

# Recent Advances in Conformal Prediction: Multivariate Predictions and Anytime Guarantees

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Inria - Ecole Normale Supérieure



ICSDS Conference, Seville, Spain - December 16, 2025

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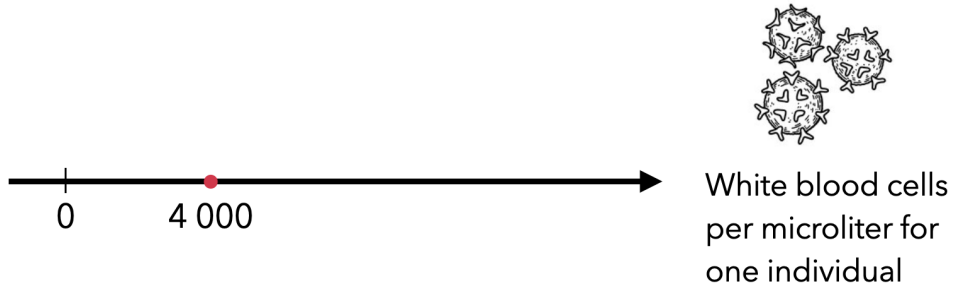
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Joint work with **Sacha Braun**, **Etienne Gauthier**, **Eugène Berta**,  
**David Holzmüller**, **Liviu Aolaritei**, and **Michael Jordan**

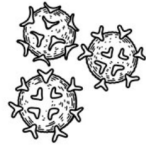
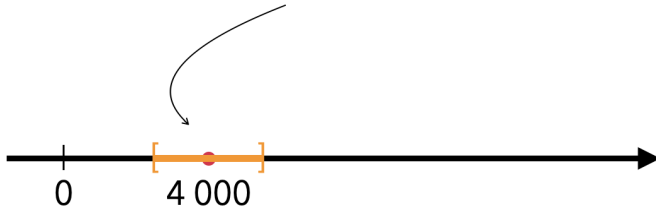
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# Need for uncertainty quantification



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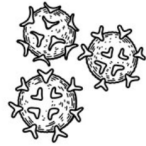
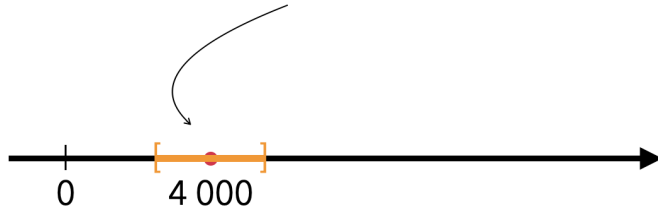
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per microliter for  
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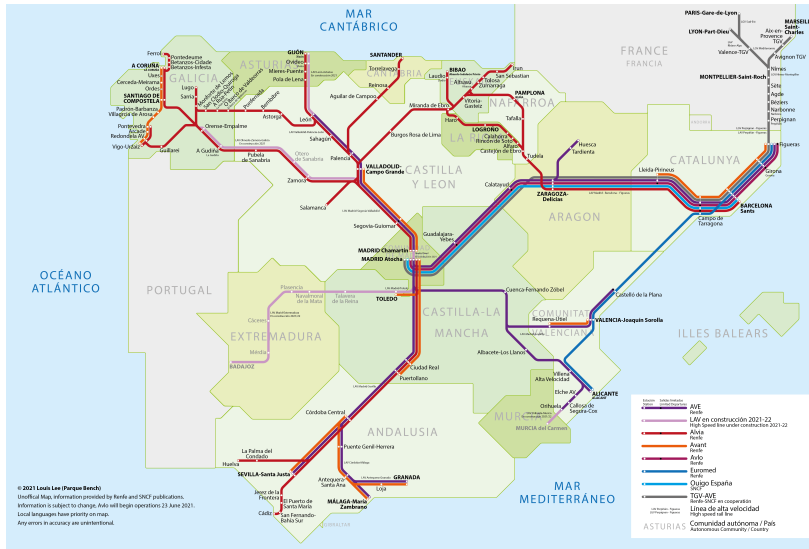
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Difficulty: High-dimensional inputs/outputs, no distributional assumptions

## Need for uncertainty quantification

- Predicting delays on train networks



# Need for uncertainty quantification

- Reinforcement learning and robotics



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# Foundations of conformal prediction

# Conformal prediction yields finite sample guarantees

- **Observation:** dataset  $\mathcal{D}$  of  $n$  independent and identically distributed (i.i.d.) samples  $(X_i, Y_i) \sim \mathbb{P}_{X,Y}$  with  $(X_i, Y_i) \in \mathcal{X} \times \mathcal{Y}$
- **Goal:** Given a target miscoverage level  $\alpha \in (0, 1)$ , construct a **set-valued predictor**  $C_\alpha(X)$  such that

$$\mathbb{P}_{X,Y}(Y_{n+1} \in C_\alpha(X_{n+1})) \approx 1 - \alpha$$

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- **Conformal prediction allows finite sample guarantees**  
(Vovk et al., 2005; Shafer and Vovk, 2008; Angelopoulos and Bates, 2023; Angelopoulos et al., 2024)
- **Alternative frameworks**
  - Bayesian, resampling, PCS (predictability, computability, and stability), etc.

