Abstract Interpretation and Application to Logic Programs *

Patrick Cousot
LIENS, École Normale Supérieure
45, rue d'Ulm
75230 Paris cedex 05 (France)
cousot@dmi.ens.fr

Radhia Cousot
LIX, École Polytechnique
91128 Palaiseau cedex (France)
radhia@polytechnique.fr

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Abstract. Abstract interpretation is a theory of semantics approximation which is used for the construction of semantics-based program analysis algorithms (sometimes called "data flow analysis"), the comparison of formal semantics (e.g., construction of a denotational semantics from an operational one), the design of proof methods, etc.

Automatic program analysers are used for determining statically conservative approximations of dynamic properties of programs. Such properties of the run-time behavior of programs are useful for debugging (e.g., type inference), code optimization (e.g., compile-time garbage collection, useless occur-check elimination), program transformation (e.g., partial evaluation, parallelization), and even program correctness proofs (e.g., termination proof).

After a few simple introductory examples, we recall the classical framework for abstract interpretation of programs. Starting from a standard operational semantics formalized as a transition system, classes of program properties are first encapsulated in collecting semantics expressed as fixpoints on partial orders representing concrete program properties. We consider invariance properties characterizing the descendant states of the initial states (corresponding to top/down or forward analyses), the ascendant states of the final states (corresponding to bottom/up or backward analyses) as well as a combination of the two. Then we choose specific approximate abstract properties to be gathered about program behaviors and express them as elements of a poset of abstract properties. The correspondence between concrete and abstract properties is established by a concretization and abstraction function that is a Galois connection formalizing the loss of information. We can then constructively derive the abstract program properties from the collecting semantics by a formal computation leading to a fixpoint expression in terms of abstract operators on the domain of abstract properties. The design of the abstract interpreter then involves the choice of a chaotic iteration strategy to solve this abstract fixpoint equation. We insist on the compositional design of this abstract interpreter, which is formalized by a series of propositions for designing Galois connections (such as Moore families, decomposition by partitioning, reduced product, down-set completion, etc.). Then we recall the convergence acceleration methods using widening and narrowing allowing for the use of very expressive infinite domains of abstract properties.

We show that this classical formal framework can be applied in extenso to logic programs. For simplicity, we use a variant of SLD-resolution as the standard operational semantics. The first example is groundness analysis, which is a variant of Mellish mode analysis. It is extended to a combination of top/down and bottom/up analyses. The second example is the derivation of constraints among argument sizes, which involves an infinite abstract domain requiring the use of convergence acceleration methods. We end up with a short thematic guide to the literature on abstract interpretation of logic programs.

Keywords: Abstract interpretation, fixpoint approximation, abstraction, concretization, Galois connection, compositionality, chaotic iteration, convergence acceleration, widening/narrowing, operational and collecting semantics, top/down, bottom/up and combined analyses, logic programming, groundness analysis, argument sizes analysis.

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1. INTRODUCTION

Program manipulators (such as programmers who write, debug, and attempt to understand programs or computer programs which interpret, compile, or execute programs) reason upon or are constructed by relying on the syntax but mainly on the semantics of these programs. The *semantics* of a program describes the set of all possible behaviors of that program when executed for all possible input data. For logic programs, the input data are questions. The behaviors can be non-termination, termination with a run-time error, failure, or correct termination delivering one or more output answers.

For a given type of reasoning about programs, not all aspects and details about their possible behaviors during execution have to be considered. Each program manipulation is facilitated by reasoning upon a well-adapted semantics, abstracting away from irrelevant matters. For example, logical programs debugging often refers to a small-step operational semantics with backtracking. On the contrary, programs explanation often refers to the declarative aspect of a logic program providing the relation between questions and answers. Therefore, there is no universal general-purpose semantics of programs, and, in everyday life, more or less formal, more or less precise, special-purpose semantics are in current use. *Abstract interpretation* is a method for relating these semantics.

We will explain the abstract interpretation framework that we introduced in [25], [26], [28], [29], [32], [34] and illustrate it for logic programs. Thanks to examples, we will consider two essential utilizations of abstract interpretation: (a) The first utilization is the design of an abstract semantics in order to show off an underlying structure in a concrete, more detailed semantics. Hence, properties of programs are induced, without loss of indispensable information, from a concrete into a more abstract setting. A typical example consists in designing a proof method starting from a collecting semantics [27]. (b) The second utilization of abstract interpretation is the design of an abstract semantics in order to specify an automatic program analyser for the static determination of dynamic properties of programs. Here, properties of programs are approximated, with an inevitable loss of information, from a concrete to a less precise abstract setting. Such semantics-based sound but approximate information is indispensable to identify errors in a program, as performed by program debuggers and type checkers. Another use is in program transformers such as compilers, partial evaluators, and parallelizers, where the analysis determines the applicability of various transformations.

After a presentation of abstract interpretation, we will consider its application to static analysis of logic programs starting from a variant of SLD-resolution as operational semantics. We will illustrate the design of abstract interpretations by the typical example of groundness analysis (which will be extended to a bi-directional combination of top/down and bottom/up analyses) and the atypical example of argument size relation (involving an infinite domain). Finally, we will very briefly review the main applications to logic programs that have been considered in the already abundant literature.

2. SIMPLE EXAMPLES OF ABSTRACT INTERPRETATION

As a first approximation, abstract interpretation can be understood as a nonstandard semantics, i.e., one in which the domain of values is replaced by a domain of descriptions of values, and in which the operators are given a corresponding nonstandard interpretation.

2.1. Rule of Signs

For example, rather than using integers as concrete values, an abstract interpretation may use abstract values -1 and $+1$ to describe negative and positive integers, respectively [138]. Then by reinterpreting operations like addition or multiplication according to the "rule of signs" due to the ancient Greek mathematicians, the abstract interpretation may establish certain properties

of a program such as "whenever this loop body is entered, variable x is assigned a positive value (or perhaps is uninitialized)."

2.1.1. The Rule of Signs Calculus

For example, $(x \times x) + (y \times y)$ yields the value 25 when x is 3 and y is -4 and when $\times$ and $+$ are the usual arithmetical multiplication and addition. But when applying the "rule of signs":

$$\begin{array}{lll} +1 + +1 = +1 & +1 \times +1 = +1 & -1 \times +1 = -1 \\ -1 + -1 = -1 & +1 \times -1 = -1 & -1 \times -1 = +1 \end{array}$$

(where the abstract value $+1$ represents any positive integer, while -1 represents any negative integer) one concludes that the sign of $(3 \times 3) + (-4 \times -4)$ is always $+1$ since $(+1 \times +1) + (-1 \times -1) = (+1) + (+1) = +1$. However, this simple abstract calculus fails to prove that $x^2 + 2 \times x \times y + y^2$ is always positive.

Although very simple, this example shows that abstract interpretations may fail. To avoid errors due to such failures in a partial abstract calculus, we choose to use a total abstract calculus where an abstract value $\top$ is introduced to represent the fact that nothing is known about the result:

$$\begin{array}{llll} +1 + -1 = \top & +1 + \top = \top & \top \times +1 = \top & -1 \times \top = \top \\ -1 + +1 = \top & -1 + \top = \top & \top \times -1 = \top & \top \times \top = \top \\ \top + +1 = \top & \top + \top = \top & +1 \times \top = \top & \\ \top + -1 = \top & & & \end{array}$$

Now, several abstract values can be used to approximate a given concrete value. For example, the concrete value 5 can be approximated by $+1$ or $\top$. A partial order relation $\preceq$ can be introduced to compare the precision of abstract values ([155], [95]). For example, $-1 \preceq \top$ and $+1 \preceq \top$ since -1 or $+1$ are more precise than $\top$, whereas -1 and $+1$ are not comparable since no one can always safely replace the other.

A concrete value may be approximated by several minimal values. For example, 0 can be approximated by minimal abstract values -1 or $+1$. In this case, the best choice may depend upon the expression to be analysed. For example, when analysing $0+x$ it is better to approximate 0 by $+1$ if x is known to be positive and by -1 when x is negative. In order to avoid having to do the choice during the abstract calculus or to explore all alternatives, it is always possible to enrich the abstract domain so that the set of upper approximations of any given concrete value has a best element [34]. For our example, this leads to the introduction of an abstract value 0:

$$\begin{array}{llll} 0 + +1 = +1 & +1 + 0 = +1 & 0 \times +1 = 0 & +1 \times 0 = 0 \\ 0 + -1 = -1 & -1 + 0 = -1 & 0 \times -1 = 0 & -1 \times 0 = 0 \\ 0 + \top = \top & \top + 0 = \top & 0 \times \top = 0 & \top \times 0 = 0 \\ 0 + 0 = 0 & & 0 \times 0 = 0 & \end{array}$$

2.1.2. Generalization to Interval Analysis

In [28], this "rule of signs" idea was generalized to interval analysis, i.e., to properties of the form $l \leq x \leq u$ where $l, u \in \mathbb{Z} \cup \{-\infty, +\infty\}$, $\mathbb{Z}$ is the set of integers, and $l \leq u$. The main innovations were the idea of soundness proof by relating the abstract interpretations to an operational semantics and the use of infinite abstract domains, which led to very powerful analyses, as shown by the following results (where the comments have been generated automatically [7]):

```
function F(X : integer) : integer;
begin
  if X > 100 then begin
    F := X - 10
    { X∈[101, maxint] ∧ F∈[91, maxint - 10] }
  end else begin
    F := F(F(X + 11))
```

```
      { X ∈ [minint, 100] ∧ F = 91 }
    end;
  end;
```

This analysis supersedes the most sophisticated methods based upon data flow analysis. Let us consider the following program given in [76]:

```
program AnOldLookAtOptimizingArrayBoundChecking;
  var
    i, j, k, l, m : integer;
    a : array[1..100] of real;
begin
  read(i, j);
  { i∈⋆[1, 99]⋆ ∧ j∈[-maxint-1, maxint] }
  k := i;
  { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 99] }
  l := 1;
  { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 99] ∧ l∈[1, 1]}
  while l <= i do begin
    { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 999] ∧ l∈[1, 99] }
    m := i;
    { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 999] ∧ l∈[1, 99] ∧ m∈[1, 99] }
    while m <= j do begin
      { i∈[1, 99] ∧ j∈[1, maxint] ∧ k∈[1, maxint-1] ∧ l∈[1, 99] ∧ m∈[1, maxint-1] }
      k := k + m;
      { i∈[1, 99] ∧ j∈[1, maxint] ∧ k∈[2, maxint]# ∧ l∈[1, 99] ∧ m∈[1, maxint-1] }
      m := m + 1;
      { i∈[1, 99] ∧ j∈[1, maxint] ∧ k∈[2, maxint] ∧ l∈[1, 99] ∧ m∈[2, maxint] }
    end;
    { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, maxint] ∧ l∈[1, 99] ∧ m∈[1, maxint] }
    a[l] := k;
    { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, maxint] ∧ l∈[1, 99] ∧ m∈[1, maxint] }
    if k < 1000 then begin
      { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 999] ∧ l∈[1, 99] ∧ m∈[1, maxint] }
      write(k);
      { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 999] ∧ l∈[1, 99] ∧ m∈[1, maxint] }
    end else begin
      { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1000, maxint] ∧ l∈[1, 99] ∧ m∈[1, maxint] }
      k := i;
      { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 99] ∧ l∈[1, 99] ∧ m∈[1, maxint] }
    end;
    { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 999] ∧ l∈[1, 99] ∧ m∈[1, maxint] }
    a[l + 1] := a[l] / 2;
    { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 999] ∧ l∈[1, 99] ∧ m∈[1, maxint] }
    l := l + 1;
    { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 999] ∧ l∈[2, 100] ∧ m∈[1, maxint] }
  end;
  { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 999] ∧ l∈[2, 100] ∧ m∈[1, maxint] }
  write(a[i]);
  { i∈[1, 99] ∧ j∈[-maxint-1, maxint] ∧ k∈[1, 999] ∧ l∈[2, 100] ∧ m∈[1, maxint] }
end.
```

The invariants given in comments have been discovered automatically. They hold during any execution of the program without run-time error. If any one of these invariants is violated during execution, then a later run-time error is inevitable. To detect these run-time errors before they occur, it is shown automatically that only two bound checks (marked $\star$) are necessary upon initialization as well as an overflow check (marked $\#$) within the loop. This analysis seems well out of reach of the data flow analysis of [76] based upon the syntactical elimination, propagation, and combination of range checks.

2.2. Dimension Calculus

Let us now consider a familiar example from elementary physics.

2.2.1. The Dimension Calculus

The dimension calculus uses the abstract values *length*, *surface*, *volume*, *time*, *speed*, *acceleration*, *mass*, *force*, ..., *nodimension*. The abstract version $\bar{op}$ of an operator *op* is defined as follows:

$$\begin{array}{rcl} \mathit{length} \mathbin{\bar{+}} \mathit{length} & = & \mathit{length} \\ \mathit{length} \mathbin{\bar{\times}} \mathit{length} & = & \mathit{surface} \\ \mathit{length} \mathbin{\bar{/}} \mathit{length} & = & \mathit{nodimension} \\ \mathit{length} \mathbin{\bar{/}} \mathit{time} & = & \mathit{speed} \\ \mathit{speed} \mathbin{\bar{/}} \mathit{time} & = & \mathit{acceleration} \end{array}$$

$$\begin{array}{rcl} \mathit{mass} \mathbin{\bar{\times}} \mathit{acceleration} & = & \mathit{force} \\ & \cdots & \\ x \mathbin{\bar{/}} y^{\overline{n+1}} & = & \bar{(}x \mathbin{\bar{/}} y^{\bar{n}}\bar{)} \mathbin{\bar{/}} y \\ y^{\bar{1}} & = & y \\ \bar{(}x\bar{)} & = & x \\ & \cdots & \end{array}$$

The correspondence between concrete values and abstract values can be formalized by an abstraction function α mapping units to dimensions:

$$\begin{array}{rcl} \alpha(\mathit{meter}) & = & \mathit{length} \\ \alpha(\mathit{mile}) & = & \mathit{length} \\ \alpha(\mathit{acre}) & = & \mathit{surface} \\ \alpha(\mathit{second}) & = & \mathit{time} \\ \alpha(\mathit{minute}) & = & \mathit{time} \\ \alpha(\mathit{hour}) & = & \mathit{time} \\ \alpha(\mathit{kilogram}) & = & \mathit{mass} \end{array}$$

$$\begin{array}{rcl} \alpha(\mathit{pound}) & = & \mathit{mass} \\ \alpha(\mathit{ton}) & = & \mathit{mass} \\ \alpha(\mathit{Newton}) & = & \mathit{force} \\ \alpha(\mathit{nounit}) & = & \mathit{nodimension} \\ & \cdots & \\ \alpha(E_1\ \mathit{op}\ E_2) & = & \alpha(E_1)\ \bar{op}\ \alpha(E_2) \\ \alpha((E)) & = & \bar{(}\alpha(E)\bar{)} \end{array}$$

The abstract interpretation of an expression can be done in two distinct steps: it begins with the derivation of an abstract expression from the concrete expression and goes on with the evaluation of the abstract expression using the definition of the abstract operators. In our example, the abstract expression is first obtained using the abstraction operator α:

$$\begin{array}{rcl} \alpha(kg \times (m/s^2)) & = & \alpha(kg) \mathbin{\bar{\times}} \alpha((m/s^2)) \\ & = & \mathit{mass} \mathbin{\bar{\times}} \bar{(}\alpha(m \,/\, s^2)\bar{)} \\ & = & \mathit{mass} \mathbin{\bar{\times}} \bar{(}\alpha(m) \mathbin{\bar{/}} \alpha(s^2)\bar{)} \\ & = & \mathit{mass} \mathbin{\bar{\times}} \bar{(}\mathit{length} \mathbin{\bar{/}} \alpha(s)^{\bar{2}}\bar{)} \\ & = & \mathit{mass} \mathbin{\bar{\times}} \bar{(}\mathit{length} \mathbin{\bar{/}} \mathit{time}^{\bar{2}}\bar{)} \end{array}$$

Since, in general, the abstraction function α is not computable, this first phase, which is usually done by hand, can be understood as the design of an abstract compiler. Then, the abstract expression can be evaluated using an abstract interpreter:

$$\begin{array}{rcl} \mathit{mass} \mathbin{\bar{\times}} \bar{(}\mathit{length} \mathbin{\bar{/}} \mathit{time}^{\bar{2}}\bar{)} & = & \mathit{mass} \mathbin{\bar{\times}} \bar{(}\bar{(}\mathit{length} \mathbin{\bar{/}} \mathit{time}\bar{)} \mathbin{\bar{/}} \mathit{time}\bar{)} \\ & = & \mathit{mass} \mathbin{\bar{\times}} \bar{(}\bar{(}\mathit{speed}\bar{)} \mathbin{\bar{/}} \mathit{time}\bar{)} \\ & = & \mathit{mass} \mathbin{\bar{\times}} \bar{(}\mathit{speed} \mathbin{\bar{/}} \mathit{time}\bar{)} \\ & = & \mathit{mass} \mathbin{\bar{\times}} \bar{(}\mathit{acceleration}\bar{)} \\ & = & \mathit{mass} \mathbin{\bar{\times}} \mathit{acceleration} \\ & = & \mathit{force} \end{array}$$

This second phase of abstract execution must always be finitely computable, hence must only involve the finite iterated application of computable abstract operations on finitely representable abstract values.

The main interest of this example is to illustrate the idea of proving the correctness of the abstract interpretation relatively to a semantics via an abstraction operator as introduced in [28] and [29]. The importance of this idea was that by relating abstract interpretations not to

programming languages but to their operational semantics, one was able to define abstract interpretation independently of any programming language, thus obtaining a theory applicable to all programming languages. This can also be understood as meaning that abstract interpretations designed for a language can systematically be transferred to any other language. Moreover, by making clear the relationships between analysis and semantics [34], independently of any program property, a theory of discrete approximation emerged, which has a very broad scope since it is applicable from the design of semantics to that of low-level data flow analyses.

2.2.2. Generalization to Type Checking and Type Inference

Computer scientists would understand the dimension calculus as a type checking ensuring the correct use of units of measure. The idea of using a calculus for type-checking programs is due to Naur ([127], [128]) in the GIER ALGOL III compiler: "The basic method is a pseudo-evaluation of the expressions of the program. This proceeds like a run-time evaluation as far as the combining of operators and operands is concerned, but works with descriptions of the types and kinds of the operand instead of with values." Pseudo-evaluation is an abstract interpretation where the abstract operators are:

$$\begin{array}{rcl} \text{integer} + \text{integer} = \text{integer} & \qquad & \text{integer} \leq \text{integer} = \text{Boolean} \\ \text{integer} + \text{real} = \text{real} & & \text{integer} \leq \text{real} = \text{Boolean} \\ \text{real} + \text{integer} = \text{real} & & \text{real} \leq \text{integer} = \text{Boolean} \\ \text{real} + \text{real} = \text{real} & & \text{real} \leq \text{real} = \text{Boolean} \end{array}$$

Errors were handled using an "error" ("undeclared" in [128]) abstract value. An error message was produced when it appeared for the first time in the abstract interpretation of an expression. Thereafter, "error" was accepted as abstract operand in order to prevent redundant error messages:

$$\begin{array}{rcl} \text{integer} + \text{Boolean} = \text{error} & \qquad & \text{error} + \text{integer} = \text{error} \\ \text{Boolean} + \text{integer} = \text{error} & & \text{real} + \text{error} = \text{error} \\ \text{Boolean} + \text{Boolean} = \text{error} & & \text{error} + \text{real} = \text{error} \\ \text{real} + \text{Boolean} = \text{error} & & \text{Boolean} + \text{error} = \text{error} \\ \text{Boolean} + \text{real} = \text{error} & & \text{error} + \text{Boolean} = \text{error} \\ \text{integer} + \text{error} = \text{error} & & \text{error} + \text{error} = \text{error} \end{array}$$

In total, 25 abstract values were used, in fact much more since the number of dimensions of arrays and the number of parameters (not their type) of procedures and functions was taken into account.

2.3. Casting Out of Nine

Our last introductory example is well known by French pupils who use casting out of nine to check their additions and multiplications. To check the correctness of the multiplication $217 \times 38 = 8256$, one computes the respective rests $r_1 = (2 + 1 + 7) \bmod 9 = 1$, $r_2 = (3 + 8) \bmod 9 = 2$ and $r = (8 + 2 + 5 + 6) \bmod 9 = 3$ of the division by 9 of the sum of the digits of the first factor 217, of the second factor 38 and of the result 8256. Then one computes the rest $p = (r_1 \times r_2) \bmod 9 = (1 \times 2) \bmod 9 = 2$ of the division by 9 of the product $r_1 \times r_2$ of the rests. The disposition of the calculation on paper is shown in Figure 1. If $r \neq p$, then one concludes that the multiplication was done incorrectly. This is the case in our example. Whenever $r = p$, one cannot conclude that the operation is correct (although most pupils get very confident in their result; the unfortunate French name of "proof by nine" certainly enforcing this undue conviction).

2.3.1. The Casting Out of Nine Calculus

Since casting out of nine is a rather simple abstract interpretation, we will design it formally so as to justify the above rule. To do this, we follow the systematic approach introduced in [25], [26], [29], and [34].

2.3.1.1. SYNTAX OF EXPRESSIONS. The syntax of expressions is given by the following grammar where E is an expression, P a product, N a number, and D a digit:

$$\begin{array}{lcl} E & ::= & P = N \\ P & ::= & N_1 \times N_2 \\ N & ::= & D \mid ND \\ D & ::= & 0 \mid 1 \mid 2 \mid 3 \mid 4 \mid 5 \mid 6 \mid 7 \mid 8 \mid 9 \end{array}$$

2.3.1.2. OPERATIONAL SEMANTICS OF EXPRESSIONS. The operational semantics of expression E is a boolean $\mathcal{E}[\![E]\!] \in \{true, false\}$, defined as follows:

$$\begin{array}{rcll} \mathcal{E}[\![P = N]\!] & = & true & \text{if } \mathcal{E}[\![P]\!] = \mathcal{E}[\![N]\!] \\ \mathcal{E}[\![P = N]\!] & = & false & \text{if } \mathcal{E}[\![P]\!] \neq \mathcal{E}[\![N]\!] \\ \mathcal{E}[\![N_1 \times N_2]\!] & = & \mathcal{E}[\![N_1]\!] \times \mathcal{E}[\![N_2]\!] & \\ \mathcal{E}[\![ND]\!] & = & (10 \times \mathcal{E}[\![N]\!]) + \mathcal{E}[\![D]\!] & \\ \mathcal{E}[\![0]\!] & = & 0 & \\ \ldots & & & \\ \mathcal{E}[\![9]\!] & = & 9 & \end{array}$$

2.3.1.3. ABSTRACTION BY CASTING OUT OF NINE. The approximation consists in computing modulo nine ($[x]_9$ denotes the remainder upon division by 9 of integer $x \in \mathbb{Z}$):

$$\begin{array}{rcll} \alpha(X) & = & [\mathcal{E}[\![X]\!]]_9 & \text{if } X \text{ is } P, N, \text{ or } D \\ \alpha(P = N) & = & error & \text{if } [\mathcal{E}[\![P]\!]]_9 \neq [\mathcal{E}[\![N]\!]]_9 \\ \alpha(P = N) & = & unknown & \text{if } [\mathcal{E}[\![P]\!]]_9 = [\mathcal{E}[\![N]\!]]_9 \end{array}$$

The intuition behind this formal definition is that $[x]_9 \neq [y]_9$ implies $x \neq y$ so that whenever the abstract value *error* is found, the multiplication is incorrect.

2.3.1.4. SYSTEMATIC DESIGN OF THE ABSTRACT INTERPRETER. The design of the abstract interpreter consists in expressing $\alpha(E)$ in an equivalent form involving only arithmetic modulo 9, i.e., operations on the abstract values *unknown*, *error*, 0, 1, ... , 8. Such abstract operations are effective since they involve a finite domain. We proceed by induction on the syntax of expressions. For the basis, we have:

FIGURE 1. Casting out of nine calculation.

$$\begin{array}{rcll}
\alpha(0) & = & [\mathcal{E}[\![0]\!]]_9 & \text{by definition of } \alpha;\\
 & = & [0]_9 & \text{by definition of } \mathcal{E};\\
 & = & 0 & \text{by definition of remainders.}\\
\ldots & = & \ldots & \ldots\\
\alpha(9) & = & [\mathcal{E}[\![9]\!]]_9 & \text{by definition of } \alpha;\\
 & = & [9]_9 & \text{by definition of } \mathcal{E};\\
 & = & 0 & \text{by definition of remainders.}
\end{array}$$

Now, for the induction hypothesis, we assume that we have already expressed $\alpha(t_i)$ by composition of operators on abstract values for subterms t_i, $i \in [1,n]$. To do the same for term $f(t_1,\ldots,t_n)$, we look for an abstract operator $\bar{f}$ such that we can prove $\alpha(f(t_1,\ldots,t_n)) = \bar{f}(\alpha(t_1),\ldots,\alpha(t_n))$ and insist upon the fact that $\bar{f}$ should be effectively computable using only abstract values:

$\alpha(ND)$

$$\begin{array}{rcll}
 & = & [\mathcal{E}[\![ND]\!]]_9 & \text{by definition of } \alpha;\\
 & = & [(10 \times \mathcal{E}[\![N]\!]) + \mathcal{E}[\![D]\!]]_9 & \text{by definition of } \mathcal{E};\\
 & = & [[(10 \times \mathcal{E}[\![N]\!])]_9 + [\mathcal{E}[\![D]\!]]_9]_9 & \text{since } [x+y]_9 = [[x]_9 + [y]_9]_9;\\
 & = & [[[10]_9 \times [\mathcal{E}[\![N]\!]]_9]_9 + [\mathcal{E}[\![D]\!]]_9]_9 & \text{since } [x \times y]_9 = [[x]_9 \times [y]_9]_9;\\
 & = & [[1 \times [\mathcal{E}[\![N]\!]]_9]_9 + \alpha(D)]_9 & \text{since } [10]_9 = 1 \text{ and by definition of } \alpha;\\
 & = & [[[\mathcal{E}[\![N]\!]]_9]_9 + \alpha(D)]_9 & \text{since } 1 \times x = x;\\
 & = & [[\mathcal{E}[\![N]\!]]_9 + \alpha(D)]_9 & \text{since } [[x]_9]_9 = [x]_9;\\
 & = & [\alpha(N) + \alpha(D)]_9 & \text{by definition of } \alpha;\\
 & = & (\alpha(N) \mathbin{\bar{+}} \alpha(D)) & \text{by letting } x \mathbin{\bar{+}} y \stackrel{\text{def}}{=} [x+y]_9.
\end{array}$$

$\alpha(N_1 \times N_2)$

$$\begin{array}{rcll}
 & = & [\mathcal{E}[\![N_1 \times N_2]\!]]_9 & \text{by definition of } \alpha;\\
 & = & [\mathcal{E}[\![N_1]\!] \times \mathcal{E}[\![N_2]\!]]_9 & \text{by definition of } \mathcal{E};\\
 & = & [[\mathcal{E}[\![N_1]\!]]_9 \times [\mathcal{E}[\![N_2]\!]]_9]_9 & \text{since } [x \times y]_9 = [[x]_9 \times [y]_9]_9;\\
 & = & [\alpha(N_1) \times \alpha(N_2)]_9 & \text{by definition of } \alpha;\\
 & = & (\alpha(N_1) \mathbin{\bar{\times}} \alpha(N_2)) & \text{by letting } x \mathbin{\bar{\times}} y \stackrel{\text{def}}{=} [x \times y]_9.
\end{array}$$

$\alpha(P = N)$

$$\begin{array}{rcll}
 & = & \mathit{error} & \text{if } [\mathcal{E}[\![P]\!]]_9 \neq [\mathcal{E}[\![N]\!]]_9,\\
 & = & \mathit{unknown} & \text{if } [\mathcal{E}[\![P]\!]]_9 = [\mathcal{E}[\![N]\!]]_9;
\end{array}$$

whence, by definition of α,

$$\begin{array}{rcll}
 & = & \mathit{error} & \text{if } \alpha(P) \neq \alpha(N),\\
 & = & \mathit{unknown} & \text{if } \alpha(P) = \alpha(N);
\end{array}$$

and letting $x \mathbin{\bar{=}} y \stackrel{\text{def}}{=}$ if $x = y$ then *unknown* else *error*,

$$= \quad \alpha(P) \mathbin{\bar{=}} \alpha(N).$$

2.3.1.5. Abstract Interpretation by Casting Out of Nine. The above design leads to an automatic semantic analyser that consists of a compiler and an interpreter, organized as follows:

1. The abstract compiler reads an expression E and produces (a computer representation of) an abstract expression $\mathcal{C}[\![E]\!]$ defined as follows:

$$\begin{array}{rcl}
\mathcal{C}[\![P = N]\!] & = & (\mathcal{C}[\![P]\!] \mathbin{\bar{=}} \mathcal{C}[\![N]\!])\\
\mathcal{C}[\![N_1 \times N_2]\!] & = & (\mathcal{C}[\![N_1]\!] \mathbin{\bar{\times}} \mathcal{C}[\![N_2]\!])\\
\mathcal{C}[\![ND]\!] & = & (\mathcal{C}[\![N]\!] \mathbin{\bar{+}} \mathcal{C}[\![D]\!])\\
\mathcal{C}[\![0]\!] & = & 0\\
\ldots & & \\
\mathcal{C}[\![8]\!] & = & 8\\
\mathcal{C}[\![9]\!] & = & 0
\end{array}$$

2. An abstract interpreter $\mathcal{I}$ is written to evaluate abstract expressions, as follows:

$$\begin{array}{rcll}
\mathcal{I}[\![(v_1 \doteq v_2)]\!] & = & \mathit{unknown} & \text{if } \mathcal{I}[\![v_1]\!] = \mathcal{I}[\![v_2]\!] \\
 & = & \mathit{error} & \text{if } \mathcal{I}[\![v_1]\!] \neq \mathcal{I}[\![v_2]\!] \\
\mathcal{I}[\![(v_1 \bar{\times} v_2)]\!] & = & [\mathcal{I}[\![v_1]\!] \times \mathcal{I}[\![v_2]\!]]_9 & \\
\mathcal{I}[\![(v_1 \bar{+} v_2)]\!] & = & [\mathcal{I}[\![v_1]\!] + \mathcal{I}[\![v_2]\!]]_9 & \\
\mathcal{I}[\![0]\!] & = & 0 & \\
 & \cdots & & \\
\mathcal{I}[\![8]\!] & = & 8 &
\end{array}$$

The correctness of our semantic analyser follows from its design since we have:

$$\alpha(E) = \mathcal{I}[\![\mathcal{C}[\![E]\!]]\!]$$

For example, the abstract interpretation of the concrete expression $E = 217 \times 38 = 8256$ first consists in compiling into:

$$\bar{E} \;=\; \mathcal{C}[\![E]\!] \;= ((((2 \bar{+} 1) \bar{+} 7) \bar{\times} (3 \bar{+} 8)) \doteq (((8 \bar{+} 2) \bar{+} 5) \bar{+} 6))$$

Then evaluation of the abstract expression $\bar{E}$ results into:

$$\begin{array}{rcl}
\mathcal{I}[\![\bar{E}]\!] & = & [[[2+1]_9 + 7]_9 \times [3+8]_9]_9 \doteq [[[8+2]_9 + 5]_9 + 6]_9 \\
 & = & [1 \times 2]_9 \doteq 3 \\
 & = & 2 \doteq 3 \\
 & = & \mathit{error}
\end{array}$$

thus proving that the equality does not hold.

2.3.2. Generalization to Congruence Analysis

Abstract interpretations of integers modulo some given integer can be applied to the analysis of programs, such as the parity analysis considered in [34]. They have been generalized to the automatic discovery of invariants that are conjunctions of arithmetical congruences of the form $\alpha x \equiv \beta \pmod{\gamma}$ where α, β, and γ are integer constants automatically discovered during the analysis and x denotes the value of an integer variable of the program [74] and then to the discovery of linear congruences of the form $\alpha_1 x_1 + \cdots + \alpha_n x_n \equiv \beta \pmod{\gamma}$ where $\alpha_1, \ldots, \alpha_n, \beta$, and γ are integer constants automatically discovered during the analysis and $x_1, \ldots, x_n$ denote the values of integer variables of the program [75]. For example, this last analysis, automatically discovers the invariant given after the loop of the program below, which computes the integer root x of $n \geq 0$:

```
x := 0; y := 1; z := 1;
while y <= n do begin
  x := x + 1; z := z + 2; y := y + z;
end;
```
{ $2x - z + 1 \equiv 0 \pmod{0} \;\wedge\; x + y \equiv 1 \pmod{2}$ }

3. PRINCIPLES OF ABSTRACT INTERPRETATION

The abstract interpretation framework that we introduced, illustrated and explained in a series of papers [28], [29], [31], [32], [30], [25], [44], [34], [35] and [26] was motivated by the desire to justify the specification of program analysers with respect to some formal semantics. The guiding idea is that this process is a discrete inducing or approximation of properties from the exact or concrete semantics onto an approximate or abstract semantics that explicitly exhibits an underlying particular structure implicitly present in the richer concrete structure associated to program executions. Hence, abstract interpretation has a constructive aspect, as opposed to

a mere a posteriori justification, in that the abstract semantics can be derived systematically from the concrete one, with the hope that this process will be ultimately computer-aided. We think here, for example, to the partly automatic generation of program analysers. Therefore, the subject of abstract interpretation involves the study of program semantics, of program proof methods, and of program analyser's specification, realization, and experimentation with the underlying idea that these different descriptions, views, facets, or abstractions of run-time behaviors of programs are all linked together by an inducing or approximation, i.e., abstraction process. Clearly, this involves the deep understanding and creation of mathematical structures to describe program executions and the study of their relationships, which is a vast subject mainly remaining to be explored when considering, for a provocative example, what is known in algebra about numbers and the simplicity of this structure when compared to that of computer programs.

The classical framework summarized in [26] starts from an operational semantics describing, for example, small program execution steps using a transition system (for example, flowcharts in [29]) or execution traces (example 7.2.0.6 in [34]). Then a static or collecting semantics, often described using fixpoints on ordered structures, is designed that is minimal, sound, and relatively complete for the program properties of interest. Intuitively, the collecting semantics is the most precise of the semantics that can be conceived to describe a certain class of so-called concrete program properties without referring to other program properties out of the scope of interest. It can be used for example to design proof methods [37], [45], [38]. The design of program analysers is based on abstract semantics that are approximations of the collecting semantics. There, the main concern is the compromise to be found between the difficulty of the analysis conception, the flexibility, the precision, and the cost of the analyses. Everything is fixed by the choice of the abstract properties to be considered (which can be governed, for example, by computer representation considerations) and by their semantics that is their correspondence with concrete properties. The use of Galois connections to express this correspondence squares with an ideal situation where there is a best way to approximate any concrete property by an abstract one. These two interrelated choices entirely determine the abstract semantics, which can be derived from the concrete collecting semantics and described using fixpoints. Then, the practical problem of effectively computing these fixpoints must be grappled with. There, chaotic and asynchronous methods are useful. Convergence can be accelerated using widening and narrowing operators so as to cope with infinite domains of abstract properties or to avoid combinatorial explosions. Hence, the approximation process is split up in the static design of an abstract semantics expressed as an equation and the iterative resolution of this equation. Independent designs also have to be combined.

We now enter into more details of this approach, which we illustrate using logic programs.

4. APPROXIMATION METHODS FOR ABSTRACT INTERPRETATION

We start with a few, hopefully well-known, mathematical facts.

4.1. Lattice and Fixpoint Theory

Let be given sets S, T and U. The *powerset* $\wp(S)$ is the set $\{X \mid X \subseteq S\}$ of all subsets of S. The *cartesian product* $S \times T$ is the set $\{\langle s, t\rangle \mid s \in S \wedge t \in T\}$ of all pairs with first component in S and second component in T. A *binary relation* on $S \times T$ is a subset $\rho \in \wp(S \times T)$ of $S \times T$. A *pre-order* on a set S is a binary relation $\sqsubseteq$ that is *reflexive* ($\forall x \in S : x \sqsubseteq x$, where $x \sqsubseteq x'$ stands for $\langle x, x'\rangle \in \sqsubseteq$) and *transitive* ($\forall x, y, z \in X : (x \sqsubseteq y \ \wedge \ y \sqsubseteq z) \Rightarrow x \sqsubseteq z$). We write $x \sqsubset y$ for $(x \sqsubseteq y \ \wedge \ x \neq y)$. A *partial order* on a set S is a pre-order that is *antisymmetric* ($\forall x, y \in S : (x \sqsubseteq y \ \wedge \ y \sqsubseteq x) \Rightarrow x = y$).

