

# Rethinking Early Stopping: Refine, Then Calibrate

Eugène Berta, David Holzmüller, Michael I. Jordan, Francis Bach

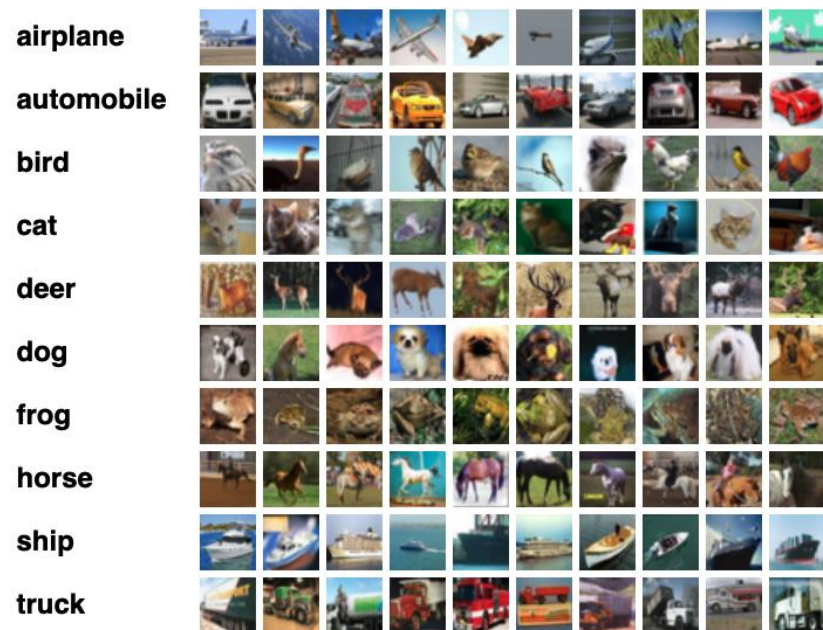


# Outline

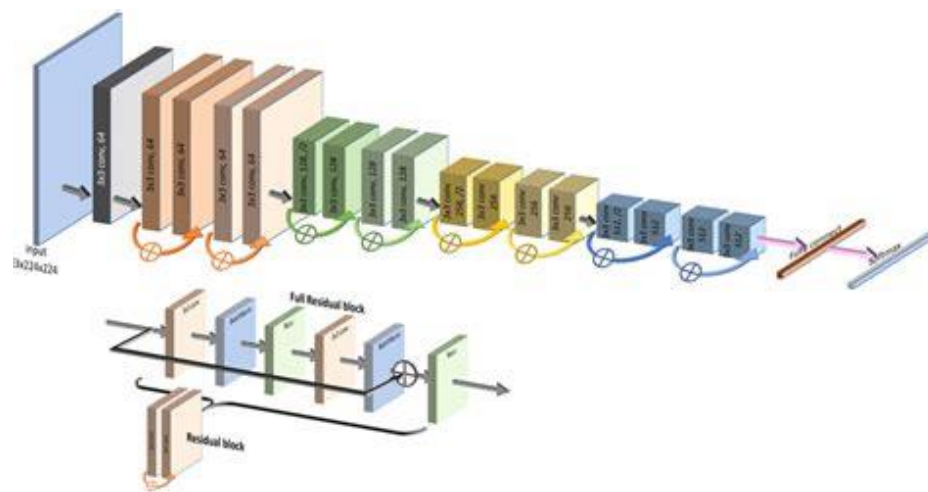
- Motivating example
- Loss function decomposition in classification
- Proposed method
- Empirical results
- A (simple)theoretical analysis: logistic regression in the high dimensional Gaussian data model

# Motivating example

Dataset  $D$   
Images, tabular, text...



Machine learning classifier  $f$   
logistic regression, boosted trees, neural net...



Predictions

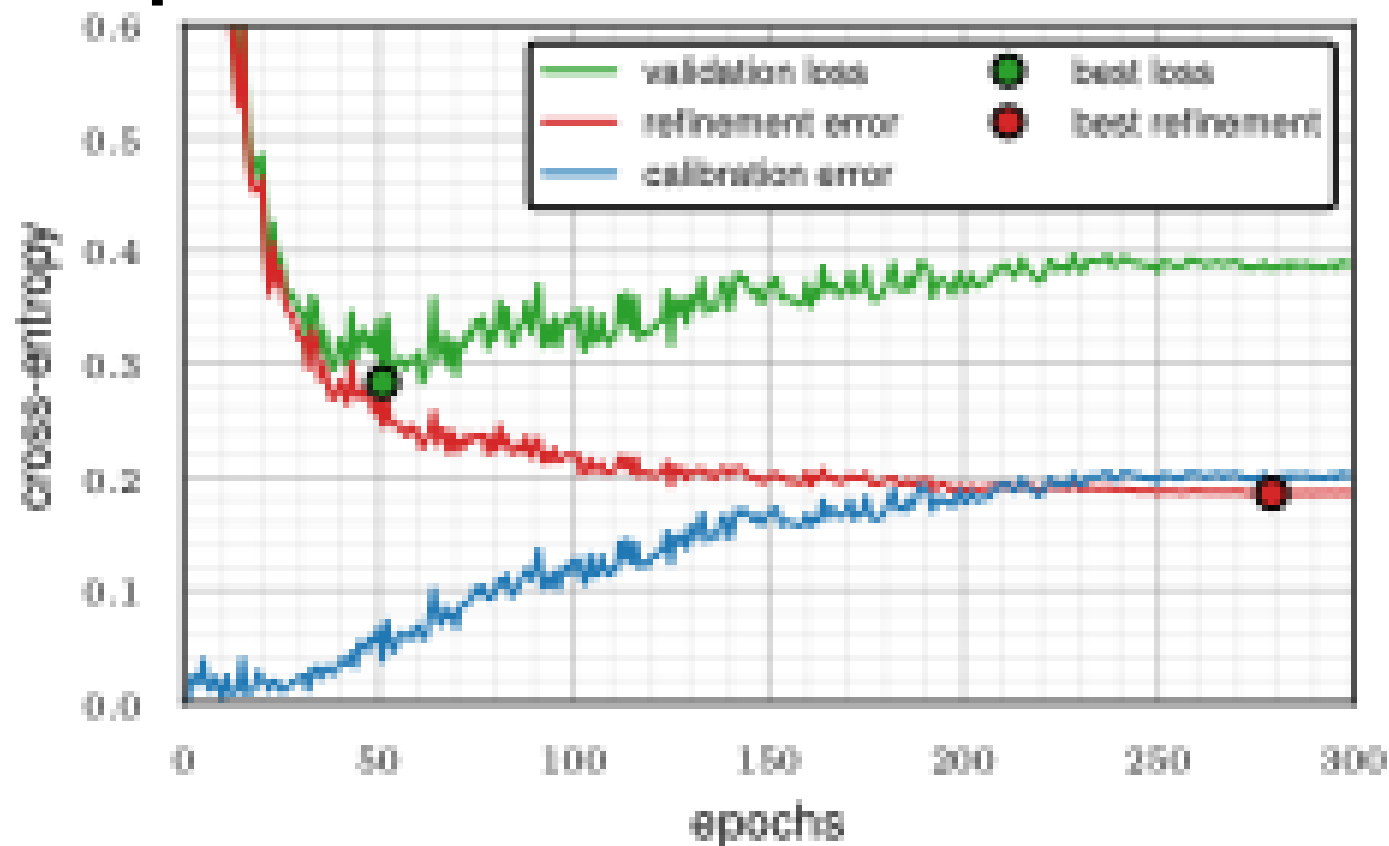
0.02	<b>airplane</b>
0.9	<b>automobile</b>
0.	<b>bird</b>
0.005	<b>cat</b>
0.	<b>deer</b>
0.005	<b>dog</b>
0.	<b>frog</b>
0.	<b>horse</b>
0.02	<b>ship</b>
0.05	<b>truck</b>