# Proof of the finite sample guarantees

## Probabilistic lemma (uniform rank statistics).

Let  $n + 1$  independent and identically distributed (i.i.d.) samples  $S_i \sim \mathbb{P}_S$  with  $S_i \in \mathbb{R}$ . Assume there are almost surely no ties between  $S_i$ .

Then  $\text{rank}(S_{n+1})$  is uniformly distributed in  $\llbracket 1, n + 1 \rrbracket$ .

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Then  $\text{rank}(S_{n+1})$  is **uniformly distributed in  $\llbracket 1, n + 1 \rrbracket$** .

*Proof:* For  $k \in \llbracket 1, n + 1 \rrbracket$ , because of **exchangeability**,

$$\mathbb{P}(\text{rank}(S_{n+1}) = k) = \frac{1}{n+1} \sum_{i=1}^{n+1} \mathbb{P}(\text{rank}(S_i) = k) = \frac{1}{n+1}$$

# Proof of the finite sample guarantees

**Proposition.** Let  $n$  i.i.d. samples  $(X_i, Y_i) \sim \mathbb{P}_{X,Y}$ , and a **fixed**  $S : \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}$ . Define  $S_i = S(X_i, Y_i)$ , and define order statistics as  $S_{(1)} < S_{(2)} < \dots < S_{(n)}$  (no ties a.s.). For  $r \leq n$ , define  $C_{1-r/(n+1)}(X) := \{y, S(X, y) \leq S_{(r)}\}$ . Then for a new test sample  $(X_{n+1}, Y_{n+1}) \sim \mathbb{P}_{X,Y}$ ,

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- Given fixed “nonconformity score function”  $S : \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}$ ,
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(see, e.g., [Vovk 2012](#); [Foygel Barber et al. 2021](#); [Lei and Wasserman 2014](#))
- Good conditional coverage  $\Leftrightarrow$  score functions that “capture uncertainty”  
and have weak dependence on  $X$
- **Choice of score function is crucial**
  - Any (even estimated) score can be “conformalized” using split conformal prediction
  - How to choose a good score?

# Split conformal prediction

- Suppose we have  $n$  samples i.i.d.  $(X_i, Y_i) \sim \mathbb{P}_{X,Y}$
- Split the dataset in two:
  - $\mathcal{D}_1 = \text{training}$  set with  $\text{Card}(\mathcal{D}_1) = n_1$
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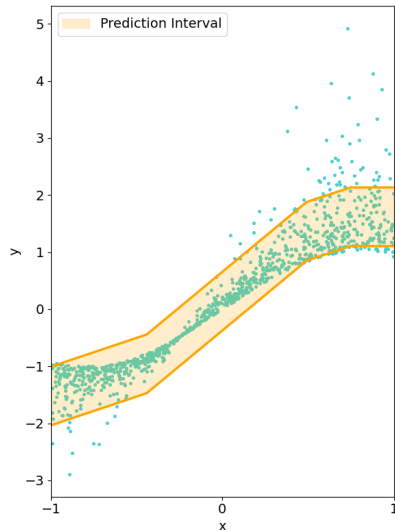
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## Improved conditional coverage with standardized residuals

- Also learn  $\sigma(X)$ , a “spread predictor” to predict the standard deviation of  $|Y - f(X)|$
- Define the non-conformity score ([Lei et al., 2018](#))

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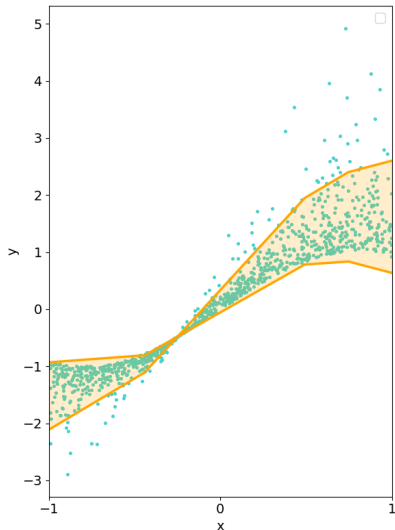
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- Define the score ([Romano et al., 2019](#))

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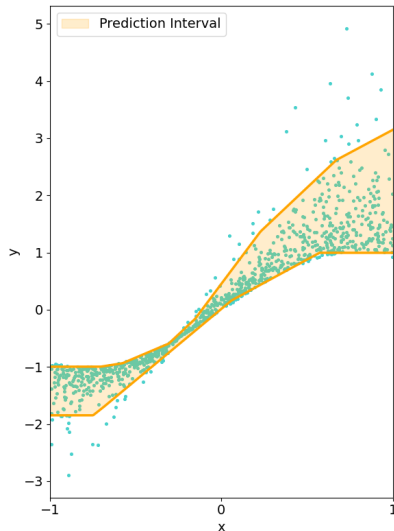
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  - Standard CP requires fixing the miscoverage level  $\alpha$  and the batch size  $n$  in advance
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- **Bonus:** How can we evaluate the conditional validity of a strategy?

