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## Isotonic Regression

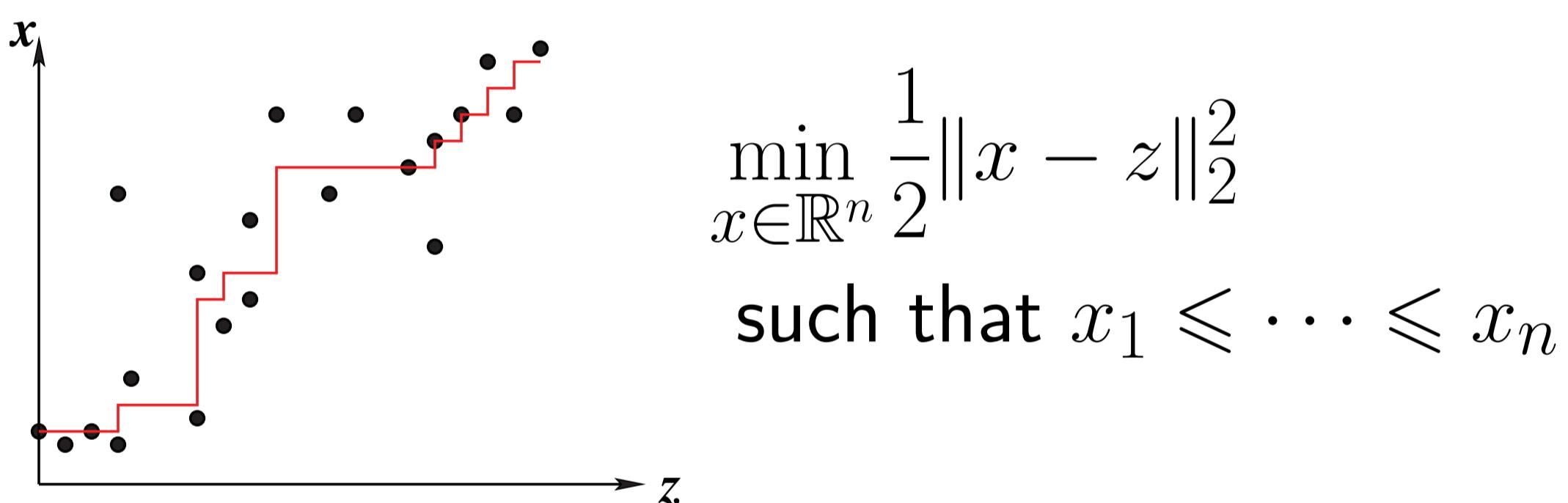
- Imposing ordering constraints on estimation problems
- Signal processing, machine learning and statistics
  - Probability calibration for classification
  - Interpretability

### Constrained optimization problem

$$\min_{x \in \mathbb{R}^n} H(x) \text{ such that } \forall (i, j) \in E, x_i \geq x_j,$$

where  $E \subset \{1, \dots, n\}^2$  is a directed acyclic graph.

