?

#### **Constraint their domain:**

```
(+): \forall cl: \mathcal{CLOCK}. ClStream(\mathtt{int}, cl) \times ClStream(\mathtt{int}, cl) \rightarrow ClStream(\mathtt{int}, cl)
```

i.e., (+) expect its two input stream to be on the same clock cl and produce an output on the same clock

These extra conditions are types which must be statically verified

**Remark (notation):** Regular types and clock types can be written separately:

- $(+): int \times int \rightarrow int \leftarrow its type signature$
- $(+):: \forall cl.cl \times cl \rightarrow cl \leftarrow \mathsf{its} \; \mathsf{clock} \; \mathsf{signature}$

In the following, we only consider the clock type.

## **Sampling**

```
s_1 when \# s_2
                                           = \epsilon \text{ if } s_1 = \epsilon \text{ or } s_2 = \epsilon
(abs.s) when \# (abs.c)
                                           = abs.s \, \text{when}^{\#} \, c
(v.s) when \# (1.c)
                                           = v.s \, \mathrm{when}^\# \, c
                                           = abs.x \, \text{when}^{\#} \, c
(v.s) when \# (0.c)
                                           = \epsilon if one of the s_i = \epsilon
merge c s_1 s_2
merge(abs.c)(abs.s_1)(abs.s_2) = abs.merge c s_1 s_2
merge (1.c) (v.s_1) (abs.s_2) = v.merge c s_1 s_2
merge(0.c)(abs.s_1)(v.s_2) = v.merge c s_1 s_2
```

### **Examples**

base = (1)	1	1	1	1	1	1	1	1	1	1	1	1	•••
$\overline{x}$	$x_0$	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7$	$x_8$	$x_9$	$x_{10}$	$x_{11}$	•••
h = (10)	1	0	1	0	1	0	1	0	1	0	1	0	•••
$y = x  \mathrm{when}  h$	$x_0$		$x_2$		$x_4$		$x_6$		$x_8$		$x_{10}$	$x_{11}$	•••
h' = (100)	1		0		0		1		0		0	1	•••
$z=y$ when $h^{\prime}$	$x_0$						$x_6$					$x_{11}$	•••
$\overline{k}$			$k_0$		$k_1$				$k_2$		$k_3$		•••
$ \overline{ \text{merge } h' \; z \; k } $	$x_0$		$k_0$		$k_1$		$x_6$		$k_2$		$k_3$		•••

let clock five =

let rec f = true fby false fby false fby false fby f in f let node stutter x = o where rec o = merge five x ((0 fby o) whenot five) in o

 $\mathtt{stutter}(nat) = 0.0.0.0.1.1.1.1.2.2.2.2.3.3...$ 

### **Sampling and clocks**

- $ightharpoonup x \, \text{when}^{\#} \, y$  is defined when x and y have the same clock cl
- $\blacktriangleright$  the clock of x when  $^{\#}c$  is written cl on c: "c moves at the pace of cl"

$$s ext{ on } c$$
  $= \epsilon ext{ if } s = \epsilon ext{ or } c = \epsilon$ 
 $(1.cl) ext{ on } (1.cl) ext{ on } c$ 
 $(1.cl) ext{ on } (0.cl) ext{ on } c$ 
 $(0.cl) ext{ on } (abs.c) ext{ on } c$ 

We get:

when:  $\forall cl. \forall x: cl. \forall c: cl. cl \text{ on } c$ 

 $\mathtt{merge}: \forall cl. \forall c: cl. \forall x: cl \ \mathtt{on} \ c. \forall y: cl \ \mathtt{on} \ \mathit{not} \ c. cl$ 

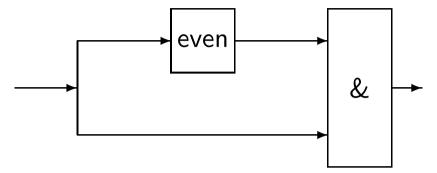
Written instead:

when:  $\forall cl.cl \rightarrow (c:cl) \rightarrow cl$  on c

 $\mathtt{merge}: \forall cl.(c:cl) \rightarrow cl \ \mathtt{on} \ c \rightarrow cl \ \mathtt{on} \ not \ c \rightarrow cl$ 

## **Checking Synchrony**

The previous program is now rejected.



