

Reductions

Pierre-Alain Fouque

Complexity class NTIME

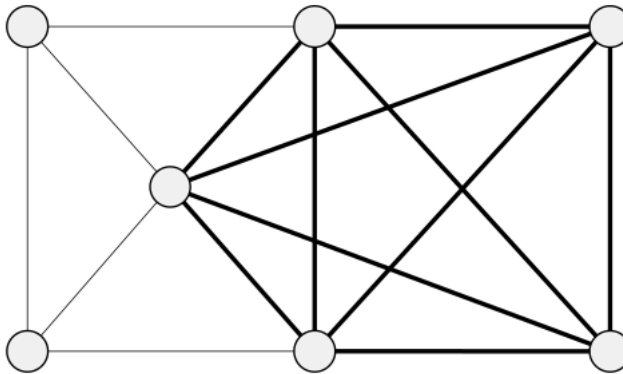
$\text{NTIME}(t(n)) = \{L \mid L \text{ is a language decided by an } O(t(n)) \text{ time nondeterministic Turing machine}\}.$

$$\text{NP} = \bigcup_k \text{NTIME}(n^k).$$

- The class NP is insensitive to the choice of reasonable non-deterministic computational model because all such models are polynomially equivalent

Examples of problems in NP

- A clique in a undirected graph is a subgraph, wherein every two nodes are connected by an edge. A k-clique is a clique that contains k nodes. E.g. A graph with a 5-clique



- The clique problem is to determine whether a graph contains a clique of a specified size: $\text{CLIQUE} = \{ \langle G, k \rangle \mid G \text{ is an undirected graph with a } k\text{-clique} \}$

CLIQUE is in NP

PROOF IDEA The clique is the certificate.

PROOF The following is a verifier V for *CLIQUE*.

$V =$ “On input $\langle\langle G, k \rangle, c \rangle$:

1. Test whether c is a subgraph with k nodes in G .
2. Test whether G contains all edges connecting nodes in c .
3. If both pass, *accept*; otherwise, *reject*.”

ALTERNATIVE PROOF If you prefer to think of NP in terms of nondeterministic polynomial time Turing machines, you may prove this theorem by giving one that decides *CLIQUE*. Observe the similarity between the two proofs.

$N =$ “On input $\langle G, k \rangle$, where G is a graph:

1. Nondeterministically select a subset c of k nodes of G .
2. Test whether G contains all edges connecting nodes in c .
3. If yes, *accept*; otherwise, *reject*.”

SUBSET-SUM Problem

$SUBSET-SUM = \{\langle S, t \rangle \mid S = \{x_1, \dots, x_k\}, \text{ and for some } \{y_1, \dots, y_l\} \subseteq \{x_1, \dots, x_k\}, \text{ we have } \sum y_i = t\}.$

For example, $\langle \{4, 11, 16, 21, 27\}, 25 \rangle \in SUBSET-SUM$ because $4 + 21 = 25$. Note that $\{x_1, \dots, x_k\}$ and $\{y_1, \dots, y_l\}$ are considered to be *multisets* and so allow repetition of elements.

THEOREM 7.25

$SUBSET-SUM$ is in NP.

PROOF IDEA The subset is the certificate.

PROOF The following is a verifier V for $SUBSET-SUM$.

$V =$ “On input $\langle \langle S, t \rangle, c \rangle$:

1. Test whether c is a collection of numbers that sum to t .
2. Test whether S contains all the numbers in c .
3. If both pass, *accept*; otherwise, *reject*.”

- Given a set of number x_1, \dots, x_k and a target number t , determine whether the collection contains a subset that adds up to t

$N =$ “On input $\langle S, t \rangle$:

1. Nondeterministically select a subset c of the numbers in S .
2. Test whether c is a collection of numbers that sum to t .
3. If the test passes, *accept*; otherwise, *reject*.”

The complement of CLIQUE and SUBSET-SUM are not obvious members of NP. Verifying that something is not present seems more difficult than verifying it is present

The P versus NP question

- NP is the class of languages that are solvable in polynomial time on a Non-deterministic TM or whereby membership in the language can be checked in polynomial time
- P is the class of languages where membership can be tested in polynomial time.