# Motivating example

## Model fitting

training, hyper-parameter search...

$$\min_{f \in \mathcal{F}} \text{Risk}_D(f)$$



*Training a ResNet-18 on CIFAR-10. We plot the cross-entropy loss on the validation set, with its calibration and refinement error terms.*

What is this decomposition?

Is there a better way to train classifiers?

# Proper loss functions in classification

Predictions in  $\Delta_k = \{p \in [0, 1]^k | \mathbf{1}^\top p = 1\}$ , labels in  $\mathcal{Y}_k = \{y \in \{0, 1\}^k | \mathbf{1}^\top y = 1\}$ .

Evaluated with loss functions  $\ell : \Delta_k \times \mathcal{Y}_k \rightarrow \mathbb{R}_+$ ,

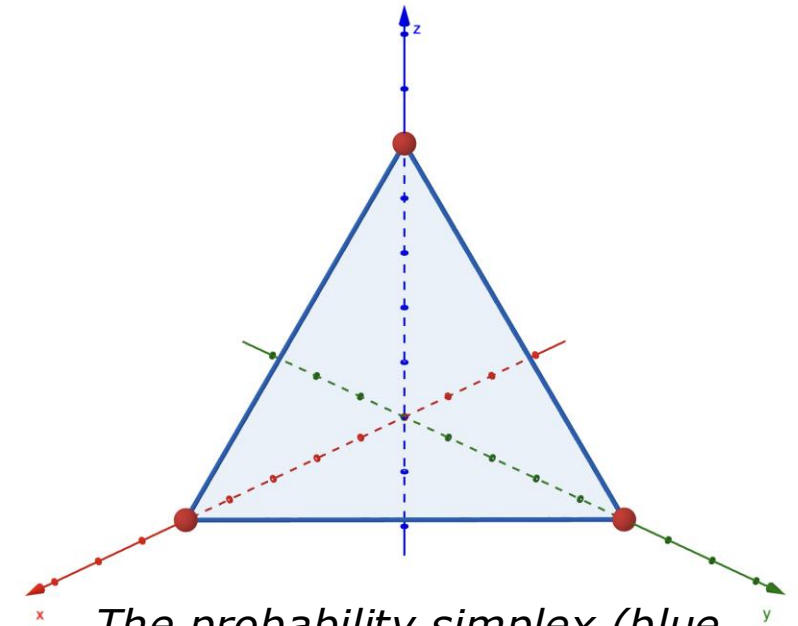
such as:

- The Brier score  $\ell(p, y) = \|y - p\|_2^2$
- The log-loss  $\ell(p, y) = -\sum_{i=1}^k y_i \log(p_i)$

We overload the notation:  $\ell(p, q) = \mathbb{E}_{y \sim q}[\ell(p, y)]$

A natural requirement is that  $\ell(q, q) \leq \ell(p, q), \forall p, q$ .

Then,  $\ell$  is called proper (**log-loss and brier are proper losses**).



The probability simplex (blue triangle) and label space (red dots) for  $k=3$ .

Gneiting, T., & Raftery, A. E. (2007). Strictly Proper Scoring Rules, Prediction, and Estimation. *Journal of the American Statistical Association*.

# Decomposition of Brier score

In machine learning, we usually have  $(X, Y) \sim \mathcal{D}$  .

We make predictions  $p = f(X)$  with a model  $f : \mathcal{X} \rightarrow \Delta_k$  .

In this setting, for the Brier score,

$$\text{Risk}_{\mathcal{D}}(f) = \mathbb{E}_{\mathcal{D}} [\|f(X) - Y\|_2^2] = \mathbb{E}_{\mathcal{D}} [\|Y - \mathbb{E}[Y|f(X)]\|_2^2] + \mathbb{E}_{\mathcal{D}} [\|f(X) - \mathbb{E}[Y|f(X)]\|_2^2]$$

Bröcker, J. (2009). Reliability, sufficiency, and the decomposition of proper scores. *Quarterly Journal of the Royal Meteorological Society*.

Kull, M., & Flach, P. (2015). Novel decompositions of proper scoring rules for classification: Score adjustment as precursor to calibration. *Machine Learning and Knowledge Discovery in Databases: European Conference*.

# Decomposition of proper losses

In machine learning, we usually have  $(X, Y) \sim \mathcal{D}$  .

We make predictions  $p = f(X)$  with a model  $f : \mathcal{X} \rightarrow \Delta_k$  .

In this setting, for any proper loss,

$$\text{Risk}_{\mathcal{D}}(f) = \mathbb{E}_{\mathcal{D}}[\ell(f(X), Y)] = \mathbb{E}_{\mathcal{D}}[d_{\ell}(f(X), C)] + \mathbb{E}_{\mathcal{D}}[e_{\ell}(C)]$$

with  $\underbrace{d_{\ell}(p, q) = \ell(p, q) - \ell(q, q)}_{\ell\text{-divergence}}$  ,  $\underbrace{e_{\ell}(q) = \ell(q, q)}_{\ell\text{-entropy}}$  , and  $\underbrace{C = \mathbb{E}_{\mathcal{D}}[Y|f(X)]}_{\text{Calibrated scores}}$  .