- Most classical example: separable quadratic cost



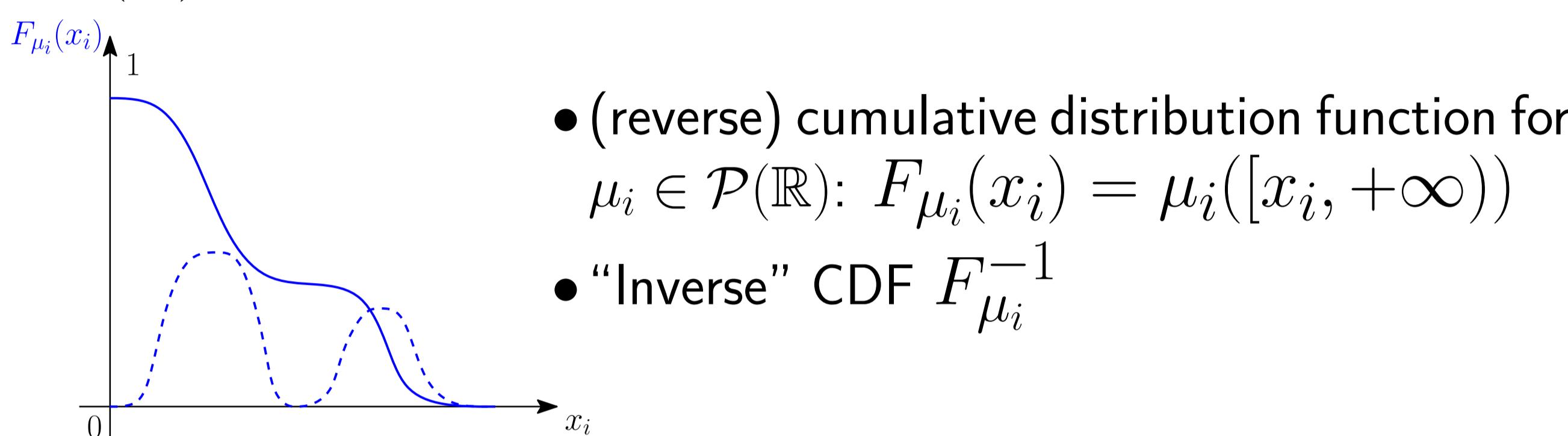
- Convex function  $H \Rightarrow$  convex optimization problem
  - Efficient first-order algorithms
- Non-convex function  $H$ 
  - No efficient algorithms general

## Submodular Functions

- Definition ([1]):  $\forall x \in \mathbb{R}^n, \forall i \neq j, \frac{\partial^2 H}{\partial x_i \partial x_j}(x) \leq 0$
- Example 1 (Laplacian):  $H(x) = \sum_{i,j=1}^n w_{ij}(x_i - x_j)^2$
- Example 2 (Separable functions):  $H(x) = \sum_{i=1}^n h_i(x_i)$ 
  - For any (e.g., non-convex) functions  $h_i : \mathbb{R} \rightarrow \mathbb{R}$

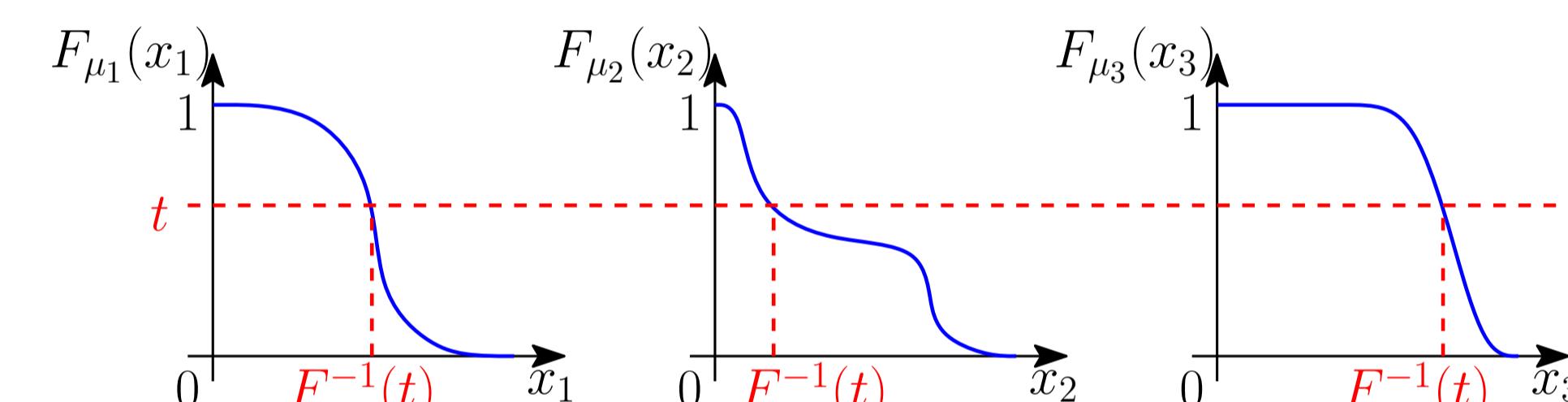
## Convex Extension with Measures

- $\mathcal{P}(\mathbb{R})$  = set of Radon probability measures on  $\mathbb{R}$