Minimum volume covering sets

## Minimum volume covering set (Braun et al., 2025a)

- **Goal:** Given a set of points  $\{y_1, \dots, y_n\}$  in  $\mathbb{R}^k$ ,
  - Find the smallest set that contains at least a fraction  $1 - \alpha$  of points,  $\alpha \in (0, 1)$

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- Define sets, with  $M \in S_k^+$  (positive definite matrix),  $\mu \in \mathbb{R}^k$ ,  $\|\cdot\|$  a norm,

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- **Formulation as optimization problem (MVCS):**

$$\begin{aligned} \min \quad & \text{Vol}(\mathbb{B}(\|\cdot\|, M, \mu)) = \lambda(B_{\|\cdot\|}(1)) \cdot \det(M)^{-1} \\ \text{s.t.} \quad & M \succcurlyeq 0, \mu \in \mathbb{R}^k, \\ & \text{Card} \{i \in [n] \mid \|M(y_i - \mu)\| \leq 1\} \geq n - r + 1 \end{aligned} \tag{1}$$

## Minimum volume covering set (Braun et al., 2025a)

**Proposition (unconstrained formulation).** Problem (MVCS) is equivalent to

$$\begin{aligned} \min \quad & -\log \det(\Lambda) + \sigma_r \{\|\Lambda y_i + \eta\|\} + \log \lambda(B_{\|\cdot\|}(1)) \\ \text{s.t.} \quad & \Lambda \succcurlyeq 0, \eta \in \mathbb{R}^k, \end{aligned}$$

where  $\sigma_r\{a_i\}$  is the  $r$ -th largest element of a set  $\{a_i\}_{i=1}^n$  with  $a_i \in \mathbb{R}$ .

*Proof:* Change of coordinates  $\Lambda := \nu M$ , for  $\nu > 0$ , and  $\eta := -\Lambda \mu$

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$$\begin{aligned} \min \quad & -\log \det(\Lambda) + \sigma_r \{\|\Lambda y_i + \eta\|\} + \log \lambda(B_{\|\cdot\|}(1)) \\ \text{s.t.} \quad & \Lambda \succcurlyeq 0, \eta \in \mathbb{R}^k, \end{aligned}$$

where  $\sigma_r\{a_i\}$  is the  $r$ -th largest element of a set  $\{a_i\}_{i=1}^n$  with  $a_i \in \mathbb{R}$ .

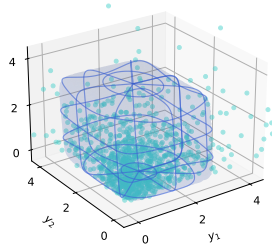
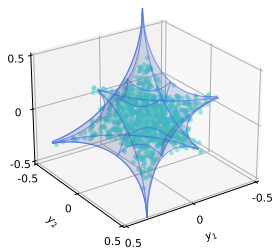
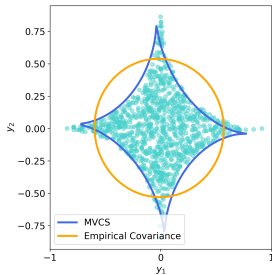
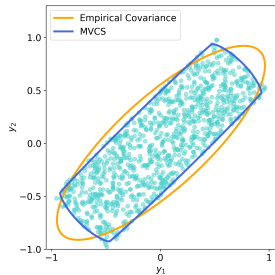
*Proof:* Change of coordinates  $\Lambda := \nu M$ , for  $\nu > 0$ , and  $\eta := -\Lambda\mu$

- Non-convex optimization problem, in fact NP-hard ([Ahmadi et al., 2014](#))
- Convex relaxation akin to pinball loss:  $\sigma_r\{a_i\} \leq \text{sum of } r \text{ largest elements}$
- Classical convex problem for  $r = 1$  and  $\|\cdot\| = \|\cdot\|_2$  (minimum-volume enclosing ellipsoid)



# Shape obtained for different distributions of points

- $\|\cdot\| = \|\cdot\|_p$  does not need to be a norm ( $p$  can be less than one)



## Minimum volume covering set (input / output)

Let  $\mathbb{B}(M, \mu, p) := \{y \in \mathbb{R}^k \mid \|M(y - \mu)\|_p \leq 1\}$ , where  $M \succcurlyeq 0$ ,  $\mu \in \mathbb{R}^k$ ,  $p > 0$ .

$$\begin{array}{ll} \min & \mathbb{E} [\text{Vol}(\mathbb{B}(M(X), f_\theta(X), p))] \\ \text{s.t.} & \mathbb{P}(Y \in \mathbb{B}(p, M(X), f_\theta(X))) \geq 1 - \alpha \end{array} \quad (\text{MVCS-cond.})$$

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**Proposition** Let  $(X_i, Y_i)_{1 \leq i \leq n}$  be  $n$  i.i.d. samples, with  $X_i \in \mathbb{R}^d$ ,  $Y_i \in \mathbb{R}^k$ .