Bröcker, J. (2009). Reliability, sufficiency, and the decomposition of proper scores. *Quarterly Journal of the Royal Meteorological Society*.  
Kull, M., & Flach, P. (2015). Novel decompositions of proper scoring rules for classification: Score adjustment as precursor to calibration. *Machine Learning and Knowledge Discovery in Databases: European Conference*.



# Decomposition of proper losses

$$\underbrace{\mathbb{E}_{\mathcal{D}}[\ell(f(X), Y)]}_{\text{Risk}} = \underbrace{\mathbb{E}_{\mathcal{D}}[d_{\ell}(f(X), C)]}_{\text{Calibration error}} + \underbrace{\mathbb{E}_{\mathcal{D}}[e_{\ell}(C)]}_{\text{Refinement error}}$$

Risk: How good are my predictions?

=

Calibration error: is my model over/under confident?

+

Refinement error: how well does my model separates classes? (accuracy, AUROC)

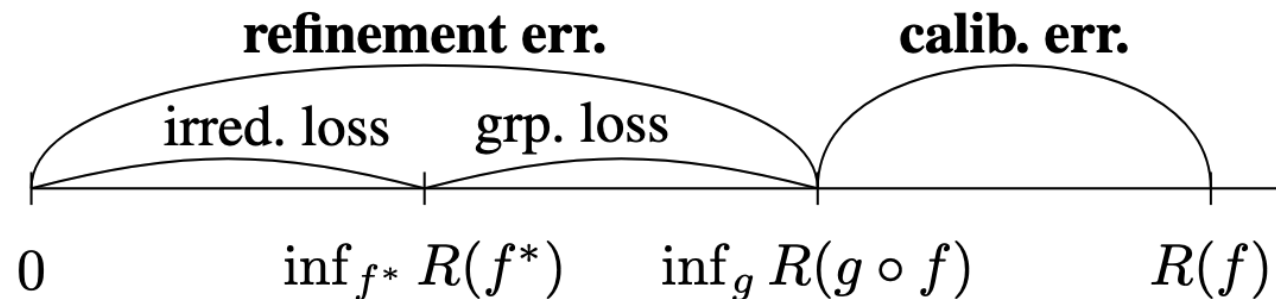
Proper loss $\ell$	Divergence $d_{\ell}$	Entropy $e_{\ell}$
Logloss $-\sum_i y_i \log(p_i)$	KL divergence $\sum_i q_i \log \frac{q_i}{p_i}$	Shannon entropy $-\sum_i q_i \log q_i$
Brier score $\ y - p\ _2^2$	Squared distance $\ p - q\ _2^2$	Gini index $\sum_i q_i(1 - q_i)$

# A new variational decomposition

**Proposition**  
**[BHJB,2025]:**

**Refinement error:**  $\mathcal{R}_\ell(f) = \min_g \text{Risk}_\mathcal{D}(g \circ f)$

**Calibration error:**  $\mathcal{K}_\ell(f) = \text{Risk}_\mathcal{D}(f) - \min_g \text{Risk}_\mathcal{D}(g \circ f)$



# A new variational decomposition

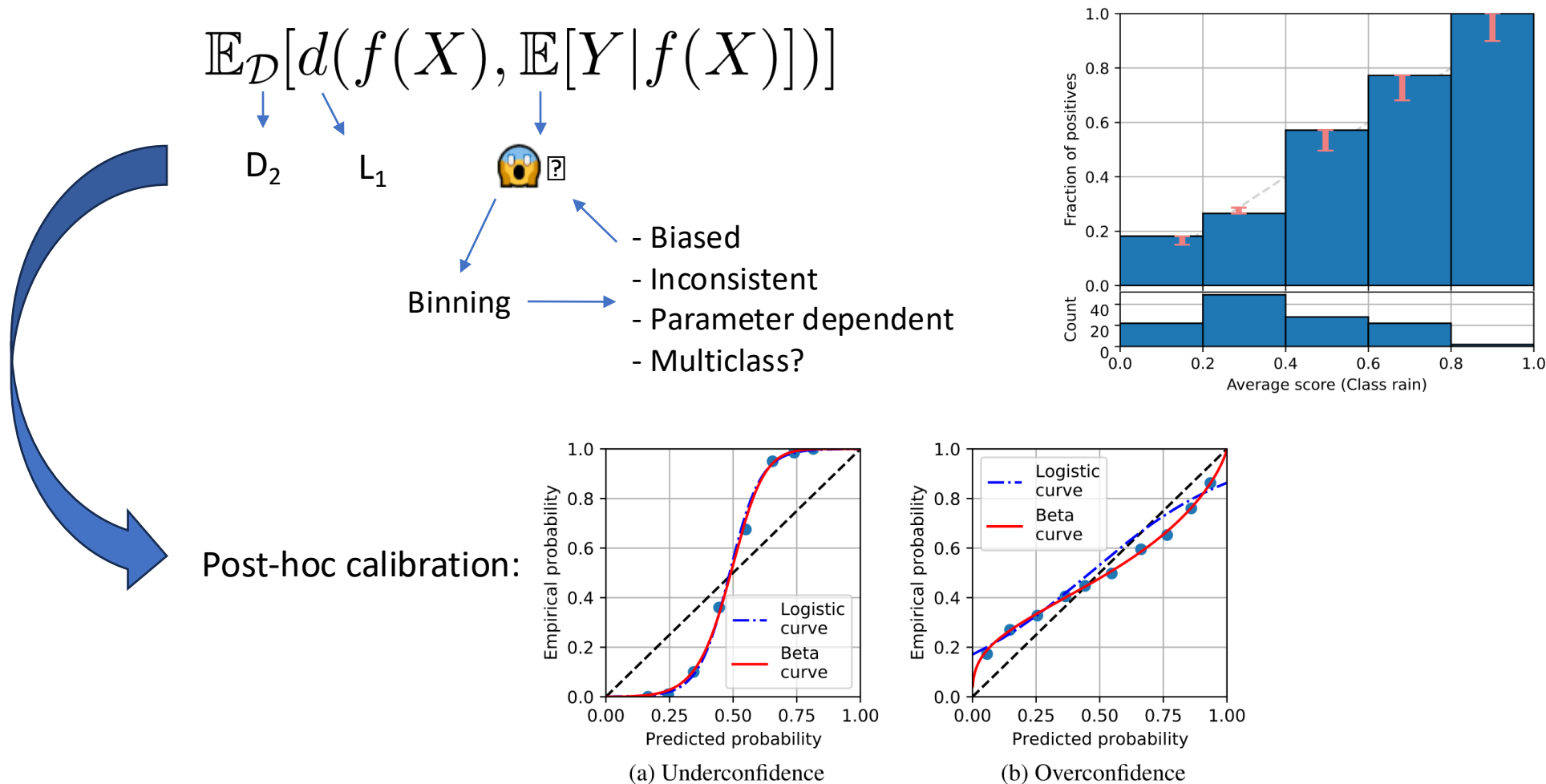
**Proposition**  
**[BHJB, 2025]:** **Refinement error:**  $\mathcal{R}_\ell(f) = \min_g \text{Risk}_{\mathcal{D}}(g \circ f)$