P = the class of languages for which membership can be *decided* quickly.

NP = the class of languages for which membership can be *verified* quickly.

P vs. NP ?

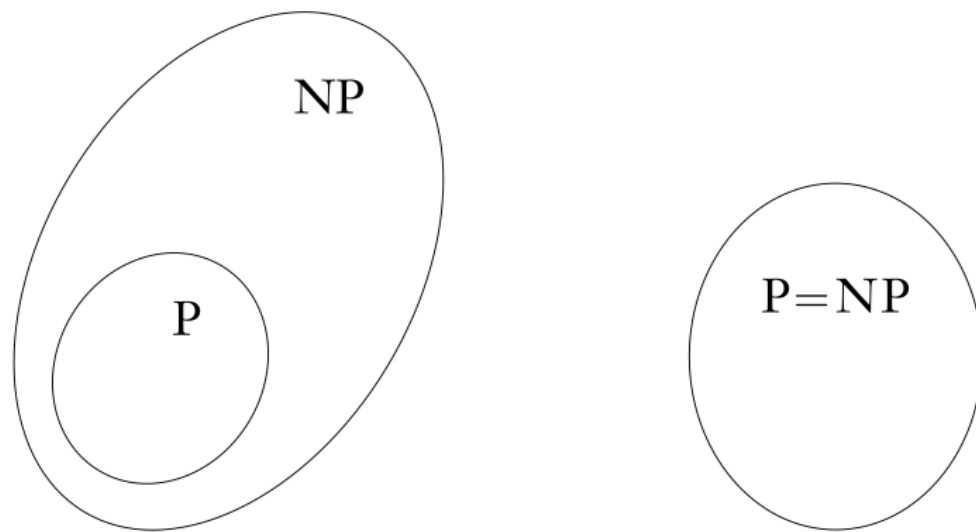


FIGURE 7.26

One of these two possibilities is correct

The best deterministic method currently known for deciding languages in NP uses exponential time. In other words, we can prove that

$$\text{NP} \subseteq \text{EXPTIME} = \bigcup_k \text{TIME}(2^{n^k}),$$

but we don't know whether NP is contained in a smaller deterministic time complexity class.

NP-completeness

- Important advance on the P vs. NP question came in the early 1970s with the work of Stephen Cook and Leonid Levin
- They discover that certain problems in NP whose individual complexity is related to that of the entire class
- If a polynomial time algorithm exists for any of these problems, all problems in NP would be polynomial time solvable
- These problems are called **NP-complete**
- Theory: if we have a polynomial time algorithm for an NP-complete problem, $P=NP$
- Practice: Prevent wasting time searching a nonexistent polynomial time algorithm to solve a particular problem

The satisfiability problem

- Boolean variables can take values: TRUE (1) and FALSE (0)
- Boolean operations AND (\wedge), OR (\vee) and NOT (\neg)
- Boolean formula: $\Phi = (\bar{a} \wedge y) \vee (a \wedge z)$
- A boolean formula is satisfiable if some assignment of 0s and 1s to the variables makes the formula evaluate to 1

$$SAT = \{ \langle \phi \rangle \mid \phi \text{ is a satisfiable Boolean formula} \}.$$

Now we state a theorem that links the complexity of the *SAT* problem to the complexities of all problems in NP.

$$SAT \in P \text{ iff } P=NP$$

Polynomial time reducibility

DEFINITION 7.28

A function $f: \Sigma^* \rightarrow \Sigma^*$ is a *polynomial time computable function* if some polynomial time Turing machine M exists that halts with just $f(w)$ on its tape, when started on any input w .

DEFINITION 7.29

Language A is *polynomial time mapping reducible*,¹ or simply *polynomial time reducible*, to language B , written $A \leq_P B$, if a polynomial time computable function $f: \Sigma^* \rightarrow \Sigma^*$ exists, where for every w ,

$$w \in A \iff f(w) \in B.$$

The function f is called the *polynomial time reduction* of A to B .

Thm

If $A \leq_P B$ and $B \in P$, then $A \in P$.