- Extension to  $\mu = (\mu_1, \dots, \mu_n)$  – see [2]:

$$h(\mu_1, \dots, \mu_m) = \int_0^1 H[F_{\mu_1}^{-1}(t), \dots, F_{\mu_n}^{-1}(t)] dt$$

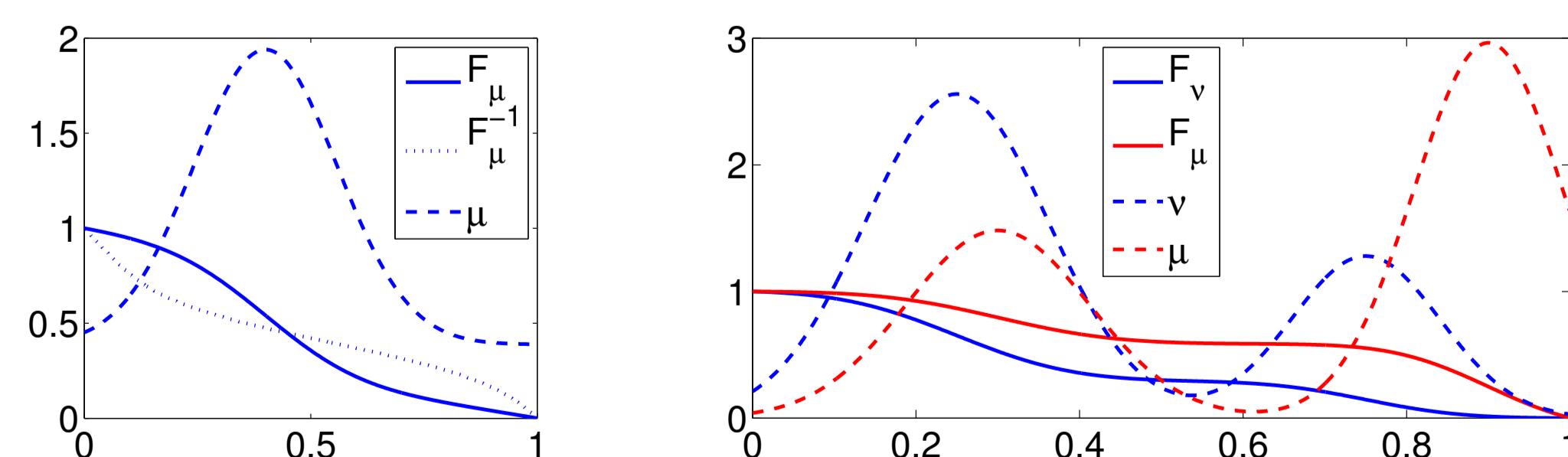


- Property 1:  $H$  submodular  $\Leftrightarrow h$  convex
- Property 2: minimizers of  $H$  can be recovered from minimizers of  $h$
- Consequence: Submodular function minimization is a convex optimization problem

## Extension for Isotonic Constraints

- First-order stochastic dominance between  $\mu, \nu \in \mathcal{P}(\mathbb{R})$ :

$$\mu \succcurlyeq \nu \text{ if and only if } \forall x \in \mathbb{R}, F_\mu(x) \geq F_\nu(x)$$



- Equivalent optimization problem

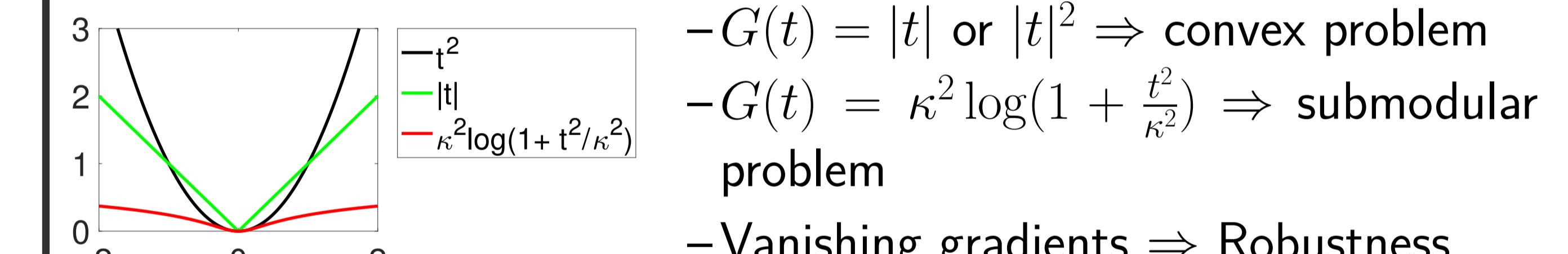
$$\min_{\mu \in \mathcal{P}(\mathbb{R})^n} h(\mu) \text{ such that } \forall (i, j) \in E, \mu_i \succcurlyeq \mu_j$$