Then (MVCS-cond.) is equivalent to:

$$\begin{aligned} \min \quad & \log \left( \sum_{i=1}^n \frac{1}{\det(\Lambda_\phi(x_i))} \right) + k \log \sigma_r \{ \|\Lambda_\phi(x_i)(y_i - f_\theta(x_i))\|_p \} + \log \lambda(B_{\|\cdot\|_p}(1)) \\ \text{s.t.} \quad & \Lambda_\phi(\cdot) \succcurlyeq 0, \quad p > 0, \quad \theta, \phi \in \Theta. \end{aligned}$$

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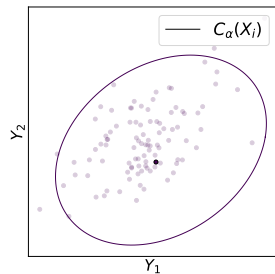
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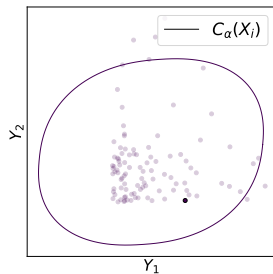
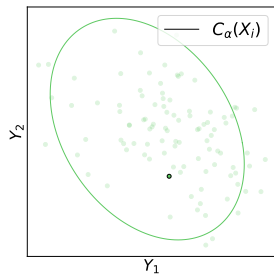
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- The conformalisation step is made with the score  $S(X, Y) = \|\Lambda_\phi(X)(Y - f_\theta(X))\|_p$
- Only marginal coverage

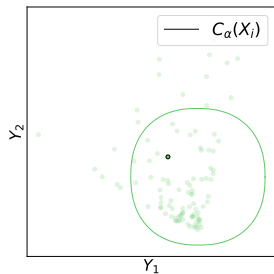
# Empirical illustration for different distributions



Left: Gaussian noise



Right: exponential noise



Samples from the distribution of  $Y|X \sim f(X) + B(X)$  where  $B(X)$  is an heteroskedastic noise

## Gaussian conformal prediction

# Extending standardized residuals to multivariate regression

Assume

$$Y|X \sim \mathcal{N}(f(X), \Sigma(X)),$$

where  $Y \in \mathbb{R}^k$ . We can define the Mahalanobis score ([Braun et al., 2025b](#))

$$S_{\text{Mah}}(X, Y) = \|\Sigma(X)^{-1/2}(Y - f(X))\|_2$$

- Generalization of the standardized residuals ([Lei et al., 2018](#)) in multivariate regression
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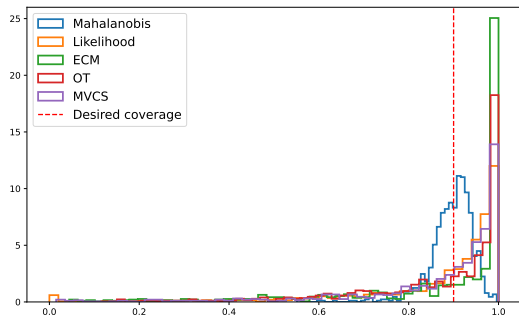
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- Generalization of the standardized residuals ([Lei et al., 2018](#)) in multivariate regression
- Under the Gaussian assumption,  $S_{\text{Mah}}(X, Y)|X \sim \chi_2(k)$  which is independent of  $X$
- Even if the distribution is not Gaussian, we expect our score to be less dependent on  $X$ 
  - Let  $f(X) = \mathbb{E}[Y|X]$  and  $\Sigma(X) = \text{cov}(Y|X)$ , and  $U = \Sigma(X)^{-1/2}(Y - f(X))$
  - Then  $\mathbb{E}[U|X] = 0$  and  $\text{cov}(U|X) = I_k$  so the distribution of  $S_{\text{Mah}}(X, Y) = \|U\|_2$  should less depend on  $X$
- NB: all developments can be extended to elliptical distributions

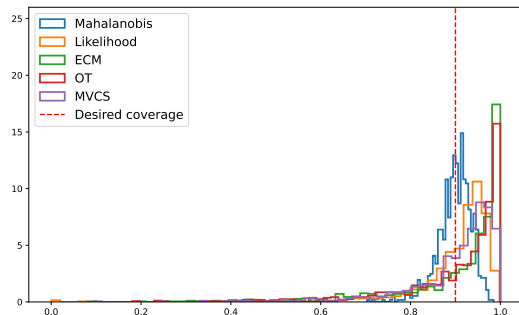


# Improved Conditional Coverage

- Modeling via ellipsoids  $\Rightarrow$  estimation of variance along all directions



Histograms of conditional coverage  $\mathbb{P}(Y \in C_\alpha(X_i) \mid X_i)$  on a synthetic dataset ( $\alpha = 0.1$ )  
(left) heteroskedastic Gaussian noise



(right) heteroskedastic exponential noise

- Baselines: empirical covariance matrix ([Johnstone and Cox, 2021](#)), optimal transport ([Thurin et al., 2025](#))

## Partially revealed outputs: motivation

- **Example:** predict fasting blood glucose ( $Y^1$ ) and cholesterol ( $Y^2$ )
  - If conformal set too wide, a costly test (e.g.,  $Y^1$ ) may be performed
  - Once  $Y^1$  is revealed, we want to **refine prediction for  $Y^2$**
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  - Standard approach: retrain model with  $(X, Y^1) \Rightarrow$  expensive
- **Goal: update conformal sets directly** using the probabilistic model
  - Leverage classical conditioning properties of the Gaussian distribution

## Method: Gaussian conditioning

- Assuming a Gaussian predictive model:

$$\hat{p}(Y|X) = \mathcal{N}\left(\begin{pmatrix} f^r(X) \\ f^h(X) \end{pmatrix}, \begin{pmatrix} \Sigma^{rr}(X) & \Sigma^{rh}(X) \\ \Sigma^{hr}(X) & \Sigma^{hh}(X) \end{pmatrix}\right)$$