**Proof for log loss:**  $\min_g \mathbb{E}_{\mathcal{D}}[\ell(Y, g(f(X)))] = - \sum_{i=1}^k \mathbb{E}_{\mathcal{D}}[Y_i \log g(f(X))_i]$

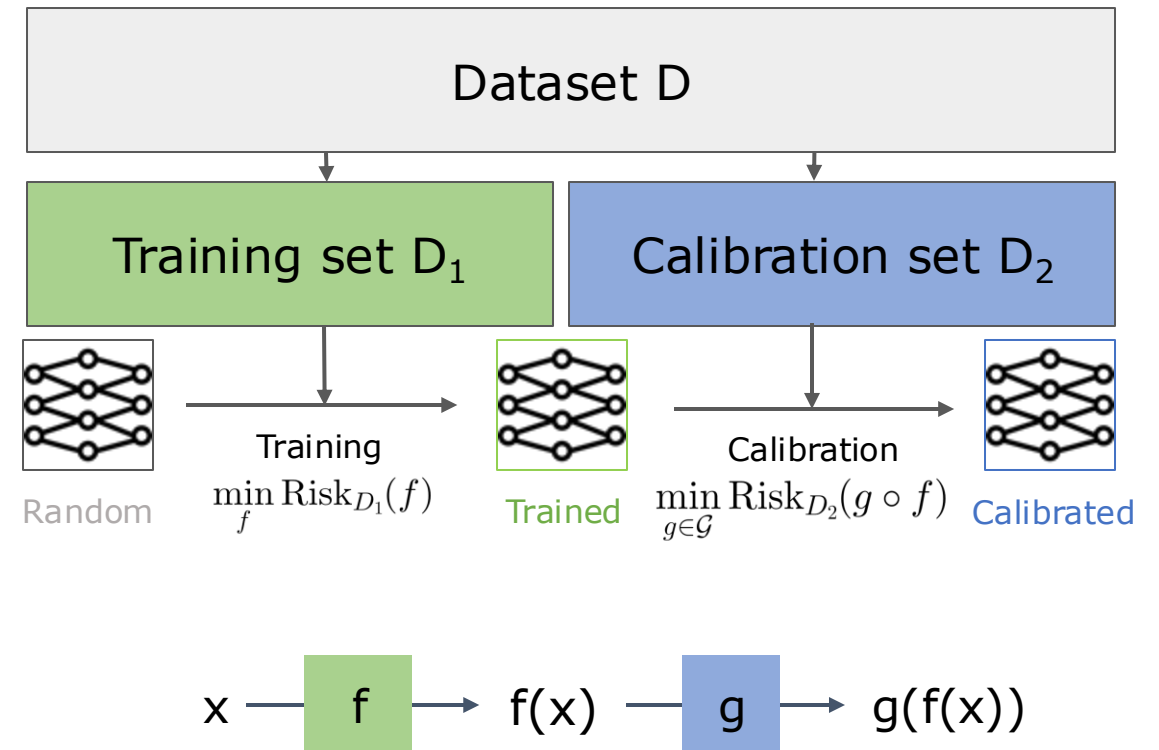
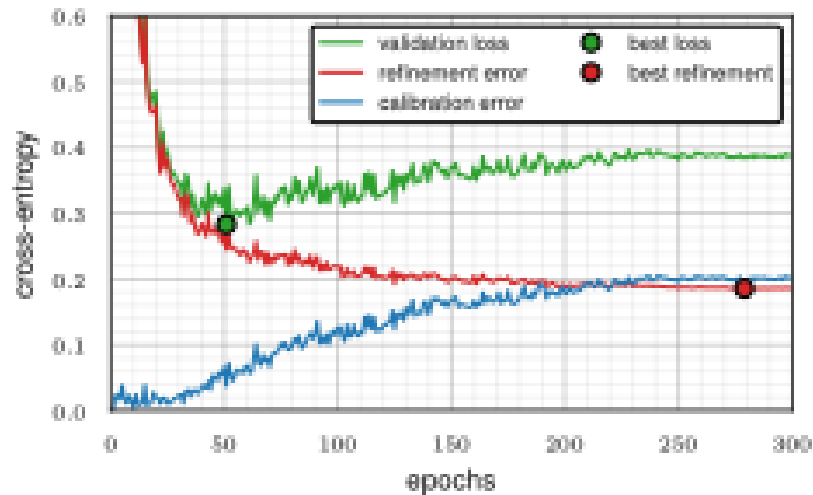
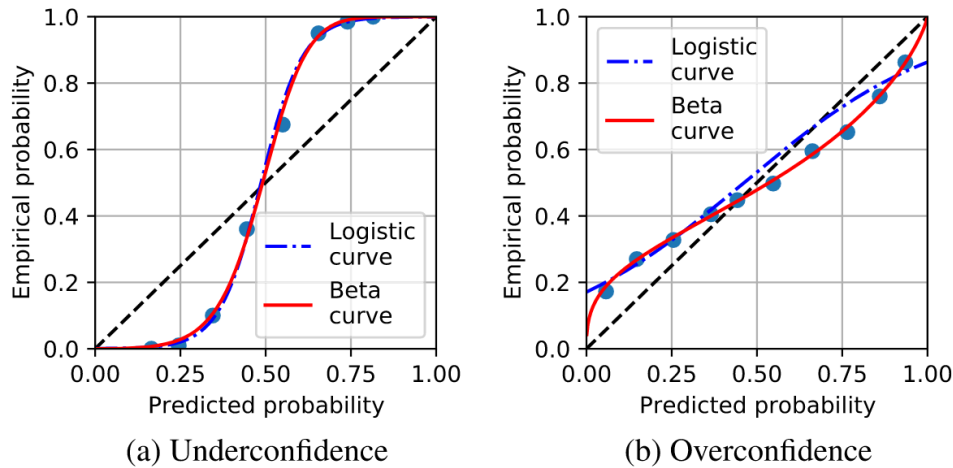
minimized when  $g(f(X)) = \mathbb{E}[Y|f(X)]$

with value  $\mathbb{E}_{\mathcal{D}}[e_\ell(\mathbb{E}[Y|f(X)])] = - \sum_{i=1}^k \mathbb{E}[Y_i|f(X)] \log(\mathbb{E}[Y_i|f(X)])$

# Calibration in the ML literature



# Post-hoc calibration



# Post-hoc calibration

## Isotonic regression

$$\min_{g \nearrow} \text{Risk}_{D_2}(g \circ f)$$

- ✓ Preserves the ROC convex hull.
- ✓ Theoretical guarantees.
- ✗ Ill defined in the multi-class case.