This is a now a typing error

#### Final remarks:

- We only considered clock equality, i.e., "two streams are either synchronous or not"
- Clocks are used extensively to generate efficient sequential code

# From Synchrony to Relaxed Synchrony <sup>a</sup>

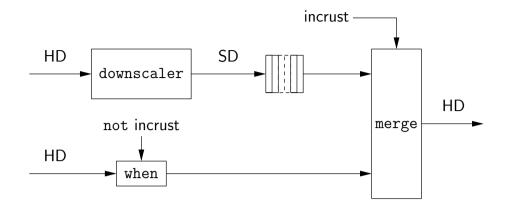
- can we compose non strictly synchronous streams provided their clocks are closed from each other?
- communication between systems which are "almost" synchronous
- model jittering, bounded delays
- Give more freedom to the compiler, generate more efficient code, translate into regular synchronous code if necessary

Course notes - Marc Pouzet

46/74

a. Joint work with Albert Cohen, Marc Duranton, Louis Mandel and Florence Plateau (PhD. Thesis at https://www.lri.fr/~mandel/lucy-n/~plateau/)

### A typical example : Picture in Picture



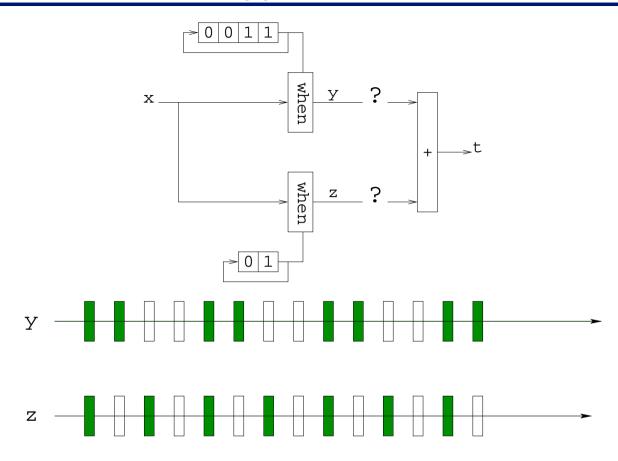
Incrustation of a Standard Definition (SD) image in a High Definition (HD) one

- ▶ downscaler : reduction of an HD image  $(1920 \times 1080 \text{ pixels})$  to an SD image  $(720 \times 480 \text{ pixels})$
- ▶ when : removal of a part of an HD image
- merge : incrustation of an SD image in an HD image

#### Question:

- buffer size needed between the downscaler and the merge nodes?
- delay introduced by the picture in picture in the video processing chain?

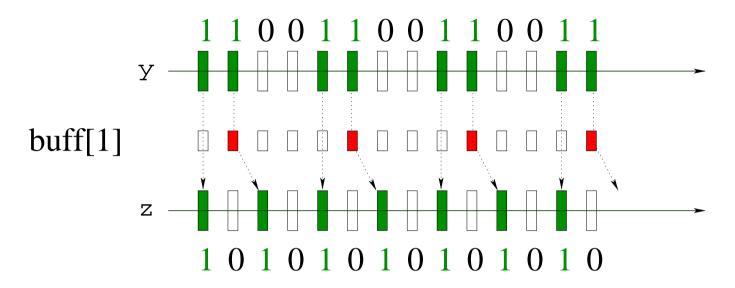
### Too restrictive for video applications



- streams should be synchronous
- adding buffer (by hand) difficult and error-prone
- compute it automatically and generate synchronous code

relax the associated clocking rules

## N-Synchronous Kahn Networks



- based on the use of *infinite ultimately periodic sequences*
- a precedence relation  $cl_1 <: cl_2$

### **Ultimately periodic sequences**

 $\mathbb{Q}_2$  for the set of infinite periodic binary words.