## Discretization Algorithms

- Discretize each interval with  $k$  values
  - Approximation  $O(n/k)$
  - Number of queries of  $H$  is  $O(tnk)$  for  $t$  operations of projected subgradient descent
  - Projection based on (efficient) quadratic cost isotonic regression [3]
  - Extra approximation factor  $O(n/\sqrt{t})$
- With  $k = n/\varepsilon$  and  $t = n^2/\varepsilon^2$ 
  - Error  $\varepsilon$  and number of queries  $O(n^4/\varepsilon^3)$
- For improved behavior, see paper

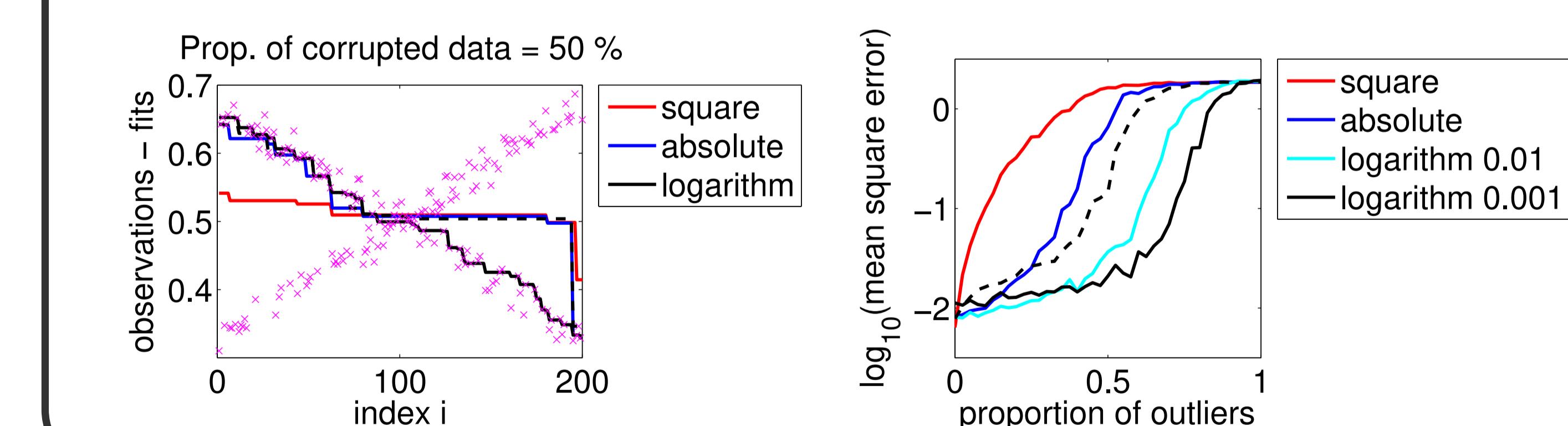
## Experiments

- Robust isotonic regression:  $H(x) = \frac{1}{n} \sum_{i=1}^n G(x_i - z_i)$



- Data with adversarial perturbations

- Goal: learn decreasing functions
- Perturbation by noise and increasing function (observations in pink)



## References

- [1] D. M. Topkis. Minimizing a submodular function on a lattice. *Operations Research*, 26(2):305–321, 1978.
- [2] F. Bach. Submodular functions: from discrete to continuous domains. *Mathematical Programming*, 2018
- [3] Q. F. Stout. Isotonic regression via partitioning. *Algorithmica*, 66(1):93–112, 2013.