- Partition output into revealed  $Y^r$  and hidden  $Y^h$

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- Partition output into revealed  $Y^r$  and hidden  $Y^h$
- Conditional distribution (closed form):

$$\hat{p}(Y^h|X, Y^r) = \mathcal{N}(\tilde{f}(X), \tilde{\Sigma}(X))$$

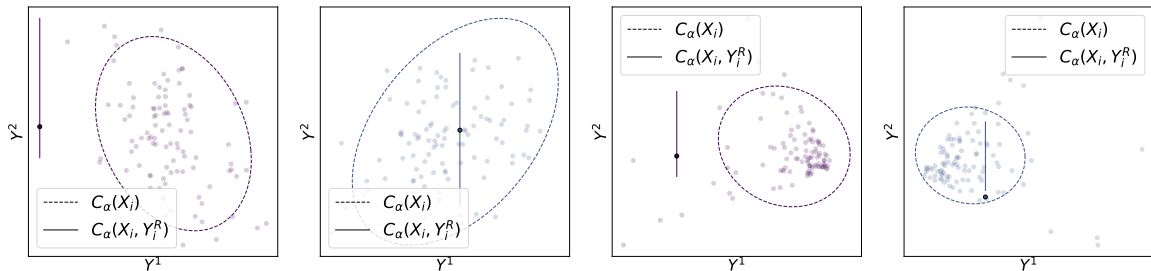
$$\tilde{f}(X) = f^h(X) + \Sigma^{hr}\Sigma^{rr^{-1}}(Y^r - f^r(X)), \quad \tilde{\Sigma}(X) = \Sigma^{hh} - \Sigma^{hr}\Sigma^{rr^{-1}}\Sigma^{rh}$$

- Non-conformity score:

$$S_{\text{Revealed}}(X, Y^r, Y^h) = \|\tilde{\Sigma}(X)^{-1/2}(Y^h - \tilde{f}(X))\|_2$$

# Illustration of benefits

- Uses revealed  $Y^r$  without retraining
- Produces **narrower, adaptive sets**, and avoids empty sets (robustness)



Left: Gaussian noise

Right: exponential noise.

Different samples from the distribution of  $Y|X \sim f(X) + B(X)$   
( $B(X)$ =heteroskedastic noise and  $Y^1$  is revealed)

## Projection of the output: motivation

- High-dimensional predictions:  $Y \in \mathbb{R}^k$
- Often (at test time) only a subset or linear combination  $\varphi(Y)$  is of interest
- Example:
  - Finance: portfolio returns  $(R^1, R^2) = (rY^1, pY^2 + qY^3)$ .

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- **Naive approach:** project conformal set  $\tilde{C}_\alpha(X)$  onto  $\varphi(Y)$   
 $\Rightarrow$  conservative (overly large) sets
- **Goal:** construct **direct conformal sets for  $\varphi(Y)$**  without retraining



## Method: linear transformations

- Trained Gaussian model:

$$\hat{p}(Y|X) = \mathcal{N}(f(X), \Sigma(X))$$

- For linear  $\varphi(Y) = MY$  ( $M \in \mathbb{R}^{p \times k}$ ):

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- Non-conformity score in transformed space:

$$S_{\text{Lin.Trans.}}(X, Y) = \|(M\Sigma(X)M^\top)^{-1/2}(MY - Mf(X))\|_2$$

- Coverage guarantee:

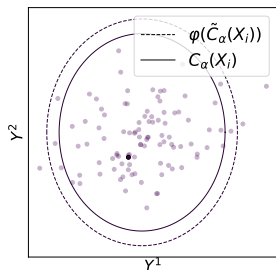
$$\mathbb{P}(MY \in C_\alpha(X)) \in \left[1 - \alpha, 1 - \alpha + \frac{1}{n_2+1}\right)$$

## Results: projected vs. direct sets

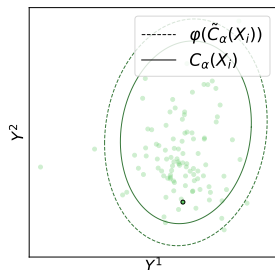
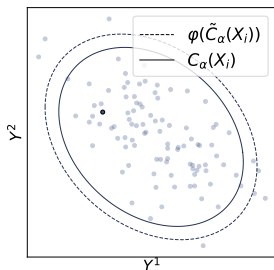
- Direct conformalization with  $S_{\text{Lin.Trans.}}$  (full line) gives:
  - **Tighter sets**, correct coverage (if well-specified)
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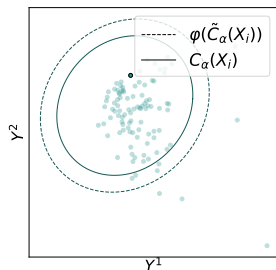
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Projection of samples from the distribution of  $Y|X \sim f(X) + B(X)$   
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  - Beyond ellipsoids

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- **Elliptical conditional model**

- Allow conditioning and linear projection without retraining
- Added flexibility

## Conformal Prediction with E-values

## Standard conformal prediction: a p-value perspective

**Proposition (reformulation).** Under the exchangeability assumption,

$$P = \frac{1 + \sum_{i=1}^n \mathbb{1}\{S(X_i, Y_i) \geq S(X_{n+1}, Y_{n+1})\}}{n + 1}$$