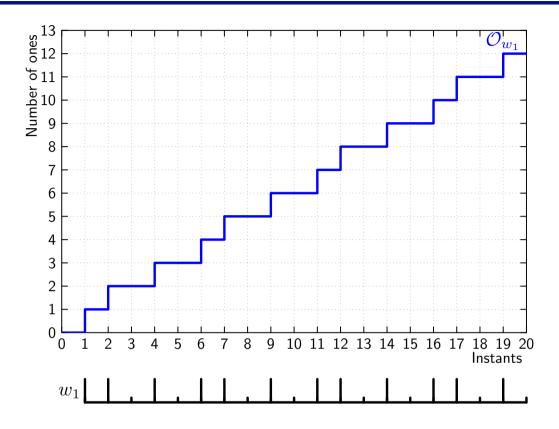
$$(01) = 01\ 01\ 01\ 01\ 01\ 01\ 01\ 01\ \dots$$
$$0(1101) = 0\ 1101\ 1101\ 1101\ 1101\ 1101\ 1101\ 1101\ \dots$$

- 1 for presence
- 0 for absence

#### **Definition:**

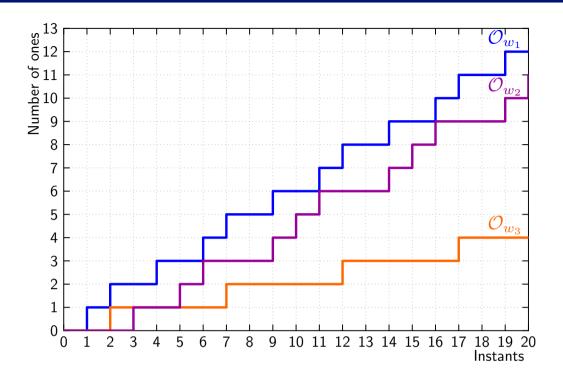
$$w ::= u(v)$$
 where  $u \in (0+1)^*$  and  $v \in (0+1)^+$ 

# Clocks and infinite binary words



 $\mathcal{O}_w(i) = \text{cumulative function of 1 from } w$ 

# Clocks and infinite binary words



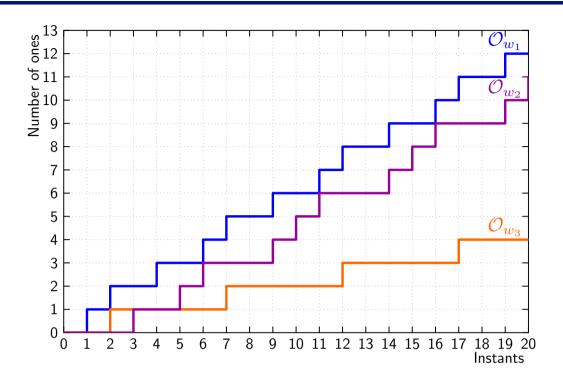
buffer

$$size(w_1, w_2) = \max_{i \in \mathbb{N}} (\mathcal{O}_{w_1}(i) - \mathcal{O}_{w_2}(i))$$

sub-typing

$$w_1 <: w_2 \stackrel{def}{\Leftrightarrow} \exists n \in \mathbb{N}, \forall i, \ 0 \leq \mathcal{O}_{w_1}(i) - \mathcal{O}_{w_2}(i) \leq n$$

## **Clocks and infinite binary words**



buffer 
$$size(w_1, w_2) = \max_{i \in \mathbb{N}} (\mathcal{O}_{w_1}(i) - \mathcal{O}_{w_2}(i))$$
  
sub-typing  $w_1 <: w_2 \overset{def}{\Leftrightarrow} \exists n \in \mathbb{N}, \forall i, \ 0 \leq \mathcal{O}_{w_1}(i) - \mathcal{O}_{w_2}(i) \leq n$   
synchronizability  $w_1 \bowtie w_2 \overset{def}{\Leftrightarrow} \exists b_1, b_2 \in \mathbb{Z}, \forall i, \ b_1 \leq \mathcal{O}_{w_1}(i) - \mathcal{O}_{w_2}(i) \leq b_2$   
precedence  $w_1 \preceq w_2 \overset{def}{\Leftrightarrow} \forall i, \ \mathcal{O}_{w_1}(i) \geq \mathcal{O}_{w_2}(i)$ 

### Multi-clock

$$c ::= w \mid c \text{ on } w \qquad w \in (0+1)^{\omega}$$

c on w is a sub-clock of c, by moving in w at the pace of c. E.g., 1(10) on (01) = (0100).