## Temperature scaling

$$\min_{\alpha \in \mathbb{R}} \text{Risk}_{D_2}(g_\alpha \circ f)$$

Where  $g_\alpha(p) = \text{Softmax}(\alpha \log(p))$

- ✓ Preserves refinement error.
- ✓ Inherently multi-class.
- ✗ No theoretical guarantees?

Zadrozny, B., & Elkan, C. (2002). Transforming classifier scores into accurate multiclass probability estimates. *International conference on KDD*.

Berta, E., Bach, F. & Jordan, M.. (2024). Classifier Calibration with ROC-Regularized Isotonic Regression. *AISTATS*

Guo, C., Pleiss, G., Sun, Y., & Weinberger, K. Q. (2017). On calibration of modern neural networks. *International conference on machine learning*.

# A new variational decomposition

**Proposition**  
**[BHJB,2025]:**

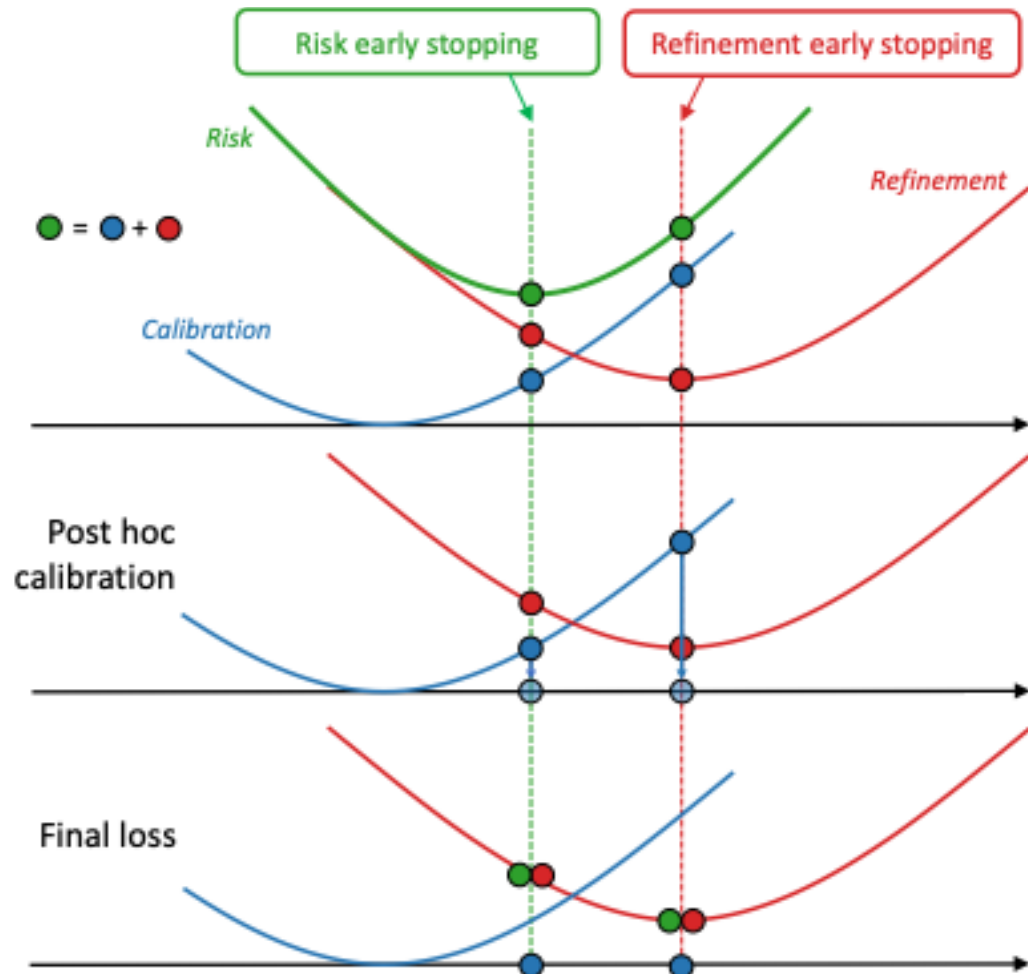
**Refinement error:**  $\mathcal{R}_\ell(f) = \min_g \text{Risk}_{\mathcal{D}}(g \circ f)$

**Calibration error:**  $\mathcal{K}_\ell(f) = \text{Risk}_{\mathcal{D}}(f) - \min_g \text{Risk}_{\mathcal{D}}(g \circ f)$

**Consequences:** Post-hoc calibration

1. is an estimator of (bounds on) the calibration error
2. reduces calibration error
3. does not impact refinement error

# Our method: Refine, Then Calibrate



Early stopping	Training minimizes	Post hoc minimizes
Risk	Cal. + Ref.	Cal.
Refinement	Ref.	Cal.



# How can we estimate refinement?

Validation accuracy? Area under the ROC curve?

$$\mathcal{R}_\ell(f) = \min_g \text{Risk}_{\mathcal{D}}(g \circ f)$$

$$\mathcal{R}_\ell(f) \simeq \min_{g \in \mathcal{G}} \text{Risk}_{\mathcal{D}_2}(g \circ f)$$



Validation loss after post-hoc calibration.