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*Proof:*

- The quantity  $\sum_{i=1}^n \mathbb{1}\{S(X_i, Y_i) \geq S(X_{n+1}, Y_{n+1})\}$  is  $n - R$  where  $R$  is the rank of  $S(X_{n+1}, Y_{n+1})$  among  $S_1, \dots, S_n$
- Thus,  $P = 1 - \frac{R}{n+1}$
- From previous guarantees,  $\mathbb{P}(P \leq \alpha) = \mathbb{P}(1 - \frac{R}{n+1} \leq \alpha) \in (\alpha - \frac{1}{n+1}, \alpha]$

# Limitations of the p-value framework

- Reformulation as  $p$ -value

$$\mathbb{P}(Y_{n+1} \notin C_\alpha(X_{n+1})) \leq \alpha \quad \Longleftrightarrow \quad \mathbb{P}(P \leq \alpha) \leq \alpha$$

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- To enable **post-hoc** choices of  $\alpha$  and **anytime-valid** monitoring  
 $\Rightarrow$  Need a more flexible evidence measure: **e-values**  
(Grünwald et al., 2020; Wasserman et al., 2020; Shafer, 2021; Vovk and Wang, 2021)

# Post-hoc guarantees and e-values

## Standard CP (fixed $\alpha$ ):

The standard validity  $\mathbb{P}(Y_{n+1} \notin C_\alpha(X_{n+1})) = \mathbb{P}(P \leq \alpha) \leq \alpha$  for all  $\alpha$  is equivalent to:

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To enable data-dependent decision making, we seek a stronger **post-hoc guarantee**:

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This requires the concept of **post-hoc p-values** and **e-values**.

## Definitions (Ramdas and Wang, 2025)

- An **e-value**  $E$  is a non-negative random variable such that  $\mathbb{E}[E] \leq 1$
- A **post-hoc p-value**  $P$  satisfies the post-hoc guarantee above:  $\mathbb{E}[\sup_{\alpha} \mathbb{1}\{P \leq \alpha\}/\alpha] \leq 1$

**Theorem (Koning, 2024):** Post-hoc p-values are exactly the inverses of e-values ( $P = 1/E$ ).

# Conformal prediction with adaptive coverage

Here, the e-value is the *soft-rank* e-value ([Wang and Ramdas, 2022](#); [Koning, 2025](#)):

$$E = \frac{(n+1)S(X_{n+1}, Y_{n+1})}{\sum_{i=1}^n S(X_i, Y_i) + S(X_{n+1}, Y_{n+1})} = \frac{S(X_{n+1}, Y_{n+1})}{\frac{1}{n+1} \sum_{i=1}^n S(X_i, Y_i) + \frac{1}{n+1} S(X_{n+1}, Y_{n+1})}$$



# Conformal prediction with adaptive coverage

## Adaptive Coverage Guarantee (Gauthier et al., 2025b)

Let  $\tilde{\alpha}$  be any (possibly data-dependent) miscoverage level that can depend on the calibration data  $\{(X_i, Y_i)\}_{i=1}^n$  and the test feature  $X_{n+1}$ . Then we have:

$$\mathbb{E} \left[ \frac{\mathbb{1}\{Y_{n+1} \notin \mathcal{C}_{\tilde{\alpha}}(X_{n+1})\}}{\tilde{\alpha}} \right] \leq 1,$$

where the prediction set  $\mathcal{C}_{\tilde{\alpha}}$  is defined as:

$$\mathcal{C}_{\tilde{\alpha}}(X_{n+1}) = \left\{ y \in \mathcal{Y} : \frac{(n+1)S(X_{n+1}, y)}{\sum_{i=1}^n S(X_i, Y_i) + S(X_{n+1}, y)} < \frac{1}{\tilde{\alpha}} \right\}.$$

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## Application: backward conformal prediction ([Gauthier et al., 2025a](#))

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  - **Calibration uncertainty** ( $\mathcal{D}_{cal}$ ): high variance  $\implies$  increase the budget  $k$
- **Backward CP:** fix size  $k(X_{n+1}, \mathcal{D}_{cal})$ , and adjust miscoverage:

$$\tilde{\alpha} = \inf \{ \alpha \in (0, 1) : |\mathcal{C}_\alpha(X_{n+1})| \leq k(X_{n+1}, \mathcal{D}_{cal}) \}.$$

- **Guarantee:**  $\mathbb{E}[\mathbb{1}\{Y_{n+1} \notin \mathcal{C}_{\tilde{\alpha}}(X_{n+1})\} / \tilde{\alpha}] \leq 1 \implies \mathbb{P}(Y_{n+1} \in \mathcal{C}_{\tilde{\alpha}}(X_{n+1})) \gtrsim 1 - \mathbb{E}[\tilde{\alpha}]$

# Estimating expected miscoverage $\mathbb{E}[\tilde{\alpha}]$

**Problem:** Coverage depends on unknown  $\mathbb{E}[\tilde{\alpha}]$

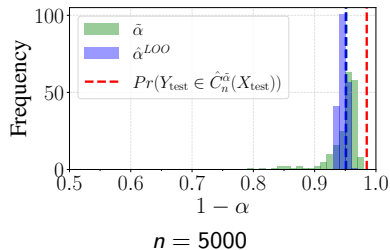
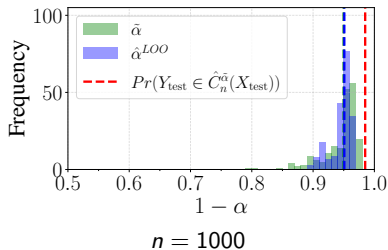
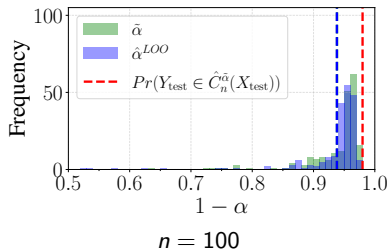
**Solution:** Estimate via **Leave-One-Out (LOO)** on calibration set