base	1	1	1	1	1	1	1	1	1	1	•••	(1)
$p_1$	1	1	0	1	0	1	0	1	0	1	• • •	1(10)
base on $p_1$	1	1	0	1	0	1	0	1	0	1	•••	1(10)
$p_2$	0	1		0		1		0		1	• • •	(01)
(base on $p_1$ ) on $p_2$	0	1	0	0	0	1	0	0	0	1	•••	(0100)

For ultimately periodic clocks, precedence, synchronizability and equality are decidable (but expensive)

## Come-back to the language

### **Pure synchrony:**

- close to an ML type system (e.g., SCADE 6)
- structural equality of clocks

$$\frac{H \vdash e_1 : ck \qquad H \vdash e_2 : ck}{H \vdash op(e_1, e_2) : ck}$$

### **Relaxed Synchrony:**

we add a sub-typing rule :

$$(SUB) \quad \frac{H \vdash e : ck \text{ on } w \quad w <: w'}{H \vdash \text{buffer}(e) : ck \text{ on } w'}$$

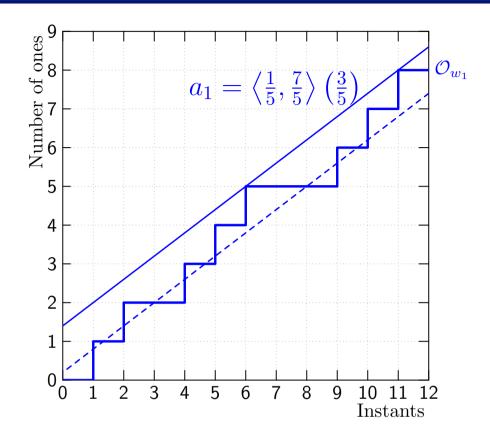
- defines synchronization points when a buffer is inserted
- ▶ the basis of the language Lucy-N (Plateau and Mandel).

### What about non periodic systems?

- ➤ The same idea : synchrony + properties between clocks. Insuring the absence of deadlocks and bounded buffering.
- ► The exact computation with periodic clocks is expensive. E.g., (10100100) on  $0^{3600}(1)$  on  $(101001001) = 0^{9600}(10^410^710^710^2)$
- Motivations :
  - 1. To treat long periodic patterns. To avoid an exact computation.
  - 2. To deal with almost periodic clocks. E.g.,  $\alpha$  on w where  $w=00.(\ (10)+(01)\ )^*$  (e.g. w=00 01 10 01 10 01 10 . . . )

Idea: manipulate sets of clocks; turn questions into arithmetic ones

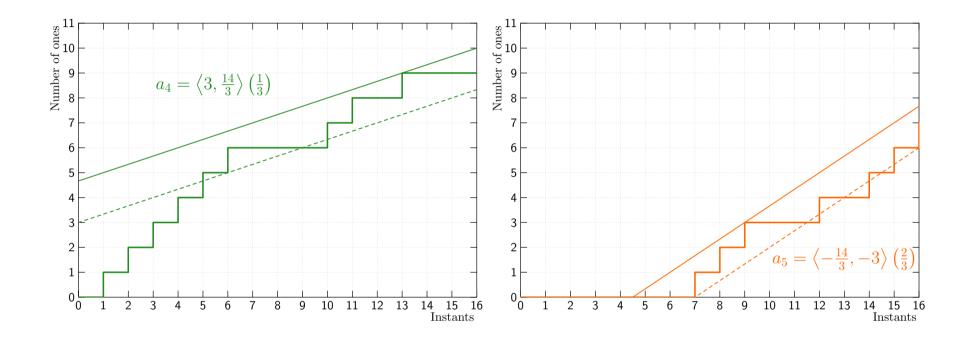
## **Abstraction of Infinite Binary Words**