PROOF Let M be the polynomial time algorithm deciding B and f be the polynomial time reduction from A to B . We describe a polynomial time algorithm N deciding A as follows.

$N =$ “On input w :

1. Compute $f(w)$.
2. Run M on input $f(w)$ and output whatever M outputs.”

We have $w \in A$ whenever $f(w) \in B$ because f is a reduction from A to B . Thus, M accepts $f(w)$ whenever $w \in A$. Moreover, N runs in polynomial time because each of its two stages runs in polynomial time. Note that stage 2 runs in polynomial time because the composition of two polynomials is a polynomial.

3-CNF

form. A *literal* is a Boolean variable or a negated Boolean variable, as in x or \bar{x} . A *clause* is several literals connected with \vee s, as in $(x_1 \vee \bar{x}_2 \vee \bar{x}_3 \vee x_4)$. A Boolean formula is in *conjunctive normal form*, called a *cnf-formula*, if it comprises several clauses connected with \wedge s, as in

$$(x_1 \vee \bar{x}_2 \vee \bar{x}_3 \vee x_4) \wedge (x_3 \vee \bar{x}_5 \vee x_6) \wedge (x_3 \vee \bar{x}_6).$$

It is a *3cnf-formula* if all the clauses have three literals, as in

$$(x_1 \vee \bar{x}_2 \vee \bar{x}_3) \wedge (x_3 \vee \bar{x}_5 \vee x_6) \wedge (x_3 \vee \bar{x}_6 \vee x_4) \wedge (x_4 \vee x_5 \vee x_6).$$

Let $3SAT = \{\langle \phi \rangle \mid \phi \text{ is a satisfiable 3cnf-formula}\}$. If an assignment satisfies a cnf-formula, each clause must contain at least one literal that evaluates to 1.

The following theorem presents a polynomial time reduction from the $3SAT$ problem to the *CLIQUE* problem.

THEOREM 7.32

$3SAT$ is polynomial time reducible to *CLIQUE*.

Proof

Let f be a formula with k clauses

We can generate a string $\langle G, k \rangle$ where G is an undirected graph and k an integer

The nodes are labeled by the literals in the clauses

There is an edge between each nodes in the clauses if there is no incompatibility

Th: There is an assignment for f if and only if there is a k -clique in G

(\Rightarrow) If we have a valid assignment then we pick each valid variable in each clause and they form a valid clique

(\Leftarrow) If we have a valid k -clique, then we can put these variables to true and the formula is valid

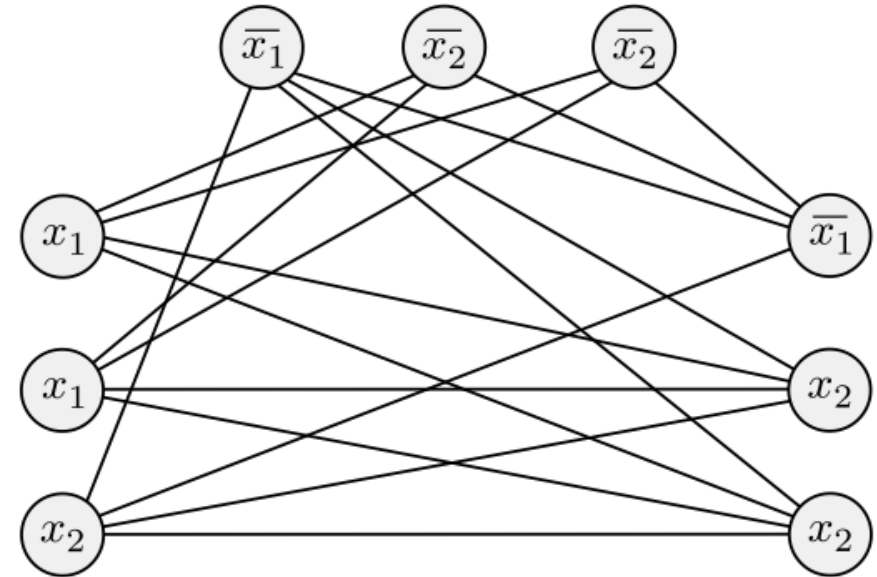


FIGURE 7.33

The graph that the reduction produces from

$$\phi = (x_1 \vee x_1 \vee x_2) \wedge (\bar{x}_1 \vee \bar{x}_2 \vee \bar{x}_2) \wedge (\bar{x}_1 \vee x_2 \vee x_2)$$