Let $\sqsubseteq$ be a partial order on a set S. u is an *upper bound* of a subset X of S if and only if u is greater than or equal to all members of X ($\forall x \in X : x \sqsubseteq u$). The *least upper bound* u

of a subset X of S is an upper bound of X that is smaller than any other upper bound of X ($\forall x \in X : x \sqsubseteq u \ \wedge \ \forall u' \in S : (\forall x \in X : x \sqsubseteq u') \Rightarrow (u \sqsubseteq u')$). A least upper bound is unique. If it exists, the least upper bound of X is written $\sqcup X$. The *lower bounds* and *greatest lower bound* $\sqcap X$ of $X \subseteq S$ are *dual* (i.e. their definition is obtained from that of upper bounds and the least upper bound by replacing $\sqsubseteq$ by its dual $\sqsupseteq$).

A *poset* $P(\sqsubseteq)$ is a partial order $\sqsubseteq$ on a set P. A *complete lattice* $L(\sqsubseteq, \bot, \top, \sqcup, \sqcap)$ is a poset $L(\sqsubseteq)$ such that any subset X of L has a least upper bound $\sqcup X$ and a greatest lower bound $\sqcap X$. In particular, the *infimum* $\bot = \sqcup\emptyset = \sqcap L$ is the smallest element of L whilst the *supremum* $\top = \sqcap\emptyset = \sqcup L$ is the greatest. A *linear order* $\sqsubseteq$ is a partial order such that any two elements of P are comparable: $\forall x, y \in P : x \sqsubseteq y \ \vee \ y \sqsubseteq x$. An *increasing chain* is a subset X of P such that $\sqsubseteq$ is a linear order on X. A *complete partial order*, for short *cpo*, is a poset such that every increasing chain has a least upper bound. A *strict* cpo has an infimum.

We write $\varphi \in S \rightarrowtail T$ to mean that φ is a *partial function* of S into T, i.e., a relation $\varphi \in \wp(S \times T)$ such that $\langle s, t\rangle \in \varphi$ only if $s \in S$ and $t \in T$ and, for every $s \in S$, there exists at most one $t \in T$, written φs, $\varphi[\![s]\!]$, $\varphi[s]$, or $\varphi(s)$, satisfying $\langle s, t\rangle \in \varphi$. We say that $\varphi(s)$ is *well-defined* when the definition of φ implies the existence of $\varphi(s)$. We write $\varphi \in S \mapsto T$ to mean that φ is a *total function* of S into T i.e. $\varphi(s)$ is well-defined for all s in S ($\forall s \in S : \exists t \in T : \langle s, t\rangle \in \varphi$). As usual function composition $\circ$ is defined by $\varphi \circ \psi(s) = \varphi(\psi(s))$. The *image* of $X \subseteq S$ by $\varphi \in S \mapsto T$ is $\varphi^*(X) = \{\varphi(x) \mid x \in X\}$. Let $P(\sqsubseteq, \sqcup)$ be a poset with least upper bound $\sqcup$ and $Q(\preceq, \vee)$ be a poset with least upper bound $\vee$. $P(\sqsubseteq) \stackrel{m}{\longmapsto} Q(\preceq)$ denotes the set of total functions $\varphi \in P \mapsto Q$ that are *monotone*, i.e., order morphisms: $\forall x \in P : \forall y \in Q : x \sqsubseteq y \Rightarrow \varphi x \preceq \varphi y$. $P(\sqsubseteq, \sqcup) \stackrel{c}{\longmapsto} Q(\vee)$ denotes the set of total functions $\varphi \in P \mapsto Q$ that are *upper-continuous*, i.e., which preserve existing least upper bounds of increasing chains: if $X \subseteq P$ is an increasing chain for $\sqsubseteq$ and $\sqcup X$ exists then $\varphi(\sqcup X) = \vee\varphi^*(X)$. $P(\sqcup) \stackrel{a}{\longmapsto} Q(\vee)$ denotes the set of total functions $\varphi \in P \mapsto Q$ that are *additive*, i.e., complete join-morphisms preserving least upper bounds of arbitrary subsets, when they exist: if $X \subseteq P$ and $\sqcup X$ exists then $\varphi(\sqcup X) = \vee\varphi^*(X)$. When the above notions are restricted to sets equipotent with the set $\mathbb{N}$ of natural numbers, they are qualified by the attribute ω as in *ω-chain*, *ω-cpo*, *ω-continuity*, etc.

A *fixpoint* $x \in P$ of $\varphi \in P \mapsto P$ is such that $\varphi x = x$. We write $\varphi^=$ for the set $\{x \in P \mid \varphi x = x\}$ of fixpoints of φ. The *least fixpoint* $lfp\,\varphi$ of φ is the unique $x \in \varphi^=$ such that $\forall y \in \varphi^= : x \sqsubseteq y$. The dual notion is that of *greatest fixpoint* $gfp\,\varphi$. By Tarski's fixpoint theorem [141], the fixpoints of a monotone mapping $\varphi \in L(\sqsubseteq) \stackrel{m}{\longmapsto} L(\sqsubseteq)$ on a complete lattice $L(\sqsubseteq, \bot, \top, \sqcup, \sqcap)$ form a complete lattice $\varphi^=$ for $\sqsubseteq$ with infimum $lfp\,\varphi = \sqcap\varphi^{\sqsubseteq}$ and supremum $gfp\,\varphi = \sqcup\varphi^{\sqsupseteq}$ where $\varphi^{\sqsubseteq} = \{x \in L \mid \varphi x \sqsubseteq x\}$ is the set of *postfixpoints* and $\varphi^{\sqsupseteq} = \{x \in L \mid \varphi x \sqsupseteq x\}$ is the set of *prefixpoints* of φ. Moreover, if φ is ω-upper-continuous (hence, in particular, additive), $lfp\,\varphi = \sqcup_{n \geq 0}\varphi^n(\bot)$ where $\varphi^0(x) = \bot$ and $\varphi^{n+1}(x) = \varphi(\varphi^n(x))$ for all $x \in L$. This is illustrated in Figure 2 (where a poset P is represented by its Hasse diagram so that its elements are figured by points, a point being above and linked by a line to another if it corresponds to a strictly greater element and a function φ is represented by its sagittal graph using arrows linking all each point for $x \in P$ to the point corresponding to $\varphi(x)$).

4.2. Approximation of Fixpoint Semantics by Simplification Using Galois Connections

Two fixpoint approximation methods were considered in [29]. One is static in that it can be understood as the simplification of the equation involved in the concrete semantics into an approximate abstract equation which solution provides the abstract semantics. Galois connections are used to formalize this discrete approximation process. The second is dynamic in that it takes place during the iterative resolution of the abstract equation (or system of equations). This separation introduces additional flexibility allowing for both expressiveness and efficiency.

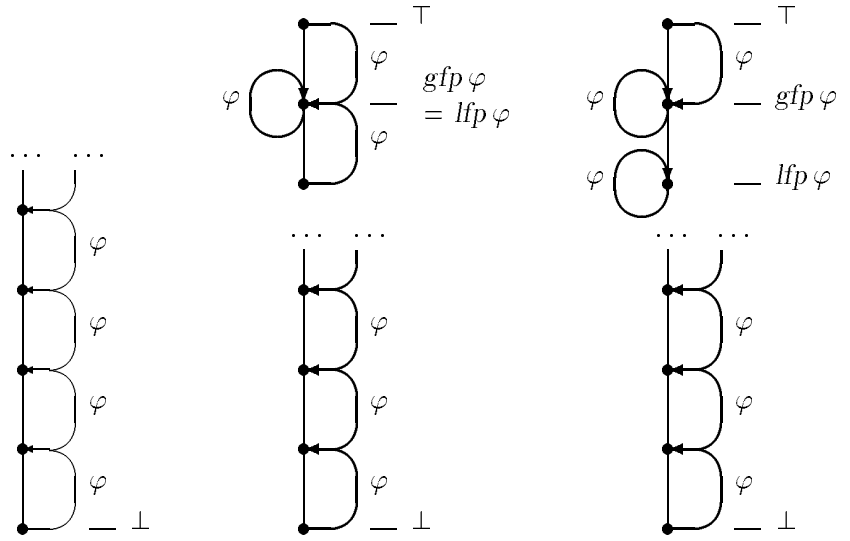


FIGURE 2. Fixpoints.

4.2.1. Approximation of Concrete Program Properties by Abstract Properties

We assume that the concrete program properties are described by elements of a given set $P^\flat$. Let $\preceq^\flat$ be a partial order relation on $P^\flat$ defining the relative precision of concrete properties: ${p^\flat}_1 \preceq^\flat {p^\flat}_2$ means that ${p^\flat}_1$ and ${p^\flat}_2$ are comparable properties of the program, ${p^\flat}_1$ being more precise than ${p^\flat}_2$, the relative precision being left unquantified. The abstract program properties are assumed to be represented by elements of a poset $P^\sharp(\preceq^\sharp)$ where the partial order relation $\preceq^\sharp$ defines the relative precision of abstract properties.

Example 1 (Rule of signs). For a trivial example, we can chose $P^\flat = \{\text{false}, <0, =0, >0, \leq 0, \neq 0, \geq 0, \text{true}\}$ with the intended meaning that these properties refer to the possible values x of some program variable and therefore false $\stackrel{\text{def}}{=} \emptyset$, $<0 \stackrel{\text{def}}{=} \{x \in \mathbb{Z} \mid x < 0\}$, $=0 \stackrel{\text{def}}{=} \{0\}$, ... , true $\stackrel{\text{def}}{=} \mathbb{Z}$. For example, $=0 \preceq^\flat \geq 0$ since "is equal to zero" is more precise than "is positive or zero" (but it would be difficult to say of how much!). Hence for this example $\preceq^\flat$ is the subset ordering $\subseteq$. A possible approximation of $P^\flat$ would be $P^\sharp = \{f^\sharp, -1, 0, +1, t^\sharp\}$ where strict inequalities are ignored. □

The semantics of the abstract properties is given by a concretization function $\gamma \in P^\sharp \mapsto P^\flat$: $\gamma(p^\sharp)$ is the concrete property corresponding to the abstract description $p^\sharp \in P^\sharp$. The notion of approximation is formalized by an abstraction function $\alpha \in P^\flat \mapsto P^\sharp$ giving the best abstract approximation $\alpha(p^\flat)$ of concrete properties $p^\flat \in P^\flat$.

Example 2 (Rule of signs, continued). The concretization function for our trivial example is given in Figure 3, (where posets $P^\flat(\preceq^\flat)$ and $P^\sharp(\preceq^\sharp)$ are represented by their Hasse diagrams and γ by its sagittal graph). For example, $+1$ means ≥ 0 that is "belonging to the set of zero or positive integers". In Figure 3, we would have:

$p^\flat$	false	<0	$=0$	>0	≤ 0	$\neq 0$	≥ 0	true
$\alpha(p^\flat)$	$f^\sharp$	-1	0	$+1$	-1	$\top$	$+1$	$t^\sharp$

with the obvious meaning that, e.g. "is strictly positive" can be approximate from above by "is zero or positive" for subset approximation ordering $\subseteq$. □

If $p^\sharp{}_1 = \alpha(p^\flat)$ and $p^\sharp{}_1 \preceq^\sharp p^\sharp{}_2$ then $p^\sharp{}_2$ is also a correct, although less precise abstract approximation of the concrete property $p^\flat$. Hence, the soundness of approximations, i.e., the fact that $p^\sharp$ is a valid approximation of the information given by $p^\flat$ can be expressed by $\alpha(p^\flat) \preceq^\sharp p^\sharp$. If $p^\flat{}_1 = \gamma(p^\sharp)$ and $p^\flat{}_2 \preceq^\flat p^\flat{}_1$ then $p^\sharp$ is also a correct approximation of the concrete property $p^\flat{}_2$ although this concrete property $p^\flat{}_2$ provides more accurate information about program executions than $p^\flat{}_1$. So the soundness of approximations, that is the fact that $p^\sharp$ is a valid approximation of the information given by $p^\flat$, can also be expressed by $p^\flat \preceq^\flat \gamma(p^\sharp)$. When these two soundness conditions are equivalent, we have got a Galois connection. We now examine more precisely the motivations for and consequences of this hypothesis. This requires the study of mathematical properties of Galois connections.

4.2.2. Galois Connections

Given posets $P^\flat(\preceq^\flat)$ and $P^\sharp(\preceq^\sharp)$, a *Galois connection* is a pair of maps such that:

$$\begin{array}{rcl} \alpha & \in & P^\flat \mapsto P^\sharp \\ \gamma & \in & P^\sharp \mapsto P^\flat \\ \forall p^\flat \in P^\flat : \forall p^\sharp \in P^\sharp : \alpha(p^\flat) \preceq^\sharp p^\sharp & \Leftrightarrow & p^\flat \preceq^\flat \gamma(p^\sharp) \end{array} \tag{1}$$

in which case we write:

$$P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$$

Galois connections have numerous properties, which are recalled in [34] (particularly theorems 5.3.0.5 and 5.3.0.7), where the references to the mathematical literature are also found. For example, $\gamma \circ \alpha$ is *extensive*:

$$\forall p^\flat \in P^\flat : p^\flat \preceq^\flat \gamma \circ \alpha(p^\flat) \tag{2}$$

since $\alpha(p^\flat) \preceq^\sharp \alpha(p^\flat)$ by reflexivity, hence $p^\flat \preceq^\flat \gamma \circ \alpha(p^\flat)$ by (1) with $p^\sharp = \alpha(p^\flat)$. This can be interpreted by the fact that the loss of information in the abstraction process is sound. The same way, $\alpha \circ \gamma$ is *reductive*:

$$\forall p^\sharp \in P^\sharp : \alpha \circ \gamma(p^\sharp) \preceq^\sharp p^\sharp \tag{3}$$

since $\gamma(p^\sharp) \preceq^\flat \gamma(p^\sharp)$ by reflexivity, hence $\alpha \circ \gamma(p^\sharp) \preceq^\sharp p^\sharp$ by (1) with $p^\flat = \gamma(p^\sharp)$. This can be interpreted by the fact that the concretization process introduces no loss of information. From an abstract point of view, $\alpha(p^\flat)$ is as precise as possible.

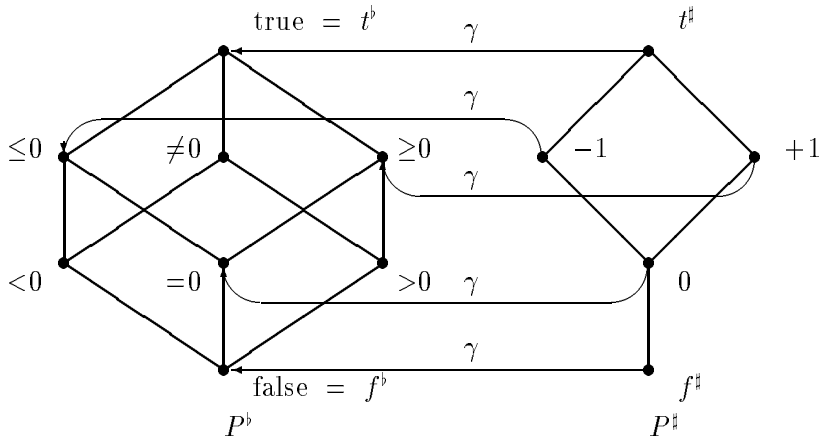


FIGURE 3. Concretization function.

It follows that α is monotone [since ${p^\flat}_1 \preceq^\flat {p^\flat}_2$ implies ${p^\flat}_1 \preceq^\flat \gamma\circ\alpha({p^\flat}_2)$ by (2) and transitivity whence $\alpha({p^\flat}_1) \preceq^\sharp \alpha({p^\flat}_2)$ by (1)] and so is γ [since ${p^\sharp}_1 \preceq^\sharp {p^\sharp}_2$ implies $\alpha\circ\gamma({p^\sharp}_1) \preceq^\sharp {p^\sharp}_2$ by (3) and transitivity whence $\gamma({p^\sharp}_1) \preceq^\flat \gamma({p^\sharp}_2)$ by (1)]:

$$\begin{array}{rcl} \alpha & \in & P^\flat(\preceq^\flat) \stackrel{m}{\longmapsto} P^\sharp(\preceq^\sharp) \\ \gamma & \in & P^\sharp(\preceq^\sharp) \stackrel{m}{\longmapsto} P^\flat(\preceq^\flat) \end{array} \tag{4}$$

Monotony can be interpreted as the fact that the abstraction and concretization process preserves the soundness of the approximation.

(2), (3), and (4) imply (1), hence can be chosen as an equivalent definition of Galois connections:

$$\begin{array}{rcl} P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp) & \Longleftrightarrow & [\alpha \in P^\flat(\preceq^\flat) \stackrel{m}{\longmapsto} P^\sharp(\preceq^\sharp)] \ \wedge \ [\gamma \in P^\sharp(\preceq^\sharp) \stackrel{m}{\longmapsto} P^\flat(\preceq^\flat)] \ \wedge \\ & & [\forall p^\flat \in P^\flat : p^\flat \preceq^\flat \gamma\circ\alpha(p^\flat)] \ \wedge \ [\forall p^\sharp \in P^\sharp : \alpha\circ\gamma(p^\sharp) \preceq^\sharp p^\sharp] \end{array} \tag{5}$$

Observe that $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$ if and only if $P^\sharp({\preceq^\sharp}^{-1}) \underset{\gamma}{\overset{\alpha}{\leftrightarrows}} P^\flat({\preceq^\flat}^{-1})$ where the inverse $\leq^{-1}$ of the partial order $\leq$ is $\geq$. It follows that the duality principle on posets stating that any theorem is true for all posets, then so is its dual obtained by substituting $\geq$, $>$, $\top$, $\bot$, $\vee$, $\wedge$, etc. respectively for $\leq$, $<$, $\bot$, $\top$, $\wedge$, $\vee$, etc. can be extended to Galois connections by exchanging α and γ.

For all $p^\flat \in P^\flat$ and $p^\sharp \in P^\sharp$, we have $\alpha\circ\gamma(p^\sharp) \preceq^\sharp p^\sharp$ by (3) whence by monotony $\gamma\circ\alpha\circ\gamma(p^\sharp) \preceq^\sharp \gamma(p^\sharp)$. Moreover, $\gamma(p^\sharp) \preceq^\sharp \gamma\circ\alpha\circ\gamma(p^\sharp)$ by (2) when $p^\flat$ is $\gamma(p^\sharp)$. By antisymmetry, we conclude that:

$$\forall p^\sharp \in P^\sharp : \gamma\circ\alpha\circ\gamma(p^\sharp) = \gamma(p^\sharp) \tag{6}$$

The same way, for all $p^\flat \in P^\flat$ we have $\alpha\circ\gamma(\alpha(p^\flat)) \preceq^\sharp \alpha(p^\flat)$ by letting $p^\sharp = \alpha(p^\flat)$ in (3). Moreover, (2) implies that for all $p^\flat \in P^\flat$ we have $p^\flat \preceq^\flat \gamma\circ\alpha(p^\flat)$ whence by monotony $\alpha(p^\flat) \preceq^\flat \alpha\circ\gamma\circ\alpha(p^\flat)$. By antisymmetry, we conclude:

$$\forall p^\flat \in P^\flat : \alpha\circ\gamma\circ\alpha(p^\flat) = \alpha(p^\flat) \tag{7}$$

An immediate consequence is that a Galois connection defines closure operators, as follows (a *lower closure operator* is monotone, reductive, and idempotent, whereas an *upper closure operator* is monotone, extensive, and idempotent):

$$P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp) \ \Longrightarrow \ \begin{cases} \alpha\circ\gamma \text{ is a lower closure operator,} \\ \gamma\circ\alpha \text{ is an upper closure operator.} \end{cases} \tag{8}$$

Idempotence, i.e., $\rho\circ\rho = \rho$, can be interpreted as the fact that all information is lost at once in the abstract interpretation process so that two successive abstractions with the same abstraction function are equivalent to a single one. Another consequence is that one can reason upon the abstract interpretation using only $P^\flat$ and the image of $P^\flat$ by the closure operator $\gamma\circ\alpha$ (instead of $P^\sharp$). This equivalent approach is considered in [34]. In particular, the use of *Moore families*, i.e., containing $t^\flat$ and closed under arbitrary $\wedge^\flat$, is justified by the following:

Proposition 3 (Moore family). If $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$ *and* $P^\flat(\preceq^\flat, f^\flat, t^\flat, \wedge^\flat, \vee^\flat)$ *is a complete lattice then* $\gamma^*(P^\sharp)$ *is a Moore family.*

PROOF. If $p^\flat \in \gamma^*(P^\sharp)$ then $\exists p^\sharp \in P^\sharp : p^\flat = \gamma(p^\sharp) \preceq^\flat t^\flat$, hence by monotony and (6) $p^\flat = \gamma(p^\sharp) = \gamma\circ\alpha\circ\gamma(p^\sharp) \preceq^\flat \gamma\circ\alpha(t^\flat)$, proving that $\gamma\circ\alpha(t^\flat) = t^\flat$ is the supremum of $\gamma^*(P^\sharp)$.

Assume that $X \subseteq \gamma^*(P^\sharp)$. If $p^\flat \in X$, then $\exists p^\sharp \in P^\sharp$ such that $p^\flat = \gamma(p^\sharp)$. Then $\wedge^\flat X$ exists in a complete lattice and satisfies $\wedge^\flat X \preceq^\flat p^\flat$ so that by monotony and (6) $\gamma\circ\alpha(\wedge^\flat X) \preceq^\flat \gamma\circ\alpha(p^\flat) = \gamma\circ\alpha\circ\gamma(p^\sharp) = \gamma(p^\sharp) = p^\flat$ proving that $\gamma\circ\alpha(\wedge^\flat X)$ is a lower bound of X so that $\gamma\circ\alpha(\wedge^\flat X) \preceq^\flat \wedge^\flat X$. But $\gamma\circ\alpha$ is extensive by proposition 8 so that by antisymmetry $\gamma\circ\alpha(\wedge^\flat X) = \wedge^\flat X$ proving that $\wedge^\flat X \in \gamma^*(P^\sharp)$. □

In a Galois connection, one function uniquely determines the other:

Proposition 4. *If* $P^\flat(\preceq^\flat) \underset{\alpha_1}{\overset{\gamma_1}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$ *and* $P^\flat(\preceq^\flat) \underset{\alpha_2}{\overset{\gamma_2}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$, *then* $(\alpha_1 = \alpha_2)$ *if and only if* $(\gamma_1 = \gamma_2)$.

PROOF. Assume that $\alpha_1 = \alpha_2$. For all $p^\sharp \in P^\sharp$, $\alpha_2 \circ \gamma_2(p^\sharp) \preceq^\sharp p^\sharp$ by (3), hence $\alpha_1 \circ \gamma_2(p^\sharp) \preceq^\sharp p^\sharp$ by hypothesis and therefore $\gamma_2(p^\sharp) \preceq^\flat \gamma_1(p^\sharp)$ by (1). The same way, $\alpha_1 \circ \gamma_1(p^\sharp) \preceq^\sharp p^\sharp$ by (3) hence $\alpha_2 \circ \gamma_1(p^\sharp) \preceq^\sharp p^\sharp$ by hypothesis and therefore $\gamma_1(p^\sharp) \preceq^\flat \gamma_2(p^\sharp)$ by (1). By antisymmetry, we conclude that $\gamma_1(p^\sharp) = \gamma_2(p^\sharp)$. The reciprocal follows from the duality principle. □

The practical consequence of this fact is that we can perform an abstract interpretation by defining the abstraction or, indifferently, the concretization function, since the adjoined function is uniquely determined as follows:

Proposition 5. *If* $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$, *then, for all* $p^\flat \in P^\flat$, $\alpha(p^\flat)$ *is equal to the greatest lower bound* $\bigwedge^\sharp\{p^\sharp \mid p^\flat \preceq^\flat \gamma(p^\sharp)\}$ *of the inverse image by* γ *of the set of upper bounds of* $p^\flat$. *For all* $p^\sharp \in P^\sharp$ *we have* $\gamma(p^\sharp) = \bigvee^\flat\{p^\flat \mid \alpha(p^\flat) \preceq^\sharp p^\sharp\}$.

PROOF. If $p^\flat \preceq^\flat \gamma(p^\sharp)$ then $\alpha(p^\flat) \preceq^\sharp p^\sharp$ by (1) so that $\alpha(p^\flat)$ is a lower bound of $\{p^\sharp \mid p^\flat \preceq^\flat \gamma(p^\sharp)\}$. Moreover $p^\flat \preceq^\flat \gamma \circ \alpha(p^\flat)$ by (2) so that $\alpha(p^\flat)$ belongs to $\{p^\sharp \mid p^\flat \preceq^\flat \gamma(p^\sharp)\}$. It follows that $\alpha(p^\flat)$ is the greatest lower bound of $\{p^\sharp \mid p^\flat \preceq^\flat \gamma(p^\sharp)\}$ since for any other lower bound ℓ, we must have $\ell \preceq^\sharp \alpha(p^\flat)$. The dual result holds for γ. □

Another important property of Galois connections is the preservation of bounds:

Proposition 6. *If* $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$, *then* $\alpha \in P^\flat(\vee^\flat) \overset{a}{\longmapsto} P^\sharp(\vee^\sharp)$ *preserves least upper bounds and* $\gamma \in P^\sharp(\wedge^\sharp) \overset{a}{\longmapsto} P^\flat(\wedge^\flat)$ *preserves greatest lower bounds.*

PROOF. Assume that X is a subset of $P^\flat$ such that $\bigvee^\flat X$ exists. For all $x \in X$ we have $x \preceq^\flat \bigvee^\flat X$ by definition of least upper bounds so that $\alpha(x) \preceq^\sharp \alpha(\bigvee^\flat X)$ by monotony, proving that $\alpha(\bigvee^\flat X)$ is an upper bound of the $\alpha(x)$. Let m be another upper bound of all $\alpha(x)$, $x \in X$. We have $\alpha(x) \preceq^\sharp m$, whence $x \preceq^\flat \gamma(m)$ by (1) so that $\bigvee^\flat X \preceq^\flat \gamma(m)$ by definition of least upper bounds. By monotony and (3) it follows that $\alpha(\bigvee^\flat X) \preceq^\sharp \alpha \circ \gamma(m) \preceq^\sharp m$, proving that $\alpha(\bigvee^\flat X)$ is the least upper bound of $\{\alpha(x) \mid x \in X\}$. By the duality principle, it follows that $\forall X \subseteq P^\sharp : \gamma(\bigwedge^\sharp X) = \bigwedge^\flat\{\gamma(x) \mid x \in X\}$ when $\bigwedge^\sharp X$ exists. □

Whenever we have defined an abstraction function that is a complete join morphism or a concretization function that is a complete meet morphism, then this definition entirely determines a unique Galois connection, provided that the bounds allowing for the definition of the adjoined function exist (which is the case, for example, when considering complete lattices):

Proposition 7. *Let* $P^\flat(\preceq^\flat)$ *and* $P^\sharp(\preceq^\sharp)$ *be posets. If* $\alpha \in P^\flat(\bigvee^\flat) \overset{a}{\longmapsto} P^\sharp(\bigvee^\flat)$ *and* $\bigvee^\flat\{p^\flat \mid \alpha(p^\flat) \preceq^\sharp p^\sharp\}$ *exists for all* $p^\sharp \in P^\sharp$, *then* $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$ *where* $\forall p^\sharp \in P^\sharp : \gamma(p^\sharp) = \bigvee^\flat\{p^\flat \mid \alpha(p^\flat) \preceq^\sharp p^\sharp\}$. *If* $\gamma \in P^\sharp(\bigwedge^\sharp) \overset{a}{\longmapsto} P^\flat(\bigwedge^\flat)$ *and* $\bigwedge^\sharp\{p^\sharp \mid p^\flat \preceq^\flat \gamma(p^\sharp)\}$ *exists for all* $p^\flat \in P^\flat$, *then* $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$ *where* $\forall p^\flat \in P^\flat : \alpha(p^\flat) = \bigwedge^\sharp\{p^\sharp \mid p^\flat \preceq^\flat \gamma(p^\sharp)\}$.

PROOF. If $\alpha(p^\flat) \preceq^\sharp p^\sharp$ then $p^\flat \in \{p^{\flat\prime} \mid \alpha(p^{\flat\prime}) \preceq^\sharp p^\sharp\}$, whence $p^\flat \preceq^\flat \bigvee^\flat\{p^{\flat\prime} \mid \alpha(p^{\flat\prime}) \preceq^\sharp p^\sharp\} = \gamma(p^\sharp)$ by definition of least upper bounds and of γ. Reciprocally, if $p^\flat \preceq^\flat \gamma(p^\sharp)$ then by definition of γ and monotony $\alpha(p^\flat) \preceq^\sharp \alpha(\bigvee^\flat\{p^{\flat\prime} \mid \alpha(p^{\flat\prime}) \preceq^\sharp p^\sharp\})$, which is equal to $\bigvee^\sharp\{\alpha(p^{\flat\prime}) \mid \alpha(p^{\flat\prime}) \preceq^\sharp p^\sharp\}$ since α preserves least upper bounds, proving that $\alpha(p^\flat) \preceq^\sharp p^\sharp$ by definition of least upper bounds and transitivity. A dual result holds for γ. □

By eliminating the "useless" abstract properties in the abstract domain $P^\sharp$ that are not the abstraction of some concrete property, we obtain an abstraction onto $P^\sharp$, a situation that can be characterized as follows:

Proposition 8. *If* $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$, *then* α *is onto if and only if* γ *is one-to-one if and only if* $\forall p^\sharp \in P^\sharp : \alpha \circ \gamma(p^\sharp) = p^\sharp$ *(in which case the Galois connection is said to be a* Galois

surjection*). α is one-to-one if and only if γ is onto if and only if* $\forall p^\flat \in P^\flat : \gamma \circ \alpha(p^\flat) = p^\flat$ *(in which case the Galois connection is said to be a* Galois injection*).*

PROOF. By (7) we have $\alpha \circ \gamma \circ \alpha(p^\flat) = \alpha(p^\flat)$ hence $\gamma \circ \alpha(p^\flat) = p^\flat$ for all $p^\flat \in P^\flat$ if α is one-to-one. In this case γ is onto since $p^\flat = \gamma(p^\sharp)$ by choosing $p^\sharp = \alpha(p^\flat)$. The same way, $\gamma \circ \alpha \circ \gamma(p^\sharp) = \gamma(p^\sharp)$ by (6), whence $p^\sharp = \alpha \circ \gamma(p^\sharp)$ if γ is one-to-one. In this case, it follows that α is onto since $p^\sharp = \alpha(p^\flat)$ by choosing $p^\flat = \gamma(p^\sharp)$. We conclude by application of the duality principle. □

This leads to the definition of *Galois surjections*:

$$P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp) \stackrel{\text{def}}{=} (P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)) \wedge (\forall p^\sharp \in P^\sharp : \alpha \circ \gamma(p^\sharp) = p^\sharp)) \tag{9}$$

with $\leftrightarrows$ denoting 'into' and $\rightleftarrows$ 'onto'. Galois surjections induce the order structure from concrete onto abstract properties:

Proposition 9. If $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$ *and* $P^\flat(\preceq^\flat, f^\flat, t^\flat, \wedge^\flat, \vee^\flat)$ *is a complete lattice, then so is* $P^\sharp(\preceq^\sharp)$.

PROOF. Given any subset X of $P^\sharp$, $p^\flat = \bigvee^\flat \{\gamma(p^\sharp) \mid p^\sharp \in X\}$ exists in the complete lattice $P^\flat$. Given $p^\sharp \in X$ we have $\gamma(p^\sharp) \preceq^\flat p^\flat$, whence by monotony and Galois surjection characteristic property $p^\sharp = \alpha \circ \gamma(p^\sharp) \preceq^\sharp \alpha(p^\flat)$ proving that $\alpha(p^\flat)$ is an upper bound of X.

Let ℓ be another upper bound of X. For all $p^\sharp \in X$, we have $p^\sharp \preceq^\sharp \ell$ and $\gamma(p^\sharp) \preceq^\flat \gamma(\ell)$ by monotony, whence $p^\flat \preceq^\flat \gamma(\ell)$ by definition of least upper bounds. By the Galois surjection characteristic property and monotony, $\alpha(p^\flat) \preceq^\sharp \alpha \circ \gamma(\ell) = \ell$ proving that $\alpha(p^\flat) = \vee^\sharp X$.

The proof that $\alpha(\bigwedge^\flat \{\gamma(p^\sharp) \mid p^\sharp \in X\})$ is the greatest lower bound of $X \subseteq P^\sharp$ is dual. □

As observed in theorem 10.1.0.2 of [34], each abstract property $p^\sharp$ can be improved by its lower closure $\alpha \circ \gamma(p^\sharp)$. This leads to a systematic way of obtaining Galois surjections from Galois connections by identification of the abstract properties $p^\sharp$, which meaning $\gamma(p^\sharp)$ cannot be distinguished at the concrete level, into an equivalence class:

Proposition 10 (Reduction). If $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$*, then* $p^\sharp{}_1 \equiv p^\sharp{}_2 \stackrel{def}{=} \gamma(p^\sharp{}_1) = \gamma(p^\sharp{}_2)$ *is an equivalence relation such that* $P^\flat(\preceq^\flat) \underset{\alpha_\equiv}{\overset{\gamma_\equiv}{\leftrightarrows}} P^\sharp/_\equiv(\preceq^\sharp_\equiv)$ *where* $\alpha_\equiv(p^\flat) \stackrel{def}{=} \{p^\sharp \mid p^\sharp \equiv \alpha(p^\flat)\}$, $\gamma_\equiv(X)$ *is* $\gamma(p^\sharp)$ *such that* $p^\sharp \in X$ *and* $X \preceq^\sharp_\equiv Y \stackrel{def}{=} \exists p^\sharp{}_1 \in X : \exists p^\sharp{}_2 \in Y : p^\sharp{}_1 \preceq^\sharp p^\sharp{}_2$.

PROOF. We have $[\alpha_\equiv(p^\flat) \preceq^\sharp_\equiv X] \Leftrightarrow [\exists p^\sharp{}_1 \in \alpha_\equiv(p^\flat) : \exists p^\sharp{}_2 \in X : p^\sharp{}_1 \preceq^\sharp p^\sharp{}_2] \Leftrightarrow [\exists p^\sharp{}_1 : \exists p^\sharp{}_2 \in X : p^\sharp{}_1 \equiv \alpha(p^\flat) \wedge p^\sharp{}_1 \preceq^\sharp p^\sharp{}_2] \Leftrightarrow [\exists p^\sharp{}_1 : \exists p^\sharp{}_2 \in X : \gamma(p^\sharp{}_1) = \gamma \circ \alpha(p^\flat) \wedge p^\sharp{}_1 \preceq^\sharp p^\sharp{}_2]$, which implies $[\exists p^\sharp{}_1 : \exists p^\sharp{}_2 \in X : \alpha \circ \gamma \circ \alpha(p^\flat) = \alpha \circ \gamma(p^\sharp{}_1) \wedge p^\sharp{}_1 \preceq^\sharp p^\sharp{}_2]$, and, therefore, by (7) and (3), we have $[\exists p^\sharp{}_1 : \exists p^\sharp{}_2 \in X : \alpha(p^\flat) \preceq^\sharp p^\sharp{}_1 \wedge p^\sharp{}_1 \preceq^\sharp p^\sharp{}_2]$, which implies $[\exists p^\sharp{}_2 \in X : \alpha(p^\flat) \preceq^\sharp p^\sharp{}_2] \Leftrightarrow [\exists p^\sharp{}_2 \in X : p^\flat \preceq^\flat \gamma(p^\sharp{}_2)] \Leftrightarrow [p^\flat \preceq^\flat \gamma_\equiv(X)]$. Reciprocally, $[\exists p^\sharp{}_2 \in X : \alpha(p^\flat) \preceq^\sharp p^\sharp{}_2]$ implies $[\exists p^\sharp{}_1 : \exists p^\sharp{}_2 \in X : p^\sharp{}_1 = \alpha(p^\flat) \wedge p^\sharp{}_1 \preceq^\sharp p^\sharp{}_2]$, whence $[\exists p^\sharp{}_1 : \exists p^\sharp{}_2 \in X : p^\sharp{}_1 \equiv \alpha(p^\flat) \wedge p^\sharp{}_1 \preceq^\sharp p^\sharp{}_2]$. □

From a practical point of view, this proposition corresponds to the use of a normal form for abstract properties with the same meaning. We use the following notation for the reduction:

$$P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows\!\!\!\rightrightarrows}} P^\sharp(\preceq^\sharp) \quad \stackrel{\text{def}}{=} \quad P^\flat(\preceq^\flat) \underset{\alpha_\equiv}{\overset{\gamma_\equiv}{\leftrightarrows}} P^\sharp/_\equiv(\preceq^\sharp_\equiv) \tag{10}$$

4.2.3. The Compositional Design of Galois Connections

We now study systematic ways of defining Galois connections so as to specify program analysers by successive refinements.