# Choosing $\mathcal{G}$

Large  $\mathcal{G}$ ?

e.g. Isotonic regression

✓ little bias in our estimator

✗ over-fitting the validation set  $D_2$

Small  $\mathcal{G}$ ?

e.g. Temperature scaling

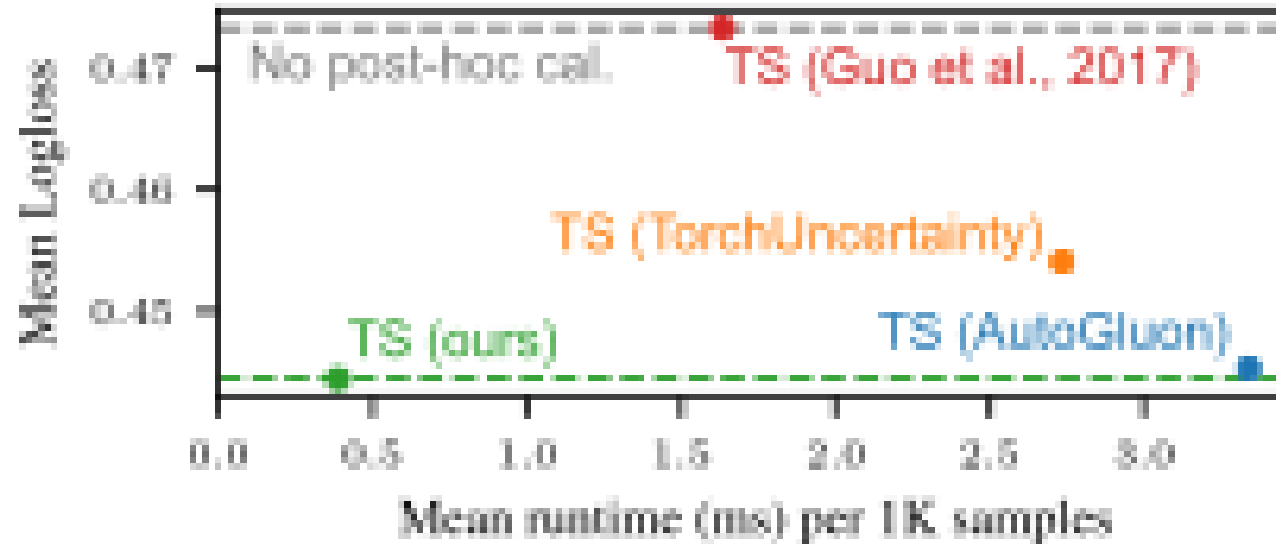
✓ robust to over-fitting

✗ biased estimator? Unless close to  $g^*(f(X)) = \mathbb{E}_{\mathcal{D}}[Y|f(X)]$

We evaluate **TS-refinement** = validation loss after temperature scaling

⚠ Could be any other refinement estimator.

# Use the best implementation, ours!

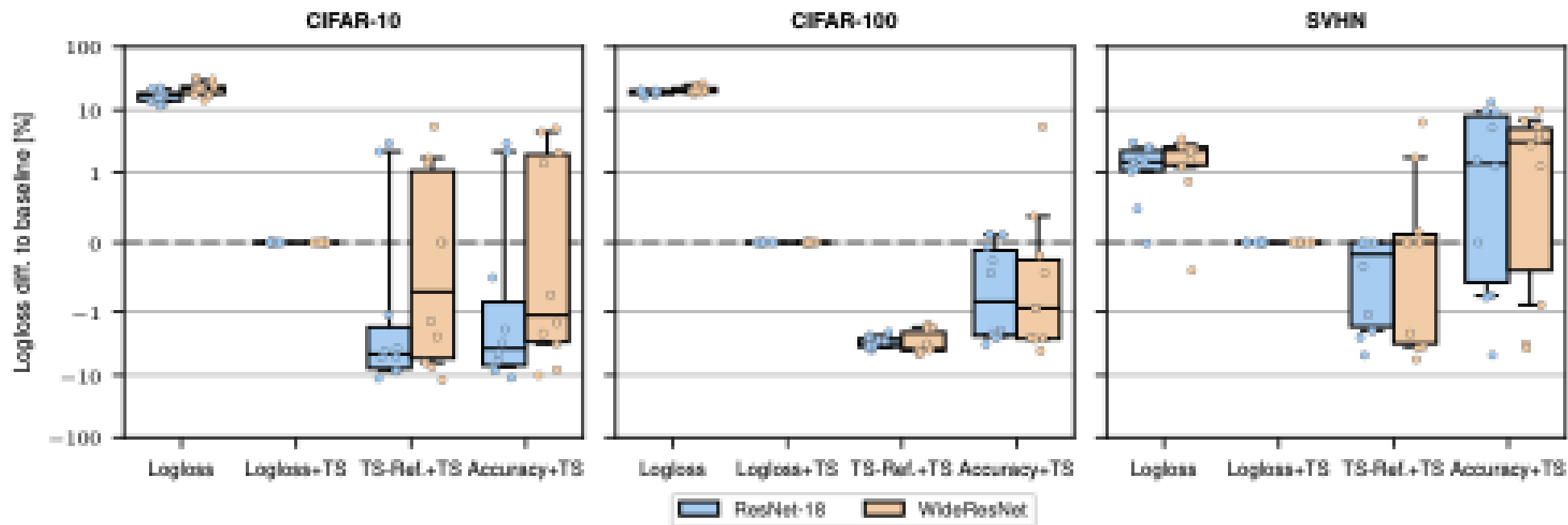


**Runtime versus mean benchmark scores of different TS implementations.**

Runtimes are averaged over validation sets with 10K+ samples. Evaluation is on XGBoost models trained with default parameters, using the epoch with the best validation accuracy.

[github.com/dholzmueller/probmetrics](https://github.com/dholzmueller/probmetrics)