Definition of NP-Completeness

DEFINITION 7.34

A language B is **NP-complete** if it satisfies two conditions:

1. B is in NP, and
2. every A in NP is polynomial time reducible to B .

THEOREM 7.35

If B is NP-complete and $B \in P$, then $P = NP$.

PROOF This theorem follows directly from the definition of polynomial time reducibility.

THEOREM 7.36

If B is NP-complete and $B \leq_P C$ for C in NP, then C is NP-complete.

PROOF We already know that C is in NP, so we must show that every A in NP is polynomial time reducible to C . Because B is NP-complete, every language in NP is polynomial time reducible to B , and B in turn is polynomial time reducible to C . Polynomial time reductions compose; that is, if A is polynomial time reducible to B and B is polynomial time reducible to C , then A is polynomial time reducible to C . Hence every language in NP is polynomial time reducible to C .

SAT is NP-complete

SAT is in NP: a ND polynomial TM guesses the assignment and we can easily checked it

Take any language A in NP and show that A is P-time reducible to SAT

Let N be a NDTM deciding A in n^k (k constant)

A tableau is accepting if any row is accepting conf.

$(n^k)^2$ cells in the tableau

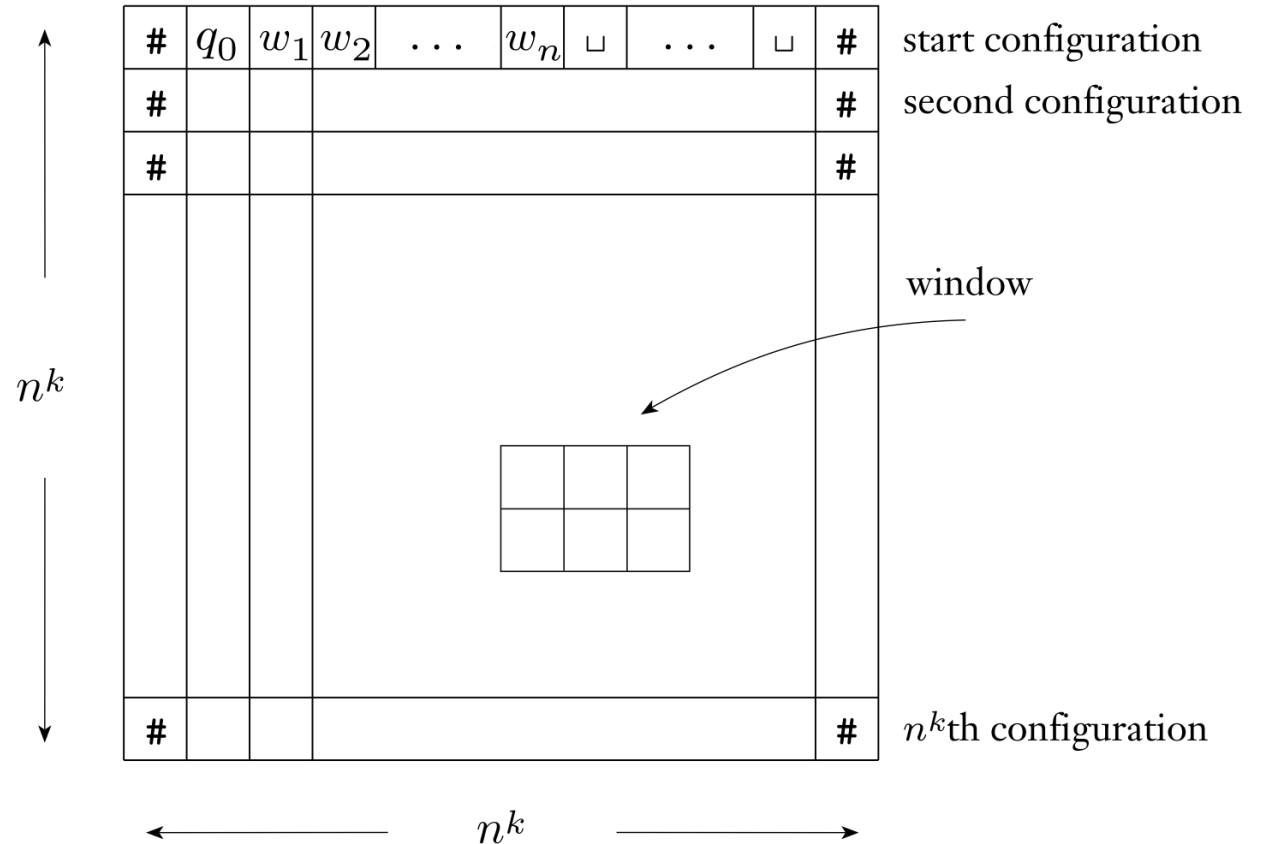
Variables $x_{i,j,s}$ is 1 if cell[i,j]==s