4.2.3.1. COMPOSITION OF GALOIS CONNECTIONS. The composition of Galois connections is a Galois connection. This fundamental property is the basis for designing program analysers by composition of successive approximations:

$$\left(P^\flat(\preceq^\flat) \underset{\alpha_1}{\overset{\gamma_1}{\leftrightarrows}} P^\natural(\preceq^\natural) \wedge P^\natural(\preceq^\natural) \underset{\alpha_2}{\overset{\gamma_2}{\leftrightarrows}} P^\sharp(\preceq^\sharp)\right) \Rightarrow P^\flat(\preceq^\flat) \underset{\alpha_2 \circ \alpha_1}{\overset{\gamma_1 \circ \gamma_2}{\leftrightarrows}} P^\sharp(\preceq^\sharp) \tag{11}$$

For example, in [29], $\langle \alpha_1, \gamma_1 \rangle$ decomposes global invariants on program counters and values of variables into local invariants upon the values of the variables attached to program points, then $\langle \alpha_2, \gamma_2 \rangle$ decomposes the relational local invariants into attribute independent ones, and then $\langle \alpha_3, \gamma_3 \rangle$ approximates the set of possible values of each variable by an abstract value such as its sign, parity, interval of values, etc.

4.2.3.2. PARTITIONING. One first standard way of obtaining Galois connections is illustrated by the decomposition of a global invariant into local invariants attached to program points [34], example 6.2.0.2.

Example 11 (Local invariants). More precisely, consider invariance properties represented as a set $p^\flat$ of states belonging to S so that $P^\flat = \wp(S)$. If states are pairs $\langle c, m \rangle$ where $c \in C$ is a control state (a control point for imperative sequential programs) and $m \in M$ is an environment delivering the values of variables then $p^\flat$ can be abstracted as a vector $p^\sharp = \alpha(p^\flat)$ such that $p^\sharp[c] = \{m \mid \langle c, m \rangle \in p^\flat\}$ for all $c \in C$. The meaning of such an abstract value $p^\sharp$ is $\gamma(p^\sharp) = \{\langle c, m \rangle \mid c \in C \wedge m \in p^\sharp[c]\}$. α is a bijection with inverse γ so that the concrete and abstract representations of an invariant are isomorphic: an invariant can be represented globally as a predicate on the control and memory states or locally as a set of invariants on the memory states attached to each program point. □

This can be easily generalized as follows:

Proposition 12 (Partitioning). Let $P^\flat(\preceq^\flat, f^\flat, t^\flat, \bigvee^\flat, \bigwedge^\flat)$ be a complete lattice that is (infinitely) distributive for intersection[1]*, i.e., the join operation is (completely) distributive on meets so that $x \wedge^\flat \bigvee^\flat X = \bigvee^\flat \{x \wedge^\flat y \mid y \in X\}$ for all $x \in P^\flat$ and any (infinite) set $X \subseteq P^\flat$. Let L be a non-empty finite (respectively infinite) set of so-called* labels *and $\delta \in L \mapsto P^\flat$ be a* partition *of $P^\flat$ (satisfying the* cover property *$t^\flat = \bigvee^\flat_{\ell \in L} \delta(\ell)$ and the* disjointness property *$\forall \ell, \ell' \in L : \ell \neq \ell' \Rightarrow \delta[\ell] \wedge^\flat \delta[\ell'] = f^\flat$). Define $P^\sharp = \prod_{\ell \in L} \{p^\flat \wedge^\flat \delta(\ell) \mid p^\flat \in P^\flat\}$ with the componentwise ordering $p^\sharp{}_1 \preceq^\sharp p^\sharp{}_2$ if and only if $\forall \ell \in L : p^\sharp{}_1[\ell] \preceq^\flat p^\sharp{}_2[\ell]$. Let $\alpha(p^\flat)[\ell] = p^\flat \wedge^\flat \delta(\ell)$ and $\gamma(p^\sharp) = \bigvee^\flat_{\ell' \in L} p^\sharp[\ell']$ for all $\ell \in L$, $p^\flat \in P^\flat$ and $p^\sharp \in P^\sharp$. Then the* partitioning *is such that $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\rightleftharpoons}} P^\sharp(\preceq^\sharp)$ whereas the* reduced partitioning *satisfies $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\rightleftharpoons}} P^\sharp(\preceq^\sharp)$.*

PROOF. For all $p^\flat \in P^\flat$ and $p^\sharp \in P^\sharp$, if $\alpha(p^\flat) \preceq^\sharp p^\sharp$, then for all $\ell \in L$ we have $p^\flat \wedge^\flat \delta(\ell) = \alpha(p^\flat)[\ell] \preceq^\flat p^\sharp[\ell] \preceq^\flat \bigvee^\flat_{\ell' \in L} p^\sharp[\ell'] = \gamma(p^\sharp)$ by definition of α, of the componentwise ordering, of least upper bounds $\bigvee^\flat$ and of γ. So $p^\flat$ is equal to $p^\flat \wedge^\flat t^\flat$ by definition of the supremum $t^\flat$, hence to $p^\flat \wedge^\flat \bigvee^\flat_{\ell \in L} \delta(\ell)$ by the cover property, so to $\bigvee^\flat_{\ell \in L} p^\flat \wedge^\flat \delta(\ell)$ by $\wedge^\flat$–distributivity, which is upper $\preceq^\flat$–bounded by $\gamma(p^\sharp)$ by definition of least upper bounds.

Reciprocally, if $p^\flat \preceq^\flat \gamma(p^\sharp)$, then $p^\flat \preceq^\flat \bigvee^\flat_{\ell' \in L} p^\sharp[\ell']$ by definition of the concretization γ, whence for all $\ell \in L$, $\alpha(p^\flat)[\ell] = p^\flat \wedge^\flat \delta[\ell] \preceq^\flat \left(\bigvee^\flat_{\ell' \in L} p^\sharp[\ell']\right) \wedge^\flat \delta[\ell]$ by definition of the abstraction α and of greatest lower bounds. But $\left(\bigvee^\flat_{\ell' \in L} p^\sharp[\ell']\right) \wedge^\flat \delta[\ell]$ is equal to $\bigvee^\flat_{\ell' \in L} \left(p^\sharp[\ell'] \wedge^\flat \delta[\ell]\right)$ by distributivity. Moreover, $p^\sharp[\ell'] \preceq^\flat \delta[\ell']$ and $\delta[\ell] \wedge^\flat \delta[\ell'] = f^\flat$ so that $p^\sharp[\ell'] \wedge^\flat \delta[\ell'] = f^\flat$ by definition of greatest lower bounds and of the infimum when $\ell \neq \ell'$. It follows that $\bigvee^\flat_{\ell' \in L} \left(p^\sharp[\ell'] \wedge^\flat \delta[\ell]\right)$ $= p^\sharp[\ell] \wedge^\flat \delta[\ell] = p^\sharp[\ell]$ since $p^\sharp[\ell] \preceq^\flat \delta[\ell]$ by definition of $P^\sharp$. By transitivity and definition of the pointwise ordering $\preceq^\sharp$, we conclude that $\alpha(p^\flat) \preceq^\sharp p^\sharp$. The reduction follows from proposition 10. □

This Galois connection enables us to decompose an equation into a system of equations, one for each label. For logical programs, the choice of labels can vary considerably. For example, one can choose a single one for the whole program, one for each predicate, one for each clause (after head unification), two for each clause (after call and before exit), one before and after each atom of a clause [140], [131] or one before and/or after a call [11] in an AND/OR tree, bi-labels

[1] *Such lattices are called* Brouwerian.

corresponding to pairs of the previous choices or even paths to the calls in the computations within AND/OR trees [160], [157]. The choice of the best decomposition obviously depends upon the kind and quality of the information that is to be gathered about programs and of the acceptable memory and computation costs.

4.2.3.3. Reduced Product. If several independent abstract interpretations $P^{\sharp\,i}(\preceq^{\sharp\,i})$, $i \in \Delta$ have been designed with respect to a concrete domain $P^\flat(\preceq^\flat)$ of program properties using Galois connections $P^\flat(\preceq^\flat) \underset{\alpha^i}{\overset{\gamma^i}{\leftrightarrows}} P^{\sharp\,i}(\preceq^{\sharp\,i}), i \in \Delta$, then there are many ways to combine them to perform all abstract interpretations simultaneously. Several such combinations of abstract interpretations have been suggested in sections 9 and 10 of [34]. We will use the following ones:

Proposition 13 (Reduced product). Let $P^\flat(\preceq^\flat)$ and $P^{\sharp\,i}(\preceq^{\sharp\,i})$ be posets for all i in the index set Δ such that for all i in Δ, $P^\flat(\preceq^\flat) \underset{\alpha^i}{\overset{\gamma^i}{\leftrightarrows}} P^{\sharp\,i}(\preceq^{\sharp\,i})$. Define $P^\sharp = \prod_{i\in\Delta} P^{\sharp\,i}$, $p^\sharp{}_1 \preceq^\sharp p^\sharp{}_2$ if and only if $\forall i \in \Delta : p^\sharp{}_1[i] \preceq^{\sharp\,i} p^\sharp{}_2[i]$, $\alpha \in P^\flat \mapsto P^\sharp$ such that $\alpha(p^\flat) = \prod_{i\in\Delta} \alpha^i(p^\flat)$ and $\gamma \in P^\sharp \rightarrowtail P^\flat$ such that $\gamma(p^\sharp) = \bigwedge^\flat_{i\in\Delta} \gamma^i(p^\sharp[i])$.

If Δ is finite and $P^\flat(\preceq^\flat, \wedge^\flat)$ is a meet-semi-lattice or Δ is infinite and $P^\flat(\preceq^\flat, \wedge^\flat)$ is a complete meet-semi-lattice (hence a complete lattice), then the product *is such that $P^\flat(\preceq^\flat) \underset{\alpha^\tau}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$, whereas the* reduced product *satisfies $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\rightleftharpoons}} P^\sharp(\preceq^\sharp)$.*

proof. By definition of α and $\preceq^\sharp$, $\alpha(p^\flat) \preceq^\sharp p^\sharp$ is equivalent to $\forall i \in \Delta : \alpha^i(p^\flat) \preceq^{\sharp\,i} p^\sharp[i]$ or, by definition (1) of Galois connections, to $\forall i \in \Delta : p^\flat \preceq^\flat \gamma^i(p^\sharp[i])$. By definition of greatest lower bounds, which exist by the lattice hypothesis, this is equivalent to $p^\flat \preceq^\flat \bigwedge^\flat_{i\in\Delta} \gamma^i(p^\sharp[i])$, i.e., to $p^\flat \preceq^\flat \gamma(p^\sharp)$ by definition of γ. The reduction follows from proposition 10. □

This combination of abstract interpretations can be qualified of attribute independent. A classical example consists in analysing the possible values of the variables of a program by analysing independently the possible values of each variable in the program, as, for example, in [28]. The information obtained by the combination of the analyses is essentially the same as the one obtained by performing the analyses separately. However, the separate analyses can be mutually improved using proposition 10. For example, the reduced product of sign and parity analysis would exclude the case when a variable is both zero and odd, a situation that may not be recognizable by separate analyses (for example the conjunction of {0} `x := 1` {+} and {odd} `x := 1` {even} would be $\{\langle 0, \text{odd}\rangle\}$ `x := 1` $\{\langle +, \text{even}\rangle\}$ which reduces to $\{\langle \bot, \bot\rangle\}$ `x := 1` $\{\langle +, \text{even}\rangle\}$ whereas for the reduced product we would have $\{\langle \bot, \bot\rangle\}$ `x := 1` $\{\langle \bot, \bot\rangle\}$).

Example 14 (Attribute independent groundness analysis). In groundness analysis, the lattice $P^{\sharp\,i}, i = 1, 2$ represents the set of terms to which some logical variable $X^i, i = 1, 2$ can be bounded during execution of a logic program, $\bot$ corresponding to the empty set, G corresponding to the set of ground terms, NG corresponding to the set of terms containing at least one free variable, and $\top$ corresponding to all possible terms. Their reduced product $P^\sharp = \prod_{i\in\{1,2\}} P^{\sharp\,i}$ can be used to represent the possible values of the pair of variables $\langle X^1, X^2\rangle$ (which implies that all abstract pairs of values containing $\bot$ are semantically equivalent hence reduced to $\langle \bot, \bot\rangle$, as shown in Figure 4). The analysis is attribute independent in that no relationship can be expressed between the groundness of X^1 and that of X^2 (such as X^1 is ground if and only if X^2 is not ground). □

4.2.3.4. Down-set Completion. A method was given in paragraph 9.2 of [34] to provide a disjunctive concrete interpretation of sets of abstract properties. It was used to show that merge over all paths data flow analyses can always be expressed in fixpoint form. This construction is of general use to enrich an abstract interpretation. The intuitive idea is that the abstrac-

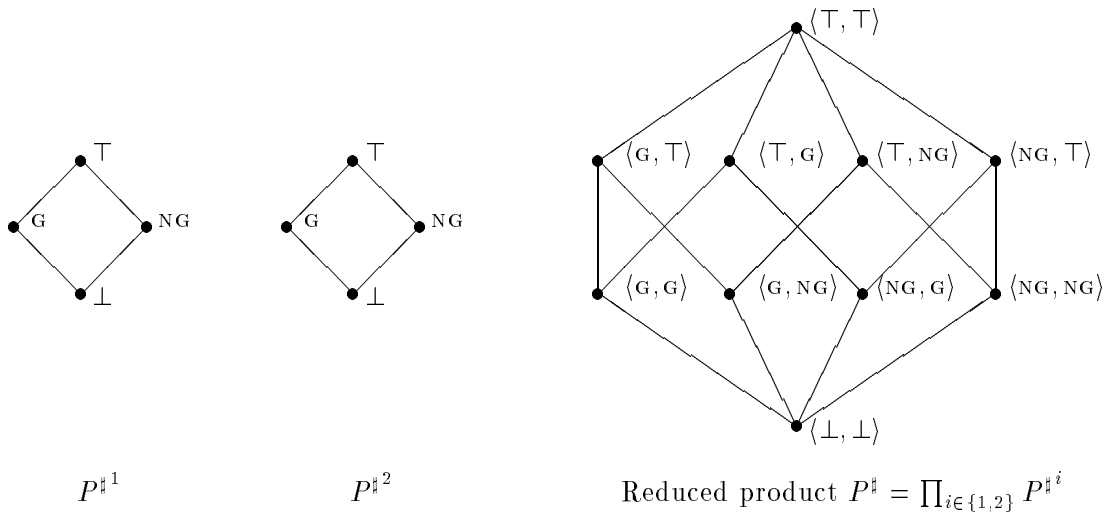


FIGURE 4. Lattice of attribute independent groundness analysis.

tion α loses no information about meets (proposition 3), whereas joins are preserved by losing information (proposition 6). For example, in the rule of signs, $\alpha(\{n \in \mathbb{N} \mid n > 0\} \cup \{n \in \mathbb{N} \mid n < 0\}) = \alpha(\{n \in \mathbb{N} \mid n > 0\}) \sqcup \alpha(\{n \mid n < 0\}) = + \sqcup - = \top$, thus losing the information that 0 is impossible. This situation can be improved by moving to the more expressive abstract domain $\wp(P^\sharp)$ and considering sets of abstract values in $P^\sharp$ the meaning of which is the disjunction of the meaning of the individual abstract values in the set. This corresponds to a case analysis. For example, $\{-,+\}$ expresses a non-zero value since $\gamma(\{-,+\}) = \gamma(-) \cup \gamma(+) = \{n \in \mathbb{N} \mid n \neq 0\}$. Now, several sets of abstract values can have the same concrete meaning such as, for example, $\{\top\}$, $\{\top,-\}$, and $\{\top,-,0,+,\bot\}$. Therefore, a reduction is necessary to reduce the size of the abstract lattice, hence that of its computer representation. Proposition 10 can be used for that purpose, but in this case this can be done, at least partially, in a syntactic way, by considering down closed sets only, which contain all abstract values which can be approximated by an element of the set. Following theorems 9.2.0.2 to 9.2.0.4 of [34], this intuitive idea can be formalized as follows:

Proposition 15 (Down-set completion). Let $P^\flat(\preceq^\flat, f^\flat, t^\flat, \wedge^\flat, \vee^\flat)$ *be a complete lattice that is* completely distributive *(i.e.* $\bigwedge^\flat\{\bigvee^\flat\{x_{ij} \mid j \in J_i\} \mid i \in I\} = \bigvee^\flat\{\bigwedge^\flat\{x_{i\varphi(i)} \mid i \in I\} \mid \varphi \in \prod_{k\in I} J_k\}$ *for all* $J_i, i \in I$*) and assume* $P^\flat(\preceq^\flat) \underset{\alpha^\flat}{\overset{\gamma^\flat}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$. *Let* $\downarrow^\preceq X = \{y \mid \exists x \in X : y \preceq x\}$ *be the* down closure *of* X *for* $\preceq$. *Define:*

$$\mathfrak{D}^{\preceq^\sharp}(P^\sharp) = \downarrow^{\preceq^{\sharp *}}(\wp(P^\sharp))$$

$$\gamma^\flat \in \mathfrak{D}^{\preceq^\sharp}(P^\sharp) \mapsto P^\flat \qquad \alpha^\flat \in P^\flat \mapsto \mathfrak{D}^{\preceq^\sharp}(P^\sharp)$$

$$\gamma^\flat(X) \stackrel{def}{=} \bigvee^\flat \gamma^*(X) \qquad \alpha^\flat(p^\flat) \stackrel{def}{=} \cap\{X \mid p^\flat \preceq^\flat \gamma^\flat(X)\}$$

then $P^\flat(\preceq^\flat) \underset{\alpha^\flat}{\overset{\gamma^\flat}{\leftrightarrows}} \mathfrak{D}^{\preceq^\sharp}(P^\sharp)(\subseteq)$ *and* $P^\flat(\preceq^\flat) \underset{\alpha^\flat}{\overset{\gamma^\flat}{\rightleftharpoons}} \mathfrak{D}^{\preceq^\sharp}(P^\sharp)(\subseteq)$.

PROOF. We show that $\gamma^\flat$ is a complete meet morphism so that the conclusion follows from proposition 7.

We prove the preliminary lemma stating that $\{\bigwedge^\flat_{i\in I} \varphi[i] \mid \varphi \in \prod_{k\in I}\{p^\flat \mid \exists p^\sharp \in X_k : p^\flat \preceq^\flat \gamma(p^\sharp)\}\} = \{p^\flat \mid \exists p^\sharp \in \bigcap_{i\in I} X_i : p^\flat \preceq^\flat \gamma(p^\sharp)\}$ when $X_k \in \mathfrak{D}^{\preceq^\sharp}(P^\sharp))$ for all $k \in I$. So let φ be any element of $\prod_{k\in I}\{p^\flat \mid \exists p^\sharp \in X_k : p^\flat \preceq^\flat \gamma(p^\sharp)\}$ and $k \in I$. Then $\bigwedge^\flat_{i\in I} \varphi[i] \preceq^\flat \varphi[k] \in \{p^\flat \mid \exists p^\sharp \in X_k : p^\flat \preceq^\flat \gamma(p^\sharp)\}$, proving by transitivity that $\exists p^\sharp{}_k \in X_k : \bigwedge^\flat_{i\in I} \varphi[i] \preceq^\flat \gamma(p^\sharp{}_k)$. Hence $\bigwedge^\flat_{i\in I} \varphi[i] \preceq^\flat \bigwedge^\flat_{k\in I} \gamma(p^\sharp{}_k)$. By proposition 3, $\gamma^*(P^\sharp)$ is a Moore family so there exists some $p^\sharp \in P^\sharp$ such that $\bigwedge^\flat_{k\in I} \gamma(p^\sharp{}_k) = \gamma(p^\sharp)$, whence by (6) $\bigwedge^\flat_{i\in I} \varphi[i] \preceq^\flat \gamma(p^\sharp) = \gamma \circ \alpha \circ \gamma(p^\sharp)$. But for all $k \in I$, we have $\gamma(p^\sharp) = \bigwedge^\flat_{k\in I} \gamma(p^\sharp{}_k) \preceq^\flat \gamma(p^\sharp{}_k)$, whence by monotony and (3), $\alpha \circ \gamma(p^\sharp) \preceq^\sharp$

$\alpha \circ \gamma({p^\sharp}_k) \preceq^\sharp {p^\sharp}_k \in X_k$. But X_k is down closed for $\preceq^\sharp$, whence $\alpha \circ \gamma(p^\sharp) \in X_k$. We conclude that $\alpha \circ \gamma(p^\sharp) \in \bigcap_{k \in I} X_k$ so that $\bigwedge^\flat_{i \in I} \varphi[i] \in \{p^\flat \mid \exists p^\sharp \in \bigcap_{i \in I} X_i : p^\flat \preceq^\flat \gamma(p^\sharp)\}$ proving inclusion in one direction. Reciprocally, assume that $\exists p^\sharp \in \bigcap_{i \in I} X_i : p^\flat \preceq^\flat \gamma(p^\sharp)$. Define $\varphi[i] = p^\flat$ for all $i \in I$. Then $\varphi \in \prod_{k \in I} \{p^\flat \mid \exists p^\sharp \in X_k : p^\flat \preceq^\flat \gamma(p^\sharp)\}$ and $p^\flat = \bigwedge^\flat_{i \in I} \varphi[i]$ proving the inverse inclusion.

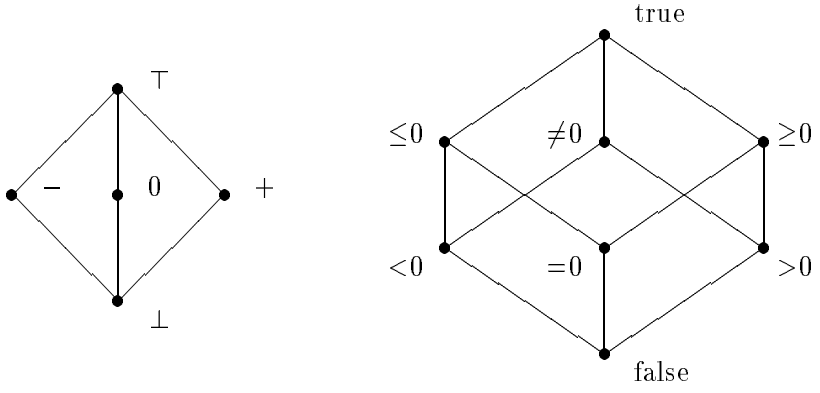
To prove that γ^ϑ is a complete meet morphism, we observe that by definition $\gamma^\vartheta(\bigcap_{i \in I} X_i)$ is equal to $\bigvee^\flat \gamma^*(\bigcap_{i \in I} X_i) = \bigvee^\flat \downarrow^{\preceq^\flat}(\{\gamma(p^\sharp) \mid p^\sharp \in \bigcap_{i \in I} X_i\}) = \bigvee^\flat \{p^\flat \mid \exists p^\sharp \in \bigcap_{i \in I} X_i : p^\flat \preceq^\flat \gamma(p^\sharp)\}$, i.e., by the previous lemma, to $\bigvee^\flat \{\bigwedge^\flat_{i \in I} \varphi[i] \mid \varphi \in \prod_{k \in I} \{p^\flat \mid \exists p^\sharp \in X_k : p^\flat \preceq^\flat \gamma(p^\sharp)\}\}$, which by complete distributivity is $\bigwedge^\flat \{\bigvee^\flat \{p^\flat \mid \exists p^\sharp \in X_i : p^\flat \preceq^\flat \gamma(p^\sharp)\} \mid i \in I\}$, which by definition of γ^ϑ is equal to $\bigwedge^\flat_{i \in I} \bigvee^\flat \downarrow^{\preceq^\flat}(\{\gamma(p^\sharp) \mid p^\sharp \in X_i\}) = \bigwedge^\flat_{i \in I} \bigvee^\flat \downarrow^{\preceq^\flat}(\gamma^*(X_i)). = \bigwedge^\flat_{i \in I} \bigvee^\flat \gamma^*(X_i). = \bigwedge^\flat_{i \in I} \gamma^\vartheta(X_i)$. The reduction follows from proposition 10. □

Example 16 (Rule of signs, continued). Assume that $P^\flat = \wp(\mathbb{Z})$ and $P^\sharp$ is $\{\bot, -, 0, +, \top\}$ with the obvious meaning $\gamma(\bot) = \emptyset$, $\gamma(-) = \{x \in \mathbb{Z} \mid x < 0\}$, $\gamma(0) = \{0\}$, $\gamma(+) = \{x \in \mathbb{Z} \mid x > 0\}$ and $\gamma(\top) = \mathbb{Z}$. Using proposition 15, define $\alpha(X)$ as the least $s \in P^\sharp$ such that $X \subseteq \gamma(s)$. The down-set completion of $P^\sharp$ contains the elements: false $\stackrel{\text{def}}{=} \emptyset \equiv \{\bot\}$; $<0 \stackrel{\text{def}}{=} \{-, \bot\}$; $=0 \stackrel{\text{def}}{=} \{0, \bot\}$; $>0 \stackrel{\text{def}}{=} \{+, \bot\}$; $\leq 0 \stackrel{\text{def}}{=} \{-, 0, \bot\}$; $\neq 0 \stackrel{\text{def}}{=} \{-, +, \bot\}$; $\geq 0 \stackrel{\text{def}}{=} \{+, 0, \bot\}$ and true $\stackrel{\text{def}}{=} \{\top, +, -, 0, \bot\}$ ordered by subset inclusion so that we obtain the lattice that is shown in Figure 5. □

Another equivalent way to define the down-set completion consists in considering Hoare's lower powerdomain that is subsets of $P^\sharp$ pre-ordered by $X \precsim X'$ if and only if $\forall p^\sharp \in X : \exists {p^\sharp}' \in X' : p^\sharp \preceq^\sharp {p^\sharp}'$. Let $\approx$ be the corresponding equivalence relation defined by $X \approx X' \stackrel{\text{def}}{=} (X \precsim X') \wedge (X' \precsim X)$. The equivalence class of $X \subseteq P^\sharp$ is $[X]_\approx \stackrel{\text{def}}{=} \{X' \subseteq P^\sharp \mid X' \approx X\}$. $\wp(P^\sharp)/_\approx$ is the set of all equivalence classes $[X]_\approx$ for all $X \subseteq P^\sharp$. It is partially ordered by $[X]_\approx \precsim [X']_\approx$ if and only if there exist Y, $Y' \subseteq P^\sharp$ such that $(Y \approx X) \wedge (Y' \approx X') \wedge (Y \precsim Y')$. The fact that $\wp(P^\sharp)/_\approx (\precsim)$ is the down-set completion of $P^\sharp$ follows from the following:

Proposition 17. $\wp(P^\sharp)/_\approx (\precsim)$ is order-isomorphic with $\mathfrak{D}^{\preceq^\sharp}(P^\sharp)(\subseteq)$.

PROOF. Define $\alpha \in \mathfrak{D}^{\preceq^\sharp}(P^\sharp) \mapsto \wp(P^\sharp)/_\approx$ by $\alpha(X) \stackrel{\text{def}}{=} [X]_\approx$ and $\gamma \in \wp(P^\sharp)/_\approx \mapsto \mathfrak{D}^{\preceq^\sharp}(P^\sharp)$ by $\gamma([X]_\approx) \stackrel{\text{def}}{=} \downarrow^{\preceq^\sharp} X$. For all $X \in \mathfrak{D}^{\preceq^\sharp}(P^\sharp)$, we have $\gamma \circ \alpha(X) = \downarrow^{\preceq^\sharp} X = X$ since X is down-closed. Moreover, $\alpha \circ \gamma([X]_\approx) = [\downarrow^{\preceq^\sharp} X]_\approx = [X]_\approx$ since for all $p^\sharp \in X$, we have $p^\sharp \in \downarrow^{\preceq^\sharp} X$, whence $X \precsim \downarrow^{\preceq^\sharp} X$ since $\preceq^\sharp$ is reflexive and by definition of the down closure, for all $p^\sharp \in \downarrow^{\preceq^\sharp} X$ there exists ${p^\sharp}' \in X$ such that $p^\sharp \preceq^\sharp {p^\sharp}'$, whence $\downarrow^{\preceq^\sharp} X \precsim X$. It follows that α is an isomorphism with inverse γ.



$P^\sharp$ Down-set completion of $P^\sharp$

FIGURE 5. Lattices of signs.

If X, $X' \subseteq P^\sharp$, and $X \subseteq X'$, then for all $p^\flat \in X$, $p^{\flat\prime} \in X'$ and $p^\flat \preceq^\sharp p^{\flat\prime}$ so that $X \precsim X'$ and therefore $[X]_\approx \precsim [X']_\approx$. Reciprocally, if X, $X' \subseteq P^\sharp$ and $[X]_\approx \precsim [X']_\approx$, then there exist $\bar{X}$, $\bar{X}' \subseteq P^\sharp$ such that $\bar{X} \approx X$, $\bar{X}' \approx X'$ and $\bar{X} \precsim \bar{X}'$ so that by definition of $\approx$ and transitivity, $X \precsim X'$ so that $\forall p^\flat \in X : \exists p^{\flat\prime} \in X : p^\flat \preceq^\sharp p^{\flat\prime}$ whence $\downarrow^{\preceq^\sharp} X \subseteq \downarrow^{\preceq^\sharp} X'$ proving that $\alpha(X) \precsim \alpha(X')$ which implies $\gamma \circ \alpha(X) \subseteq \gamma \circ \alpha(X')$ that is $X \subseteq X'$. We conclude that α is an order-isomorphism, that is $X \subseteq X'$ if and only if $\alpha(X) \precsim \alpha(X')$. □

The situation observed in example 16 where the down-set completion of $P^\sharp$ is the set of subsets of the atoms $\{-, 0, +\}$ of $P^\sharp$ is in fact more general. An element a of a lattice $L(\leq)$ with infimum $\bot$ is an *atom* if it covers $\bot$, that is $\bot < x \leq a \Rightarrow x = a$. L is *atomistic* if and only if every element of L is a join of atoms, and hence of the atoms which it contains. We write $\mathfrak{A}(L)$ for the set of atoms of L. Two abstract interpretations are *equivalent* if and only if any concrete property is approximated in the same way in both interpretations. More formally, if $P^\flat(\preceq^\flat) \underset{\alpha_1}{\overset{\gamma_1}{\leftrightarrows}} P^\sharp{}_1(\preceq^\sharp{}_1)$ and $P^\flat(\preceq^\flat) \underset{\alpha_2}{\overset{\gamma_2}{\leftrightarrows}} P^\sharp{}_2(\preceq^\sharp{}_2)$ then $\forall p^\flat \in P^\flat : \gamma_1 \circ \alpha_1(p^\flat) = \gamma_2 \circ \alpha_2(p^\flat)$.

Proposition 18 (Representation of the down-set completion using atoms). Let $P^\flat(\preceq^\flat, f^\flat, t^\flat, \wedge^\flat, \vee^\flat)$ be a completely distributive complete lattice and $P^\sharp(\preceq^\sharp, f^\sharp, t^\sharp, \wedge^\sharp, \vee^\sharp)$ be an atomistic complete lattice such that $P^\flat(\preceq^\flat) \underset{\alpha^\mathfrak{a}}{\overset{\gamma^\mathfrak{a}}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$. Define:

$$\gamma^\mathfrak{a} \in \wp(\mathfrak{A}(P^\sharp)) \mapsto \mathfrak{D}^{\preceq^\sharp}(P^\sharp) \qquad \alpha^\mathfrak{a} \in \mathfrak{D}^{\preceq^\sharp}(P^\sharp) \mapsto \wp(\mathfrak{A}(P^\sharp))$$
$$\gamma^\mathfrak{a}(X) \overset{def}{=} \{\bigvee^\sharp S \mid S \subseteq X\} \qquad \alpha^\mathfrak{a}(X) \overset{def}{=} X \cap \mathfrak{A}(P^\sharp)$$

Then $\mathfrak{D}^{\preceq^\sharp}(P^\sharp)(\subseteq) \underset{\alpha^\mathfrak{a}}{\overset{\gamma^\mathfrak{a}}{\leftrightarrows}} \wp(\mathfrak{A}(P^\sharp))(\subseteq)$. If, moreover, γ is join atomistic, *that is to say:*

$$\forall X \subseteq P^\sharp : \bigvee^\flat \gamma^*(X) = \bigvee^\flat \gamma^*\left((\downarrow^{\preceq^\sharp} X) \cap \mathfrak{A}(P^\sharp)\right)$$

then the two abstract interpretations are equivalent in that $\gamma^\mathfrak{d} \circ \alpha^\mathfrak{d} = \gamma^\mathfrak{d} \circ \gamma^\mathfrak{a} \circ \alpha^\mathfrak{a} \circ \alpha^\mathfrak{d}$.

PROOF. If $X \subseteq \mathfrak{A}(P^\sharp)$, then for all $x \in X$ we have $\{x\} \subseteq X$ and $\vee^\sharp\{x\} = x$ proving that $X \subseteq \{\bigvee^\sharp S \mid S \subseteq X\} \cap \mathfrak{A}(P^\sharp) = \alpha^\mathfrak{a} \circ \gamma^\mathfrak{a}(X)$. Moreover, if $S \subseteq X$ and $\bigvee^\sharp S \in \mathfrak{A}(P^\sharp)$ then S cannot be empty since the infimum $\vee^\sharp\emptyset = f^\sharp$ does not belong to $\mathfrak{A}(P^\sharp)$. Moreover, S cannot contain two distinct atoms x_1 and x_2 since we would have $f^\sharp \prec^\sharp x_1 \preceq^\sharp (x_1 \vee^\sharp x_2) \preceq^\sharp \bigvee^\sharp S$ hence $x_1 = (x_1 \vee^\sharp x_2) = \bigvee^\sharp S$ since x_1 and $\bigvee^\sharp S$ are atoms and therefore the contradiction $f^\sharp \prec^\sharp x_1 \prec^\sharp x_2$ since x_1 and x_2 are distinct atoms. It follows that $\bigvee^\sharp S = \vee^\sharp\{x\} = x$ where $x \in X$ proving that $\{\bigvee^\sharp S \mid S \subseteq X\} \cap \mathfrak{A}(P^\sharp) \subseteq X$ hence by antisymmetry that $\alpha^\mathfrak{a} \circ \gamma^\mathfrak{a}$ is the identity.