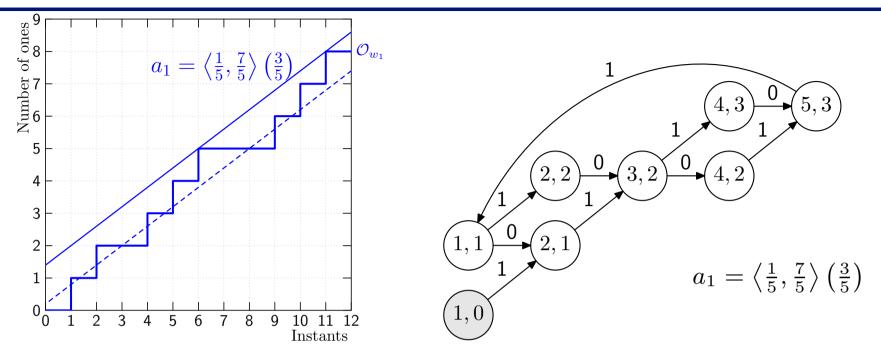
A word w can be abstracted by two lines :  $abs(w) = \left\langle b^0, b^1 \right\rangle(r)$ 

$$concr\left(\left\langle b^{0},b^{1}\right\rangle (r)\right)\overset{def}{\Leftrightarrow}\left\{ w,\ \forall i\geq1,\ \wedge\begin{array}{ll} w[i]=1&\Rightarrow&\mathcal{O}_{w}(i)\leq r\times i+b^{1}\\ w[i]=0&\Rightarrow&\mathcal{O}_{w}(i)\geq r\times i+b^{0} \end{array}\right\}$$

# **Abstraction of Infinite Binary Words**

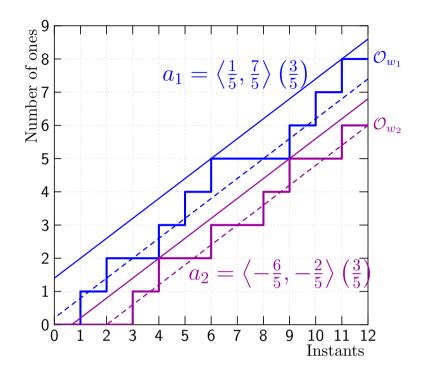


### **Abstract Clocks as Automata**



- $\blacktriangleright$  set of states  $\{(i,j)\in\mathbb{N}^2\}$  : coordinates in the 2D-chronogram
- ► finite number of state equivalence classes
- $\blacktriangleright \text{ transition function } \delta: \left\{ \begin{array}{l} \delta(1,(i,j)) = nf(i+1,j+1) & \text{if } j+1 \leq r \times i + b^1 \\ \delta(0,(i,j)) = nf(i+1,j+0) & \text{if } j+0 \geq r \times i + b^0 \end{array} \right.$
- allows to check/generate clocks

### **Abstract Relations**



Synchronizability:  $r_1 = r_2 \Leftrightarrow \left\langle b^0_1, b^1_1 \right\rangle(r_1) \bowtie^{\sim} \left\langle b^0_2, b^1_2 \right\rangle(r_2)$ 

 $\mathsf{Precedence}: b^1{}_2 - b^0{}_1 < 1 \Rightarrow \left\langle b^0{}_1, b^1{}_1 \right\rangle(r) \preceq^{\sim} \left\langle b^0{}_2, b^1{}_2 \right\rangle(r)$ 

Subtyping :  $a_1 <:^{\sim} a_2 \Leftrightarrow a_1 \bowtie^{\sim} a_2 \land a_1 \preceq^{\sim} a_2$ 

 $\triangleright$  proposition :  $abs(w_1) <:^{\sim} abs(w_2) \Rightarrow w_1 <: w_2$ 

 $\triangleright$  buffer :  $size(a_1, a_2) = |b^1_1 - b^0_2|$ 

## **Abstract Operators**

Composed clocks :  $c := w \mid not w \mid c on c$ 

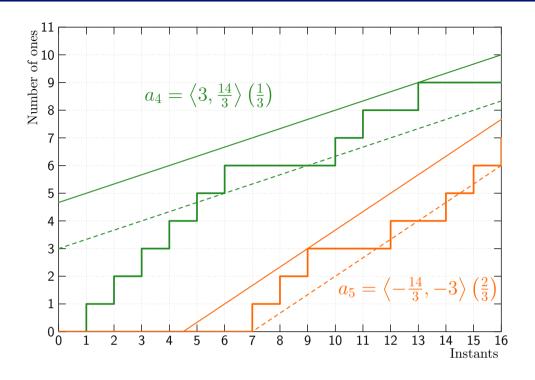
Abstraction of a composed clock:

$$abs(not w) = not^{\sim} abs(w)$$
  
 $abs(c_1 on c_2) = abs(c_1) on^{\sim} abs(c_2)$ 

Operators correctness property:

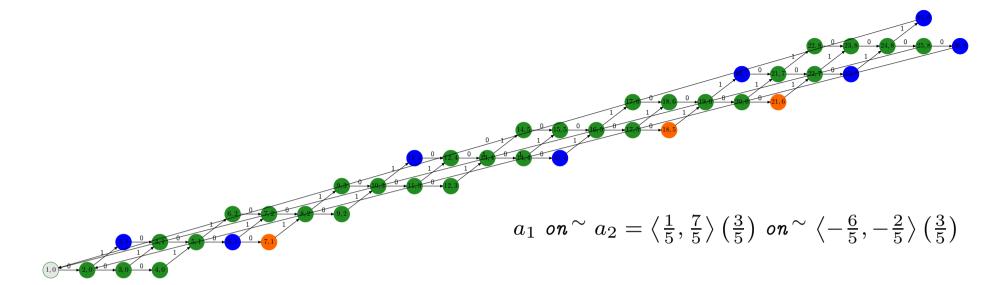
$$egin{array}{lll} {\it not} \ w & \in & concr({\it not}^\sim abs(w)) \ & c_1 \ {\it on} \ c_2 & \in & concr(abs(c_1) \ {\it on}^\sim abs(c_2)) \end{array}$$

## **Abstract Operators**



 $not^{\sim}$  operator definition :

## **Abstract Operators**

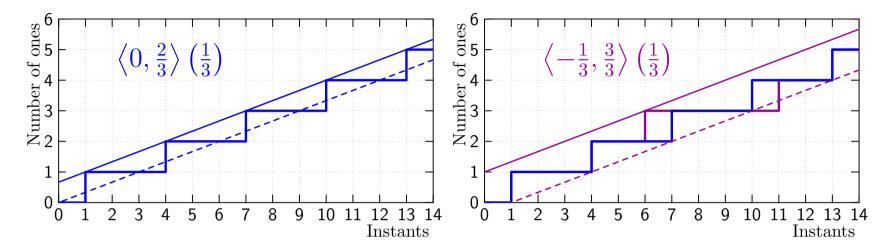


 $on^{\sim}$  operator definition :

$$egin{array}{lll} & \left\langle & b^0{}_1 & , & b^1{}_1 & \right
angle (& r_1 &) \ & on^\sim & \left\langle & b^0{}_2 & , & b^1{}_2 & \right
angle (& r_2 &) \ & = & \left\langle b^0{}_1 imes r_2 + b^0{}_2 \; , b^1{}_1 imes r_2 + b^1{}_2 
ight
angle (& r_1 imes r_2 \;) \end{array}$$

with 
$$b_1^0 \le 0$$
,  $b_2^0 \le 0$ 

### **Modeling Jitter**



- ▶ set of clock of rate  $r = \frac{1}{3}$  and jitter 1 can be specified by  $\left\langle -\frac{1}{3}, \frac{3}{3} \right\rangle \left(\frac{1}{3}\right)$
- ►  $f :: \forall \alpha.\alpha \to \alpha \text{ on}^{\sim} \left\langle -\frac{1}{3}, \frac{3}{3} \right\rangle \left(\frac{1}{3}\right)$

#### Formalization in a Proof Assistant

By Louis Mandel and Florence Plateau

Most of the properties have been proved in Coq

example of property

```
Property on_absh_correctness:

forall (w1:ibw) (w2:ibw),

forall (a1:abstractionh) (a2:abstractionh),

forall H_wf_a1: well_formed_abstractionh a1,

forall H_wf_a2: well_formed_abstractionh a2,

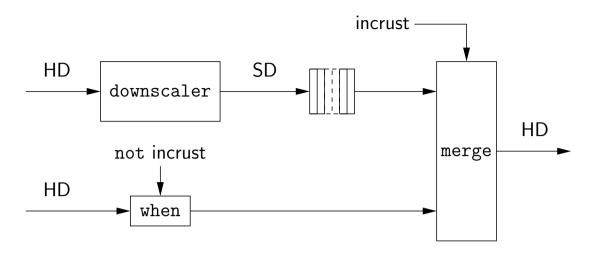
forall H_a1_eq_absh_w1: in_abstractionh w1 a1,

forall H_a2_eq_absh_w2: in_abstractionh w2 a2,

in_abstractionh (on w1 w2) (on_absh a1 a2).
```