# Results – computer vision

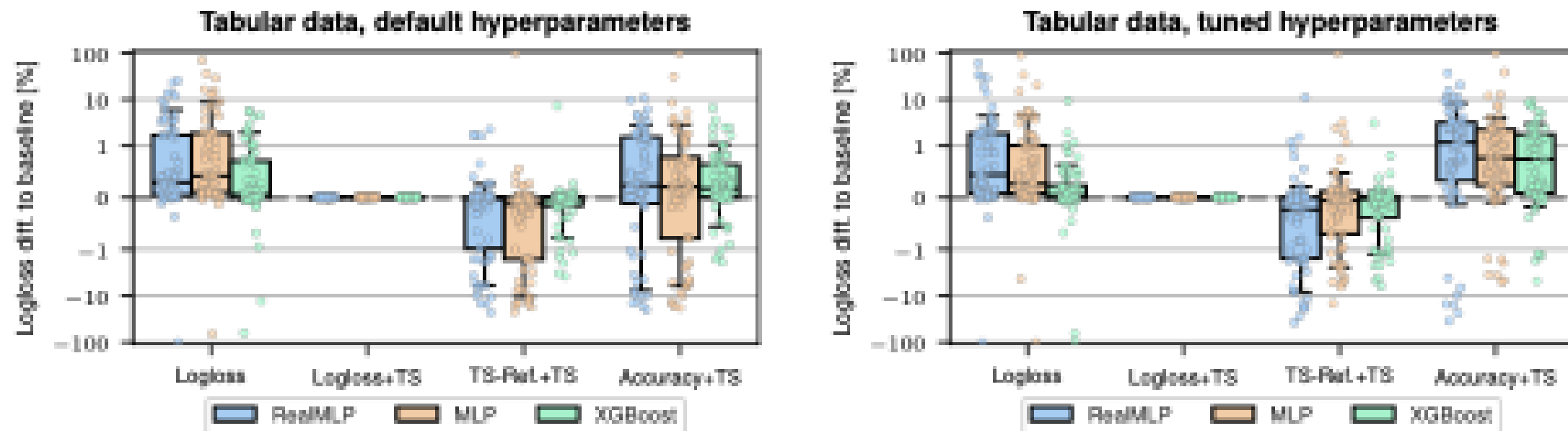


**Relative differences in test log-loss (lower is better) between logloss+TS and other procedures on vision datasets.**

“+TS” indicates temperature scaling applied to the final model. Each dot represents a training run on one dataset. Box-plots show the 10%, 25%, 50%, 75%, and 90% quantiles. Relative differences (y-axis) are plotted using a log scale.

[github.com/eugeneberta/RefineThenCalibrate-Vision](https://github.com/eugeneberta/RefineThenCalibrate-Vision)

# Results – tabular data



**Relative differences in test logloss (lower is better) between logloss+TS and other procedures on tabular datasets.**

“+TS” indicates temperature scaling applied to the final model. Each dot represents one dataset with 10K+ samples. Percentages are clipped to  $[-100, 100]$  due to one outlier with almost zero loss. Box-plots show the 10%, 25%, 50%, 75%, and 90% quantiles. Relative differences (y-axis) are plotted using a log scale.

[github.com/dholzmueLLer/pytabkit](https://github.com/dholzmueLLer/pytabkit)

# Theoretical analysis: the Gaussian data model

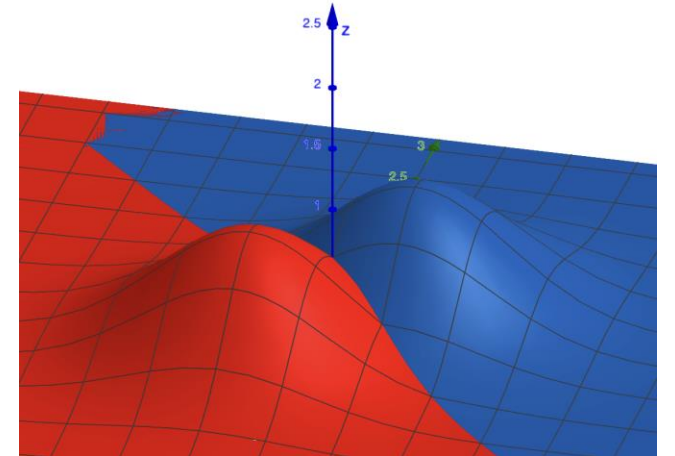
Gaussian data model:

$$X \in \mathbb{R}^p, Y \in \{-1, 1\} \begin{cases} X \sim \mathcal{N}(\mu, \Sigma) & \text{if } Y = 1 \\ X \sim \mathcal{N}(-\mu, \Sigma) & \text{if } Y = -1 \end{cases}$$

Linear classifier:

$$f(X) = \sigma(w^\top X) \quad \text{with} \quad \sigma(x) = \frac{1}{1 + \exp(-x)}$$

In this well studied setting,  $w^* = 2\Sigma^{-1}\mu$



Jordan, M. I. Why the logistic function? a tutorial discussion on probabilities and neural networks. Computational Cognitive Science Technical Report 9503, 1995.

# Theoretical analysis: the Gaussian data model

The error rate writes  $\text{err}(w) = \Phi(-a_w/2)$  with,  $\Phi(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^x \exp(-\frac{t^2}{2}) dt$

And  $\underbrace{a_w = \frac{\langle w, w^* \rangle_{\Sigma}}{\|w\|_{\Sigma}}}_{\text{Expertise level}}$  with  $\underbrace{\|w\|_{\Sigma} = \sqrt{w^{\top} \Sigma w}}_{\text{Confidence level}}, \langle w, w^* \rangle_{\Sigma} = w^{\top} \Sigma w^*$

**Theorem 5.1.** *For proper loss  $\ell$ , the calibration and refinement errors of our model are*

$$\mathcal{K}_{\ell}(w) = \mathbb{E} \left[ d_{\ell} \left( \sigma \left( \|w\|_{\Sigma} \left( z + \frac{a_w}{2} \right) \right), \sigma \left( a_w \left( z + \frac{a_w}{2} \right) \right) \right) \right]$$

$$\mathcal{R}_{\ell}(w) = \mathbb{E} \left[ e_{\ell} \left( \sigma \left( a_w \left( z + \frac{a_w}{2} \right) \right) \right) \right],$$

**Theorem 5.2.** *The re-scaled weight vector  $w_s \leftarrow sw$  with  $s = \langle w, w^* \rangle_{\Sigma} / \|w\|_{\Sigma}^2$  yields null calibration error  $\mathcal{K}(w_s) = 0$  while preserving the refinement error  $\mathcal{R}(w_s) = \mathcal{R}(w)$ .*

where the expectation is taken on  $z \sim \mathcal{N}(0, 1)$ .

# Theoretical analysis: regularized logistic regression in high dimension

The weight vector learned with regularized logistic regression:

$$\min_{w \in \mathbb{R}^p} \frac{1}{n} \sum_{i=1}^n \log(1 + \exp(-y_i w^\top X_i)) + \frac{\lambda}{2} \|w\|^2$$

Has the following distr. when  $n, p \rightarrow \infty$  with a constant ratio,

$$w_\lambda \sim \mathcal{N}\left(\eta(\lambda I_p + \tau \Sigma)^{-1} \mu, \frac{\gamma}{n} (\lambda I_p + \tau \Sigma)^{-1} \Sigma (\lambda I_p + \tau \Sigma)^{-1}\right)$$

We deduce **Proposition 6.1.** For  $n, p \rightarrow \infty$ ,

$$\langle w_\lambda, w^* \rangle_\Sigma \xrightarrow{P} \mathbb{E}_{\sigma \sim F} \left[ \frac{2\eta c^2}{\lambda + \tau \sigma} \right],$$

$$\|w_\lambda\|_\Sigma^2 \xrightarrow{P} \mathbb{E}_{\sigma \sim F} \left[ \frac{\gamma r \sigma^2 + \eta^2 c^2 \sigma}{(\lambda + \tau \sigma)^2} \right],$$