**LOO Estimator:** For each  $i = 1, \dots, n$ :

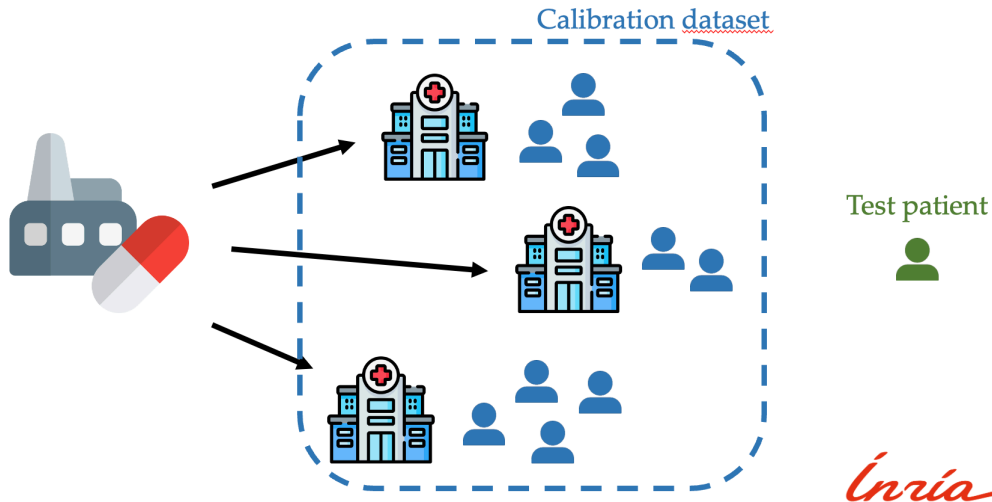
- 1 Treat  $(X_i, Y_i)$  as pseudo-test point
- 2 Compute  $\tilde{\alpha}_i$  using remaining data  $\mathcal{D}_{cal} \setminus \{(X_i, Y_i)\}$

$$\hat{\alpha}_{\text{LOO}} = \frac{1}{n} \sum_{i=1}^n \tilde{\alpha}_i$$

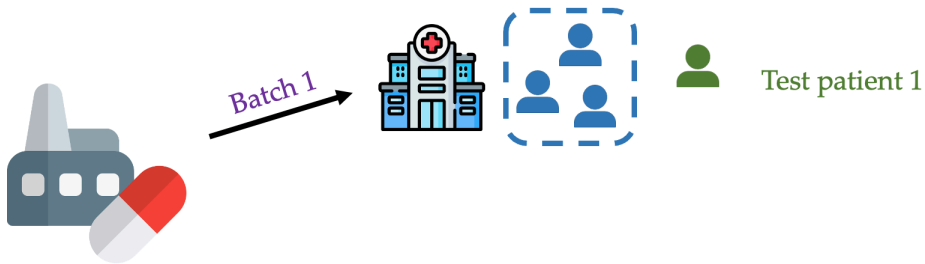
**Guarantee:**  $|\hat{\alpha}_{\text{LOO}} - \mathbb{E}[\tilde{\alpha}]| = O_P(1/\sqrt{n})$ ,  $\text{Var}(\hat{\alpha}_{\text{LOO}}) = O_P(1/n)$ .



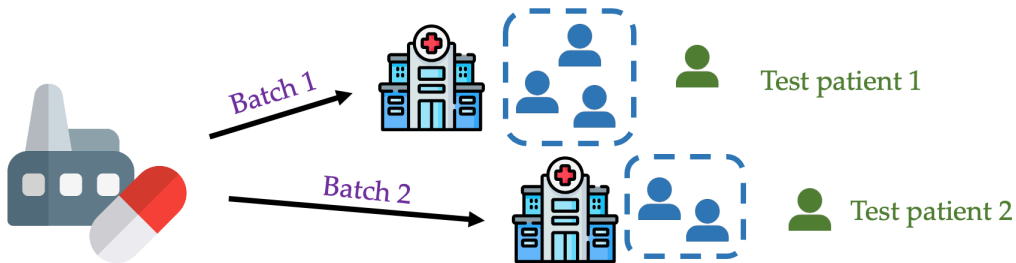
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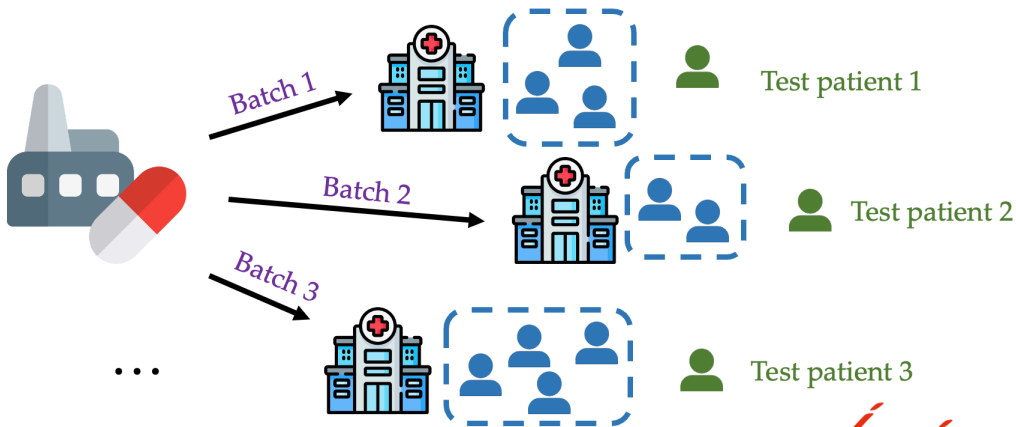