Formula: f_{cell} AND f_{start} AND f_{move} AND f_{accept}

$$\phi_{\text{cell}} = \bigwedge_{1 \leq i, j \leq n^k} \left[\left(\bigvee_{s \in C} x_{i,j,s} \right) \wedge \left(\bigwedge_{\substack{s, t \in C \\ s \neq t}} (\overline{x_{i,j,s}} \vee \overline{x_{i,j,t}}) \right) \right].$$

$$\begin{aligned} \phi_{\text{start}} = & x_{1,1,\#} \wedge x_{1,2,q_0} \wedge \\ & x_{1,3,w_1} \wedge x_{1,4,w_2} \wedge \dots \wedge x_{1,n+2,w_n} \wedge \\ & x_{1,n+3,\sqcup} \wedge \dots \wedge x_{1,n^k-1,\sqcup} \wedge x_{1,n^k,\#}. \end{aligned}$$

$$\phi_{\text{accept}} = \bigvee_{1 \leq i, j \leq n^k} x_{i,j,q_{\text{accept}}}.$$



Legal Moves

It is possible to encode each legal moves based on the transition table using a small number of variables

We can verify that the size of the formula is polynomial in n ($2k$ is a constant in the exponent)

$$\phi_{\text{move}} = \bigwedge_{1 \leq i < n^k, 1 \leq j < n^k} (\text{the } (i, j)\text{-window is legal}).$$

(a)

a	q_1	b
q_2	a	c

(b)

a	q_1	b
a	a	q_2

(c)

a	a	q_1
a	a	b

(d)

#	b	a
#	b	a

(e)

a	b	a
a	b	q_2

(f)

b	b	b
c	b	b

FIGURE 7.39
Examples of legal windows

(a)

a	b	a
a	a	a

(b)

a	q_1	b
q_2	a	a

(c)

b	q_1	b
q_2	b	q_2

FIGURE 7.40
Examples of illegal windows

$$\bigvee_{\substack{a_1, \dots, a_6 \\ \text{is a legal window}}} (x_{i,j-1,a_1} \wedge x_{i,j,a_2} \wedge x_{i,j+1,a_3} \wedge x_{i+1,j-1,a_4} \wedge x_{i+1,j,a_5} \wedge x_{i+1,j+1,a_6})$$

From SAT to 3SAT: 3SAT is NP-complete

- We can replace each clause with at most 3 variables
- If a clause contains more than 3 variables ($a_1 \text{ OR } a_2 \text{ OR } a_3 \text{ OR } a_4$) it can be rewritten as $(a_1 \text{ OR } a_2 \text{ OR } z) \text{ AND } (\text{NOT}(z) \text{ OR } a_3 \text{ OR } a_4)$
- More generally

$$(a_1 \vee a_2 \vee \cdots \vee a_l),$$

we can replace it with the $l - 2$ clauses

$$(a_1 \vee a_2 \vee z_1) \wedge (\overline{z_1} \vee a_3 \vee z_2) \wedge (\overline{z_2} \vee a_4 \vee z_3) \wedge \cdots \wedge (\overline{z_{l-3}} \vee a_{l-1} \vee a_l).$$

- CLIQUE is NP-complete
- 2-SAT is not NP-complete

Other reductions: Vertex cover

$VERTEX-COVER = \{\langle G, k \rangle \mid G \text{ is an undirected graph that has a } k\text{-node vertex cover}\}.$

THEOREM 7.44

$VERTEX-COVER$ is NP-complete.