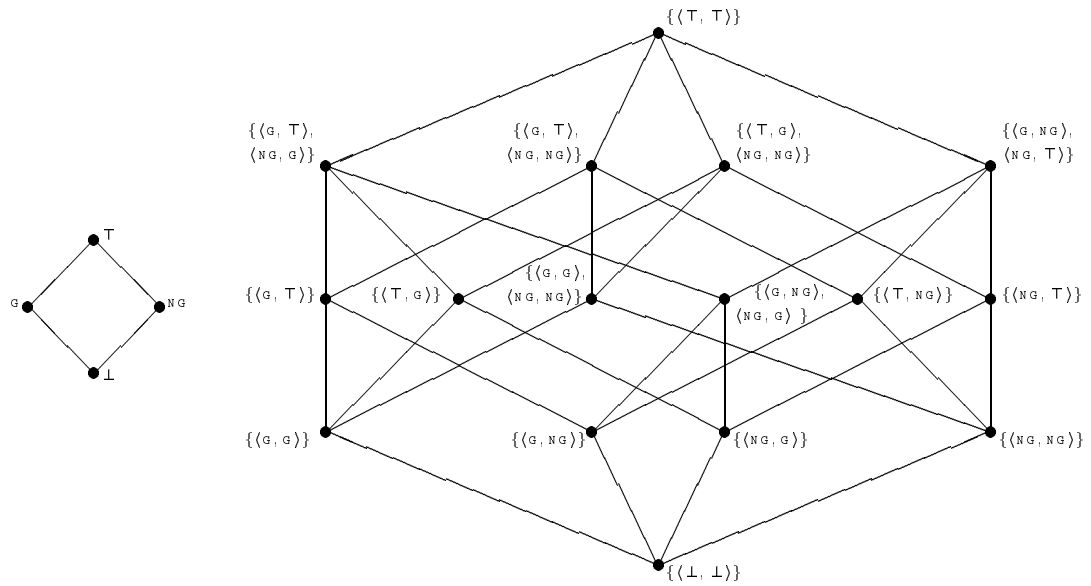
Assume now that $X \in \mathfrak{D}^{\preceq^\sharp}(P^\sharp)$ and $x \in X$. Let S be $\{a \in \mathfrak{A}(P^\sharp) \mid a \preceq^\sharp x\}$. We have $S \subseteq X$ since X is down closed and $x = \bigvee^\sharp S$ since $P^\sharp(\preceq^\sharp, \vee^\sharp)$ is an atomistic complete lattice proving that $X \subseteq \{\bigvee^\sharp S \mid S \subseteq X \cap \mathfrak{A}(P^\sharp)\} = \gamma^\mathfrak{a} \circ \alpha^\mathfrak{a}(X)$.

We conclude that $\mathfrak{D}^{\preceq^\sharp}(P^\sharp)(\subseteq) \underset{\alpha^\mathfrak{a}}{\overset{\gamma^\mathfrak{a}}{\leftrightarrows}} \wp(\mathfrak{A}(P^\sharp))(\subseteq)$.

Finally, if $X \in \mathfrak{D}^{\preceq^\sharp}(P^\sharp)$ then $\gamma^\mathfrak{d} \circ \gamma^\mathfrak{a} \circ \alpha^\mathfrak{a}(X) = \bigvee^\flat \gamma^*(\{\bigvee^\sharp S \mid S \subseteq X \cap \mathfrak{A}(P^\sharp)\}) = \bigvee^\flat \gamma^*(\{a \in \mathfrak{A}(P^\sharp) \mid \exists S \subseteq X \cap \mathfrak{A}(P^\sharp) : a \preceq^\sharp \bigvee^\sharp S\})$ since γ is join-atomistic. Since $P^\sharp$ is atomistic, this is equal to $\bigvee^\flat \gamma^*(\{S \mid S \subseteq X \cap \mathfrak{A}(P^\sharp)\}) = \bigvee^\flat \gamma^*(X \cap \mathfrak{A}(P^\sharp)) = \bigvee^\flat \gamma^*\left((\downarrow^{\preceq^\sharp} X) \cap \mathfrak{A}(P^\sharp)\right)$ since X is down closed, which is equal to $\bigvee^\flat \gamma^*(X)$ that is to $\gamma^\mathfrak{d}(X)$. □

4.2.3.5. TRANSFORMING AN ATTRIBUTE INDEPENDENT ANALYSIS INTO A RELATIONAL ANALYSIS. If we have obtained independent analyses $P^{\sharp\,i}(\preceq^{\sharp\,i}), i \in \Delta$, then the down-set completion of their reduced product provides a relational analysis.

Example 19 (Relational groundness analysis). By considering the down-set completion of the reduced product for groundness given in example 14, one can express that X^1 is ground if and only if X^2 is not ground by the element $\{\langle \text{G}, \text{NG}\rangle, \langle \text{NG}, \text{G}\rangle\}$, as shown in Figure 6. □



$P^{\sharp\,i},\ i = 1, 2$ Down-set completion of the reduced product $P^\sharp = \prod_{i\in\{1,2\}} P^{\sharp\,i}$

FIGURE 6. Lattice of relational groundness analysis.

However the lattice which is obtained can be very large. If we consider the down-set completion of the reduced product of n rules of signs lattices shown in example 16 then the longest strictly increasing chain in the down-set completion has length $3^n + 1$ hence this lattice is very large, so the corresponding program analyses might be very expensive.

Various other forms of relational combinations can be considered. For example, the set of monotone maps in $P^\sharp{}_1 \mapsto P^\sharp{}_2$ is considered in section 10.2 of [34], so as to obtain relational properties the complexity of which is included between those of the reduced product and down-set completion of the reduced product. By restricting to complete join morphisms, that is equivalently to Galois connections between $P^\sharp{}_1$ and $P^\sharp{}_2$, one obtains, up to an isomorphism, the tensor product considered in [129]. However tensor products cannot represent all relations that can be specified by elements of the down-set completion of the reduced product.

4.2.3.6. Transforming a Relational Analysis into an Attribute Independent Analysis. As shown by [86], relational analyses can be very expensive. A radical method to reduce the analysis cost is to transform the relational analysis into an attribute independent analysis. We now explain a systematic way to do so. In order to formalize the notion of relational analysis, let us consider a set Δ of program attributes, the properties of each attribute $i \in \Delta$ being described by elements of a given set $P^{\sharp\,i}$ of properties. A relational property $X = \{\vec{p^\sharp}_j \mid j \in J\} \in \wp(\prod_{i\in\Delta} P^{\sharp\,i})$ represents the disjunction for $j \in J$ of the conjunction for $i \in \Delta$ of the meanings of $\vec{p^\sharp}_j[i]$: $\gamma(X) = \bigvee_{j\in J} \bigwedge_{i\in\Delta} \gamma^i_j(\vec{p^\sharp}_j[i])$. Such a relational property can be approximated by a vector of attribute independent properties, as follows:

Proposition 20. Let $P^{\sharp\,i}(\preceq^{\sharp\,i}, f^{\sharp\,i}, t^{\sharp\,i}, \wedge^{\sharp\,i}, \vee^{\sharp\,i})$ be complete lattices for $i \in \Delta$. Define:

$$\alpha^{\mathrm{i}} \in \wp(\prod_{i\in\Delta} P^{\sharp\,i}) \mapsto \prod_{i\in\Delta} P^{\sharp\,i} \qquad \gamma^{\mathrm{i}} \in \prod_{i\in\Delta} P^{\sharp\,i} \mapsto \wp(\prod_{i\in\Delta} P^{\sharp\,i})$$

$$\alpha^{\mathrm{i}}(X) = \prod_{i\in\Delta} \vee^{\sharp\,i}\{\vec{p^\sharp}[i] \mid \vec{p^\sharp} \in X\} \qquad \gamma^{\mathrm{i}}(\vec{p^\sharp}) = \{\vec{p^\sharp}\}$$

Then $\wp(\prod_{i\in\Delta} P^{\sharp\,i})(\vec{\lesssim}) \underset{\alpha^{\mathrm{i}}}{\overset{\gamma^{\mathrm{i}}}{\rightleftarrows}} \prod_{i\in\Delta} P^{\sharp\,i}(\vec{\preceq^\sharp})$, where $X \vec{\lesssim} X' \overset{def}{=} \forall \vec{p^\sharp} \in X : \exists \vec{p^\sharp}' \in X' : \vec{p^\sharp} \vec{\preceq^\sharp} \vec{p^\sharp}'$ and $\vec{p^\sharp} \vec{\preceq^\sharp} \vec{p^\sharp}' \overset{def}{=} \forall i \in \Delta : \vec{p^\sharp}[i] \preceq^{\sharp\,i} \vec{p^\sharp}'[i]$.

PROOF. $\alpha^{\mathfrak{i}}(X) \mathrel{\vec{\preceq}^\sharp} \vec{p^\sharp} \Leftrightarrow \prod_{i\in\Delta} \vee^{\sharp^i}\{\vec{p^\sharp}'[i] \mid \vec{p^\sharp}' \in X\} \mathrel{\vec{\preceq}^\sharp} \vec{p^\sharp} \Leftrightarrow \forall i \in \Delta : \forall \vec{p^\sharp}' \in X : \vec{p^\sharp}'[i] \mathrel{\preceq^{\sharp^i}} \vec{p^\sharp}[i] \Leftrightarrow \forall \vec{p^\sharp}' \in X : \forall i \in \Delta : \vec{p^\sharp}'[i] \mathrel{\preceq^{\sharp^i}} \vec{p^\sharp}[i] \Leftrightarrow \forall \vec{p^\sharp}' \in X : \vec{p^\sharp}' \mathrel{\vec{\preceq}^\sharp} \vec{p^\sharp} \Leftrightarrow X \mathrel{\vec{\preceq}} \{\vec{p^\sharp}\} \Leftrightarrow X \mathrel{\vec{\preceq}} \gamma^{\mathfrak{i}}(\vec{p^\sharp})$. □

In practice the attribute independent analysis is often not precise enough whilst the relational one is too expensive. The idea is then to consider some but not all relationships between attributes. Doing so a priori without knowing at all the program to be analysed, i.e., using the Galois connection approach, is then almost impossible. A better approach is to take decisions progressively during the analysis, as the relationships holding between attributes are discovered. This is the widening/narrowing approach discussed below. There a criterion is given to throw away the relationships considered uninteresting with respect to what is presently known about the program properties.

4.2.3.7. LIFTING TO PROPERTY TRANSFORMERS. As observed in paragraph 7.1 of [34], Galois connections can be lifted from sets of properties to sets of monotone properties transformers:

Proposition 21. If $P^\flat(\preceq^\flat) \underset{\alpha^\sharp}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$, *then*

$$P^\flat \overset{m}{\longmapsto} P^\flat(\preceq^\flat) \underset{\lambda\,\varphi\cdot\alpha\circ\varphi\circ\gamma}{\overset{\lambda\,\phi\cdot\gamma\circ\phi\circ\alpha}{\leftrightarrows}} P^\sharp \overset{m}{\longmapsto} P^\sharp(\preceq^\sharp)$$

where the ordering on functions is pointwise that is $\varphi \preceq \phi$ *if and only if* $\forall x : \varphi(x) \preceq \phi(x)$.

PROOF. If $\alpha \circ \varphi \circ \gamma \preceq^\sharp \phi$, then for all x in $P^\sharp$, we have $\alpha \circ \varphi \circ \gamma(x) \preceq^\sharp \phi(x)$ by definition of pointwise orderings whence $\varphi \circ \gamma(x) \preceq^\flat \gamma \circ \phi(x)$ by (1). In particular when $x = \alpha(p^\flat)$ for any $p^\flat \in P^\flat$, we have $\varphi \circ \gamma \circ \alpha(p^\flat) \preceq^\flat \gamma \circ \phi \circ \alpha(p^\flat)$. But $p^\flat \preceq^\flat \gamma \circ \alpha(p^\flat)$ by (2) so that by monotony of φ for $\preceq^\flat$ we have $\varphi(p^\flat) \preceq^\flat \varphi \circ \gamma \circ \alpha(p^\flat)$ proving by transitivity and definition of pointwise orderings that $\varphi \preceq^\flat \gamma \circ \phi \circ \alpha$. Reciprocally, if $\varphi \preceq^\flat \gamma \circ \phi \circ \alpha$ then $\forall x \in P^\flat : \varphi(x) \preceq^\flat \gamma \circ \phi \circ \alpha(x)$ whence $\alpha \circ \varphi \circ \gamma(p^\sharp) \preceq^\sharp \phi \circ \alpha \circ \gamma(p^\sharp)$ by (1) for $x = \gamma(p^\sharp)$. Moreover $\phi \circ \alpha \circ \gamma(p^\sharp) \preceq^\sharp \phi(p^\sharp)$ by (3) and monotony of ϕ for $\preceq^\sharp$. By transitivity and definition of pointwise ordering we conclude that $\alpha \circ \varphi \circ \gamma \preceq^\sharp \phi$. □

For example, starting from an approximation of values, the repeated application of this property can be used to approximate functions, functionals, etc. In particular, it follows that the choice of an approximation of program properties uniquely determines the way of approximating fixpoints of properties transformers. This result is also the basis for extending abstract interpretation from first-order to higher-order functional languages.

4.2.4. Approximation of a Concrete Program Fixpoint Semantics by an Abstract Semantics

We assume that the concrete semantics is defined as a least fixpoint $lfp\, F^\flat = \bigsqcup^\flat_{n\geq 0} {F^\flat}^n(\bot^\flat)$ where $X = F^\flat(X)$ is the equation (or system of equations) associated to the program, $P^\flat(\sqsubseteq^\flat, \bot^\flat, \bigsqcup^\flat)$ is a poset of concrete program properties and $F^\flat \in P^\flat(\sqsubseteq^\flat) \overset{c}{\longmapsto} P^\flat(\sqsubseteq^\flat)$ is continuous. We assume that the least upper bound of the ${F^\flat}^n(\bot^\flat)$, $n \geq 0$ exists, for example because $P^\flat(\sqsubseteq^\flat, \bot^\flat, \bigsqcup^\flat)$ is a strict cpo.

Example 22 (Semantics of logic programs). Let $\mathtt{P}$ be a logic program (containing at least one constant), $U_\mathtt{P}$ be its Herbrand universe and $ground(\mathtt{P})$ be the set of all ground instances of clauses in $\mathtt{P}$. The poset $P^\flat(\sqsubseteq^\flat, \bot^\flat, \bigsqcup^\flat)$ of concrete properties is the complete lattice $\wp(U_\mathtt{P})(\subseteq, \emptyset, U_\mathtt{P}, \cap, \cup)$. $F^\flat$ is the immediate consequence operator $T_\mathtt{P}$ of van Emden and Kowalski [146] defined by:

$$\begin{array}{rcl} T_\mathtt{P} & \in & \wp(U_\mathtt{P}) \mapsto \wp(U_\mathtt{P}) \\ T_\mathtt{P}(X) & = & \{\mathtt{a}_0 \mid \mathtt{a}_0\texttt{->}\mathtt{a}_1, \ldots, \mathtt{a}_n \in ground(\mathtt{P}) \wedge \forall i \in [1,n] : a_i \in X\} \end{array} \tag{12}$$

Observe that $T_\mathtt{P}$ is a complete $\cup$-morphism. A postfixpoint $I \in {T_\mathtt{P}}^\subseteq$ of $T_\mathtt{P}$ is a model of $\mathtt{P}$. The application of Tarski's fixpoint theorem [141] yields van Emden and Kowalski characterization

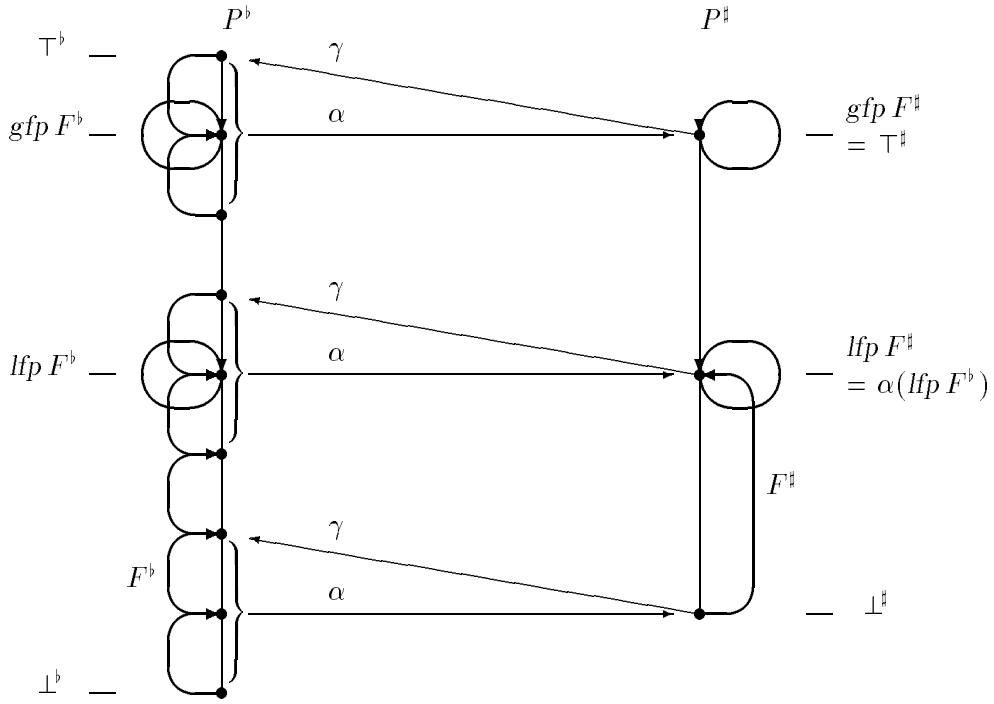


FIGURE 7. Fixpoint inducing using a Galois connection.

theorem of the semantics of the logic program P, which is the least model of P, that is $lfp\, T_{\mathtt{P}} = \bigcup_{n\geq 0} {T_{\mathtt{P}}}^n(\emptyset)$ with ${T_{\mathtt{P}}}^n(\emptyset) \subseteq {T_{\mathtt{P}}}^{n+1}(\emptyset)$ for all $n > 0$. □

Observe that two partial orderings are involved on $P^\flat$ (and $P^\sharp$). In general these orderings are distinct but they may coincide. $\sqsubseteq^\flat$ is called the *computational ordering*. It holds between iterates ${F^\flat}^n(\bot^\flat)$ during the fixpoint computation. $\preceq^\flat$ is called the *approximation ordering*. It specifies the relative precision of concrete program properties.

Let us now examine the problem of computing and then approximating from above for $\preceq^\sharp$ the abstract semantics $\alpha(lfp\, F^\flat)$ of the program.

4.2.4.1. Fixpoint Inducing Using Galois Connections. Assume that $P^\flat(\sqsubseteq^\flat, \bigsqcup^\flat)$ and $P^\sharp(\sqsubseteq^\sharp, \bigsqcup^\sharp)$ are posets, that $F^\flat \in P^\flat \mapsto P^\flat$ provides the concrete semantics $lfp\, F^\flat$ of a program and we are interested in its abstraction $\alpha(lfp\, F^\flat)$ where $P^\flat(\sqsubseteq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\sqsubseteq^\sharp)$. Assuming that $lfp\, F^\flat$ is obtained as the limit of the iteration sequence ${F^\flat}^0(\bot^\flat) = \bot^\flat$, ${F^\flat}^1(\bot^\flat) = F^\flat(\bot^\flat)$, ..., ${F^\flat}^{n+1}(\bot^\flat) = F^\flat({F^\flat}^n(\bot^\flat))$, ..., ${F^\flat}^\omega = \bigsqcup^\flat_{n\geq 0} {F^\flat}^n(\bot^\flat) = lfp\, F^\flat$, it is natural to try to obtain $\alpha(lfp\, F^\flat)$ by computing the abstract image of this iteration sequence that is: $\alpha({F^\flat}^0(\bot^\flat)) = \alpha(\bot^\flat)$, $\alpha({F^\flat}^1(\bot^\flat)) = \alpha(F^\flat(\bot^\flat))$, ..., $\alpha({F^\flat}^{n+1}(\bot^\flat)) = \alpha(F^\flat({F^\flat}^n(\bot^\flat)))$, ..., $\alpha({F^\flat}^\omega) = \alpha(\bigsqcup^\flat_{n\geq 0} {F^\flat}^n(\bot^\flat)) = \alpha(lfp\, F^\flat)$. Since, in general, the computation must be done entirely in the set $P^\sharp$ of abstract program properties, we would like to obtain this iteration sequence using an abstract infimum $\bot^\sharp$, an abstract operator $F^\sharp$ and an abstract least upper bound $\sqcup^\sharp$ on $P^\sharp$ in the form ${F^\sharp}^0(\bot^\sharp) = \bot^\sharp$, ${F^\sharp}^1(\bot^\sharp) = F^\sharp(\bot^\sharp)$, ..., ${F^\sharp}^{n+1}(\bot^\sharp) = F^\sharp({F^\sharp}^n(\bot^\sharp))$, ..., ${F^\sharp}^\omega = \bigsqcup^\sharp_{n\geq 0} {F^\sharp}^n(\bot^\sharp)$. This is possible if ${F^\sharp}^n(\bot^\sharp) = \alpha({F^\flat}^n(\bot^\flat))$ for all $n = 0, 1, \ldots, \omega$. The situation is illustrated in Figure 7. When looking for hypotheses implying the desired property ${F^\sharp}^n(\bot^\sharp) = \alpha({F^\flat}^n(\bot^\flat))$ for all $n = 0, 1, \ldots, \omega$, it is interesting to favor inductive reasonings on n, as follows:

— For $n = 0$, $\alpha(\bot^\flat) = \bot^\sharp$ which yields the definition of $\bot^\sharp$;

— For all $n \geq 0$, $\alpha({F^\flat}^n(\bot^\flat)) = {F^\sharp}^n(\bot^\sharp)$ implies $\alpha({F^\flat}^{n+1}(\bot^\flat)) = {F^\sharp}^{n+1}(\bot^\sharp)$ that is by definition of the iteration sequences $\alpha(F^\flat({F^\flat}^n(\bot^\flat))) = F^\sharp({F^\sharp}^n(\bot^\sharp))$ that is using the induction hypothesis $\alpha(F^\flat({F^\flat}^n(\bot^\flat))) = F^\sharp(\alpha({F^\flat}^n(\bot^\flat)))$ which obviously holds when $\forall p^\flat \in P^\flat : \alpha(F^\flat(p^\flat)) =$

$F^\sharp(\alpha(p^\flat))$ or $F^\sharp = \alpha \circ F^\flat \circ \gamma$ and $\forall p^\flat \in P^\flat : \gamma \circ \alpha(p^\flat) = p^\flat$;

— Lastly for $n = \omega$, we must have $\forall n \geq 0 : \alpha({F^\flat}^n(\bot^\flat)) = {F^\sharp}^n(\bot^\sharp)$ which implies $\alpha\left(\bigsqcup^\flat_{n\geq 0} {F^\flat}^n(\bot^\flat)\right) = \bigsqcup^\sharp_{n\geq 0} {F^\sharp}^n(\bot^\sharp)$. But this is true since $\bigsqcup^\sharp_{n\geq 0} \alpha({F^\flat}^n(\bot^\flat)) = \bigsqcup^\sharp_{n\geq 0} {F^\sharp}^n(\bot^\sharp)$ by induction hypothesis and $\bigsqcup^\sharp_{n\geq 0} \alpha({F^\flat}^n(\bot^\flat)) = \alpha\left(\bigsqcup^\flat_{n\geq 0} {F^\flat}^n(\bot^\flat)\right)$ since, by proposition 6, α is a complete join morphism, whence we conclude by transitivity.

Moreover if $p^\flat$ is a fixpoint of $F^\flat$ then $F^\flat(p^\flat) = p^\flat$ whence $\alpha(F^\flat(p^\flat)) = \alpha(p^\flat)$ and therefore $F^\sharp(\alpha(p^\flat)) = \alpha(p^\flat)$ since $\alpha \circ F^\flat = F^\sharp \circ \alpha$ proving that $\alpha(p^\flat)$ is a fixpoint of $F^\sharp$. In particular $\alpha(\bigsqcup^\flat_{n\geq 0} {F^\flat}^n(\bot^\flat)) = \bigsqcup^\sharp_{n\geq 0} {F^\sharp}^n(\bot^\sharp)$ is a fixpoint of $F^\sharp$.

Assume that $F^\sharp \in P^\sharp(\sqsubseteq^\sharp) \stackrel{m}{\longmapsto} P^\sharp(\sqsubseteq^\sharp)$ is monotone and $p^\sharp$ is a fixpoint of $F^\sharp$ such that $\bot^\sharp \sqsubseteq^\sharp p^\sharp$. Then ${F^\sharp}^0(\bot^\sharp) = \bot^\sharp \sqsubseteq^\sharp p^\sharp$. If ${F^\sharp}^n(\bot^\sharp) \sqsubseteq^\sharp p^\sharp$ then ${F^\sharp}^{n+1}(\bot^\sharp) = F^\sharp({F^\sharp}^n(\bot^\sharp)) \sqsubseteq^\sharp F^\sharp(p^\sharp) = p^\sharp$ by monotony and fixpoint property. If $\forall n \geq 0 : {F^\sharp}^n(\bot^\sharp) \sqsubseteq^\sharp p^\sharp$ then $\bigsqcup^\sharp_{n\geq 0} {F^\sharp}^n(\bot^\sharp) \sqsubseteq^\sharp p^\sharp$ by definition of least upper bounds proving that $\bigsqcup^\sharp_{n\geq 0} {F^\sharp}^n(\bot^\sharp)$ is the least fixpoint of $F^\sharp$ greater than or equal to $\bot^\sharp$.

In summary, we have just proved the following proposition ([34], theorem 7.1.0.4–(3)):

Proposition 23 (Fixpoint inducing). If $P^\flat(\sqsubseteq^\flat, \bigsqcup^\flat)$ and $P^\sharp(\sqsubseteq^\sharp, \bigsqcup^\sharp)$ are posets, $P^\flat(\sqsubseteq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\sqsubseteq^\sharp)$, $F^\flat \in P^\flat \mapsto P^\sharp$ is such that $lfp\, F^\flat = \bigsqcup^\flat_{n\geq 0} {F^\flat}^n(\bot^\flat)$, $\bot^\sharp = \alpha(\bot^\flat)$, $F^\sharp \in P^\sharp \mapsto P^\sharp$ is such that $\alpha \circ F^\flat = F^\sharp \circ \alpha$ (which is implied by $F^\sharp = \alpha \circ F^\flat \circ \gamma$ and $\forall p^\flat \in P^\flat : \gamma \circ \alpha(p^\flat) = p^\flat$), then $\alpha(lfp\, F^\flat) = \bigsqcup^\sharp_{n\geq 0} {F^\sharp}^n(\bot^\sharp)$. $\bigsqcup^\sharp_{n\geq 0} {F^\sharp}^n(\bot^\sharp)$ is a fixpoint of $F^\sharp$. When $F^\sharp \in P^\sharp(\sqsubseteq^\sharp) \stackrel{m}{\longmapsto} P^\sharp(\sqsubseteq^\sharp)$ is monotone, it is the least fixpoint of $F^\sharp$ greater than or equal to $\bot^\sharp$.

The fact that $lfp\, F^\flat = \bigsqcup^\flat_{n\geq 0} {F^\flat}^n(\bot^\flat)$ follows for example from ω-upper-continuity on a complete partial order. It can be relaxed into monotony by using transfinite iteration sequences, as in [33]. Observe that no such hypothesis is necessary on the abstract domain $P^\flat$ since it is induced from $P^\flat$ by the Galois connection.

4.2.4.2. Fixpoint Abstraction Using Galois Connections. In general, a fixpoint inducing is not computable so that one must be satisfied with an abstract approximation $p^\sharp$ from above of the concrete fixpoint $\alpha(lfp\, F^\flat)$ that is $\alpha(lfp\, F^\flat) \preceq^\sharp p^\sharp$ or equivalently $lfp\, F^\flat \preceq^\flat \gamma(p^\sharp)$. When a Galois connection has been established between concrete and abstract properties, any concrete fixpoint can be approximated by an abstract fixpoint using an approximation of the function as indicated in proposition 21. We obtain theorem 7.1.0.4 of [34]:

Proposition 24 (Fixpoint abstraction). If $P^\flat(\preceq^\flat, f^\flat, t^\flat, \wedge^\flat, \vee^\flat)$ and $P^\sharp(\preceq^\sharp, f^\sharp, t^\sharp, \wedge^\sharp, \vee^\sharp)$ are complete lattices, $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$ and $F^\flat \in P^\flat(\preceq^\flat) \stackrel{m}{\longmapsto} P^\flat(\preceq^\flat)$, then $\alpha(lfp\, F^\flat) \preceq^\sharp lfp\, \alpha \circ F^\flat \circ \gamma$.

proof. By Tarski's fixpoint theorem [141], the least fixpoints exist. So let $p^\sharp = lfp\, \alpha \circ F^\flat \circ \gamma$. We have $\alpha \circ F^\flat \circ \gamma(p^\sharp) = p^\sharp$ whence $F^\flat \circ \gamma(p^\sharp) \preceq^\flat \gamma(p^\sharp)$ by (1). It follows that $\gamma(p^\sharp)$ is a postfixpoint of $F^\flat$ whence $lfp\, F^\flat \preceq^\flat \gamma(p^\sharp)$ by Tarski's fixpoint theorem or equivalently $\alpha(lfp\, F^\flat) \preceq^\sharp p^\sharp = lfp\, \alpha \circ F^\flat \circ \gamma$. □

A consequence of this theorem is that the choice of the concrete semantics $F^\flat$ and of the abstraction $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$ of program properties entirely determines the abstract semantics $lfp\, \alpha \circ F^\flat \circ \gamma$. It follows that the abstract semantics can be constructively derived from the concrete semantics by a formal computation consisting in simplifying $\alpha \circ F^\flat \circ \gamma$ so as to express it using operators on abstract properties only (this has been illustrated on the casting out of nine introductory example). But for a few exceptions (such as [15] where $P^\flat$ is finite), this simplification is not mechanizable and must be done by hand. This simplification is facilitated by the observation that $\alpha \circ F^\flat \circ \gamma$ can be approximated from above by $F^\sharp$ such that $\forall p^\sharp \in P^\sharp : \alpha \circ F^\flat \circ \gamma(p^\sharp) \preceq^\sharp F^\sharp(p^\sharp)$:

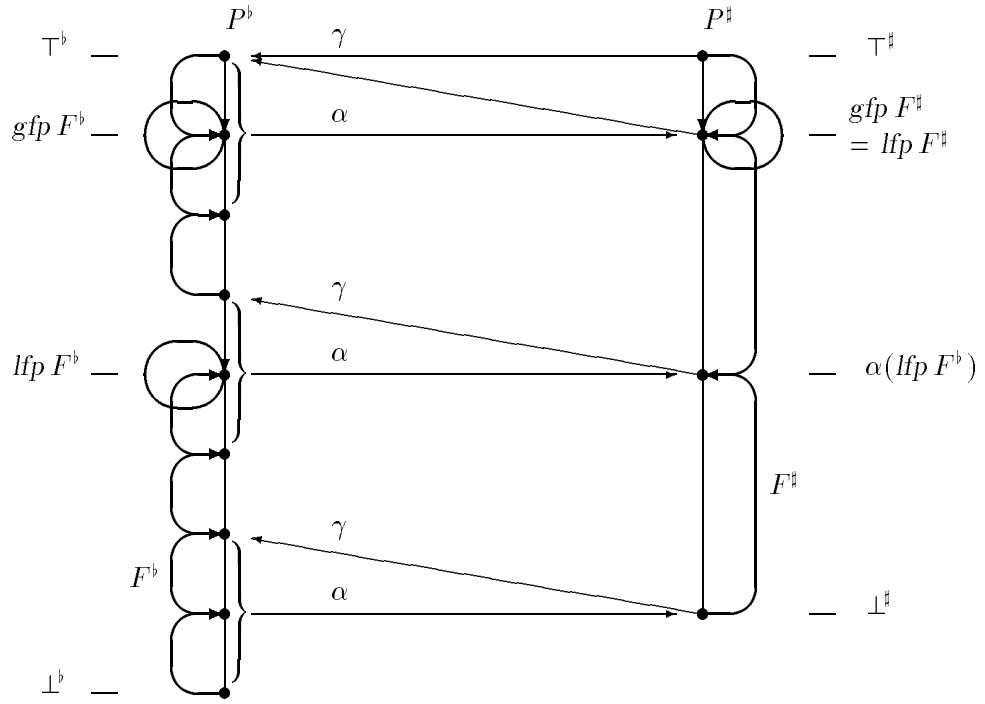


FIGURE 8. Fixpoint approximation using a Galois connection.

Proposition 25 (Fixpoint approximation). If $P^\sharp(\preceq^\sharp, f^\sharp, t^\sharp, \wedge^\sharp, \vee^\sharp)$ *is a complete lattice,* $F^\sharp$, $\bar{F}^\sharp \in P^\sharp(\preceq^\sharp) \stackrel{m}{\longmapsto} P^\sharp(\preceq^\sharp)$, *and* $F^\sharp \preceq^\sharp \bar{F}^\sharp$, *then* $lfp\, F^\sharp \preceq^\sharp lfp\, \bar{F}^\sharp$.

PROOF. We have $F^\sharp(lfp\, \bar{F}^\sharp) \preceq^\sharp \bar{F}^\sharp(lfp\, \bar{F}^\sharp) = lfp\, \bar{F}^\sharp$ whence $lfp\, F^\sharp \preceq^\sharp lfp\, \bar{F}^\sharp$ since $lfp\, F^\sharp = \bigwedge^\sharp\{X \mid F^\sharp(X) \preceq^\sharp X\}$ by Tarski's fixpoint theorem [141]. □

Apart from this, theorem 24 has numerous variants depending upon the hypotheses ensuring the existence of fixpoint (for example see theorem 7.1.0.5 of [34] which avoids the monotony hypothesis). The general idea is that the abstract iterates approximate from above the concrete iterates, as illustrated in Figure 8. We will use the following variant of proposition 24 which is based upon the ideas sketched above, where the computational and approximation orderings are distinguished:

Proposition 26 (Fixpoint abstract approximation). If $P^\flat(\sqsubseteq^\flat, \bot^\flat, \sqcup^\flat)$ *and* $P^\sharp(\sqsubseteq^\sharp, \bot^\sharp, \sqcup^\sharp)$ *are cpos,* $F^\flat \in P^\flat(\sqsubseteq^\flat, \sqcup^\flat) \stackrel{c}{\longmapsto} P^\flat(\sqsubseteq^\flat, \sqcup^\flat)$, $F^\flat \in P^\flat(\preceq^\flat) \stackrel{m}{\longmapsto} P^\flat(\preceq^\flat)$, $F^\sharp \in P^\sharp(\sqsubseteq^\sharp, \sqcup^\sharp) \stackrel{c}{\longmapsto} P^\sharp(\sqsubseteq^\sharp, \sqcup^\sharp)$, $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightharpoons}} P^\sharp(\preceq^\sharp)$, $\alpha(\bot^\flat) \preceq^\sharp \bot^\sharp$, $\forall p^\sharp \in P^\sharp : \alpha \circ F^\flat \circ \gamma(p^\sharp) \preceq^\sharp F^\sharp(p^\sharp)$ *and for any* $\sqsubseteq^\flat$*-increasing chain* ${p^\flat}_i, i \in \mathbb{N}$ *and any* $\sqsubseteq^\sharp$*-increasing chain* ${p^\sharp}_i, i \in \mathbb{N}$ *such that* $\forall i \in \mathbb{N} : \alpha({p^\flat}_i) \preceq^\sharp {p^\sharp}_i$ *we have* $\alpha(\bigsqcup^\flat_{i\in\mathbb{N}} {p^\flat}_i) \preceq^\sharp \bigsqcup^\sharp_{i\in\mathbb{N}} {p^\sharp}_i$, *then* $\alpha(lfp\, F^\flat) \preceq^\sharp lfp\, F^\sharp$.

PROOF. Since $\alpha(\bot^\flat) \preceq^\sharp \bot^\sharp$, we have $\alpha({F^\flat}^0(\bot^\flat)) \preceq^\sharp {F^\sharp}^0(\bot^\sharp)$. If $n \geq 0$ and $\alpha({F^\flat}^n(\bot^\flat)) \preceq^\sharp {F^\sharp}^n(\bot^\sharp)$ by induction hypothesis, then ${F^\flat}^n(\bot^\flat) \preceq^\flat \gamma({F^\sharp}^n(\bot^\sharp))$ by (1) so that by monotony $\alpha \circ F^\flat \circ {F^\flat}^n(\bot^\flat) \preceq^\sharp \alpha \circ F^\flat \circ \gamma({F^\sharp}^n(\bot^\sharp)) \preceq^\sharp F^\sharp({F^\sharp}^n(\bot^\sharp))$ whence $\alpha({F^\flat}^{n+1}(\bot^\flat)) \preceq^\sharp {F^\sharp}^{n+1}(\bot^\sharp)$. We conclude by continuity and the last hypothesis that $\alpha(lfp\, F^\flat) = \alpha(\bigsqcup^\flat_{i\in\mathbb{N}} {F^\flat}^n(\bot^\flat)) \preceq^\sharp \bigsqcup^\sharp_{i\in\mathbb{N}} {F^\sharp}^n(\bot^\sharp) = lfp\, F^\sharp$. □

When the computational and approximation orderings coincide, this proposition amounts to the more simple:

Proposition 27. If $P^\flat(\preceq^\flat, f^\flat, \vee^\flat)$ *and* $P^\sharp(\preceq^\sharp, f^\sharp, \vee^\sharp)$ *are cpos,* $F^\flat \in P^\flat(\preceq^\flat, \vee^\flat) \stackrel{c}{\longmapsto} P^\flat(\preceq^\flat, \vee^\flat)$, $F^\sharp \in P^\sharp(\preceq^\sharp, \vee^\sharp) \stackrel{c}{\longmapsto} P^\sharp(\preceq^\sharp, \vee^\sharp)$, $P^\flat(\preceq^\flat) \underset{\alpha}{\overset{\gamma}{\leftrightharpoons}} P^\sharp(\preceq^\sharp)$, $\alpha(\bot^\flat) \preceq^\sharp \bot^\sharp$ *and* $\forall p^\sharp \in P^\sharp : \alpha \circ F^\flat \circ \gamma(p^\sharp) \preceq^\sharp F^\sharp(p^\sharp)$, *then* $\alpha(lfp\, F^\flat) \preceq^\sharp lfp\, F^\sharp$.