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**Scenario:** We perform conformal prediction on multiple data batches sequentially. At each step  $t$ , we process a batch (where we aim to cover the target  $Y_{n_t+1}^t$ ):

$$\{(X_1^t, Y_1^t), \dots, (X_{n_t}^t, Y_{n_t}^t), (X_{n_t+1}^t, Y_{n_t+1}^t)\}$$

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$$M_t = \prod_{s=1}^t (1 - \beta_s + \beta_s E_s), \quad \text{where } E_s = \frac{(n_s + 1) S(X_{n_s+1}^s, Y_{n_s+1}^s)}{\sum_{i=1}^{n_s} S(X_i^s, Y_i^s) + S(X_{n_s+1}^s, Y_{n_s+1}^s)}$$

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- **Ville's Inequality for supermartingales**  $\mathbb{P}(\sup_t M_t \geq \alpha) \leq \mathbb{E}[M_0]/\alpha$ , ensures the coverage holds *simultaneously* for all time steps  $t$  (provided that the data in each batch is exchangeable conditional on the history:

$$\mathbb{P}(\forall t, Y_{n_t+1} \in C_t(X_{n_t+1})) \geq 1 - \alpha$$

Bonus: Evaluating conditional miscoverage

## Excess risk of the target coverage

- For any data-dependent set  $C_\alpha$ , let  $Z = \mathbb{1}\{Y \in C_\alpha(X)\} \in \{0, 1\}$
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- **“Excess risk of target coverage”** (Braun et al., 2025c)

$$\ell\text{-ERT} = \mathcal{R}_\ell(1 - \alpha) - \mathcal{R}_\ell(p) = \mathcal{R}_\ell(1 - \alpha) - \inf_h \mathcal{R}_\ell(h)$$

- Provides a measure of miscoverage and a detailed diagnostic of over/under coverage
- Can be estimated with standard tools from non-parametric estimation

## Benefits: a set of interpretable metrics

- Property of excess risk for a proper loss

$$\ell\text{-ERT} = \mathcal{R}_\ell(1 - \alpha) - \mathcal{R}_\ell(p) = \mathbb{E}_X[d_\ell(1 - \alpha, p(X))]$$

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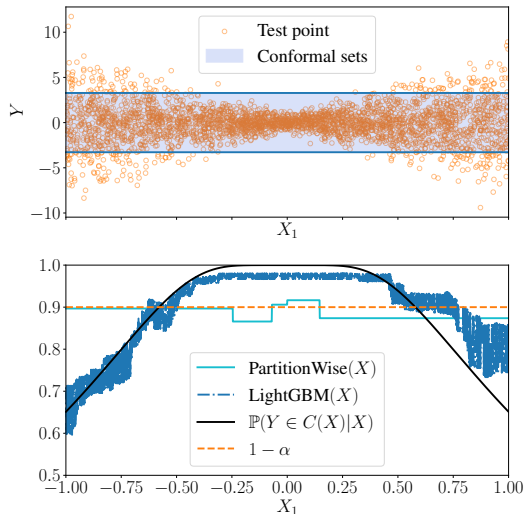
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- Examples of proper scoring rules and their associated ERT scores

Name	Proper score $\ell(p, y)$	$\ell$ -ERT
$L_1$ -ERT	$\text{sgn}(p - (1 - \alpha))(1 - \alpha - y)$	$\mathbb{E}_X[ 1 - \alpha - p(X) ]$
$L_2$ -ERT (Brier score)	$(y - p)^2$	$\mathbb{E}_X[(1 - \alpha - p(X))^2]$
KL-ERT (Log loss)	$-\log p_y$	$\mathbb{E}_X[D_{\text{KL}}(p(X) \  1 - \alpha)]$

# Metrics comparison without conditional coverage

- $X \sim \mathcal{U}([-1, 1]^8)$
- $Y \sim \mathcal{N}(0, \sigma(X_1))$
- Sets are obtained by doing conformal prediction with the score  $S(X, Y) = |Y|$
- $L_1\text{-ERT}(\text{LightGBM}) = 0.09$   
(boosting with decision trees)
- $L_1\text{-ERT}(\text{PartitionWise}) = 0.01$   
(a classical diagnostic measure)



## Conclusion

# Conclusion - Challenges in conformal prediction

- **Multivariate problems**

- Choice of conformity score based on generalized ellipsoids
- Trade-offs between volume, coverage, and “flexibility”
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