- number of Source Lines of Code
  - specifications : about 1600 SLOC
  - proofs : about 5000 SLOC

### **Back to the Picture in Picture Example**



abstraction of downscaler output :

$$abs((10100100) \ on \ 0^{3600}(1) \ on \ (1^{720}0^{720}1^{720}0^{720}0^{720}1^{720}0^{720}0^{720}1^{720})) \\ = \left<0, \frac{7}{8}\right>\left(\frac{3}{8}\right) \ on^{\sim} \ \left<-3600, -3600\right>(1) \ on^{\sim} \ \left<-400, 480\right>\left(\frac{4}{9}\right) = \left<-2000, -\frac{20153}{18}\right>\left(\frac{1}{6}\right)$$

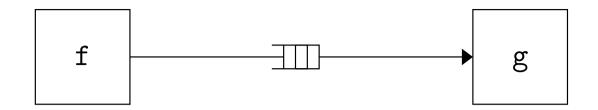
minimal delay and buffer :

	delay	buffer size				
exact result	9598~(pprox time to receive 5 HD lines)	$192~240~(\approx 267~\mathrm{SD~lines})$				
abstract result	11~995~(pprox time to receive 6 HD lines)	$193~079~(\approx 268~\text{SD lines})$				

This is implemented in Lucy-N http://lucy-n.org by Louis Mandel.



### Parallel processes communicating through a buffer



Buffers allow to desynchronize the execution

### FIFO with batching

To pop, the consumer has to check for the availability of data. This check is expensive. It is better to communicate by chunks.

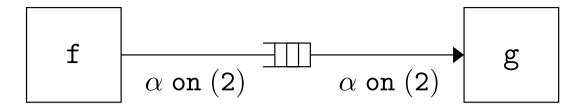
#### Batch:

- ▶ the consumer can read in the fifo only when batch values are available
- ▶ the producer can write in the fifo only when batch rooms are available

Batch size :	001	Cycles/push:	23.07	Bandwidth :	589.45 MB/s
Batch size :	002	Cycles/push:	15.79	Bandwidth :	861.40 MB/s
Batch size :	004	Cycles/push:	12.06	Bandwidth :	1127.83 MB/s
Batch size :	800	Cycles/push:	10.00	Bandwidth :	1359.69 MB/s
Batch size :	016	Cycles/push:	7.51	Bandwidth :	1810.58 MB/s
Batch size :	032	Cycles/push:	7.33	Bandwidth :	1855.32 MB/s
Batch size :	064	Cycles/push:	7.33	Bandwidth :	1855.20 MB/s

Batching: reduce the synchronization with the FIFO

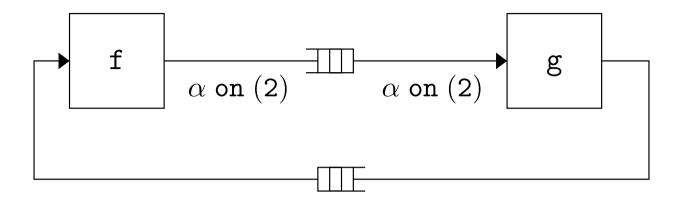
## **Integer clocks**



#### Burst:

- ▶ allows to compute and communicate several values within one instant
- formulas can be easily lifted to integers

### **Integer clocks**



#### Burst:

- ▶ allows to compute several values into one instant
- formulas can be easily lifted to integers
- ▶ impacts causality

This has been studied by Adrien Guatto in his PhD. thesis (2016).

### Type based clock calculus

### **Lucid Synchrone**

- stream Kahn semantics, clocks, functions possibly higher-order
- study (implement) extensions of Lustre
- experiment things, manage all the compilation chain and write programs!
- Version 1 (1995), Version 2 (2001), V3 (2006)

#### Quite fruitful:

- the Scade 6 language and its compiler (first release in 2008) incorporates several features from Lucid Synchrone
- the LCM language at Dassault-Systmes (Delmia Automation) based on the same principles
- several features reused in Stimulus, a language for requirement simulation.

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