PROOF. This is a corollary of proposition 26 since for any $\preceq^\flat$-increasing chain $p^\flat{}_i, i \in \mathbb{N}$ and any $\preceq^\sharp$-increasing chain $p^\sharp{}_i, i \in \mathbb{N}$ such that $\forall i \in \mathbb{N} : \alpha(p^\flat{}_i) \preceq^\sharp p^\sharp{}_i$, we have $\alpha(\vee^\flat{}_{i\in\mathbb{N}} p^\flat{}_i) = \vee^\sharp{}_{i\in\mathbb{N}} \alpha(p^\flat{}_i) \preceq^\sharp \vee^\sharp{}_{i\in\mathbb{N}} p^\sharp{}_i$ by proposition 6 and definition of least upper bounds. □

As usual continuity hypotheses can be avoided using monotony and transfinite iteration sequences.

4.2.4.3. CHAOTIC AND ASYNCHRONOUS ITERATIONS. Using a decomposition by partitioning, a 'concrete' fixpoint equation $X = F^\flat(X)$ can be decomposed into an 'abstract' system of equations:

$$\begin{cases} X_i = F^\sharp{}_i(X_1, X_2, \ldots, X_n) \\ i = 1, \ldots, n \end{cases} \tag{13}$$

where each X_i belongs to a cpo or complete lattice $P^\sharp{}_i(\sqsubseteq^\sharp{}_i)$ and $F^\sharp{}_i(X_1, X_2, \ldots, X_n)$ is equal to the i-th component $F^\sharp(X)[i]$ of $F^\sharp(X)$. If $F^\sharp$ is upper-continuous then the least fixpoint $lfp\, F^\sharp = \bigsqcup^\sharp{}_{k\geq 0} F^{\sharp\, k}$ where $F^{\sharp\, 0} = \bot^\sharp$ and $F^{\sharp\, k+1} = F^\sharp(F^{\sharp\, k})$ can be computed by Jacobi's method of successive approximations, which can be detailed as:

$$\begin{cases} X_i^{k+1} = F^\sharp{}_i(X_1^k, X_2^k, \ldots, X_n^k) \\ i = 1, \ldots, n \end{cases} \tag{14}$$

In practice the Gauss-Seidel's iterative method:

$$\begin{cases} X_1^{k+1} = F^\sharp{}_1(X_1^k, X_2^k, \ldots, X_{i-1}^k, X_i^k, \ldots, X_{n-1}^k, X_n^k) \\ \ldots \quad \ldots\ldots\ldots\

Jacobi's successive approximations are obtained by choosing $\forall k \geq 0 : J_k = \{1, \ldots, n\}$, whereas the choice $\forall k \geq 0 : J_k = \{(k \mod n) + 1\}$ corresponds to Gauss-Seidel's iterative method. In [30], we proved:

Proposition 28 (Convergence of an ascending sequence of chaotic iterations). The limit $\bigsqcup^\sharp_{k\geq 0} X^k$ *of any ascending sequence of chaotic iterations* $X^k, k \geq 0$ *for an upper-continuous map* $F^\sharp \in \prod_{i=1}^n P^\sharp{}_i \mapsto \prod_{i=1}^n P^\sharp{}_i$ *is the least fixpoint of* $F^\sharp$ *greater than or equal to* X^0.

PROOF. 1°) Let us first remark that whenever $X \sqsubseteq^\sharp F^\sharp(X) \sqsubseteq^\sharp lfp\, F^\sharp$, we have $\forall J \subseteq \{1, \ldots, n\}$, $X \sqsubseteq^\sharp F^\sharp{}_J(X) \sqsubseteq^\sharp F^\sharp(X) \sqsubseteq^\sharp lfp\, F^\sharp$. Indeed for all $i = 1, \ldots, n$, $X_i \sqsubseteq^\sharp{}_i F^\sharp{}_i(X)$, therefore, if $i \in J$, then $X_i \sqsubseteq^\sharp{}_i F^\sharp{}_i(X) = F^\sharp(X)[i] = F^\sharp{}_J(X)[i]$, else $X_i \sqsubseteq^\sharp{}_i F^\sharp{}_J(X)[i] \sqsubseteq^\sharp{}_i F^\sharp{}_i(X)$.

2°) Let us now prove that $\forall k \geq 0 : X^k \sqsubseteq^\sharp X^{k+1} \sqsubseteq^\sharp F^\sharp(X^k) \sqsubseteq^\sharp lfp\, F^\sharp$. For the infimum $X^0 \sqsubseteq^\sharp lfp\, F^\sharp$ we have $X^0 \sqsubseteq^\sharp F^\sharp(X^0) \sqsubseteq^\sharp F^\sharp(lfp\, F^\sharp) = lfp\, F^\sharp$ by monotony and fixpoint property hence $X^0 \sqsubseteq^\sharp X^1 = F^\sharp{}_{J_0}(X^0) \sqsubseteq^\sharp F^\sharp(X^0) \sqsubseteq^\sharp lfp\, F^\sharp$ by 1°). For the induction step, let us assume that $X^{k-1} \sqsubseteq^\sharp X^k \sqsubseteq^\sharp F^\sharp(X^{k-1}) \sqsubseteq^\sharp lfp\, F^\sharp$ for some $k > 0$. If $i \in J_{k-1}$, then $X^k_i = F^\sharp{}_i(X^{k-1}) \sqsubseteq^\sharp{}_i F^\sharp{}_i(X^k) \sqsubseteq^\sharp{}_i lfp\, F^\sharp[i]$ since $X^{k-1} \sqsubseteq^\sharp X^k \sqsubseteq^\sharp lfp\, F^\sharp$ and $F^\sharp{}_i$ is monotone. Otherwise, $i \notin J_{k-1}$, and $X^k_i = X^{k-1}_i \sqsubseteq^\sharp{}_i F^\sharp{}_i(X^{k-1}) \sqsubseteq^\sharp{}_i lfp\, F^\sharp[i]$ by induction hypothesis so that $X^k_i \sqsubseteq^\sharp{}_i F^\sharp{}_i(X^{k-1}) \sqsubseteq^\sharp{}_i F^\sharp{}_i(X^k) \sqsubseteq^\sharp{}_i lfp\, F^\sharp[i]$ by monotony. In both cases, we have $X^k_i \sqsubseteq^\sharp{}_i F^\sharp{}_i(X^k) \sqsubseteq^\sharp{}_i lfp\, F^\sharp[i]$ for all $i = 1, \ldots, n$, therefore $X^k \sqsubseteq^\sharp F^\sharp(X^k) \sqsubseteq^\sharp lfp\, F^\sharp$, proving that $X^k \sqsubseteq^\sharp X^{k+1} = F^\sharp{}_{J_k}(X^k) \sqsubseteq^\sharp F^\sharp(X^k) \sqsubseteq^\sharp lfp\, F^\sharp$.

3°) Let us now prove that $\forall k \geq 0 : \exists m \geq k : F^\sharp(X^k) \sqsubseteq^\sharp X^m$. If $i \in \{1, \ldots, n\}$ and $k \geq 0$ then, by weak fairness, there exists $\ell(i)$ such that $i \in J_{k+\ell(i)}$. It follows that $X^{k+\ell(i)+1}[i] = F^\sharp{}_i(X^{k+\ell(i)})$. By induction using 2°), we have $X^k \sqsubseteq^\sharp X^{k+\ell(i)}$, so that, by monotony, $F^\sharp(X^k)[i] = F^\sharp{}_i(X^k) \sqsubseteq^\sharp{}_i X^{k+\ell(i)+1}[i] \sqsubseteq^\sharp{}_i X^m[i]$, where m is the maximum of the $\ell(i)$ for $i = 1, \ldots, n$. Whence $F^\sharp(X^k) \sqsubseteq^\sharp X^m$.

4°) Let X^ω be $\bigsqcup^\sharp_{k\geq 0} X^k$. By 2°), definition of least upper bounds, and upper-continuity, $X^\omega \sqsubseteq^\sharp \bigsqcup^\sharp_{k\geq 0} F^\sharp(X^k) = F^\sharp(X^\omega)$. By 3°), $\forall k \geq 0 : F^\sharp(X^k) \sqsubseteq^\sharp \bigsqcup^\sharp_{m\geq 0} X^m$, whence $F^\sharp(X^\omega) = \bigsqcup^\sharp_{k\geq 0} F^\sharp(X^k) \sqsubseteq^\sharp X^\omega$. By antisymmetry, X^ω is a fixpoint of $F^\sharp$. By 2°), $X^\omega \sqsubseteq^\sharp lfp\, F^\sharp$, whence equality holds by unicity of the least fixpoint. □

Proposition 28 justifies the use of abstract interpreters in which the chaotic iteration strategy is chosen so as to mimic actual program executions. Examples of practical implementation of a particular strategy of chaotic iteration are given by [133], [103], [64], [131], [69], [158]. An example of an abstract interpreter written in a version of Prolog is given in [152].

This result has been generalized to *asynchronous iterations* [25] corresponding to a parallel implementation where X is a shared array and each process i reads the value x_j of element $X[j]$ in any order for $j = 1, \ldots, n$, then computes $x'_i = F^\sharp{}_i(x_1, \ldots, x_n)$ and finally asynchronously writes this value x'_i in shared memory $X[i]$. The relative speed of the processes is irrelevant provided execution is weakly fair. Another generalization in [32] concerns systems of functional fixpoint equations $f_i(\vec{X}_i) = F_i[f_1, \ldots, f_n](\vec{X}_i)$, $i = 1, \ldots, n$. When each $f_i(\vec{X}_i)$ needs to be known only for a subset ϕ_i of the domain P_i of $\vec{X}_i$, it is necessary and sufficient to compute the value of $f_i(\vec{X}_i)$ for $\vec{X}_i$ belonging to a subset the domain of X called the ϕ-F-closure and such that $\phi_i \subseteq \phi\text{-}F\text{-closure}_i \subseteq P_i$. This technique, which was later popularized by Jones and Mycroft [84] under the name *minimal function graphs*, may be used as a basis for the tabulation method of [9], [89], [59], [154].

4.2.4.4. CONVERGENCE AND TERMINATION. Convergence to the least fixpoint $lfp\, F^\sharp$ is obtained in proposition 28 by taking the join $\bigsqcup^\sharp_{k\geq 0} X^k$ of infinitely many terms in the chaotic iteration sequence. In practice this can be avoided when using finite lattices, posets satisfying the *ascending chain condition*, and more generally in any case when the chaotic iteration sequence is increasing but not strictly (because of properties of $P^\sharp$ and/or $F^\sharp$) so that the fixpoint must be reached after finitely many steps. For example, we have:

Proposition 29 (Termination of an ascending sequence of chaotic iterations). If the length of strictly increasing chains in $\prod_{i=1}^{n} P^\sharp{}_i$ is bounded by ℓ and the number of steps which are necessary for any component to evolve in chaotic iterations X^k, $k \geq 0$ for $F^\sharp$ is bounded by m, then $lfp\, F^\sharp = X^{\ell m}$.

PROOF. Observe that by cases 1°) and 3°) in the proof of proposition 28, we have $X^k \sqsubseteq^\sharp F^\sharp(X^k) \sqsubseteq^\sharp X^{k+m}$ for all $k \geq 0$. Therefore if there exists $k \geq 0$, hence a least one, such that $X^k = X^{k+m}$ then X^k is a fixpoint of $F^\sharp$, whence the least one and X^{im}, $0 \leq i \leq k$ is a strictly increasing chain so that $k \leq \ell$. When a fixpoint is reached, the chaotic iterations are stabilized so that $lfp\, F^\sharp = X^{\ell m}$. The remaining case $\forall k \geq 0 : X^k \sqsubset^\sharp X^{k+m}$ is impossible since it is in contradiction with the ascending chain condition. □

Other theoretical upper bounds on fixed point iterations have been given by [130], but these worst case analyses do not take into account the fact that $F^\sharp$ is not indifferent. In particular, proofs that these bounds are tight may lead to consider peculiar $F^\sharp$ not corresponding to any program at all! Pending average-case analyses, practical experiences such as [64], [103], [149], [142], [154] are very useful. Moreover, in practice, it is always possible to use extrapolation techniques such as widenings and narrowings considered below to speed-up convergence at the price of overshooting the least fixpoint.

4.2.4.5. ON THE USE OF GALOIS CONNECTIONS. Galois connections correspond to an ideal situation where the set $P^\sharp$ of abstract properties has been defined so that any concrete property has a best abstract upper approximation. Numerous practical abstract interpretations, such as [44] or the k-depth success pattern analysis of Sato and Tamaki [137], [109], which do not satisfy this condition can be easily handled by relaxing some of the hypotheses involved in the Galois connection approach [42].

4.3. Approximation of Fixpoint Semantics by Convergence Acceleration Using Widenings and Narrowings

In [28], we introduced the idea of using widening and narrowing operators to accelerate convergence for fixpoint approximation from above (the dual case considered in [25] is also useful for some applications such as type inference [121] where a sound approximation is from below). This idea offered the possibility of considering infinite lattices not satisfying the ascending chain condition or of speeding up convergence in case of combinatorial explosion [79]. The larger the abstract domain $P^\sharp$ is, the more precise the analyses tend to be because less information is lost. For termination, widening and narrowing operators ensure that only a finite $P^\sharp[\![p]\!]$ subspace of $P^\sharp$ will be considered during analysis of any program p. A Galois connection upon that subspace $P^\sharp[\![p]\!]$ would not do when $P^\sharp[\![p]\!]$ is different for each program p and the union of these subspaces $P^\sharp[\![p]\!]$ for all programs p is infinite.

4.3.1. Downward Abstract Iteration Sequence with Narrowing

A first idea to effectively approximate $lfp\, F^\sharp$ from above is to use a downward iteration $\check{X}^k$, $k \geq 0$, all elements of which are upper approximations of the least fixpoint $lfp\, F^\sharp$ and which is stationary after finitely many steps. In order to ensure that all $\check{X}^k$, $k \geq 0$ are upper approximations of the least fixpoint $lfp\, F^\sharp$, one can look for an inductive argument using the basis $lfp\, F^\sharp \preceq^\sharp \check{X}^0$ and the inductive step $lfp\, F^\sharp \preceq^\sharp \check{X}^k \Rightarrow lfp\, F^\sharp \preceq^\sharp \check{X}^{k+1} \preceq^\sharp \check{X}^k$. The basis is easily handled with by starting from the supremum $\check{X}^0 = t^\sharp$. Finding general purpose sufficient conditions ensuring the validity of the inductive step $lfp\, F^\sharp \preceq^\sharp \check{X}^k$ implies $lfp\, F^\sharp \preceq^\sharp \check{X}^{k+1}$ together with $\check{X}^{k+1} \preceq^\sharp \check{X}^k$ is a bit more difficult since the only available information is $\check{X}^k$ and $F^\sharp(\check{X}^k)$ and the least fixpoint $lfp\, F^\sharp$ and more generally the fixpoints of $F^\sharp$ are unknown. Hence we define $\check{X}^{k+1}$ to be $\check{X}^k \mathbin{\triangle} F^\sharp(\check{X}^k)$ that is the composition of the available information using a so called *narrowing*

operator $\triangle$. To ensure $\check{X}^k \triangle F^\sharp(\check{X}^k) = \check{X}^{k+1} \preceq^\sharp \check{X}^k$ with the additional constraint that it must be valid for all program, that is all $F^\sharp$, we can require more specifically that $\forall x, y \in P^\sharp : x \triangle y \preceq^\sharp x$. Ensuring $lfp\, F^\sharp \preceq^\sharp \check{X}^k \triangle F^\sharp(\check{X}^k)$ for all $F^\sharp$, hence without knowing its fixpoints, is a bit more difficult. In practice however, $F^\sharp$ is often monotone for $\preceq^\sharp$. In this case if $p^\sharp$ is a fixpoint of $F^\sharp$ then $p^\sharp \preceq^\sharp x$ implies $p^\sharp \preceq^\sharp F^\sharp(x)$ by monotony and fixpoint property. Therefore if $p^\sharp \preceq^\sharp x$ and $p^\sharp \preceq^\sharp y$ imply $p^\sharp \preceq^\sharp x \triangle y$ then obviously $lfp\, F^\sharp \preceq^\sharp \check{X}^k$ implies $lfp\, F^\sharp \preceq^\sharp \check{X}^{k+1}$. Since the fixpoints $p^\sharp$ of $F^\sharp$ are unknown, we require the narrowing operator to satisfy $\forall x, y, z \in P^\sharp : z \preceq^\sharp x \wedge z \preceq^\sharp y \Rightarrow z \preceq^\sharp x \triangle y$. Finally the downward iteration sequence $\check{X}^0$, ..., $\check{X}^{k+1} = \check{X}^k \triangle F^\sharp(\check{X}^k)$, ... must be finite. Again since this must be true for all possible $F^\sharp$, we require the non-existence of strictly decreasing chains of the form x^0, ..., $x^{k+1} = x^k \triangle y^k$ where y^k, $k \geq 0$ is a decreasing chain (due to monotony of $F^\sharp$).

The above discussion is a motivation for the definition of a *narrowing operator*, such that:

$$\triangle \in P^\sharp \times P^\sharp \mapsto P^\sharp \tag{16a}$$

$$\forall {p^\sharp}_1, {p^\sharp}_2 \in P^\sharp : {p^\sharp}_1 \triangle {p^\sharp}_2 \preceq^\sharp {p^\sharp}_1 \tag{16b}$$

$$\forall {p^\sharp}_1, {p^\sharp}_2, {p^\sharp}_3 \in P^\sharp : {p^\sharp}_1 \preceq^\sharp {p^\sharp}_2 \wedge {p^\sharp}_1 \preceq^\sharp {p^\sharp}_3 \Rightarrow {p^\sharp}_1 \preceq^\sharp {p^\sharp}_2 \triangle {p^\sharp}_3 \tag{16c}$$

$$\begin{array}{l}\text{for all decreasing chains } {p^\sharp}^k, k \geq 0 \text{ and } {p^\sharp}' \in P^\sharp \text{ the chain} \\ \check{X}^0 = {p^\sharp}', \ldots, \check{X}^{k+1} = \check{X}^k \triangle {p^\sharp}^k, \ldots \text{ is not strictly decreasing} \\ \text{for } \preceq^\sharp\end{array} \tag{16d}$$

with the following convergence property showing how to improve upper-approximations of fixpoints:

Proposition 30 (Downward abstract iteration sequence with narrowing). If $F^\sharp \in P^\sharp(\preceq^\sharp) \stackrel{m}{\longmapsto} P^\sharp(\preceq^\sharp)$, $\triangle \in P^\sharp \times P^\sharp \mapsto P^\sharp$ *is a narrowing operator and* $F^\sharp(p^\sharp) = p^\sharp \preceq^\sharp {p^\sharp}'$, *then the decreasing chain* $\check{X}^0 = {p^\sharp}'$, ..., $\check{X}^{k+1} = \check{X}^k \triangle F^\sharp(\check{X}^k)$ *is stationary with limit* $\check{X}^\ell$, $\ell \in \mathbb{N}$ *such that* $p^\sharp \preceq^\sharp \check{X}^\ell \preceq^\sharp {p^\sharp}'$.

PROOF. We prove $p^\sharp \preceq^\sharp \check{X}^k$ for all $k \in \mathbb{N}$. This holds for $k = 0$ by hypothesis. If $p^\sharp \preceq^\sharp \check{X}^k$ by induction hypothesis, then $p^\sharp = F^\sharp(p^\sharp) \preceq^\sharp F^\sharp(\check{X}^k)$ by monotony whence $p^\sharp \preceq^\sharp \check{X}^{k+1} = \check{X}^k \triangle F^\sharp(\check{X}^k) \preceq^\sharp \check{X}^k$ by (16b) and (16c). Since the chain $\check{X}^k$, $k \geq 0$ is decreasing for $\preceq^\sharp$ then so is $F^\sharp(\check{X}^k)$, $k \geq 0$ by monotony. Therefore $\check{X}^k$, $k \geq 0$, which is not strictly decreasing by (16d), has a limit $\check{X}^\ell$ such that $p^\sharp \preceq^\sharp \check{X}^\ell \preceq^\sharp \check{X}^0 = {p^\sharp}'$. □

Observe that in a complete lattice satisfying the *descending chain condition* (that is all strictly decreasing chains for $\preceq^\sharp$ are finite) the narrowing operator $x \triangle y$ can be defined as the greatest lower bound of x and y for $\preceq^\sharp$. Hypotheses (16) have numerous variants. For example if the starting point ${p^\sharp}'$ is a postfixpoint of $F^\sharp$ we can assume that ${p^\sharp}_2 \preceq^\sharp {p^\sharp}_1$ in (16b). Moreover, the narrowing operator can be chosen to depend upon the iteration step. In particular since any term of the chain $\check{X}^k$, $k \geq 0$ is sound we can stop iterations after an arbitrary number n of steps so as to cut analysis costs down. In this case the narrowing $x \triangle^i y$ would be y if $i \leq n$ else x. Finally, more sophisticated convergence enforcement strategies could be designed by using not a single but all previous iterates.

4.3.2. Upward Abstract Iteration Sequence with Widening

In general no approximation of the least fixpoint better than the supremum $t^\sharp$ is known to start with. Since the downward abstract iteration sequence with narrowing cannot undershoot fixpoints no approximation of the least fixpoint better than the greatest fixpoint can be computed by the method of proposition 30. Therefore, in order to get a better initial upper-approximation of the least fixpoint, one can start from below, for example from the infimum $f^\sharp$, using an increasing chain so as to overshoot this unknown least fixpoint. As shown by the practical experience, the benefit of this method is that very often the limit will be below the greatest fixpoint and in all cases below the supremum $t^\sharp$. Three problems have to be solved. When using

an increasing chain $\hat{X}^k$, $k \in \mathbb{N}$ starting from below the least fixpoint $lfp\, F^\sharp$, we must first have a computable criterion to check whether a point $\hat{X}^\ell$ above the least fixpoint has been reached. Depending on the problem to be solved, several criteria are available such as $\hat{X}^\ell$ is a fixpoint of $F^\sharp$ or, by Tarski's fixpoint theorem, $\hat{X}^\ell$ is a postfixpoint of $F^\sharp$. Second, we must ensure that the sequence $\hat{X}^k$, $k \in \mathbb{N}$ eventually reaches a point above the least fixpoint. A simple way to do so is to iterate above the chain ${F^\sharp}^0 = \bot^\sharp, \ldots, {F^\sharp}^{k+1} = F^\sharp({F^\sharp}^k), \ldots$, converging to the least fixpoint $lfp\, F^\sharp = \sqcup^\sharp_{k \geq 0} {F^\sharp}^k$. To do so we can use a *widening operator* $\triangledown \in P^\sharp \times P^\sharp \mapsto P^\sharp$ in order to extrapolate to $\hat{X}^{k+1} = \hat{X}^k \triangledown F^\sharp(\hat{X}^k)$ from two consecutive terms $\hat{X}^k$ and $F^\sharp(\hat{X}^k)$ so that $\hat{X}^k \preceq^\sharp \hat{X}^{k+1}$ and $F^\sharp(\hat{X}^k) \preceq^\sharp \hat{X}^{k+1}$. Third, we must ensure that the iteration sequence $\hat{X}^k$, $k \in \mathbb{N}$ stabilizes after finitely many steps. This leads to the definition of a widening operator, such that:

$$\triangledown \in P^\sharp \times P^\sharp \mapsto P^\sharp \tag{17a}$$

$$\forall {p^\sharp}_1, {p^\sharp}_2, {p^\sharp}'_1, {p^\sharp}'_2 \in P^\sharp : ({p^\sharp}_1 \sqsubseteq^\sharp {p^\sharp}_2) \wedge ({p^\sharp}_1 \preceq^\sharp {p^\sharp}'_1) \wedge ({p^\sharp}_2 \preceq^\sharp {p^\sharp}'_2) \Rightarrow ({p^\sharp}'_1 \preceq^\sharp {p^\sharp}_1 \triangledown {p^\sharp}'_2) \wedge ({p^\sharp}_2 \preceq^\sharp {p^\sharp}_1 \triangledown {p^\sharp}'_2) \tag{17b}$$

$$\text{for all increasing chains } {p^\sharp}^k, k \geq 0, \text{ the chain } \hat{X}^0 = {p^\sharp}^0, \ldots, \hat{X}^{k+1} = \hat{X}^k \triangledown {p^\sharp}^k, \ldots \text{ is not strictly increasing for } \preceq^\sharp \tag{17c}$$

with the following convergence property showing how to compute upper-approximations of the least fixpoint starting from below:

Proposition 31 (Upward abstract iteration sequence with widening). If $F^\sharp \in P^\sharp(\sqsubseteq^\sharp) \xrightarrow{c} P^\sharp(\sqsubseteq^\sharp)$, $F^\sharp \in P^\sharp(\preceq^\sharp) \xrightarrow{m} P^\sharp(\preceq^\sharp)$, $\triangledown$ *is a widening operator and* $\forall k \in \mathbb{N} : {p^\sharp}^k \preceq^\sharp {p^\sharp}' \Rightarrow \sqcup^\sharp_{k \in \mathbb{N}} {p^\sharp}^k \preceq^\sharp {p^\sharp}'$, *then the increasing chain* $\hat{X}^0 = \bot^\sharp$, $\hat{X}^{k+1} = \hat{X}^k \triangledown F^\sharp(\hat{X}^k)$ *for* $k \in \mathbb{N}$ *is stationary with limit* $\hat{X}^\ell$ *such that* $lfp\, F^\sharp \preceq^\sharp \hat{X}^\ell$.

PROOF. Since $\preceq^\sharp$ is reflexive, we have ${F^\sharp}^0 = \bot^\sharp \preceq^\sharp \bot^\sharp = \hat{X}^0$. Assume ${F^\sharp}^k \preceq^\sharp \hat{X}^k$ then ${F^\sharp}^{k+1} = F^\sharp({F^\sharp}^k) \preceq^\sharp F^\sharp(\hat{X}^k)$ by monotony whence $\hat{X}^k \preceq^\sharp \hat{X}^{k+1}$ and ${F^\sharp}^{k+1} \preceq^\sharp \hat{X}^{k+1}$ by (17b) and $\hat{X}^{k+1} = \hat{X}^k \triangledown F^\sharp(\hat{X}^k)$. It follows that the chain $\hat{X}^k$, $k \geq 0$ hence by monotony $F^\sharp(\hat{X}^k)$, $k \geq 0$ is increasing but not strictly by (17c). For the limit $\hat{X}^\ell$ where $\ell \in \mathbb{N}$, we have ${F^\sharp}^k \preceq^\sharp \hat{X}^k \preceq^\sharp \hat{X}^\ell$ for all $k \leq \ell$. Moreover, if $m \geq \ell$ and ${F^\sharp}^m \preceq^\sharp \hat{X}^m = \hat{X}^\ell$, then $\hat{X}^{m+1} = \hat{X}^m \triangledown F^\sharp(\hat{X}^m) = \hat{X}^\ell \triangledown F^\sharp(\hat{X}^\ell) = \hat{X}^\ell$. It follows that $\forall k \in \mathbb{N} : {F^\sharp}^k \preceq^\sharp \hat{X}^\ell$, whence $lfp\, F^\sharp = \sqcup^\sharp_{k \in \mathbb{N}} {F^\sharp}^k \preceq^\sharp \hat{X}^\ell$. □

Once again one can imagine a number of weaker hypotheses on the widening operator, such as expressing correctness criteria (17) with respect to concrete properties, using widenings based upon all previous iterates and depending upon the rank of the iterates (so as for example to be able to speed up convergence by loosing more information as iteration time passes), using chaotic iterations with one widening operator only along each cycle in the dependence graph of the system of equations, etc. Proposition 31 only shows the way. Moreover, it is not always necessary to wait for the iterates to stabilize since for example, by Tarski's theorem [141], if the computational ordering $\sqsubseteq^\sharp$ coincides with the approximation $\preceq^\sharp$ ordering then $F^\sharp(\hat{X}^\ell) \preceq^\sharp \hat{X}^\ell$ implies $lfp\, F^\sharp \preceq^\sharp \hat{X}^\ell$.

Observe that [11], [10] and [83] use an infinite domain and a nonmonotone widening operator that enlarges, in a nonunique way, the denoted set of terms. This so-called *restriction* operation on normal types/abstract substitutions consists in removing from a type graph the paths of forward arcs where the number of occurrences of the same functor is greater than some given fixed constant. To do so, a cyclic graph is created describing infinitely many trees by paths of all possible lengths. It is also observed that to get more precise analyses, application of the restriction algorithm could be delayed until a diverging computation is observed for recursive calls. Finally, since the widening is not necessarily monotone, proposition 28 on chaotic iterations no longer applies so that the precision on the result may depend upon the chaotic iteration strategy which is chosen (but not its soundness).

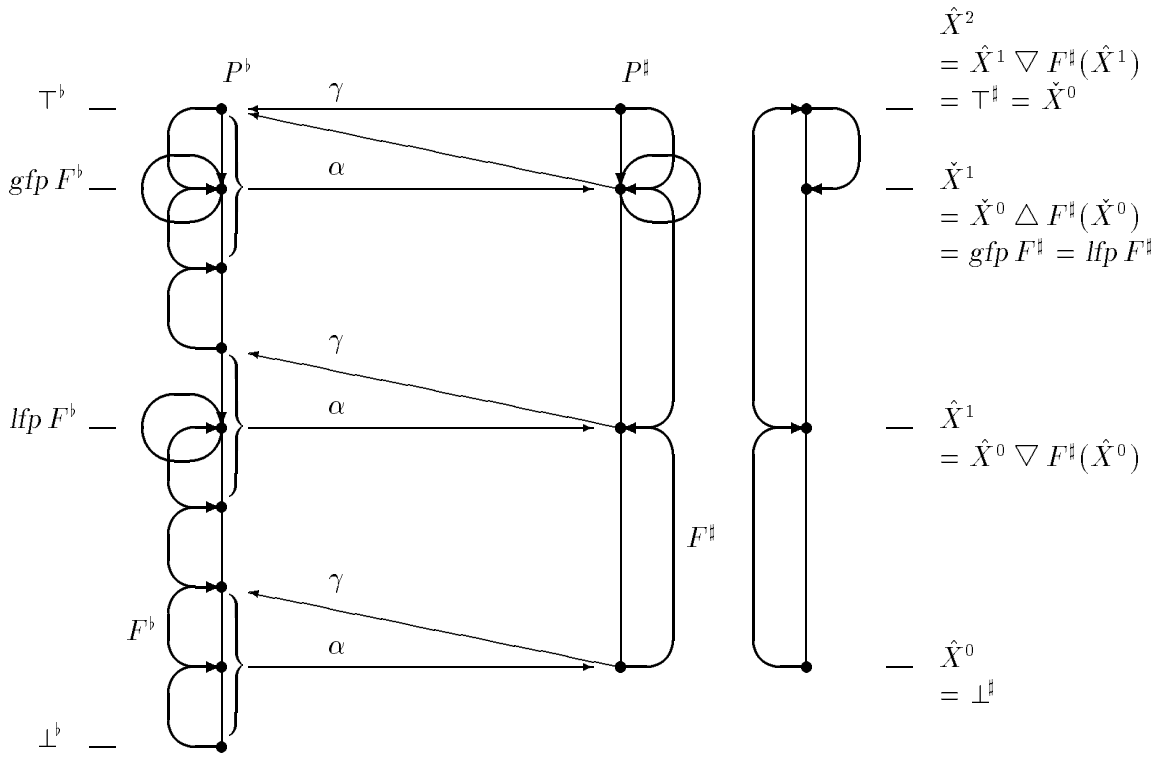


FIGURE 9. Fixpoint approximation using a Galois connection, a widening and a narrowing.

4.3.3. Upward and Downward Abstract Iteration Sequences

In practice, one first uses an upward abstract iteration sequence with widening to obtain an upper-approximation of the least fixpoint starting from below and then a downward abstract iteration sequence with narrowing so as to improve this upper bound while remaining above any fixpoint. This is illustrated in Figure 9.

Example 32 (Interval analysis). In order to analyse the possible values of integer variables, [28] and [29] introduced the abstraction $\alpha \in P^\flat(\subseteq) \mapsto P^\sharp(\preceq^\sharp)$ where $P^\flat = \wp(\mathbb{Z})$, $P^\sharp = \{[\ell, u] \mid \ell \in \mathbb{Z} \cup \{-\infty\} \ \wedge \ u \in \mathbb{Z} \cup \{+\infty\} \ \wedge \ \ell \leq u\} \cup \{\emptyset\}$, $min\,\mathbb{Z} = -\infty$, $max\,\mathbb{Z} = +\infty$ such that $\alpha(\emptyset) = \emptyset$ and $\alpha(X) = [min\, X, max\, X]$. The computational ordering $\sqsubseteq^\sharp$ and approximation ordering $\preceq^\sharp$ are identical and defined by $\emptyset \preceq^\sharp I$ for all $I \in P^\sharp$ and $[a,b] \preceq^\sharp [c,d]$ if and only if $c \leq a \wedge b \leq d$. Since $P^\sharp$ has infinite strictly increasing chains, it is necessary to introduce a widening operator such that for all intervals $I \in P^\sharp$, $\emptyset \triangledown I = I \triangledown \emptyset = I$ and $[a,b] \triangledown [c,d] =$ [if $c < a$ then $-\infty$ else a, if $d > b$ then $+\infty$ else b]. The strictly decreasing chains of the abstract lattice $P^\sharp$ are all finite but can be very long so that it is useful to define a narrowing such that for all intervals $I \in P^\sharp$, $\emptyset \triangle I = I \triangle \emptyset = \emptyset$ and $[a,b] \triangle [c,d] =$ [if $a = -\infty$ then c else a, if $b = +\infty$ then d else b].

The analysis of the output of the following PROLOG II program:

```
program   -> init(x,1) while(x);
init(x,x) -> ;
while(x)  -> val(inf(x,100),1) out(x) line val(add(x,2),y)
             while(y);
```

consists in solving the equation:

$$X = \Big([1,1] \sqcup (X \oplus [2,2])\Big) \sqcap [-\infty, 99]$$

where $\emptyset \oplus I = I \oplus \emptyset = \emptyset$ and $[a,b] \oplus [c,d] = [a \dot{+} c, b \dot{+} d]$ with $-\infty \dot{+} x = x \dot{+} -\infty = -\infty$ and $+\infty \dot{+} x = x \dot{+} +\infty = +\infty$. The ascending abstract iteration sequence with widening is the

following:

$$\hat{X}^0 = \emptyset$$
$$\hat{X}^1 = \hat{X}^0 \triangledown \Big(([1,1] \sqcup (\hat{X}^0 \oplus [2,2])) \sqcap [-\infty, 99]\Big) = \emptyset \triangledown [1,1] = [1,1]$$
$$\hat{X}^2 = \hat{X}^1 \triangledown \Big(([1,1] \sqcup (\hat{X}^1 \oplus [2,2])) \sqcap [-\infty, 99]\Big) = [1,1] \triangledown [1,3] = [1,+\infty]$$
$$\hat{X}^3 = \hat{X}^2 \triangledown \Big(([1,1] \sqcup (\hat{X}^2 \oplus [2,2])) \sqcap [-\infty, 99]\Big) = [1,1] \triangledown [1,99] = [1,+\infty]$$

The descending abstract iteration sequence with narrowing is now:

$$\check{X}^0 = \hat{X}^3 = [1,+\infty]$$
$$\check{X}^1 = \check{X}^0 \triangle \Big(([1,1] \sqcup (\check{X}^0 \oplus [2,2])) \sqcap [-\infty, 99]\Big) = [1,+\infty] \triangle [1,99] = [1,99]$$
$$\check{X}^2 = \check{X}^1 \triangle \Big(([1,1] \sqcup (\check{X}^1 \oplus [2,2])) \sqcap [-\infty, 99]\Big) = [1,99] \triangle [1,99] = [1,99]$$

Observe that the analysis time does not depend upon the number of iterations in the while-loop which would be the case without using widening and narrowing operators. □

4.3.4. A Compromise Between Relational and Attribute Independent Analyses Using Widenings

Since relational analyses are powerful but expansive whereas attribute independent analyses are cheaper but less precise, the use of widening operators may offer an interesting compromise. For example, if $P^{\sharp^i}$ is the lattice $\{\bot, \text{G}, \text{NG}, \top\}$ for groundness analysis of term t_i then the down-set completion $P^\sharp$ of the reduced product $\prod_{i=1}^n P^{\sharp^i}$ can express dependencies between groundness properties of arguments of atoms $p(t_1, \ldots, t_n)$. By proposition 18, elements of $P^\sharp$ can be represented by subsets of $\prod_{i=1}^n \{\text{G}, \text{NG}\}$ in which case strictly increasing chains in $P^\sharp$ have a maximal size of $O(2^n)$. Expressing dependencies between the different arguments of all atoms in the program would be even more expansive [53]. This cost can be cut down using a widening operator. A brute force one would be $X \triangledown Y \stackrel{\text{def}}{=}$ if Cardinality$(Y) \leq \ell(n)$ then $X \cup Y$ else $\prod_{i=1}^n \{\text{G}, \text{NG}\}$ where $\ell(n)$ is a parameter which can be adjusted to tune the cost/performance ratio.