1. Show that $VERTEX-COVER$ is in NP
2. Show that $VERTEX-COVER$ is complete

Reduction between 3SAT and Vertex cover

$VERTEX-COVER = \{\langle G, k \rangle \mid G \text{ is an undirected graph that has a } k\text{-node vertex cover}\}.$

THEOREM 7.44

$VERTEX-COVER$ is NP-complete.

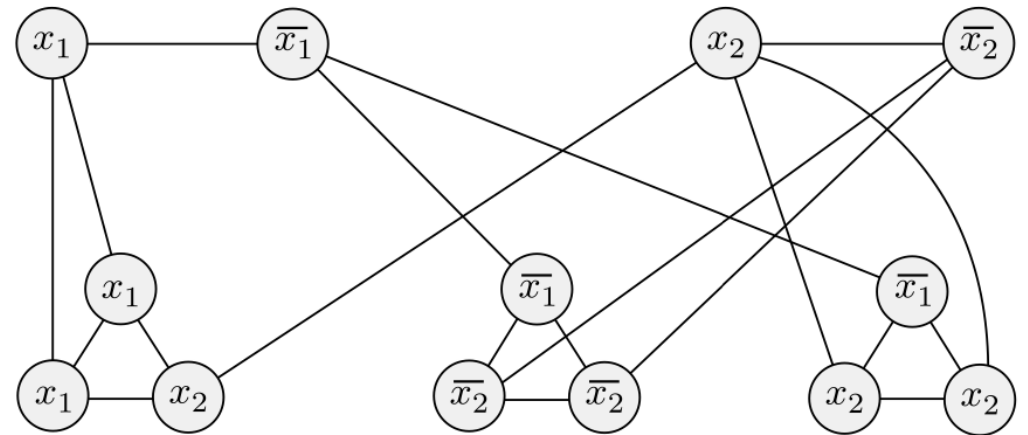


FIGURE 7.45

The graph that the reduction produces from
 $\phi = (x_1 \vee x_1 \vee x_2) \wedge (\overline{x_1} \vee \overline{x_2} \vee \overline{x_2}) \wedge (\overline{x_1} \vee x_2 \vee x_2)$

THEOREM 7.56

SUBSET-SUM is NP-complete.

	1	2	3	4	...	l	c_1	c_2	...	c_k
y_1	1	0	0	0	...	0	1	0	...	0
z_1	1	0	0	0	...	0	0	0	...	0
y_2		1	0	0	...	0	0	1	...	0
z_2		1	0	0	...	0	1	0	...	0
y_3			1	0	...	0	1	1	...	0
z_3			1	0	...	0	0	0	...	1
\vdots					\ddots	\vdots	\vdots		\vdots	\vdots
y_l						1	0	0	...	0
z_l						1	0	0	...	0
g_1							1	0	...	0
h_1							1	0	...	0
g_2								1	...	0
h_2								1	...	0
\vdots									\ddots	\vdots
g_k										1
h_k										1
t	1	1	1	1	...	1	3	3	...	3

FIGURE 7.57
Reducing 3SAT to SUBSET-SUM

THEOREM 7.56

SUBSET-SUM is NP-complete.

1. Show that SUBSET-SUM is in NP
2. Show that SUBSET-SUM is complete

Lectures

- <http://cgi.di.uoa.gr/~sgk/teaching/grad/handouts/karp.pdf>
- https://en.wikipedia.org/wiki/Karp%27s_21_NP-complete_problems
- Richard Karp gave the first 21 NP-complete problems
- It is useful to read such results to know which problems are very hard and it is useless to find a polynomial-time algorithm