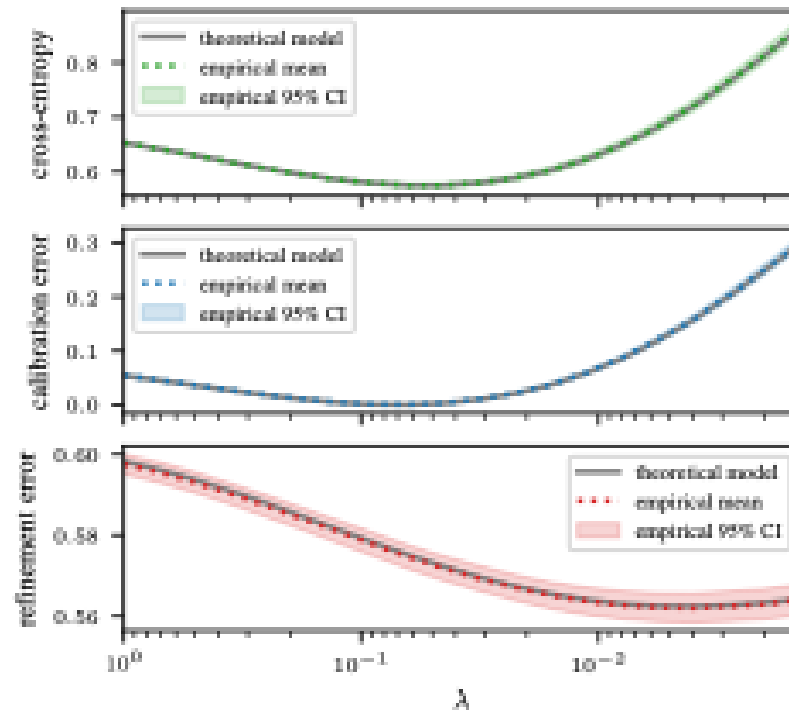
where the convergence is in probability.

Mai, X., Liao, Z., & Couillet, R. (2019). A large scale analysis of logistic regression: Asymptotic performance and new insights. *International Conference on Acoustics, Speech and Signal Processing*.



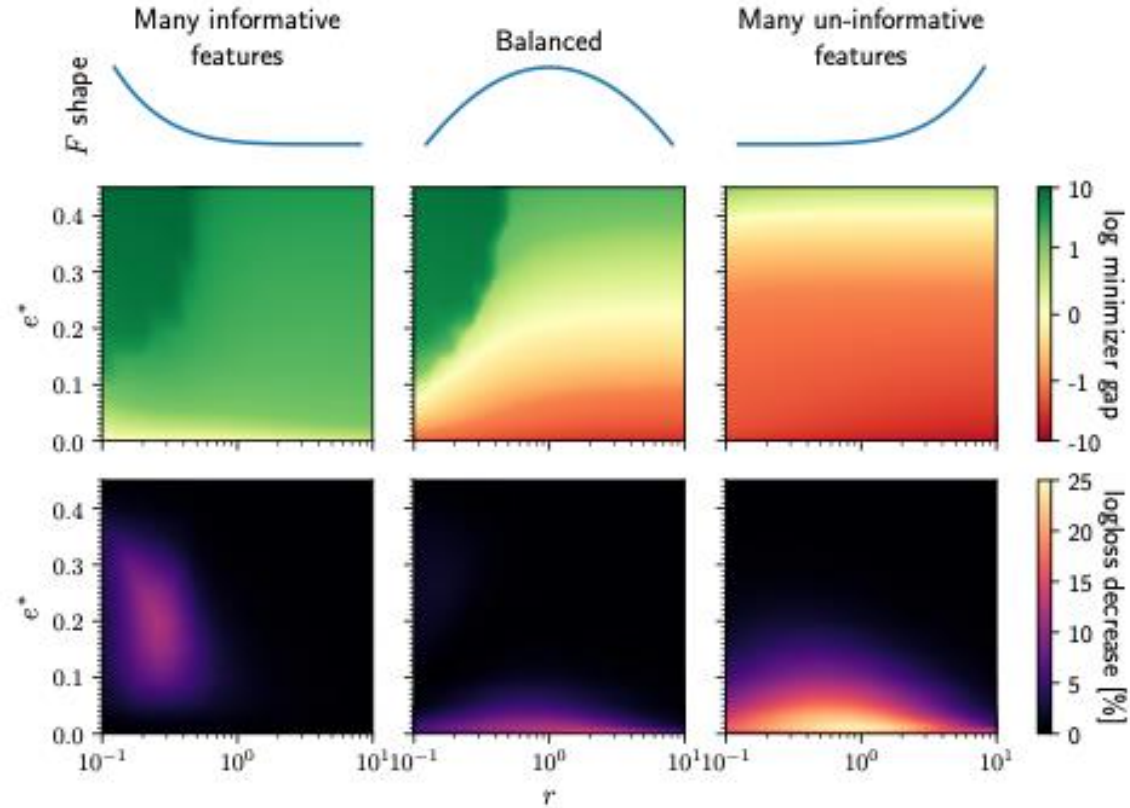
# Theoretical analysis: regularized logistic regression in high dimension

We provide an efficient solver for the problem of computing calibration and refinement errors, under our specific mathematical model, see [github.com/eugeneberta/RefineThenCalibrate-Theory](https://github.com/eugeneberta/RefineThenCalibrate-Theory)



**Cross-entropy, calibration and refinement errors when  $\lambda$  varies.** The spectral distribution  $F$  is uniform,  $e^* = 10\%$ ,  $r = 1/2$ . We fit a logistic regression on 2000 random samples from our data model, we compute the resulting calibration and refinement errors and plot 95% error bars after 50 seeds.

# Theoretical analysis: regularized logistic regression in high dimension



**Influence of problem parameters on calibration and refinement minimizers.** First row: spectral distribution shape. Second row: log gap between the two minimizers. In green regions, calibration is minimized earlier, while in red regions it is refinement. Third row: relative logloss gain (%) obtained with refinement early stopping.

[github.com/eugeneberta/RefineThenCalibrate-Theory](https://github.com/eugeneberta/RefineThenCalibrate-Theory)

# Conclusion

- New refinement estimator for classification
  - Need a family of functions (monotonic or increasing)
  - Going beyond?
- Selecting the best epoch and hyperparameters based on refinement error
  - Calibrated classifiers with lower loss!
  - Improvements in most examples with little changes
  - Online code
- (simple) theoretical analysis: logistic regression in the high dimensional Gaussian data model
  - Going beyond?

# The end, thanks for listening!



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