5. OPERATIONAL AND COLLECTING SEMANTICS

Abstract interpretations of programs must be proved correct with respect to a standard semantics of these programs. Following [26], the standard semantics that we will choose is operational. A popular alternative is to choose a denotational semantics. But this choice would be less fundamental since denotational semantics can be derived from the operational semantics by abstract interpretation [43].

It is possible to group program properties into classes, such as invariance and liveness properties, for which all correctness proofs of abstract interpretations of one class will essentially be the same, but for the particular abstract properties which are chosen in the class. By giving a correctness proof of the abstract interpretation for the strongest property in the class, we can factor all these proofs out into two independent steps. First, a fixpoint collecting semantics is given which characterizes the strongest property in the class of interest. It is proved correct with respect to the standard semantics. Second, abstract interpretations in the given class are proved correct with respect to the corresponding collecting semantics.

There are many other interests in this separation process. The collecting semantics is sound but usually also complete with respect to the considered class of program properties. Hence it can serve as a basis for developing program correctness proof methods [27]. Knowledge about the considered class of properties can be usefully incorporated once for all into the collecting semantics. For example [128] and [68] observed that invariance properties can always be proved

using sets of states attached to program points and this was incorporated into the *static semantics* of [29]. Another example, recalled in paragraph 4.2.3.6., is given in [34] (example 6.2.0.2) where it is shown how relational invariants can be decomposed into attribute independent ones (where relationships between variables are lost). Taken together these two examples show that an abstract interpretation can be decomposed into what concerns control and what concerns data, the two aspects being treated separately. Using combination methods as proposed in [34] and recalled in section 4.2.3., this leads to a modular design of abstract interpreters. In doing so, useful abstract interpretations can be easily transferred from one language to another.

Another important step was taken in [26] where it was understood that collecting semantics can be studied in abstracto, independently of a particular language. For example, the static semantics of [29] was expressed using transition systems (due to [93]) hence in a language independent manner. The difficulty of generalizing program points for expression languages was solved by understanding them as the more general technique of covering the concrete domain by partitions, partial equivalence relations or other covers.

Choosing once for all a particular collecting semantics and claiming that it is the only sensible alternative would lead to rigid approximation decisions which could later turn out to be impractical (for example by approximating functions by functions whereas tuples (as in type checking) or relations (between argument values and results) can do better) and to rule out analysing program properties which are forgotten by the collecting semantics, or very difficult to express in the chosen framework (such as execution order). Therefore, we proceed by working out meta-collecting semantics, where 'meta' means language independent and easily instantiable for particular programming languages, and by relating them by abstract interpretations, so as to understand this family of collecting semantics as a set of possible intermediate steps in the approximation of program executions.

To illustrate this approach for logic programming languages, we will chose here to start from an operational point of view formalized by transition systems. We will consider invariance properties which are characterized as fixpoints of predicate transformers. This will be first done in a language independent way. Later, these results will be instantiated for logic programs.

Abstract interpretation is mostly used to derive an abstract semantics from a concrete semantics. But the contrary is also possible. For example in [104] the standard domains of goals is the abstract domain, while the concrete domain is a new one containing timing information.

5.1. Operational Semantics as Transition Systems

The small-steps operational semantics of a programming language $\mathfrak{L}$ associates a transition system $\langle \mathfrak{S}, \mathfrak{I}, \mathfrak{F}, \vdash \mathtt{P} \rightarrow \rangle$ to each program $\mathtt{P}$ of the language. $\mathfrak{S}$ is a set of states, $\mathfrak{I} \subseteq \mathfrak{S}$ is the set of initial states, $\mathfrak{F} \subseteq \mathfrak{S}$ is the set of final states while $\vdash \mathtt{P} \rightarrow \in \wp(\mathfrak{S} \times \mathfrak{S})$ is a transition relation between a state and its possible successors. The idea is that program execution starts with some initial state $s_0 \in \mathfrak{I}$. After i execution steps leading to state $s_i \in \mathfrak{S}$ a further execution step can lead to any successor state $s_{i+1} \in \mathfrak{S}$ as given by the transition relation so that $s_i \vdash \mathtt{P} \rightarrow s_{i+1}$. This execution can either run for ever or else terminate either with a final state $s_n \in \mathfrak{F}$ or with a blocking state without successor for the transition relation. A familiar example which will be developed later is SLD-resolution for logic programs. An initial state consists of an initial goal and the empty substitution. A final state has an empty goal and an answer substitution. A state is simply a current goal and a substitution. A transition consists in unifying a selected atom in the goal with the head of a program clause and in replacing it by a unified instance of the body of the clause in the new goal together with a new substitution obtained by composition of the old one with the most general unifier.

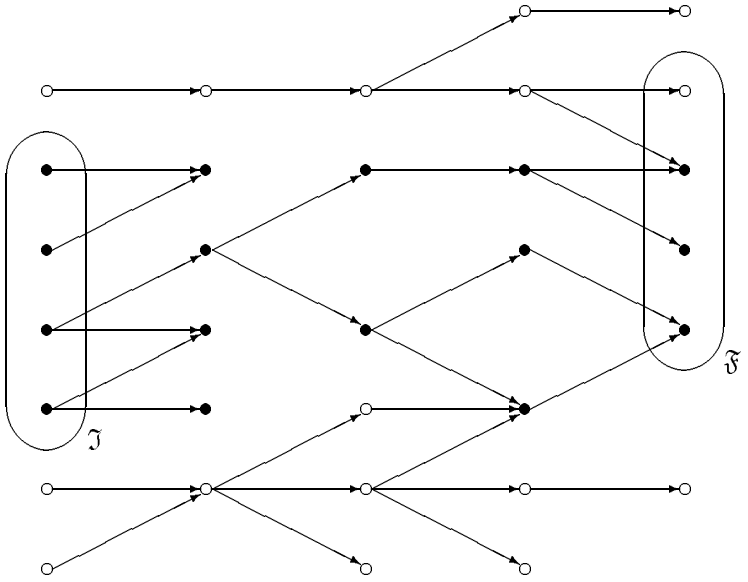


FIGURE 10. Descendant states ($\bullet$) of the initial states ($\mathfrak{I}$).

5.2. Top/Down — Forward Collecting Semantics

The top/down (also called forward) collecting semantics characterizes the descendant states of the initial states as illustrated in Figure 10 For logic programs, the set of descendant states of the initial states provides information about all calls for a given initial question regardless of whether they succeed, finitely fail or do not terminate.

Given a relation $t \in \wp(S \times S)$, its *transitive closure* is $t^\star = \bigcup_{n\in\mathbb{N}} t^n$ where $t^0 = 1 = \{\langle s, s\rangle \mid s = s'\}$, $t^{n+1} = t \circ t^n = t^n \circ t$ and $t \circ t' = \{\langle s, s''\rangle \mid \exists s' : \langle s, s'\rangle \in t \wedge \langle s', s''\rangle \in t'\}$. The fundamental fixpoint characterization of transitive closures is that $t^\star = lfp\, T$ where $T \in \wp(S \times S)(\cup) \stackrel{a}{\longmapsto} \wp(S \times S)(\cup)$ is defined by $T(X) = 1 \cup X \circ t$.

The top/down collecting semantics for program $\mathtt{P}$ is the set $\mathfrak{D}$ of descendant states of the initial states, that is $\mathfrak{D} = \{s \mid \exists s' \in \mathfrak{I} : s' \vdash \mathtt{P} \rightarrow^\star s\}$ which can be written $post[\vdash \mathtt{P} \rightarrow^\star]\mathfrak{I}$ by defining:

$$post \in \wp(\mathfrak{S} \times \mathfrak{S}) \mapsto (\wp(\mathfrak{S}) \mapsto \wp(\mathfrak{S})) \qquad post[t]X \stackrel{\text{def}}{=} \{s \mid \exists s' \in X : \langle s', s\rangle \in t\} \tag{18}$$

Using the fixpoint inducing proposition 23, we can use the above fixpoint characterization of transitive closures to provide a fixpoint definition of this top/down collecting semantics:

Proposition 33 (Fixpoint characterization of the top/down collecting semantics). $\mathfrak{D} = lfp\, F[\![\mathtt{P}]\!]$ *where* $F[\![\mathtt{P}]\!] \in \wp(S)(\cup) \stackrel{a}{\longmapsto} \wp(S)(\cup)$ *is defined by* $F[\![\mathtt{P}]\!]X = \mathfrak{I} \cup post[\vdash \mathtt{P} \rightarrow]X$.

PROOF. Observe that $\wp(\mathfrak{S} \times \mathfrak{S})(\subseteq, \emptyset, \mathfrak{S} \times \mathfrak{S}, \cup, \cap)$ and $\wp(\mathfrak{S})(\subseteq, \emptyset, \mathfrak{S}, \cup, \cap)$ are complete lattices. Define $\alpha \in \wp(\mathfrak{S} \times \mathfrak{S}) \mapsto \wp(\mathfrak{S})$ by $\alpha(X) = post[X]\mathfrak{I}$. It is a complete $\cup$-morphism so that by proposition 7 there exists γ such that $\wp(\mathfrak{S} \times \mathfrak{S})(\subseteq) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} \wp(\mathfrak{S})(\subseteq)$. We have $\vdash \mathtt{P}^\star \rightarrow = lfp\, T = \bigcup_{n\in\mathbb{N}} T^n(\emptyset)$ where $T(X) = 1 \cup X \circ \vdash \mathtt{P} \rightarrow$, $\emptyset = \alpha(\emptyset)$ and $F[\![\mathtt{P}]\!] \in \wp(S)(\cup) \stackrel{a}{\longmapsto} \wp(S)(\cup)$ is such that for all $X \in \wp(\mathfrak{S} \times \mathfrak{S})$, we have $\alpha \circ T(X) = post[T(X)]\mathfrak{I} = \{s \mid \exists s' \in \mathfrak{I} : \langle s', s\rangle \in T(X)\}$ $= \{s \mid \exists s' \in \mathfrak{I} : \langle s', s\rangle \in 1 \cup X \circ \vdash \mathtt{P} \rightarrow\} = \{s \mid \exists s' \in \mathfrak{I} : (\langle s', s\rangle \in 1) \vee (\langle s', s\rangle \in X \circ \vdash \mathtt{P} \rightarrow)\}$ $= \{s \mid \exists s' \in \mathfrak{I} : (s' = s) \vee (\langle s', s\rangle \in X \circ \vdash \mathtt{P} \rightarrow)\} = \mathfrak{I} \cup \{s \mid \exists s' \in \mathfrak{I} : \langle s', s\rangle \in X \circ \vdash \mathtt{P} \rightarrow\}$ $= \mathfrak{I} \cup \{s \mid \exists s' \in \mathfrak{I} : \exists s'' \in \mathfrak{S} : \langle s', s''\rangle \in X \wedge s'' \vdash \mathtt{P} \rightarrow s\} = \mathfrak{I} \cup \{s \mid \exists s'' \in \{s'' \mid \exists s' \in \mathfrak{I} : \langle s', s''\rangle \in X\} : s'' \vdash \mathtt{P} \rightarrow s\} = \mathfrak{I} \cup \{s \mid \exists s'' \in post[X]\mathfrak{I} : s'' \vdash \mathtt{P} \rightarrow s\} = \mathfrak{I} \cup post[\vdash \mathtt{P} \rightarrow](post[X]\mathfrak{I})$ $= F[\![\mathtt{P}]\!](post[X]\mathfrak{I}) = F[\![\mathtt{P}]\!] \circ \alpha(X)$. By proposition 23, we have $\alpha(lfp\, T) = lfp\, F[\![\mathtt{P}]\!]$ so that $\mathfrak{D} = post[\vdash \mathtt{P} \rightarrow^\star]\mathfrak{I} = \alpha(\vdash \mathtt{P} \rightarrow^\star) = \alpha(lfp\, T) = lfp\, F[\![\mathtt{P}]\!]$. □

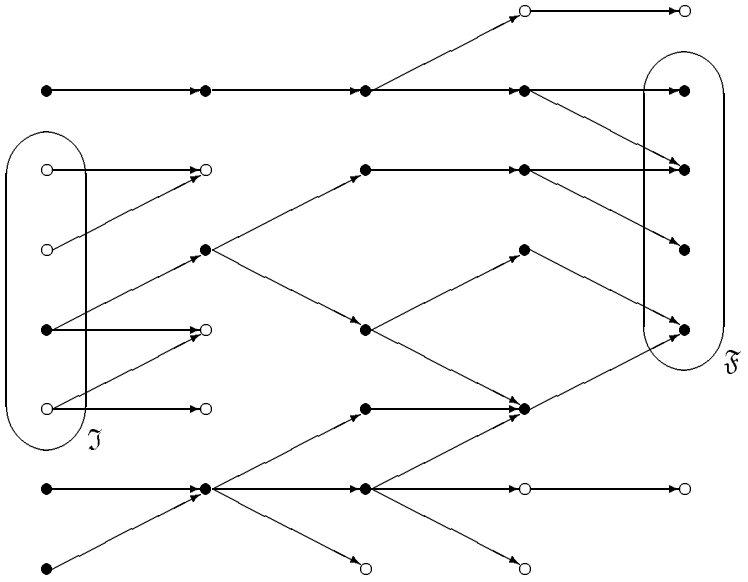


FIGURE 11. Ascendant states ($\bullet$) of the final states ($\mathfrak{F}$).

5.3. Bottom/Up — Backward Collecting Semantics

The bottom/up (also called backward) collecting semantics characterizes the ascendant states of the final states as illustrated in Figure 11. For logic programs, the set of ascendant states of the final states provides information about atoms that can succeed.

The bottom/up collecting semantics for program $\mathtt{P}$ is the set $\mathfrak{A}$ of ascendant states of the final states, that is $\mathfrak{A} = \{s \mid \exists s' \in \mathfrak{F} : s \vdash \mathtt{P} \rightarrow s'\}$ which can be written $pre[\vdash \mathtt{P} \rightarrow^\star]\mathfrak{F}$ by defining:

$$pre \in \wp(\mathfrak{S} \times \mathfrak{S}) \mapsto (\wp(\mathfrak{S}) \mapsto \wp(\mathfrak{S})) \qquad pre[t]X \stackrel{\text{def}}{=} \{s \mid \exists s' \in X : \langle s, s' \rangle \in t\} \qquad (19)$$

Observe that the ascendant states $\mathfrak{A}$ of the final states $\mathfrak{F}$ of the transition system $\langle \mathfrak{S}, \mathfrak{I}, \mathfrak{F}, \vdash \mathtt{P} \rightarrow \rangle$ is precisely the set of descendant states of the initial states of the inverse transition system $\langle \mathfrak{S}, \mathfrak{F}, \mathfrak{I}, \vdash \mathtt{P} \rightarrow^{-1} \rangle$ where the inverse t^{-1} of a relation $t \in \wp(S \times S)$ is $\{\langle s', s \rangle \mid \langle s, s' \rangle \in t\}$. For that reason it is traditional not to explicitly study the backward abstract interpretations since, from a theoretical point of view, they are essentially the same as the forward ones (provided adequate, that is invertible, collecting semantics are considered, an handicap for denotational semantics). For example, we have:

Proposition 34 (Fixpoint characterization of the bottom/up collecting semantics). $\mathfrak{A} = lfp\, B[\![\mathtt{P}]\!]$ *where* $B[\![\mathtt{P}]\!] \in \wp(S)(\cup) \stackrel{a}{\longmapsto} \wp(S)(\cup)$ *is defined by* $B[\![\mathtt{P}]\!]X = pre[\vdash \mathtt{P} \rightarrow]X \cup \mathfrak{F}$.

PROOF. Using the fact that $(t^\star)^{-1} = (t^{-1})^\star$ and $pre[t]X = post[t^{-1}]X$, we have $\mathfrak{A} = pre[\vdash \mathtt{P} \rightarrow^\star]\mathfrak{F} = post[(\vdash \mathtt{P} \rightarrow^\star)^{-1}]\mathfrak{F} = post[(\vdash \mathtt{P} \rightarrow^{-1})^\star]\mathfrak{F} = lfp\, \lambda\, X \cdot \mathfrak{F} \cup post[(\vdash \mathtt{P} \rightarrow)^{-1}]X$ by proposition 33, which is equal to $lfp\, \lambda\, X \cdot pre[\vdash \mathtt{P} \rightarrow]X \cup \mathfrak{F} = lfp\, B[\![\mathtt{P}]\!]$. □

5.4. Combining the Top/Down — Forward and Bottom/Up — Backward Collecting Semantics

In practice, we are interested by programs that succeed, so that the program interpreter should not enter dead-ends, that is states for which execution can only fail or not terminate properly. Therefore, we are interested in characterizing the descendant states of the initial states which are also ascendant states of the final states, as shown in Figure 12. The set of descendant states of the initial states which are the ascendant states of the final states of a transition system $\langle \mathfrak{S}, \mathfrak{I}, \mathfrak{F}, \vdash \mathtt{P} \rightarrow \rangle$ corresponding to a program $\mathtt{P}$ is characterized by $\mathfrak{D} \cap \mathfrak{A} = lfp\, F[\![\mathtt{P}]\!] \cap lfp\, B[\![\mathtt{P}]\!]$.

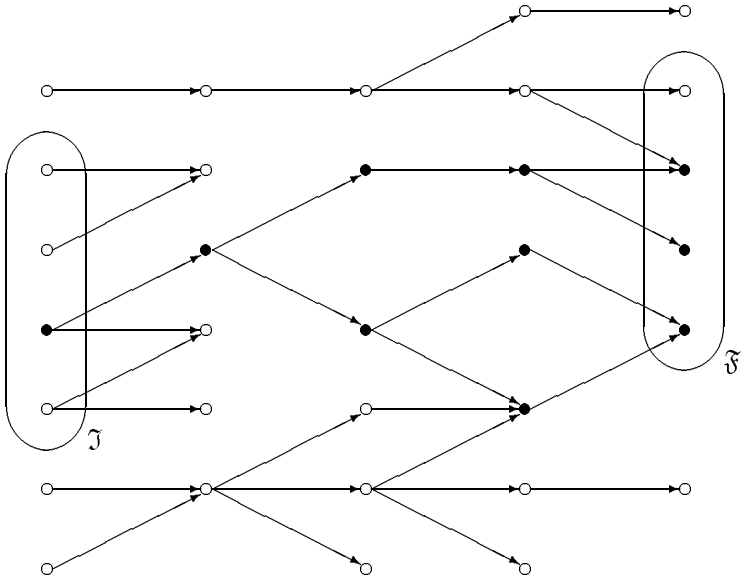


FIGURE 12. Descendant states ($\bullet$) of the initial states ($\mathfrak{I}$) which are ascendant states of the final states ($\mathfrak{F}$).

In order to justify the technique later used to approximate this meet of fixpoints, we will use the following properties ([25]):

Proposition 35 (Fixpoint properties of collecting semantics). For all transition systems $\langle \mathfrak{S}, \mathfrak{I}, \mathfrak{F}, \vdash \mathtt{P} \rightarrow \rangle$ *and* $I \subseteq \mathfrak{S}$, *we have:*

$$1^\circ \qquad (pre[\vdash \mathtt{P} \rightarrow]X) \cap lfp\, F[\![\mathtt{P}]\!] \subseteq pre[\vdash \mathtt{P} \rightarrow](X \cap lfp\, F[\![\mathtt{P}]\!])$$

$$2^\circ \qquad (post[\vdash \mathtt{P} \rightarrow]X) \cap lfp\, B[\![\mathtt{P}]\!] \subseteq post[\vdash \mathtt{P} \rightarrow](X \cap lfp\, B[\![\mathtt{P}]\!])$$

$$lfp\, F[\![\mathtt{P}]\!] \cap lfp\, B[\![\mathtt{P}]\!]$$

$$3^\circ \qquad = lfp\, \lambda\, X.(lfp\, F[\![\mathtt{P}]\!] \cap B[\![\mathtt{P}]\!]X)$$

$$4^\circ \qquad = lfp\, \lambda\, X.(lfp\, B[\![\mathtt{P}]\!] \cap F[\![\mathtt{P}]\!]X)$$

$$5^\circ \qquad = lfp\, \lambda\, X.(lfp\, F[\![\mathtt{P}]\!] \cap lfp\, B[\![\mathtt{P}]\!] \cap B[\![\mathtt{P}]\!]X)$$

$$6^\circ \qquad = lfp\, \lambda\, X.(lfp\, F[\![\mathtt{P}]\!] \cap lfp\, B[\![\mathtt{P}]\!] \cap F[\![\mathtt{P}]\!]X)$$

PROOF. — To prove 1°, observe that (19) and proposition 33 imply that $(pre[\vdash \mathtt{P} \rightarrow]X) \cap lfp\, F[\![\mathtt{P}]\!] = \{s \mid \exists s' \in X : s \vdash \mathtt{P} \rightarrow s'\} \cap \{s \mid \exists s'' \in \mathfrak{I} : s'' \vdash \mathtt{P} \rightarrow^\star s\} \subseteq \{s \mid \exists s' \in X : \exists s'' \in \mathfrak{I} : s'' \vdash \mathtt{P} \rightarrow^\star s' \wedge s \vdash \mathtt{P} \rightarrow s'\}$ since $s'' \vdash \mathtt{P} \rightarrow^\star s$ and $s \vdash \mathtt{P} \rightarrow s'$ imply $s'' \vdash \mathtt{P} \rightarrow^\star s'$. This is precisely $pre[\vdash \mathtt{P} \rightarrow](X \cap post[\vdash \mathtt{P} \rightarrow^\star]\mathfrak{I}) = pre[\vdash \mathtt{P} \rightarrow](X \cap lfp\, F[\![\mathtt{P}]\!])$. The proof of 2° is similar to that of 1°.

— To prove 3°, let $X^n, n \in \mathbb{N}$ and $Y^n, n \in \mathbb{N}$ be the iteration sequences starting from the infimum $\emptyset$ for $B[\![\mathtt{P}]\!]$ and $clambda X(lfp\, F[\![\mathtt{P}]\!] \cap B[\![\mathtt{P}]\!]X)$ respectively. We have $lfp\, F[\![\mathtt{P}]\!] \cap X^0 = \emptyset = Y^0$. Assume that $lfp\, F[\![\mathtt{P}]\!] \cap X^n \subseteq Y^n$ by induction hypothesis. Then $lfp\, F[\![\mathtt{P}]\!] \cap X^{n+1} = lfp\, F[\![\mathtt{P}]\!] \cap B[\![\mathtt{P}]\!](X^n) = lfp\, F[\![\mathtt{P}]\!] \cap (pre[\vdash \mathtt{P} \rightarrow]X^n \cup \mathfrak{F}) = lfp\, F[\![\mathtt{P}]\!] \cap \Big((pre[\vdash \mathtt{P} \rightarrow]X^n \cap lfp\, F[\![\mathtt{P}]\!]) \cup \mathfrak{F}\Big)$, which, by 1°, is included in $lfp\, F[\![\mathtt{P}]\!] \cap \Big(pre[\vdash \mathtt{P} \rightarrow](X^n \cap lfp\, F[\![\mathtt{P}]\!]) \cup \mathfrak{F}\Big)$ which, by induction hypothesis and monotony, is included in $lfp\, F[\![\mathtt{P}]\!] \cap (pre[\vdash \mathtt{P} \rightarrow](Y^n) \cup \mathfrak{F}) = lfp\, F[\![\mathtt{P}]\!] \cap B[\![\mathtt{P}]\!]Y^n = Y^{n+1}$. It follows that $lfp\, F[\![\mathtt{P}]\!] \cap lfp\, B[\![\mathtt{P}]\!] = (\cup_{n \in \mathbb{N}} X^n) \cap lfp\, F[\![\mathtt{P}]\!] = \cup_{n \in \mathbb{N}} (X^n \cap lfp\, F[\![\mathtt{P}]\!]) \subseteq \cup_{n \in \mathbb{N}} Y^n = lfp\, \lambda\, X.(lfp\, F[\![\mathtt{P}]\!] \cap B[\![\mathtt{P}]\!]X)$. But lfp is monotone so that $lfp\, \lambda\, X.(lfp\, F[\![\mathtt{P}]\!] \cap B[\![\mathtt{P}]\!]X) \subseteq lfp\, \lambda\, X.(lfp\, F[\![\mathtt{P}]\!]) \cap lfp\, \lambda\, X.(B[\![\mathtt{P}]\!]X) = lfp\, F[\![\mathtt{P}]\!] \cap lfp\, B[\![\mathtt{P}]\!]$. Equality follows by antisymmetry. The proofs of 4° to 6° are similar. □

6. COMBINING TOP/DOWN-FORWARD AND BOTTOM/UP-BACKWARD ABSTRACT INTERPRETATION

In order to approximate $lfp\, F^\flat \wedge^\flat lfp\, B^\flat$ from above using abstract interpretations $F^\sharp$ of $F^\flat$ and $B^\sharp$ of $B^\flat$, we can use the abstract upper approximation $lfp\, F^\sharp \wedge^\sharp lfp\, B^\sharp$. However, a better approximation suggested in [25] can be obtained as the limit of the decreasing chain $\dot{X}^0 = lfp\, F^\sharp$ and $\dot{X}^{2n+1} = lfp\, \lambda\, X \cdot \dot{X}^{2n} \wedge^\sharp F^\sharp(X)$, $\dot{X}^{2n+2} = lfp\, \lambda\, X \cdot \dot{X}^{2n+1} \wedge^\sharp B^\sharp(X)$ for all $n \in \mathbb{N}$. Observe that by proposition **35** there is no improvement when considering the exact collecting semantics. However, when considering approximations of the collecting semantics, not all information can be collected in one pass. So the idea is to propagate the initial conditions top/down so as to get conditions on applicability of the unit clauses. These conditions are then propagated bottom/up to get stronger necessary conditions to be satisfied by the initial goal for possible success. This restricts the possible subgoals as indicated by the next top/down pass. Going on this way, the available information on the descendant states of the initial states which are ascendant states of the final states can be improved on each successive pass, until convergence. A similar scheme was used independently by [91] to infer types in flowchart programs. If the abstract lattice does not satisfy the descending chain condition then [25] also suggests to use a narrowing operator $\triangle$ to enforce convergence of the downward iteration $\dot{X}^k, k \in \mathbb{N}$. The same way a widening/narrowing approach can be used to enforce convergence of the iterates for $\lambda\, X \cdot \dot{X}^{2n} \wedge^\sharp F^\sharp(X)$ and $\lambda\, X \cdot \dot{X}^{2n+1} \wedge^\sharp B^\sharp(X)$. The correctness of this approach follows from:

Proposition 36 (Fixpoint meet approximation). If $P^\flat(\preceq^\flat, f^\flat, t^\flat, \wedge^\flat, \vee^\flat)$ *and* $P^\sharp(\preceq^\sharp, f^\sharp, t^\sharp, \wedge^\sharp, \vee^\sharp)$ *are complete lattices,* $P^\flat(\preceq^\flat) \underset{\alpha^\flat}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\preceq^\sharp)$, $F^\flat \in P^\flat(\preceq^\flat) \overset{m}{\longmapsto} P^\flat(\preceq^\flat)$ *and* $B^\flat \in P^\flat(\preceq^\flat) \overset{m}{\longmapsto} P^\flat(\preceq^\flat)$ *satisfy hypotheses 5°) and 6°) of proposition 35,* $F^\sharp \in P^\sharp(\preceq^\sharp) \overset{m}{\longmapsto} P^\sharp(\preceq^\sharp)$, $B^\sharp \in P^\sharp(\preceq^\sharp) \overset{m}{\longmapsto} P^\sharp(\preceq^\sharp)$, $\alpha \circ F^\flat \circ \gamma \preceq^\sharp F^\sharp$, $\alpha \circ B^\flat \circ \gamma \preceq^\sharp B^\sharp$, $\dot{X}^1$ *is* $lfp\, F^\sharp$ *or* $lfp\, B^\sharp$ *and for all* $n \in \mathbb{N}$, $\dot{X}^{2n+1} = lfp\, \lambda\, X \cdot (\dot{X}^{2n} \wedge^\sharp B^\sharp(X))$ *and* $\dot{X}^{2n+2} = lfp\, \lambda\, X \cdot (\dot{X}^{2n+1} \wedge^\sharp F^\sharp(X))$ *then* $\forall k \in \mathbb{N} : \alpha(lfp\, F^\flat \wedge^\flat lfp\, B^\flat) \preceq^\sharp \dot{X}^{k+1} \preceq^\sharp \dot{X}^k$.

PROOF. Observe that by the fixpoint property, $\dot{X}^{2n+1} = \dot{X}^{2n} \wedge^\sharp B^\sharp(\dot{X}^{2n+1})$ and $\dot{X}^{2n+2} = \dot{X}^{2n+1} \wedge^\sharp F^\sharp(\dot{X}^{2n+2})$, hence $\dot{X}^{2n} \preceq^\sharp \dot{X}^{2n+1} \preceq^\sharp \dot{X}^{2n+2}$ since $\wedge^\sharp$ is the greatest lower bound for $\preceq^\sharp$ so that $\dot{X}^k$, $k \in \mathbb{N}$ is a decreasing chain.

We have $\alpha(lfp\, F^\flat \wedge^\flat lfp\, B^\flat) \preceq^\sharp \alpha(lfp\, F^\flat)$ since α is monotone and $\alpha(lfp\, F^\flat) \preceq^\sharp lfp\, F^\sharp$ by propositions 24 and 25, thus proving the proposition for $k = 0$. Let us observe that $\alpha \circ F^\flat \circ \gamma \preceq^\sharp F^\sharp$ implies $F^\flat \circ \gamma \preceq^\flat \gamma \circ F^\sharp$ by (1) so that in particular for an argument of the form $\alpha(X)$, $F^\flat \circ \gamma \circ \alpha \preceq^\flat \gamma \circ F^\sharp \circ \alpha$. By (8), $\gamma \circ \alpha$ is extensive so that by monotony and transitivity $F^\flat \preceq^\flat \gamma \circ F^\sharp \circ \alpha$. Assume now by induction hypothesis that $\alpha(lfp\, F^\flat \wedge^\flat lfp\, B^\flat) \preceq^\sharp \dot{X}^{2n}$, whence $lfp\, F^\flat \wedge^\flat lfp\, B^\flat \preceq^\sharp \gamma(\dot{X}^{2n})$ by (1). Since $F^\flat \preceq^\flat \gamma \circ F^\sharp \circ \alpha$, it follows that $\lambda\, X \cdot lfp\, F^\flat \wedge^\flat lfp\, B^\flat \wedge^\flat F^\flat(X) \preceq^\sharp \lambda\, X \cdot \gamma(\dot{X}^{2n}) \wedge^\flat \gamma \circ F^\sharp \circ \alpha(X) = \lambda\, X \cdot \gamma(\dot{X}^{2n} \wedge^\flat F^\sharp \circ \alpha(X))$ since γ is a complete meet morphism (6). Now by hypothesis 5°) of proposition 35, we have $lfp\, F^\flat \wedge^\flat lfp\, B^\flat = lfp\, \lambda\, X \cdot (lfp\, F^\flat \wedge^\flat lfp\, B^\flat \wedge^\flat F^\flat(X)) \preceq^\sharp lfp\, \lambda\, X \cdot \gamma(\dot{X}^{2n} \wedge^\flat F^\sharp \circ \alpha(X))$ by proposition 25. Let G be $\lambda\, X \cdot \dot{X}^{2n} \wedge^\flat F^\sharp(X)$. By (3), $\alpha \circ \gamma$ is reductive so that by monotony $G \circ \alpha \circ \gamma \preceq^\sharp G$ and $\alpha \circ \gamma \circ G \circ \alpha \circ \gamma \preceq^\sharp G \circ \alpha \circ \gamma$, whence, by transitivity, $\alpha \circ \gamma \circ G \circ \alpha \circ \gamma \preceq^\sharp G$. By proposition 24, we have $\alpha(lfp\, \gamma \circ G \circ \alpha) \preceq^\sharp lfp\, \alpha \circ \gamma \circ G \circ \alpha \circ \gamma \preceq^\sharp lfp\, G$ by proposition 25. Hence, $lfp\, \lambda\, X \cdot \gamma(\dot{X}^{2n} \wedge^\flat F^\sharp \circ \alpha(X)) \preceq^\flat \gamma(lfp\, \lambda\, X \cdot \dot{X}^{2n} \wedge^\flat F^\sharp(X))$ so that by transitivity we conclude that $\alpha(lfp\, F^\flat \wedge^\flat lfp\, B^\flat) \preceq^\sharp \dot{X}^{2n+1}$. The proof that $\alpha(lfp\, F^\flat \wedge^\flat lfp\, B^\flat) \preceq^\sharp \dot{X}^{2n+2}$ is similar using hypothesis 6°) of proposition 35. □

7. OPERATIONAL AND COLLECTING SEMANTICS OF LOGIC PROGRAMS

7.1. Operational Semantics of Logic Programs

7.1.1. Syntax and Semantic Domains of Logic Programs

Let $\mathfrak{v}$ be an infinite denumerable set of *variable symbols* $\mathtt{X}$, $\mathtt{Y}$, $\mathtt{Z}$, ..., $\mathfrak{f}$ be a family of sets $\mathfrak{f}^i$ of *data constructors* $\mathtt{c}$, $\mathtt{f}$, $\mathtt{g}$, ... of arity $i \geq 0$ and $\mathfrak{p}$ be a family of sets $\mathfrak{p}^i$ of *predicate symbols* $\mathtt{p}$, $\mathtt{q}$, ... of arity $i \geq 0$. The set $\mathfrak{t}$ of *terms* $\mathtt{t}$, ... is defined by $\mathtt{t} ::= \mathtt{X} \mid \mathtt{c} \mid \mathtt{f(t_1, \ldots, t_n)}$ where $\mathtt{X} \in \mathfrak{v}$, $\mathtt{c}$ is a *constant* in $\mathfrak{f}^0$ which is assumed to be non-empty and $\mathtt{f} \in \mathfrak{f}^n$ is a *functor*. The set $\mathfrak{a}$ of *atoms* $\mathtt{a}$, $\mathtt{b}$, ... is defined by $\mathtt{a} ::= \mathtt{p(t_1, \ldots, t_n)}$ where $\mathtt{p} \in \mathfrak{p}^n$ and each $\mathtt{t}_i$ belongs to $\mathfrak{t}$. A *simple expression* is either a term or an atom. The set $\mathfrak{c}$ of *clauses* $\mathtt{c}$, ... is defined by $\mathtt{c} ::= \mathtt{a_0\ ->} \mid \mathtt{a_0\ ->\ a_1 \ldots a_n}$ where each $\mathtt{a}_i$ belongs to $\mathfrak{a}$. $\mathtt{a}_0$ is the *head* of clause $\mathtt{c}$ whereas $\mathtt{a_1 \ldots a_n}$ is its *body*. A *unit clause* of the form $\mathtt{a_0\ ->}$ has an empty body. The set $\mathfrak{L}$ of *programs* $\mathtt{P}$, ... is defined by $\mathtt{P} ::= \mathtt{c_1; \ldots ; c_n;}$ where each $\mathtt{c}_i$ belongs to $\mathfrak{c}$. We define $\mathtt{P}[\ell]$ to be the $\ell^{\text{-th}}$ clause $\mathtt{c}_\ell$ of $\mathtt{P}$. The set $\mathfrak{g}$ of *resolvents* $\mathtt{g}$, ... is defined by $\mathtt{g} ::= \Box \mid \mathtt{b_1 \ldots b_n}\Box$ where each *goal* $\mathtt{b}_i$ is a triplet $\langle a, \ell, i\rangle$ where $\mathtt{a}$ is an atom belonging to $\mathfrak{a}$, $\ell \in \mathbb{N}$ is the rank of a clause $\mathtt{c}_\ell$ in $\mathtt{P}$ and i is the rank of a variant of atom $\mathtt{a}$ in $\mathtt{c}_\ell$. A *state* $s \in \mathfrak{S}$ is a quadruplet $\langle \mathtt{g}, \theta, V, \Theta\rangle$ which consists of a resolvent $\mathtt{g}$, a current substitution θ, a set of (already utilized) variables $V \subseteq \mathfrak{v}$ and an answer substitution Θ.

A *substitution* [101] is a function $\theta \in \mathfrak{s}$ from a finite set $V \subseteq \mathfrak{v}$ of variables to the set $\mathfrak{t}$ of terms such that $\theta(X) \neq X$ for every variable X in the domain V of θ. The *domain* or *support* V of the substitution θ is written $dom\,\theta$. $\{X_1/t_1, \ldots, X_n/t_n\}$ is the substitution θ with domain $dom\,\theta = \{X_1, \ldots, X_n\}$ such that $\theta(X_i) = t_i$ for $i = 1, \ldots, n$. A *renaming* $\rho \in \mathfrak{r}$ is a bijective substitution from $dom\,\rho$ onto $dom\,\rho$ whence a permutation of some finite set of variables. The *identity renaming* ϵ has an empty support. Substitutions are extended as follows:

$$
\begin{array}{rlrl}
\theta(\mathtt{c}) &= \mathtt{c} & \theta(\mathtt{X}) &= \mathtt{X} \quad \text{if } \mathtt{X} \notin dom\,\theta \\
\theta(\mathtt{f(t_1, \ldots, t_n)}) &= \mathtt{f}(\theta(\mathtt{t_1}), \ldots, \theta(\mathtt{t_n})) & \theta(\mathtt{p(t_1, \ldots, t_n)}) &= \mathtt{p}(\theta(\mathtt{t_1}), \ldots, \theta(\mathtt{t_n})) \\
\theta(\mathtt{a_0\text{->}}) &= \theta(\mathtt{a_0})\text{->} & \theta(\mathtt{a_0\text{->}a_1 \ldots a_n}) &= \theta(\mathtt{a_0})\text{->}\theta(\mathtt{a_1}) \ldots \theta(\mathtt{a_n}) \\
\theta(\mathtt{c_1; \ldots ; c_n;}) &= \theta(\mathtt{c_1}); \ldots ; \theta(\mathtt{c_n}); & \theta(\Box) &= \Box \\
\theta(\mathtt{b_1 \ldots b_n}\Box) &= \theta(\mathtt{b_1}) \ldots \theta(\mathtt{b_n})\Box & \theta(\langle \mathtt{a}, \ell, i\rangle) &= \langle \theta(\mathtt{a}), \ell, i\rangle \\
\theta(\langle \mathtt{g}, \Theta, V, \Theta'\rangle &= \langle \theta(\mathtt{g}), \theta \circ \Theta, V \cup vars\,\theta, \Theta'\rangle
\end{array}
\tag{20}
$$

where the *identity-free composition* $\sigma \circ \Theta$ of substitutions σ and Θ is θ such that $dom\,\theta = (dom\,\sigma \cup dom\,\Theta) - \{\mathtt{X} \in \mathfrak{v} \mid \sigma(\Theta(\mathtt{X})) = \mathtt{X}\}$ and for all $\mathtt{X} \in dom\,\theta$ we have $\theta(\mathtt{X}) = \sigma(\Theta(\mathtt{X}))$ and the *free variables* of an expression are inductively defined by:

$$
\begin{array}{rlrl}
vars\,\mathtt{c} &= \emptyset & vars\,\mathtt{X} &= \{\mathtt{X}\} \\
vars\,\mathtt{f(t_1, \ldots, t_n)} &= \cup_{i=1}^n vars\,\mathtt{t}_i & vars\,\mathtt{p(t_1, \ldots, t_n)} &= \cup_{i=1}^n vars\,\mathtt{t}_i \\
vars\,\mathtt{a_0\text{->}} &= vars\,\mathtt{a_0} & vars\,\mathtt{a_0\text{->}a_1 \ldots a_n} &= \cup_{i=0}^n vars\,\mathtt{a}_i \\
vars\,\mathtt{c_1; \ldots ; c_n;} &= \cup_{i=1}^n vars\,\mathtt{c}_i & vars\,\Box &= \emptyset \\
vars\,\mathtt{b_1 \ldots b_n}\Box &= \cup_{i=1}^n vars\,\mathtt{b}_i & vars\,\theta &= dom\,\theta \cup \cup_{\mathtt{X} \in dom\,\theta} vars\,\theta(\mathtt{X}) \\
vars\langle \mathtt{a}, \ell, i\rangle &= vars\,\mathtt{a} & vars\langle \mathtt{g}, \theta, V, \Theta\rangle &= vars\,\mathtt{g} \cup vars\,\theta \cup V
\end{array}
\tag{21}
$$

Two simple expressions which are equal up to variable renaming are called *variants* of each other.

7.1.2. Transition Relation of Logic Programs: SLD-Resolution

Two simple expressions e_1 and e_2 are *unifiable* if and only if there exists a *unifier* of e_1 and e_2 that is a substitution θ such that $\theta(e_1) = \theta(e_2)$. If two simple expressions e_1 and e_2 are not unifiable

then $mgu(e_1, e_2) \stackrel{\text{def}}{=} \emptyset$. If two simple expressions e_1 and e_2 are unifiable then $mgu(e_1, e_2) \stackrel{\text{def}}{=} \{\theta\}$ where θ is a unifier which is *idempotent* ($dom\,\theta \cap \bigcup_{\mathtt{X} \in dom\,\theta} vars\,\theta(\mathtt{X}) = \emptyset$ so that $\theta \circ \theta = \theta$), *relevant* ($vars\,\theta \subseteq vars\,e_1 \cup vars\,e_2$) and *most general* (for any unifier ς of e_1 and e_2, there exists a substitution σ such that $\varsigma = \sigma \circ \theta$). Most general unifiers are unique up to variable renaming in the sense that if σ and θ are most general unifiers of two simple expressions then there exists a renaming ρ such that $\sigma = \rho \circ \theta$. Conversely, if θ is a most general unifier of two simple expressions and ρ is a renaming then $\rho \circ \theta$ is also a a most general unifier of those expressions. For example $mgu(\mathtt{p(f(X),Z),p(Y,a)}) = \{\mathtt{Y/f(X)}, \mathtt{Z/a}\}$, whereas $mgu(\mathtt{p(X,X),p(Y,f(Y))}) = \emptyset$.

The set $\mathfrak{I}$ of initial states contains states of the form $\langle\langle \mathtt{a}, 0, 0\rangle\Box, \epsilon, vars\,\mathtt{a}, \Theta\rangle$ where $\mathtt{a} \in \mathfrak{a}$ is an atom, ϵ is the identity renaming and Θ is the answer substitution. The fact that the answer substitution Θ is part of the initial state can be considered either as a miracle or as naïveté in that a simple-minded Prolog interpreter might enumerate all possible answers and check them for success in turn. The set $\mathfrak{F}$ of final states contains states of the form $\langle\Box, \Theta, V, \Theta\rangle$ where $\Theta \in \mathfrak{s}$ and $V \subseteq \mathfrak{v}$. The miracle was that the answer substitution we started with is precisely the desired answer or more naïvely the initial hypothesis is now checked. An *SLD-derivation step* for a clause $\mathtt{P}[\ell]$ is defined by the following inference rule (where $n \geq 0$ and $k \geq 1$):

$$\frac{\mathtt{P}[\ell] = \mathtt{a}_0\mathtt{->}\mathtt{a}_1 \ldots \mathtt{a}_n \ \wedge\ \mathtt{b}_i = \langle \mathtt{a}, \ell', i'\rangle \ \wedge\ mgu(\mathtt{a},\, \rho\mathtt{a}_0) = \{\theta\} \ \wedge\ vars\,\rho\mathtt{P}[\ell] \cap V = \emptyset}{\begin{array}{c}\langle \mathtt{b}_1 \ldots \mathtt{b}_i \ldots \mathtt{b}_k\Box, \Theta, V, \Theta'\rangle \quad \vdash \rho\mathtt{P}[\ell] \rightarrow \\ \theta\langle \mathtt{b}_1 \ldots \mathtt{b}_{i-1}\ \langle \rho\mathtt{a}_1, \ell, 1\rangle \ldots \langle \rho\mathtt{a}_n, \ell, n\rangle\ \mathtt{b}_{i+1} \ldots \mathtt{b}_k\Box, \Theta, V \cup vars\,\rho, \Theta'\rangle\end{array}} \qquad (22)$$

Observe that the set V is used to guarantee that SLD-refutations are *variable-separated* [101], that is the variables occurring in the variant $\rho\mathtt{P}[\ell]$ of the clause $\mathtt{P}[\ell]$ of program $\mathtt{P}$ are new relative to the variables in all the goals, clauses and unifiers used in the previous SLD-derivation steps. This operational semantics keeps track of the origin of the atoms in the list of goals using a clause number and a position in this clause. Some program analyses require even more details about execution such as keeping track of the caller $\langle \rho\mathtt{a}_1, \ell', i', \ell, i\rangle$ or even of the whole computation history (using execution traces or proof trees for example). Prolog depth-first strategy consists in choosing $i = 1$ and in adding the constraint that ℓ is minimal whereas choice points have to be added if multiple answer are desired.

For example, the append program:

```
app([],X,X) -> ;
app(T:X,Y,T:Z) -> app(X,Y,Z) ;
```

has the following SLD-refutation for initial goal `app(X,Y,1:[])` (naturally the miraculous answer substitutions are omitted):

$$\begin{array}{l}\langle\langle \mathtt{app(X,Y,1:[])}, 0, 0\rangle\Box, \epsilon, \{\mathtt{X}, \mathtt{Y}\}\rangle \\ \vdash \mathtt{app([],X_0,X_0)\ ->} \rightarrow \\ \langle\Box, \{\mathtt{X/[]}, \mathtt{Y/1:[]}, \mathtt{X_0/1:[]}\}, \{\mathtt{X}, \mathtt{Y}, \mathtt{X_0}\}\rangle\end{array}$$

as well as:

$$\begin{array}{l}\langle\langle \mathtt{app(X,Y,1:[])}, 0, 0\rangle\Box, \epsilon, \{\mathtt{X}, \mathtt{Y}\}\rangle \\ \vdash \mathtt{app(T_1:X_1,Y_1,T_1:Z_1)\ ->\ app(X_1,Y_1,Z_1)} \rightarrow \\ \langle\langle \mathtt{app(X_1,Y_1,Z_1)}, 2, 1\rangle\Box, \{\mathtt{X/1:X_1}, \mathtt{Y/Y_1}, \mathtt{T_1/1}, \mathtt{Z_1/[]}\}, \{\mathtt{X}, \mathtt{Y}, \mathtt{X_1}, \mathtt{Y_1}, \mathtt{T_1}, \mathtt{Z_1}\}\rangle \\ \vdash \mathtt{app([],X_2,X_2)\ ->} \rightarrow \\ \langle\Box, \{\mathtt{X/1:[]}, \mathtt{Y/[]}, \mathtt{X_1/[]}, \mathtt{Y_1/[]}, \mathtt{T_1/1}, \mathtt{Z_1/[]}, \mathtt{X_2/[]}\}, \{\mathtt{X}, \mathtt{Y}, \mathtt{X_1}, \mathtt{Y_1}, \mathtt{T_1}, \mathtt{Z_1}, \mathtt{X_2}\}\rangle\end{array}$$

The transition relation $\vdash \mathtt{P} \rightarrow$ for program $\mathtt{P} \in \mathfrak{L}$ is defined by:

$$s \vdash \mathtt{P} \rightarrow s' \stackrel{\text{def}}{=} (\exists \ell \in \mathbb{N} : \exists \rho \in \mathfrak{r} : s \vdash \rho\mathtt{P}[\ell] \rightarrow s') \qquad (23)$$

Other operational semantics of logic programs than SLD-resolution can serve as a standard semantics for abstract interpretation, such as modeling Prolog search strategy in a constraint logic program [2], OLDT-resolution [90], [66] or bottom/up execution using magic templates [87], [132].

7.2. Top/Down Collecting Semantics of Logic Programs

The top/down collecting semantics of a logic program $\mathtt{P}$ is the set $\mathfrak{D}$ of states $\langle \mathtt{g}, \theta, V, \Theta \rangle$ which can be reached during an SLD-resolution of some initial goal $\langle \mathtt{a}\Box, \epsilon, \mathit{vars}\,\mathtt{a}, \Theta' \rangle \in \mathfrak{I}$ for query $\mathtt{a}$. By proposition 33, we have $\mathfrak{D} = \mathit{lfp}\, F[\![\mathtt{P}]\!]$ with:

$$\begin{aligned} F[\![\mathtt{P}]\!]X &= \mathfrak{I} \cup \mathit{post}[\vdash \mathtt{P} \rightarrow]X \\ &= \mathfrak{I} \cup \{\theta\langle \mathtt{b}_1 \ldots \mathtt{b}_{i-1}\, \langle \rho\mathtt{a}_1, \ell, 1\rangle \ldots \langle \rho\mathtt{a}_n, \ell, n\rangle\, \mathtt{b}_{i+1} \ldots \mathtt{b}_k\Box, \Theta, V \cup \mathit{vars}\,\rho, \Theta'\rangle \mid \\ &\qquad \langle \mathtt{b}_1 \ldots \mathtt{b}_i \ldots \mathtt{b}_k\Box, \Theta, V, \Theta'\rangle \in X \ \wedge\ \mathtt{b}_i = \langle \mathtt{a}, \ell', i'\rangle \ \wedge\ \mathtt{P}[\ell] = \mathtt{a}_0\mathtt{->}\mathtt{a}_1 \ldots \mathtt{a}_n \\ &\qquad\qquad \wedge\ \mathit{mgu}(\mathtt{a}, \rho\mathtt{a}_0) = \{\theta\} \ \wedge\ \mathit{vars}\,\rho\mathtt{P}[\ell] \cap V = \emptyset\} \end{aligned} \tag{24}$$

where $n = 0$ for clauses with empty body and $k \geq 1$.

7.3. Bottom/Up Collecting Semantics of Logic Programs

The bottom/up collecting semantics of a logic program $\mathtt{P}$ is the set $\mathfrak{A}$ of states $\langle \mathtt{g}, \theta, V, \Theta \rangle$ for which there exists a successful SLD-resolution (terminating with some success $\langle \Box, \Theta, V, \Theta \rangle \in \mathfrak{F}$). By proposition 34, we have $\mathfrak{A} = \mathit{lfp}\, B[\![\mathtt{P}]\!]$ where $B[\![\mathtt{P}]\!]$ is defined as follows (with $n = 0$ for clauses with empty body and $k \geq 0$):

$$\begin{aligned} B[\![\mathtt{P}]\!]X &= \mathit{pre}[\vdash \mathtt{P} \rightarrow]X \cup \mathfrak{F} \\ &= \mathfrak{F} \cup \{\langle \mathtt{b}_1 \ldots \mathtt{b}_{i-1}\, \langle \mathtt{a}, \ell', i'\rangle\, \mathtt{b}_{i+1} \ldots \mathtt{b}_k\Box, \Theta, V, \Theta'\rangle \mid \\ &\qquad \exists \ell \in \mathbb{N} : \mathtt{P}[\ell] = \mathtt{a}_0\mathtt{->}\mathtt{a}_1 \ldots \mathtt{a}_n \ \wedge\ \mathit{mgu}(\mathtt{a}, \rho\mathtt{a}_0) = \{\theta\} \ \wedge\ \mathit{vars}\,\rho\mathtt{P}[\ell] \cap V = \emptyset \\ &\qquad \wedge\ \theta\langle \mathtt{b}_1 \ldots \mathtt{b}_{i-1}\, \langle \rho\mathtt{a}_1, \ell, 1\rangle \ldots \langle \rho\mathtt{a}_n, \ell, n\rangle\, \mathtt{b}_{i+1} \ldots \mathtt{b}_k\Box, \Theta, V \cup \mathit{vars}\,\rho, \Theta'\rangle \in X\} \\ &= \mathfrak{F} \cup \{\langle \mathtt{b}_1 \ldots \mathtt{b}_{i-1}\, \langle \theta\rho\mathtt{a}_0, \ell', i'\rangle\, \mathtt{b}_{i+1} \ldots \mathtt{b}_k\Box, \Theta, V, \Theta'\rangle \mid \\ &\qquad \exists \ell \in \mathbb{N} : \mathtt{P}[\ell] = \mathtt{a}_0\mathtt{->}\mathtt{a}_1 \ldots \mathtt{a}_n \ \wedge\ \mathit{vars}\,\rho\mathtt{P}[\ell] \cap V = \emptyset \\ &\qquad \wedge\ \theta\langle \mathtt{b}_1 \ldots \mathtt{b}_{i-1}\, \langle \rho\mathtt{a}_1, \ell, 1\rangle \ldots \langle \rho\mathtt{a}_n, \ell, n\rangle\, \mathtt{b}_{i+1} \ldots \mathtt{b}_k\Box, \Theta, V \cup \mathit{vars}\,\rho, \Theta'\rangle \in X\} \end{aligned} \tag{25}$$

since, by induction on the syntax of terms, the atom $\mathtt{a}$ such that $\mathit{mgu}(\mathtt{a}, \rho\mathtt{a}_0) = \{\theta\}$ (where $\mathit{vars}\,\mathtt{a} \cap \mathit{vars}\,\rho\mathtt{a}_0 = \emptyset$) is $\theta\rho\mathtt{a}_0$.

The least Herbrand model $\mathit{lfp}\, T_{\mathtt{P}}$ of logic programs using immediate consequence operator $T_{\mathtt{P}}$ of program $\mathtt{P}$ [146] can be obtained from $B[\![\mathtt{P}]\!]$ by an abstract interpretation which consists in abstracting a set of states by the set of ground atoms obtained by approximating each state $\langle \mathtt{g}\Box, \Theta, V, \Theta' \rangle$ by the atoms occurring in $\mathtt{g}$. $T_{\mathtt{P}}$ can be used as a more abstract bottom/up collecting semantics for some program analysis problems but certainly not for groundness analysis since only ground atoms are considered in the standard Herbrand base $B_{\mathtt{P}}$.

However, the minimal Herbrand model with variables introduced by [3], [65] and [94] would do for groundness analysis since ground as well as nonground atoms are considered, up to renaming, in this extended Herbrand base. Observe that this minimal extended Herbrand model is an abstract interpretation $\alpha(\mathit{lfp}\, B[\![\mathtt{P}]\!])$ of the above bottom/up semantics (25) for the abstraction α defined by $\alpha(S) = \{\Theta\mathtt{b}_i \mid \langle \mathtt{b}_1 \ldots \mathtt{b}_i \ldots \mathtt{b}_n\Box, \theta, V, \Theta\rangle \in S\}$ (up to the use of equivalence classes to identify variants of atoms as indicated in proposition 10).

8. ABSTRACT INTERPRETATION OF LOGIC PROGRAMS USING FINITE ABSTRACT DOMAINS (WITH THE EXAMPLE OF GROUNDNESS ANALYSIS)

In order to illustrate the abstract interpretation of logic programs using finite abstract domains, we will consider groundness analysis, a simple version of Mellish's mode analysis [115] [116]. We will first consider a top-down groundness analysis method, which is essentially that proposed by

[105], with the difference that it will be constructively derived from the operational semantics of logic programs. Then, we will consider a bottom/up version of this groundness analysis method. The analysis algorithms are not new but their systematic derivation from the collecting semantics has not been so well understood. Most publications contain no correctness proof at all or soundness is proved a posteriori. We understand the method for deriving an abstract interpreter from the collecting semantics as an example of formal derivation of a program from its specification. This process or part of it should be automatizable. The novelty here will be combination of the top/down and bottom/up analysis methods to get a new powerful analysis algorithm which yields results that could be obtained by one of these methods using much more sophisticated abstract domains only. The methodology can be easily extended to any other type of invariance property of logic programs. Hence, our interest in groundness analysis is only that it provides a simple enough example.

8.1. Groundness

A simple expression $\mathtt{e}$ is *ground* if and only if it contains no variables, that is $\mathit{vars}\,\mathtt{e} = \emptyset$. *Groundness analysis* of a logic program $\mathtt{P}$ consists in determining which variables of which atoms of which clauses of the program are always bound to ground terms during program execution. More precisely if $\mathtt{P}[\ell] = \mathtt{a}_0\ \mathtt{->}\ \mathtt{a}_1 \ldots \mathtt{a}_i \ldots \mathtt{a}_n$ and $X \in \mathit{vars}\, a_i$ then any state $\langle \mathtt{b}_1 \ldots \langle \rho\mathtt{a}_i, \ell, i\rangle \ldots \mathtt{b}_k\Box, \Theta, V, \Theta'\rangle$ is such that $\mathit{vars}\,\Theta(\rho\mathtt{a}_i) = \emptyset$. For example in the `app` program, the variable `Z` and its variants are always bound to a ground term for an initial question `app(X,Y,t)` where `t` is a ground term.

8.2. Groundness Abstraction

A concrete property is a set of states so that $P^\flat = \wp(\mathfrak{S})$. The abstraction $\alpha(S)$ of a set S of states consists in keeping track of the groundness of the atoms occurring in states, ignoring current and answer substitutions and sets of already bounded variables as well as the order in which goals are derived, the occurrence of that atom at a given position of a given clause of the program and even the structure of that atom. To formalize this choice, we let G represent any ground term and NG any non-ground term. A set of terms can then be represented by an element of $G = \{\bot, \mathrm{G}, \mathrm{NG}, \top\}$ where $\bot$ corresponds to the empty set and $\top$ to the set $\mathtt{t}$ of all terms. A set of atoms of the form $\mathtt{p(t}_1, \ldots, \mathtt{t}_n\mathtt{)}$ (where the predicate symbol $\mathtt{p}$ is fixed) can be approximated by the down-set completion of the reduced product $\prod_{i=1}^n G$ (propositions 15 and 13). Since G is atomistic, we can, according to proposition 18, use the equivalent representation as a set of vectors $\mathtt{p(t}^\sharp{}_1, \ldots, \mathtt{t}^\sharp{}_n\mathtt{)}$ where each $\mathtt{t}^\sharp{}_i$ is an abstract term G or NG. Then, considering that the set of predicate symbols used in a logic program is finite, we can decompose a set of atoms by partitioning into a vector $\prod_{\mathtt{p}\in\mathfrak{p}} S[\mathtt{p}]$ of sets $S[\mathtt{p}]$ of atoms, one for each predicate symbol $\mathtt{p} \in \mathfrak{p}$, as suggested by proposition 12. This is of practical interest only and we will use $\cup_{\mathtt{p}\in\mathfrak{p}} S[\mathtt{p}]$ instead which is equivalent since the sets $S[\mathtt{p}]$ are disjointed. For example, the abstraction of $\{\mathtt{p(a,b)}, \mathtt{p(X,f(a,b))}, \mathtt{q(X)}\}$ would be $\{\mathtt{p(}\mathrm{G}\mathtt{,}\mathrm{G}\mathtt{)}, \mathtt{p(}\mathrm{NG}\mathtt{,}\mathrm{G}\mathtt{)}, \mathtt{q(}\mathrm{NG}\mathtt{)}\}$. A set of resolvents $\mathtt{b}_1 \ldots \mathtt{b}_n\Box$ can be approximated by the set of goals $\mathtt{b}_i$ occurring in one of these resolvents thus ignoring the relationships between goals appearing in resolvents, in particular the order in which goals are explored. Finally, we can approximate a set of states $\langle \mathtt{g}, \Theta, V, \Theta'\rangle$ by ignoring the current and answer substitutions Θ, Θ' and sets of utilized variables V and then by abstraction of the set of resolvents $\mathtt{g}$. Then (11) ensures that by composition of the above abstractions we obtain a Galois connection. To formulate this abstraction more precisely, we define the abstract domain as follows:

$$\mathtt{t}^\sharp = \{\mathrm{G}, \mathrm{NG}\} \tag{26}$$

$$\mathfrak{a}^\sharp = \{\mathtt{p(t}^\sharp{}_1, \ldots, \mathtt{t}^\sharp{}_n\mathtt{)} \mid p \in \mathfrak{p} \wedge \forall i = 1, \ldots, n : \mathtt{t}^\sharp{}_i \in \mathtt{t}^\sharp\} \tag{27}$$

$$P^\sharp = \wp(\mathfrak{a}^\sharp) \tag{28}$$

which is a complete lattice $P^\sharp(\subseteq, \emptyset, \mathfrak{a}^\sharp, \cup, \cap)$. The abstraction function $\alpha \in P^\flat \mapsto P^\sharp$ is defined as follows:

$$\begin{aligned}
\alpha(S) &= \{\alpha_{\mathfrak{S}}(s) \mid s \in S\} && (29)\\
\alpha_{\mathfrak{S}}(\langle \mathtt{g}, \theta, V, \Theta\rangle) &= \alpha_{\mathfrak{g}}(\mathtt{g}) && (30)\\
\alpha_{\mathfrak{g}}(\Box) &= \emptyset && (31)\\
\alpha_{\mathfrak{g}}(\mathtt{b}_1 \ldots \mathtt{b}_n \Box) &= \{\alpha_{\mathfrak{b}}(\mathtt{b}_i) \mid i = 1, \ldots, n\} && (32)\\
\alpha_{\mathfrak{b}}(\langle \mathtt{a}, \ell, i\rangle) &= \alpha_{\mathfrak{a}}(\mathtt{a}) && (33)\\
\alpha_{\mathfrak{a}}(\mathtt{p}(\mathtt{t}_1, \ldots, \mathtt{t}_n)) &= \mathtt{p}(\alpha_{\mathfrak{t}}(\mathtt{t}_1), \ldots, \alpha_{\mathfrak{t}}(\mathtt{t}_n)) && (34)\\
\alpha_{\mathfrak{t}}(\mathtt{X}) &= \mathrm{NG} && (35)\\
\alpha_{\mathfrak{t}}(\mathtt{c}) &= \mathrm{G} && (36)\\
\alpha_{\mathfrak{t}}(\mathtt{f}(\mathtt{t}_1, \ldots, \mathtt{t}_n)) &= \begin{cases} \mathrm{G} & \text{if } \forall i = 1, \ldots, n : \alpha_{\mathfrak{t}}(\mathtt{t}_i) = \mathrm{G} \\ \mathrm{NG} & \text{if } \exists i = 1, \ldots, n : \alpha_{\mathfrak{t}}(\mathtt{t}_i) = \mathrm{NG} \end{cases} && (37)
\end{aligned}$$

Observe that no miracle is needed since the unknown answer substitution is simply ignored. The corresponding concretization function $\gamma \in P^\sharp \mapsto P^\flat$ is defined by:

$$\begin{aligned}
\gamma(\emptyset) &= \{\langle \Box, \Theta, V, \Theta'\rangle \mid \Theta, \Theta' \in \mathfrak{s} \wedge V \subseteq \mathfrak{v}\} && (38)\\
\gamma(A) &= \{\langle \langle \mathtt{a}_1, \ell_1, i_1\rangle \ldots \langle \mathtt{b}_n, \ell_n, i_n\rangle \Box, \Theta, V, \Theta'\rangle \mid \forall k = 1, \ldots, n : \exists a^\sharp \in A : && (39)\\
&\qquad \mathtt{a}_k \in \gamma_{\mathfrak{a}}(a^\sharp) \wedge \ell_k \in \mathbb{N} \wedge \ell_i \in \mathbb{N} \wedge \Theta, \Theta' \in \mathfrak{s} \wedge V \subseteq \mathfrak{v}\}\\
\gamma_{\mathfrak{a}}(\mathtt{p}(\mathtt{t}^\sharp{}_1, \ldots, \mathtt{t}^\sharp{}_n)) &= \{\mathtt{p}(\mathtt{t}_1, \ldots, \mathtt{t}_n) \mid \forall i = 1, \ldots, n : \mathtt{t}_i \in \gamma_{\mathfrak{t}}(\mathtt{t}^\sharp{}_i)\} && (40)\\
\gamma_{\mathfrak{t}}(\mathrm{G}) &= \{\mathtt{t} \in \mathfrak{t} \mid \mathit{vars}\, \mathtt{t} = \emptyset\} && (41)\\
\gamma_{\mathfrak{t}}(\mathrm{NG}) &= \{\mathtt{t} \in \mathfrak{t} \mid \mathit{vars}\, \mathtt{t} \neq \emptyset\} && (42)
\end{aligned}$$

so that we obtain the Galois surjection:

$$P^\flat(\subseteq) \underset{\alpha}{\overset{\gamma}{\leftrightarrows}} P^\sharp(\subseteq) \qquad (43)$$

8.3. Top/Down Abstract Interpretation of Logic Programs

Given a logic program $\mathtt{P}$, we are interested in the ways in which predicates may be called during the satisfaction of those queries, that is in the set $\mathfrak{D} = \{s \mid \exists s' \in \mathfrak{I} : s' \vdash \mathtt{P} \rightarrow^\star s\}$ of the descendant states of the initial states $\mathfrak{I}$. We characterize these states in terms of groundness which means that we would like to know $\alpha(\mathfrak{D})$ that is $\alpha(\mathit{lfp}\, F[\![\mathtt{P}]\!])$ by proposition 33. Observe that the computational ordering $\sqsubseteq^\flat$ for $\mathit{lfp}\, F[\![\mathtt{P}]\!] = \cup_{n \in \mathbb{N}} F[\![\mathtt{P}]\!]^n(\emptyset)$ is $\subseteq$ and that this fixpoint is not effectively computable. In practice, approximations from above can be considered since claims that a term is ground or not ground are sound whenever it cannot be otherwise during program execution whereas it is always safe to claim that the groundness is unknown. Therefore the approximation ordering is also $\subseteq$. Consequently, the fixpoint approximation proposition 24 shows that $\alpha(\mathit{lfp}\, F[\![\mathtt{P}]\!]) \subseteq \mathit{lfp}\, \alpha \circ F[\![\mathtt{P}]\!] \circ \gamma$. This is a specification of an abstract interpreter which reads a program $\mathtt{P}$ then builds an internal representation of the equation $X = \alpha \circ F[\![\mathtt{P}]\!] \circ \gamma(X)$ and then solves it iteratively starting from the infimum $\emptyset$. To refine this specification formally, we replace α, $F[\![\mathtt{P}]\!]$ and γ by their definitions (24), (29) and (39). Then, we make simplifications (by hand) until obtaining an equivalent formulation in terms of abstract operators on $P^\sharp$ only. During this simplification process further approximations are allowed when necessary since by proposition 25 we can choose $F^\sharp[\![\mathtt{P}]\!] \in P^\sharp(\subseteq) \overset{m}{\longmapsto} P^\sharp(\subseteq)$ such that $\forall X \in P^\sharp : \alpha \circ F[\![\mathtt{P}]\!] \circ \gamma(X) \subseteq F^\sharp[\![\mathtt{P}]\!]X$.

This formal development leads to the definition of *abstract substitutions* as functions $\theta^\sharp \in \mathfrak{s}^\sharp$ from a finite set $V \subseteq \mathfrak{v}$ of variables to the abstract set $\mathfrak{t}^\sharp$ of terms. Abstract substitutions are

extended to atoms as follows:

$$\theta^\sharp(\mathtt{c}) = \mathrm{G} \tag{44}$$

$$\theta^\sharp(\mathtt{X}) = \mathrm{NG} \quad \text{if } \mathtt{X} \notin dom\,\theta^\sharp \tag{45}$$

$$\theta^\sharp(\mathtt{f}(\mathtt{t}_1,\ldots,\mathtt{t}_n)) = \begin{cases} \mathrm{G} & \forall i = 1,\ldots,n : \theta^\sharp(\mathtt{t}_i) = \mathrm{G} \\ \mathrm{NG} & \exists i = 1,\ldots,n : \theta^\sharp(\mathtt{t}_i) = \mathrm{NG} \end{cases} \tag{46}$$

$$\theta^\sharp(\mathtt{p}(\mathtt{t}_1,\ldots,\mathtt{t}_n)) = \mathtt{p}(\theta^\sharp(\mathtt{t}_1),\ldots,\theta^\sharp(\mathtt{t}_n)) \tag{47}$$

Then we get:

$$\begin{aligned} F^\sharp[\![\mathtt{P}]\!]X = {} & \{\alpha_{\mathtt{a}}(\mathtt{a}) \mid \langle \mathtt{a}\Box, \epsilon, V, \Theta\rangle \in \Im\} \cup X \\ & \cup \{\theta^\sharp(\mathtt{a}_i) \mid \exists \ell \in \mathbb{N} : \mathtt{P}[\ell] = \mathtt{a}_0 \texttt{ -> } \mathtt{a}_1 \ldots \mathtt{a}_n \wedge i \in \{1,\ldots,n\} \wedge \theta^\sharp \in vars\,\mathtt{a}_0 \mapsto \mathtt{t}^\sharp \\ & \qquad \wedge\, \theta^\sharp(\mathtt{a}_0) \in X\} \end{aligned} \tag{48}$$

Since the abstract domain $P^\sharp$ is finite the termination of the iterative computation of the least fixpoint of $F^\sharp[\![\mathtt{P}]\!]$ is guaranteed. The analysis can be of exponential size in the number of arguments in a predicate, which in practice is small ([144] suggests an average of 3). If practical experience shows that convergence should be accelerated then a widening can be useful, and chosen as suggested in section 4.3.4.. In particular, the decision to resort to widening can be dynamic, that is taken during the analysis, whenever it turns out to be too long to conclude (otherwise stated the widening is a simple join for the first n steps, where n can be tuned experimentally). Let us consider the following example (adapted from [136]):

```
p(f(X,Y),f(X,Z)) -> q(X,Y) r(Y,Z) ;
q(X,Y)           -> s(X) t(X,Y) ;
s(a)             -> ;
r(X,Y)           -> u(X) t(X,Y) ;
u(X)             -> ;
t(X,X)           -> ;
```

For ground initial questions $\mathtt{p(t_1,\ t_2)}$ such that $\{\alpha_{\mathtt{a}}(\mathtt{a}) \mid \langle \mathtt{a}\Box, \epsilon, V, \Theta\rangle \in \Im\} = \{\mathtt{p(G,G)}\}$, we obtain the following ascending iteration:

$$\begin{array}{lllll} \acute{X}^0 & = & \emptyset & & \\ \acute{X}^1 & = & F^\sharp[\![\mathtt{P}]\!]\acute{X}^0 & = & \{\mathtt{p(G,G)}\} \cup \acute{X}^0 \cup \emptyset \\ \acute{X}^2 & = & F^\sharp[\![\mathtt{P}]\!]\acute{X}^1 & = & \acute{X}^1 \cup \{\mathtt{q(G,G)}, \mathtt{r(G,G)}\} \\ \acute{X}^3 & = & F^\sharp[\![\mathtt{P}]\!]\acute{X}^2 & = & \acute{X}^2 \cup \{\mathtt{s(G)}, \mathtt{t(G,G)}, \mathtt{u(G)}\} \\ \acute{X}^4 & = & F^\sharp[\![\mathtt{P}]\!]\acute{X}^3 & = & \acute{X}^3 \end{array}$$

proving that all subgoals encountered during execution of an initial ground question are ground. If no information is known upon the groundness of initial goals so that $\{\alpha_{\mathtt{a}}(\mathtt{a}) \mid \langle \mathtt{a}\Box, \epsilon, V, \Theta\rangle \in \Im\}$ = {p(G,G), p(G,NG), p(NG,G), p(NG,NG)} we obtain no information on the groundness of predicates of the program.

In the definition (48) of $F^\sharp[\![\mathtt{P}]\!]$, we can avoid the enumeration of all abstract substitutions $\theta^\sharp \in vars\,\mathtt{a}_0 \mapsto \mathtt{t}^\sharp$ by a preliminary computation of groundness tables for each clause of the program such as the one shown in Figure 13 for the clause `p(f(X,Y),f(X,Z)) -> q(X,Y) r(Y,Z)`. Such a groundness table directly provides the set of abstract atoms $\theta^\sharp(\mathtt{a}_i)$ that can be derived from the abstract clause heads $\theta^\sharp(\mathtt{a}_0)$ belonging to X.

8.4. Bottom/Up Abstract Interpretation of Logic Programs

The method for obtaining the abstract bottom/up semantics for groundness analysis is essentially the same as for the top/down semantics. The abstraction is the same as in section 8.2. but for

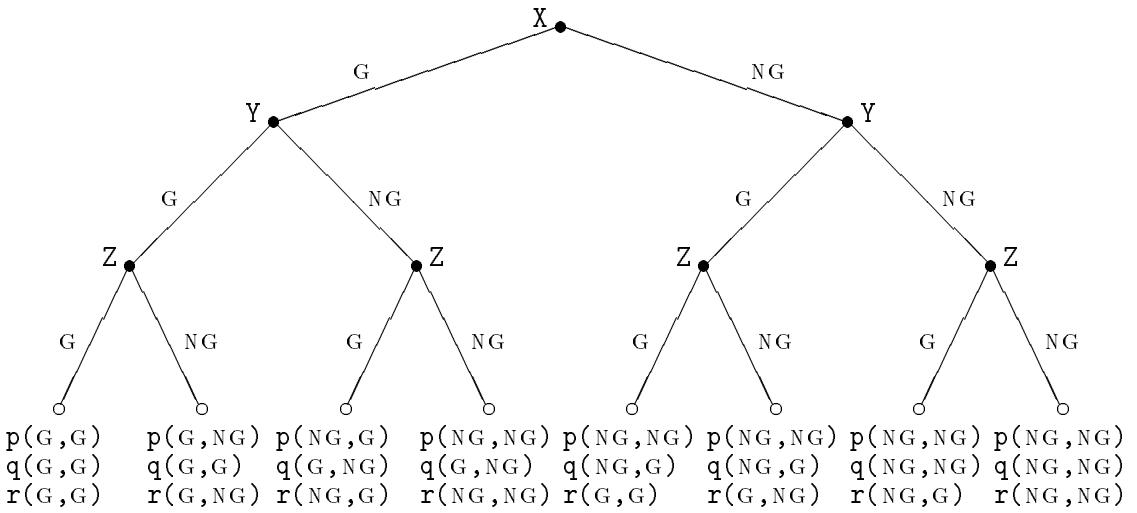


FIGURE 13. Groundness table of clause `p(f(X,Y),f(X,Z)) -> q(X,Y) r(Y,Z).`

the fact that we are now interested by subgoals instantiated by the answer substitution so that 30 is redefined as:

$$\alpha_{\mathfrak{S}}(\langle \mathtt{g}, \theta, V, \Theta \rangle) \quad = \quad \alpha_{\mathfrak{g}}(\Theta \mathtt{g}) \tag{49}$$

Observe that there is no miracle here since the answer substitution Θ is known when going bottom/up whereas the unknown current θ and set of utilized variables V are ignored by the abstraction. Now the specification $\alpha \circ B[\![\mathtt{P}]\!] \circ \gamma$ can be refined into the upper approximation:

$$B^\sharp[\![\mathtt{P}]\!]X = X \cup \{\theta^\sharp(\mathtt{a}_0) \mid \exists \ell \in \mathbb{N} : \mathtt{P}[\ell] = \mathtt{a}_0 \texttt{ -> } \mathtt{a}_1 \ldots \mathtt{a}_n \wedge \theta^\sharp \in \cup_{i=1}^n \mathit{vars}\, \mathtt{a}_i \mapsto \mathtt{t}^\sharp$$
$$\wedge \forall i = 1, \ldots, n : \theta^\sharp(\mathtt{a}_i) \in X\} \tag{50}$$

The least fixpoint of $B^\sharp[\![\mathtt{P}]\!]$ provides groundness conditions on the subgoals which may be successfully satisfied as shown by the bottom/up analysis of the above example program:

$$\begin{array}{lcll}
\grave{X}^0 & = & \emptyset & \\
\grave{X}^1 & = & B^\sharp[\![\mathtt{P}]\!]\grave{X}^0 & = \grave{X}^0 \cup \{\mathtt{s(G)}, \mathtt{u(G)}, \mathtt{u(NG)}, \mathtt{t(G,G)}, \mathtt{t(NG,NG)}\} \\
\grave{X}^2 & = & B^\sharp[\![\mathtt{P}]\!]\grave{X}^1 & = \grave{X}^1 \cup \{\mathtt{q(G,G)}, \mathtt{r(G,G)}, \mathtt{r(NG,NG)}\} \\
\grave{X}^3 & = & B^\sharp[\![\mathtt{P}]\!]\grave{X}^2 & = \grave{X}^2 \cup \{\mathtt{p(G,G)}\} \\
\grave{X}^4 & = & B^\sharp[\![\mathtt{P}]\!]\grave{X}^3 & = \grave{X}^3
\end{array}$$

Observe that groundness information originates from unit clauses (or final clauses of recursive predicates) and propagates to the variables in the invoking goals. If a goal $\mathtt{p(t_1,t_2)}$ succeeds then the answer substitution will necessarily bind terms variables occurring in terms $\mathtt{t}_1$ and $\mathtt{t}_2$ to ground terms.

8.5. Combining Top/down and Bottom/Up Abstract Interpretation of Logic Programs

The top/down abstract interpretation *lfp* $F^\sharp[\![\mathtt{P}]\!]$ characterizes the descendant states of the initial states of logic program `P`. For the groundness analysis, an abstract value such as $\{\mathtt{p(G)}\}$ means that during any execution of the program `P`, a goal `p(t)` has `t` ground. This can be used by the compiler to choose simplified versions of the unification algorithm. Hence groundness is a consequence of the form of the possible queries. The bottom/up abstract interpretation *lfp* $B^\sharp[\![\mathtt{P}]\!]$ characterizes the ascendant states of the final states of logic program `P`. A compiler might use

this information to anticipate dead-ends. For the groundness analysis, an abstract value such as $\{\mathtt{p(G)}\}$ means that during any execution of the program $\mathtt{P}$, a goal $\mathtt{p(t)}$ can only have ground instantiations or else will either fail or loop. [111] compare bottom/up and top/down analyses and particularly stress the difference in other application areas.

The combination $lfp\, F^\sharp[\![\mathtt{P}]\!] \cap lfp\, B^\sharp[\![\mathtt{P}]\!]$ of both analyses characterizes a superset of the set of states which are the descendant states of the initial states and the ascendant states of the final states, that is subgoals derived from the initial queries and which may succeed. For the groundness analysis example, the meaning of abstract value $\{\mathtt{p(G)}\}$ is now that a subgoal $\mathtt{p(t)}$ has $\mathtt{t}$ ground or else will return a ground answer unless it fails or loops. Using the technique of proposition 36 for our example program, we obtain:

$$\begin{array}{rcll}
\dot{X}^0 & = & lfp\, B^\sharp[\![\mathtt{P}]\!] & = \{\mathtt{p(G,G)},\mathtt{q(G,G)},\mathtt{s(G)},\mathtt{r(G,G)},\mathtt{r(NG,NG)},\mathtt{u(G)},\\
 & & & \quad \mathtt{u(NG)},\mathtt{t(G,G)},\mathtt{t(NG,NG)}\}\\
\dot{X}^1 & = & lfp\, \lambda X.\dot{X}^0 \cap F^\sharp[\![\mathtt{P}]\!]X & = \{\mathtt{p(G,G)},\mathtt{q(G,G)},\mathtt{r(G,G)},\mathtt{s(G)},\mathtt{u(G)},\mathtt{t(G,G)}\}\\
\dot{X}^2 & = & lfp\, \lambda X.\dot{X}^1 \cap B^\sharp[\![\mathtt{P}]\!]X & = \dot{X}^1
\end{array}$$

The analysis shows that all predicates in the program are or will be bound to ground terms. Observe that much more complicated abstract domains would have to be used to obtain the same information using purely top/down or purely bottom/up abstract interpretations [3], [72] [136].

9. ABSTRACT INTERPRETATION OF LOGIC PROGRAMS USING INFINITE ABSTRACT DOMAINS (WITH THE EXAMPLE OF ARGUMENT SIZES ANALYSIS)

With the exception of [9] most abstract interpretations of logic programs that can be found in the literature, use finite domains or domains satisfying the ascending chain condition or at least such that all possible iteration sequences are finite. However, nothing prevents considering infinite domains with potentially infinite iteration sequences provided widening operators are used to accelerate the convergence above least fixpoints. The example that we will consider is taken from [147] and consists in determining relationships between argument sizes of predicates. The size of an elementary expression is determined syntactically as follows:

$$\sigma(\mathtt{c}) = 1 \tag{51}$$

$$\sigma(\mathtt{X}) = 1 \tag{52}$$

$$\sigma(\mathtt{f(t}_1,\ldots,\mathtt{t}_n\mathtt{)}) = \sigma(\mathtt{p(t}_1,\ldots,\mathtt{t}_n\mathtt{)}) = 1+\sum_{i=1}^{n}\sigma(\mathtt{t}_i) \tag{53}$$

The idea, already explored in [44] for imperative programs, is to approximate a set of points in $\mathbb{Z}^n$ by its convex hull. It follows that a set X of atoms can be decomposed by partitioning according to the predicate symbols $\mathtt{p} \in \mathfrak{p}$ whereas each set of atoms for a given predicate symbol $\mathtt{p}$ is approximated by the convex hull of the sizes of its arguments:

$$\alpha_{\mathfrak{A}}(X) = \lambda\, \mathtt{p}.\,\mathrm{ConvexHull}(\{\langle\sigma(\mathtt{t}_1),\ldots,\sigma(\mathtt{t}_n)\rangle \mid \mathtt{p(t}_1,\ldots,\mathtt{t}_n\mathtt{)} \in X\}) \tag{54}$$

Again sets of states can be approximated by the set of atoms occurring in these states:

$$\alpha(S) = \alpha_{\mathfrak{A}}(\cup\{\alpha_{\mathfrak{S}}(s) \mid s \in S\}) \tag{55}$$

$$\alpha_{\mathfrak{S}}(\langle \mathtt{g}, \theta, V, \Theta\rangle) = \alpha_{\mathfrak{g}}(\mathtt{g}) \tag{56}$$

$$\alpha_{\mathfrak{g}}(\Box) = \emptyset \tag{57}$$

$$\alpha_{\mathfrak{g}}(\mathtt{b}_1\ldots\mathtt{b}_n\Box) = \{\alpha_{\mathfrak{b}}(\mathtt{b}_i) \mid i = 1,\ldots,n\} \tag{58}$$

$$\alpha_{\mathfrak{b}}(\langle \mathtt{a}, \ell, i\rangle) = \mathtt{a} \tag{59}$$

Consider for example the append program:

```
app([],X,X)     -> ;
app(T:X,Y,T:Z) -> app(X,Y,Z) ;
```

The set

$$\{\texttt{app([T}_1\texttt{: ... T}_n\texttt{:[],X,T}_1\texttt{: ... T}_n\texttt{:X)} \mid n \geq 0 \wedge \forall i = 1,\ldots,n : \texttt{T}_i \in \texttt{t}\}$$

of atoms can be approximated by:

$$\{\texttt{app(}x\texttt{,}y\texttt{,}z\texttt{)} \mid x \geq 0 \wedge y \geq 0 \wedge z \geq 0 \wedge (x-1)+y = z\}$$

For the following program, testing for inequality of natural numbers $n \geq 0$ represented as successors $\texttt{s}^n\texttt{(0)}$ of zero:

```
p(X,X)     -> ;
p(X,s(Y)) -> p(X,Y) ;
```

the approximation of the set of atoms

$$\{\texttt{p(X,s}^n\texttt{(X))} \mid n \geq 0\}$$

would be:

$$\{\texttt{p(}x\texttt{,}y\texttt{)} \mid x \geq 0 \wedge y \geq 0 \wedge x \leq y\}$$

[147] observes that this is the least fixpoint of an operator associated with the program:

$$B^\sharp[\![\texttt{P}]\!]X = \{\langle x,y\rangle \mid x \geq 0 \wedge y \geq 0 \wedge ((x = y) \vee (\langle x, y-1\rangle \in X))\} \tag{60}$$

which we recognize as being an upper approximation of $\alpha \circ B[\![\texttt{P}]\!] \circ \gamma$. This approximation is sound since supersets of atoms leads to upper bounds for the sizes of the arguments. The least fixpoint of this operator is not computable iteratively since the successive iterates are:

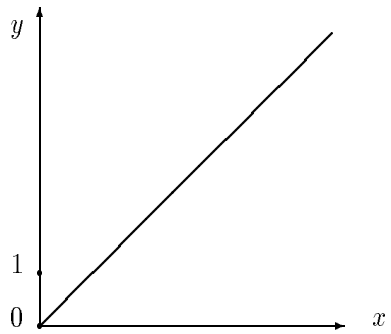
$$\begin{array}{lcll} \grave{X}^0 & = & \emptyset & \\ & & \ldots & \\ \grave{X}^{i+1} & = & B^\sharp[\![\texttt{P}]\!]\grave{X}^i & = \{\langle x,y\rangle \mid 0 \leq x \leq y \leq x+i\} \\ & & \ldots & \end{array}$$

Hence [147] "describes a method to verify a conjectured fixpoint" (since $B[\![\texttt{P}]\!]X = X$ implies $\mathit{lfp}\, B[\![\texttt{P}]\!] \subseteq X$) and then "offers an heuristic that often works for guessing a fixpoint." The conclusion is that "we need more ways to generate candidates for the fixpoint."

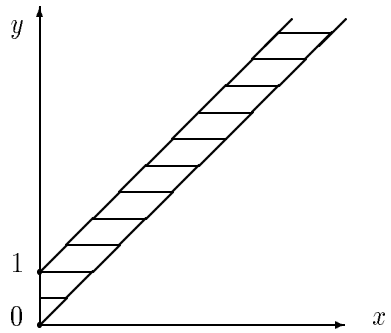
Our suggestion is to use abstract interpretation techniques. First, requiring fixpoints is too strong since postfixpoints are also correct (by Tarski's fixpoint theorem [141], $B[\![\texttt{P}]\!]X \subseteq X$ implies $\mathit{lfp}\, B[\![\texttt{P}]\!] \subseteq X$) and much easier to find, as shown for example by the long experience of program proving methods [27]. Then, using a widening/narrowing approach, we can enforce convergence to a postfixpoint. The widening that we will use is taken from [44]. If polyhedron P_1 is represented by a set $S_1 = \{\beta_1, \ldots \beta_n\}$ of linear inequalities and P_2 is represented by $S_2 = \{\gamma_1, \ldots \gamma_m\}$, then $P_1 \triangledown P_2$ is $S_1' \cup S_2'$ where S_1' is the set of inequalities $\beta_i \in S_1$ satisfied by all points of P_2, whereas S_2' is the set of linear inequalities $\gamma_i \in S_2$ which can replace some $\beta_j \in S_1$ without changing polyhedron P_1. The intuitive idea is to throw away old constraints which are not stable while keeping the new ones that would be redundant had the old ones not been discarded. For example if $P_1 = \{\langle x,y\rangle \mid x \geq 0 \wedge x \leq y \wedge y \leq x\}$ and $P_2 = \{\langle x,y\rangle \mid 0 \leq x \leq y \leq x+1\}$ then $P_1 \triangledown P_2 = \{\langle x,y\rangle \mid 0 \leq x \leq y\}$ since the inequalities $0 \leq x$ and $x \leq y$ of P_1 are satisfied by all points of P_2, which is not the case of constraint $y \leq x$. Replacing any constraint of P_1 by $y \leq x+1$ would change P_1, hence it is not incorporated in $P_1 \triangledown P_2$.

For example, the fixpoint equation (60) leads to the upward abstract iteration sequence with widening shown in Figure 14. Observe that we have computed the invariant found heuristically

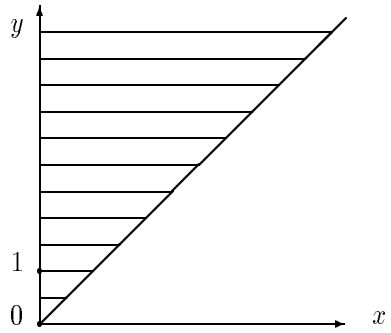
$\hat{X}^0 = \emptyset$



$$\begin{array}{rcl} \hat{X}^1 & = & B[\![\mathtt{P}]\!]\hat{X}^0 \\ & = & \{\langle x, y\rangle \mid x \geq 0 \wedge x = y\} \end{array}$$



$$B[\![\mathtt{P}]\!]\hat{X}^1 \quad = \quad \{\langle x, y\rangle \mid 0 \leq x \leq y \leq x + 1\}$$



$$\begin{array}{rcl} \hat{X}^2 & = & \hat{X}^1 \triangledown B[\![\mathtt{P}]\!]\hat{X}^1 \\ & = & \{\langle x, y\rangle \mid 0 \leq x \leq y\} \end{array}$$

$$\begin{array}{rcl} \hat{X}^3 & = & B[\![\mathtt{P}]\!]\hat{X}^2 \\ & = & \hat{X}^2 \end{array}$$

FIGURE 14. Upward abstract iteration sequence with widening for equation (60).

in example 7.1 of [147]. More generally, we stop iterating as soon as a postfixpoint is reached. Then we use an abstract iteration sequence with narrowing, with a trivial narrowing consisting in stopping the iteration after a few steps (typically one). Non-trivial invariants can be found automatically by this method [44]. It has been successfully applied to the vectorization and parallelization of sequential programs [80]. [77] contains further examples of constraints derivation among object sizes (in imperative programs). [92] is also useful when considering linear equalities instead of inequalities. Other approaches for compile-time estimating argument size relations consist in solving difference equations with boundary conditions [54], [56], [55]. Non-iterative methods for solving the fixpoint equations involved in abstract interpretation are still to be studied.

10. A THEMATIC SURVEY OF THE LITERATURE ON ABSTRACT INTERPRETATION OF LOGIC PROGRAMS

Our purpose in this section is to give a general idea of the abundant research work on abstract interpretation of logic programs and its applications for the non-specialist.

10.1. Abstract Interpretation Frameworks for Logic Programs

The goal of an abstract interpretation framework is to facilitate the design and development of abstract interpreters. A collecting semantics is chosen to deal with a given category of program properties (such as top/down or bottom/up analysis). Then, according to (11), the approximation of this collecting semantics is decomposed into a general purpose approximation and an application dependent approximation. The general purpose approximation deals with the attachment of the unspecified abstract properties to program points, execution trees or any more general notion of label attached to programs and with the control structure of logic programs. The application dependent approximation is user specified by providing a set and computer representation of abstract properties, and abstract operations for unification and for all built-ins. Specific verification conditions are also given which must be verified for these abstract operations to ensure the correctness of the application. The advantages of this approach are multiple. For example, esoteric theory need not be understood by casual users in all its detail since it is embedded into a widely distributed program with hopefully friendly interfaces. Specification, correctness proof and coding of a specific application is thus considerably reduced. The defect is that general-purpose tools may not be well-suited or efficient for a specific analysis but most users will appreciate some help in programming a non-trivial abstract interpreter.

10.1.1. Top/Down Abstract Interpretation Frameworks

Bruynooghe's top/down framework was first sketched in [11] then fully described in [9] and further refined in [10] to integrate mode, type and sharing inference. A full account can be found in [106] and applications to compile-time garbage collection are discussed in [122]. [47] argue that abstract interpretation is not only suited for applications in code optimization, but provides an excellent tool to support techniques in source level program transformation. This paper also addresses the novice in the field that might prefer to start from a concrete example rather than by an abstract presentation.

Most of the abstract interpretation frameworks for logic programs are top/down [48], [64], [103], [102], [111], [117], [118], [124], [131], [157] certainly because abstract interpretation is often understood as "acting as an interpreter" that is execution of an abstract interpreter to perform a data flow analysis instead of "understanding in a specified way" that is approximation of a semantics. Top/down abstract interpretation frameworks naturally correspond to an operational standard semantics but can also be formulated using denotational semantics [85]. This

is easily seen to be less general as soon as denotational semantics are understood as abstract interpretation of an operational trace semantics [43].

10.1.2. Bottom/Up Abstract Interpretation Frameworks

Bottom/up abstract interpretation frameworks for logic programs were first formalized by [108], using an abstract version of the semantics of [67] dealing with negation. The semantics was given in terms of ground atoms only and was used to formalize the depth-k pattern analysis of [137]. In [111], definite logic programs were considered using a version of $T_{\mathtt{P}}$ to characterize the set of atoms which the program `P` "makes true", differing from $T_{\mathtt{P}}$ in that these atoms need not be ground. Following [16], this idea was formalized by [3], [65], reformulated by [94] in an algebraic framework (which was used to justify [9]) and used by [96] to provide a declarative semantics of concurrent logic programs. Examples of bottom/up analyses are given by [72], [87], [113], [132].

10.1.3. Bottom/Up Versus Top/Down Abstract Interpretation and Their Combination

Theorem 10-13 of [26] provides a way to transform a relational bottom/up abstract interpretation into a top/down one and vice-versa. [132] applies this method to logic programs.

The collecting semantics (24) relates the root and internal nodes of the execution tree by the resolvent, current substitution and set of utilized variables and the internal nodes of the tree to the leaves through the answer substitution. Bruynooghe uses a different collecting semantics providing an infix traversal of the execution tree where each subtree is traversed top/down to determine calling-patterns and then bottom/up to return answer substitutions. In this case information is propagated from the root to the internal nodes on the first pass and then from the leaves to the internal nodes in the second pass, thus providing a combination of top/down and bottom/up analysis based upon the use of relational abstract lattices.

The multi-passes algorithm given in proposition 36 is an interesting alternative not requiring relational abstract domains. It has proved very powerful for imperative languages [7] and does not seem to have been used for logic programming languages.

10.2. Variable Binding Analysis

The most numerous applications of abstract interpretation to logic programming languages concern variable binding analysis which consists in determining when variables are bound (mode analysis) and for how long (liveness analysis), and how they can be bound (variable binding and data dependencies analysis).

10.2.1. Live Variable Analysis

Live variable analysis which consists in determining for how long variables are bounded helps the compiler generate better storage management [11], [106].

10.2.2. Mode Analysis

One of the most attractive features of Prolog is its parameter passing mechanism. A simple parameter can be used for input, output or both. The compiler must generate code for both alternatives, which can slow down execution considerably. Most predicate do not use this flexible parameter passing. [153] introduced explicit mode declarations (instantiated '+', uninstantiated '−', and unknown '?') to help the compiler generate better code. But this annotation of programs is tedious and subtle errors can be introduced in the program, in particular when the program is modified. The annotation of input arguments to a call (not further instantiated by execution

of the goal) and of output arguments (that is variables which are free at call time and will be later instantiated) can be automatically inferred using abstract interpretation.

Early work on mode inference via static analysis was done by Mellish [115], [116] who used dependencies between variables to propagate information regarding their instantiation. Since aliasing effects resulting from unification were not taken into account, the procedure sometimes produced erroneous results [48], [117]. This was later corrected and proved correct [117], [118], using abstract interpretation, as advised by Mycroft. The impact of this work was important since it introduced abstract interpretation in the logic programming community. Mode analysis has been widely studied starting from simple two-values abstract domains $\{\texttt{in}, \texttt{out}\}$ [135] to very sophisticated abstract domains for finding the instantiation state of the arguments of the calls at run-time [11], [10], [20], [46], [57], [49], [59], [60], [61], [63], [83], [98], [105], [139], [145], [154]. Mode analysis is used for code optimization. For example, in the Warren Abstract Machine (WAM), examining the contents of a variable may require dereferencing an arbitrary length chain of references. Mode analysis may reveal that some arguments will ever need dereferencing so that the branch-and-test loops needed for arbitrary dereferencing can be removed. When a variable is bound, its address is examined to see if it was created before the last choice-point and, if so, its address is pushed on to the trail stack. Mode analysis may reveal that the binding of some arguments may never need trailing. [142] proposes an abstract domain to dereference chain and choice-point analysis and provides figures showing the dramatic reduction of the amount of code a compiler need to produce for clause heads. Similar object code optimizations are considered by [50], [73], [144]. Using mode information gathered by abstract interpretation allows the generation of more specific code which executes faster. This results in substantial speedups [106], [148].

10.2.3. Sharing Analysis

This category of *sharing analyses* is concerned with analysing the occurrences of variables into terms and concerns various properties such as groundness [4], [3] [17], [19], [20], [21], [22], [23], [24], [72], [85], [96], [149], [154], aliasing [11], [17], [20], [50], [52], [72], [81], [82], [123], [125], [154], linearity [20], [124], strictness, [20], covering, and compoundness [21], [22] analyses. These properties are often related with mode analysis.

A variable is *ground* if and only if it is bound to a ground term containing no variable, in every possible substitution during execution of the program. A term is *linear* if it contains exactly one variable. In particular a variable is *uninitialized* if it is unbound and not pointed to by any other variable , it is *free* if it is just bound to another variable and one which is bound to a complex term is called *nonfree*. It is *strict* or *nonground* if it contains one variable or more. Two terms are aliases if and only if they are both reduced to one variable. Two variables in a logic program are said to be *aliased* if in some execution of the program they may be bound to terms which contain a common variable. *Covering analysis* aims at determining whether any variable occurring in a term $\texttt{t}_1$ also occurs in another term $\texttt{t}_2$, whereas *compoundness analysis* aims at determining whether a variable is always bound to a particular functor, a special case of pattern analysis.

10.2.4. Data Dependency Analysis

Dependency analysis tries to find out which arguments and subgoals are dependent in the sense that they can have shared terms. This knowledge can be used for example in organizing the parallel execution of the clause, in intelligent backtracking, in compile time garbage collection or occur-checking to detect situations where cyclic terms can be created during unification [13], [12], [105], [154], [52], [118], [123], [81], [85], [140], [134], [100], [122], [105], [123], [154].

10.3. Predicate Type Analysis

Predicate type analysis consists in characterizing the class of arguments for which predicates are true, more precisely what is the set (type analysis) or shape (pattern analysis) of possible values of these arguments, whether unification of the arguments can lead to infinite terms (occur-check analysis), whether a predicate can be true for at most one value of its arguments (functionality analysis) or can lead to no more than one success (determinacy analysis), what are the relationships between arguments sizes, etc.

10.3.1. Pattern Analysis

Pattern analysis [137] consists in determining the shape of the term to which variables are bound. In top/down analysis one obtains calling patterns whereas in bottom/up analysis we get success patterns. Patterns are usually non recursive and limited to the top of the terms, and will describe the degree of instantiation of variables whenever the clause is called, up to, for example, some fixed depth [3], [20], [51], [50], [109], [111], [113]. The main use of pattern analysis is for program specialization.

10.3.2. Type Analysis

Type analysis also describes a set of terms but it is a more refined analysis since the interior of terms can usually be described recursively [11], [10], [49], [50], [63], [66], [71], [78], [83], [88], [98], [99], [106], [107], [119], [120], [121], [126], [139], [160], [161]. Types can be used descriptively, in which case the abstract interpretation is used for type inference or prescriptively in which case the abstract interpretation is used for type checking. Type information is useful for a number of tools notably for program debugging or the elimination of *dead code* (which result is never used) and *unreachable code* (which is never executed).

10.3.3. Occur-Check Analysis

For efficiency reasons, many Prolog systems omit occur checks during unification. This makes the system unsound as a theorem prover. For example the query `q` would succeed in the following logic program:

```
p(x, f(x)) -> ;
q          -> p(x, x) ;
```

when executed without occur-check. Occur check analysis determines cases when unification can safely be performed without occur checks, which may help a compiler generate efficient programs without sacrificing soundness [17], [20], [85], [134], [140].

10.3.4. Determinacy, Functionality, and Mutual Exclusion Analysis

Although the ease of use of logic programming languages is partly due to the power of non-deterministic search, some large parts of programs may not require the use of choice points with general backtracking, in which case no backtrack is necessary, unnecessary search can be avoided and space on the run-time stack can be reclaimed early. Determinacy analysis consists in recognizing predicates that can return at most one answer to any call to it [116], [148], [145]. Functionality analysis is a special case of determinacy analysis that consists in recognizing predicates that can be true for at most one value of their arguments [58], [50], [60], [61]. Mutual exclusion analysis aims at determining pairs of clauses for a predicate such that at most one of them can succeed at runtime for a call to that predicate [61].

10.3.5. Analysis of Relationships Between Argument Sizes of Predicates

The analysis of relationships between argument sizes of predicates is a high-level abstract interpretation which can be used for code improvement using better memory allocation strategies as well as automatic termination proofs (for some but not all programs) [54], [56], [55], [147], [151].

10.4. Analysis of Logic Programs with Negation as Failure

SLDNF-resolution, i.e., SLD resolution with negation as failure [14], is not a complete proof procedure for general programs or goals. On the one hand, SLDNF-resolution is unable to prove a formula $F \vee G$ if neither F nor G is a logical consequence of the theory because of nontermination. On the other hand, SLDNF-resolution must avoid floundering, that is reaching a goal which contains only nonground negative literals. For example [4], the goal `p(X) ¬q(X)` does not fail for the program:

```
p(X) -> ;
q(a) -> ;
r(b) -> ;
```

so SLDNF-resolution cannot prove that $\exists X : p(X) \wedge \neg q(X)$ although $p(b) \wedge \neg q(b)$ obviously holds. A way to solve this problem is to consider a restricted class of programs and goals (by imposing syntactic conditions ensuring that the definition of predicates contains nonground facts, [62]) or to use abstract interpretation [4] so as to show that predicates, the definition of which contains nonground facts, are suitably used so as to produce ground answers only. Since the floundering problem is undecidable [1], one can only obtain safe approximate results (in the sense that no non floundering goal during abstract interpretation will flounder during its actual evaluation whereas a goal floundering during abstract interpretation may not flounder during its actual evaluation) [4], [5], [114], [73].

10.5. Analysis of Dynamically Modified, Concurrent, and Constraint Logic Programs

Most papers on abstract interpretation of logic programs consider definite programs and more research is needed to deal with practical programs involving imperative features. For example, [49] considers the case of programs that can be dynamically modified through the use of constructs like Prolog *assert*.

Abstract interpretation frameworks for concurrent logic programs has tended to concentrate on operational and top/down analyses to reduce the enqueuing and dequeuing of processes, to identify deadlock or unintended suspensions and to remove unnecessary synchronization instructions [18], [19], [51], [96], [97], [104]. Very few research papers are devoted to abstract interpretation of parallel imperative programs (see [35] for an early reference) and work on concurrent logic languages might originate more research on this subject from which other parallel languages might benefit.

Few work has been done on abstract interpretation of constraint logic languages [112]. Using the combined top/down and bottom/up analysis of constraint logic programs, constraints could be propagated top/down so has to statically spread the effect of the constraint on all clauses of the program and backward so has to statically anticipate future failures. This abstract interpretation might significantly reduce the search space at run-time. Moreover, abstract interpretation using such constraints is well-known [44], [77], [80] for imperative programs so that cross-fertilization should be expected. On parallel machines, one can even imagine that part of the search space to be explored later is reduced by abstract interpretation while the concrete search is pursued elsewhere.

10.6. Applications of Abstract Interpretation of Logic Programs

[154] argue that abstract interpretation of logic programs can be quite precise, yet not overly expensive and therefore has reached the stage of practicability. Applications concern program debugging (mainly by type checking or inference), compilation, transformation and correctness proof.

10.6.1. Compilation of Logic Programs

Abstract interpretation may be used by the compiler to optimize the code for the language primitives such as built-ins or unification, for the control of flow and use better memory allocation strategies such as allow a stack instead of heap allocation strategy for some variables, pass arguments always instantiated to an integer or a constant by value instead of by reference or reuse available memory thanks to compile-time garbage collection, etc. [143], [148] and [106] present some benchmark timing from an optimizing Prolog compiler using global analysis by abstract interpretation.

10.6.1.1. Unification and Code Specialization. Having derived call and success modes, the compiler can make explicit the different cases of unification. For example the unification of ground terms is a test for equality, unification between a free variable and a variable amounts to an assignment, unification between a term with free variables and a ground term is a mere selection of components [11], [106].

[70], [69], [73] produce specialized versions of predicates for different run-time instantiation situations.

10.6.1.2. Clause Selection and Efficient Backtracking. The anticipation of run-time behaviors may be used to avoid checking all possible clauses, to detect some kind of repetition in the SLD-derivations that might make the interpreter enter an infinite loop [6], to design efficient backtracking strategies [12], [60], [61].

10.6.1.3. Compile-Time Garbage Collection. [150] made a first attempt at detecting compile-time garbage collection. [8] presented a technique for global analysis which achieves compile-time garbage collection and reuse of the collected storage cells in a way similar to what a programmer achieves in imperative languages. However, the program had to be annotated with strong types and modes. In [11] an abstract interpretation framework was formulated which can be used to infer this type, mode (slightly improving [57]), aliasing and liveness information. This originated work on compile-time garbage collection [97], [100], [106], [122].

10.6.2. Transformation of Logic Programs

The information gathered about logic programs by abstract interpretation is useful not only for compilers, but also for other program transformers like partial evaluators [61], [70], [69], [73], data structures transformers [106], [110], [147], and parallelizers [10], [13], [51], [60], [63], [72], [81], [82], [123], [124], [125], [154], [156], [159] in order to automatically insert communications and synchronizations in Prolog with and-parallelism, or to eliminate the run-time independence test of goals in conditional parallelism operators which provide the control over the spawning and synchronization of such independent goals during parallel forward execution and backtracking (or to reduce the number of variables that have to be tested at runtime).

10.6.3. Correctness Proofs of Logic Programs

The idea of abstract interpretation is very close to program proof methods in that both rely upon a collecting semantics and on the use of approximation. For example the invariants of Floyd's

partial correctness proof method [128], [68] denote a postfixpoint of $F[\![\mathtt{P}]\!]$ in proposition 33 up to the Galois connection of example 11 allowing for the decomposition of global invariants into local ones. The difference is that in proof methods the information (invariants, variant functions, etc.) is provided by the user whereas in abstract interpretation it must be automatically computed. This connection between proof methods and abstract interpretation was explored in [36], [37], [38], [39], [40], [41], [27] and might also be fruitfully applied to logic programming languages.

11. CONCLUSION

Although the original work on abstract interpretation was intended for imperative [29] and recursive [32] sequential programs, it can be adapted or translated to other non-imperative languages since it was expressed in a language-independent way, using transition systems to model operational semantics [25], [34], fixpoints to model collecting semantics, Galois connections to model property approximations, the compositional design and combination of abstract domains so as to specify abstract interpreters by successive refinements, chaotic iterations to model abstract interpreters execution and widening/narrowing to model convergence acceleration. The application of these ideas to logic programming has been very fecund. We illustrated it with a naïve groundness analysis, but the main point was to stress the constructive aspects of abstract interpretation. It might turn out that the formal derivation of an abstract interpreter from a semantics is, at least partly, amenable to mechanization. The extension of abstract interpretation from imperative and functional to logic programming languages was not straightforward because of the bi-directional flow of control, owing to unification and backtracking. Moreover the program states have non-conventional and complex structures so that a number of a new abstract domains had to be discovered so as, for example, to provide precise abstract descriptions of substitutions and unification. It seems that more work is needed to study a hierarchy of abstract domains expressing from the simplest to the more complex properties of logic programs among which a choice could be made for particular applications to tune the cost/precision trade-off. We have suggested a few well-known methods that have stood the test of time in other areas and which might also be useful for the abstract interpretation of logic programs such as the combination of top/down and bottom/up analyses and the use of infinite algebraic domains expressing powerful relational properties. Presently such domains have been mainly utilized for numerical values but the community of researchers on logic programming is certainly the best placed to extend these methods to non-numerical domains. If this work, or more work on abstract interpretation of logic programs, could be expressed in language independent ways using general-purpose semantics it would certainly be easier to understand and apply in many other application areas. Beyond the present emphasis on parallelism and constraints, further specific work seems also needed to incorporate all features of logic programming such as imperative features, dynamic program modification, modular or incremental programming, etc.

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