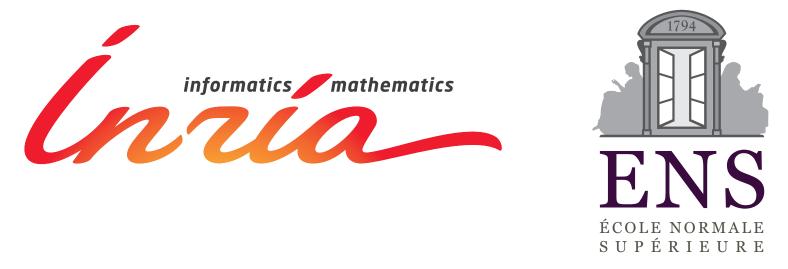
On the Effectiveness of Richardson Extrapolation in Machine Learning

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MAD+ Seminar - May 20, 2020

https://arxiv.org/pdf/2002.02835 https://francisbach.com/richardson-extrapolation/

Acceleration in numerical analysis

• Principle

- Given asymptotic expansion in t around t_{∞} (typically 0 or $+\infty$)

$$x_t = x_* + g_t + O(h_t),$$

where $x_* \in \mathbb{R}^d$ is the desired output and $h_t = o(||g_t||)$

- Combine iterates simply to obtain a sequence $y_t = x_* + O(h_t)$
- Without the full knowledge of g_t

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Richardson extrapolation (Richardson, 1911)

- Sublinear convergence: $x_t = x_* + t^{\alpha} \Delta + O(t^{\beta})$
 - Linear combination $2x_t x_{2^{1/\alpha_t}}$

$$2x_t - x_{2^{1/\alpha_t}} = 2(x_* + t^{\alpha}\Delta + O(t^{\beta})) - (x_* + (2^{1/\alpha}t)^{\alpha}\Delta + O(t^{\beta}))$$

= $x_* + O(t^{\beta})$

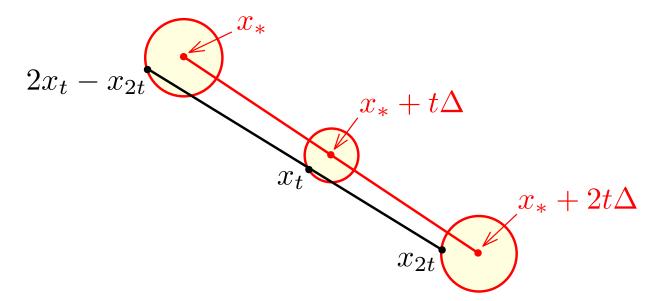
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– Illustration with $t_{\infty} = 0$ and $\alpha = 1$, that is, $x_t = x_* + t\Delta + O(t^2)$



- Typically used within integration methods (Richardson-Romberg)

- Iteration of an optimization algorithm: $t = k \rightarrow +\infty$
 - Averaged gradient descent
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 - Ridge regression (not presented)

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Iteration of an optimization algorithm

• Iterative algorithm $x_k \in \mathbb{R}^d$, $k \ge 0$, with asymptotic expansion

$$x_k = x_* + \frac{1}{k}\Delta + O(1/k^2)$$

- Extrapolation $x_k^{(1)} = 2x_k - x_{k/2}$ such that $x_k^{(1)} = x_* + O(1/k^2)$

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- When can we expect extrapolation to work?
 - Having $||x_k x_*||^2 = O(1/k^2)$ is not enough
 - Needs a specific asymptotic expansion

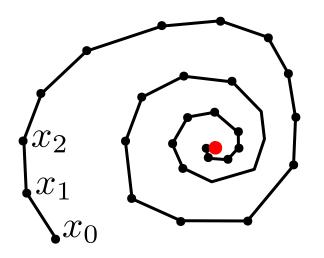
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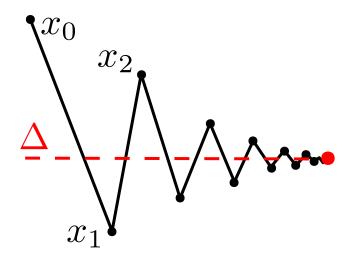
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oscillating convergence



non-oscillating convergence

Averaged gradient descent - I

- Unconstrained minimization $\min_{x \in \mathbb{R}^d} f(x)$
 - -f convex, three-times differentiable
 - Hessian eigenvalues bounded
 - Unique minimizer $x_* \in \mathbb{R}^d$ such that $f''(x_*)$ is positive definite

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$$x_k = x_{k-1} - \gamma f'(x_{k-1})$$
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- Averaging adds robustness to noise but forbids linear convergence
- Polyak and Juditsky (1992); Nemirovski et al. (2009); Bach and Moulines (2011)

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• Richardson extrapolation (for k even)

$$y_k^{(1)} = 2y_k - y_{k/2} = \frac{2}{k} \sum_{i=0}^{k-1} x_i - \frac{2}{k} \sum_{i=0}^{k/2-1} x_i = \frac{2}{k} \sum_{i=k/2}^{k-1} x_i$$

- Equivalent to tail-averaging (Jain et al., 2018)

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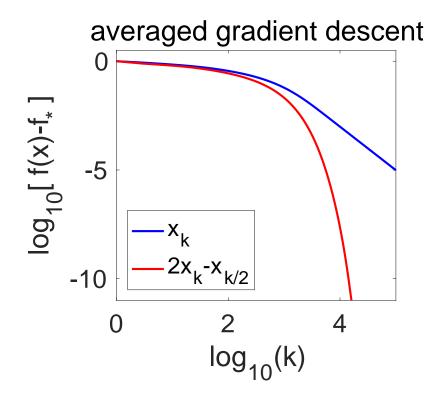
- Equivalent to tail-averaging (Jain et al., 2018)
- Asymptotic expansion: $y_k = x_* + \frac{1}{k}\Delta + O(\rho^k)$, where $\Delta = \sum_{i=0}^{\infty} (x_i - x_*)$ and $\rho \in (0, 1)$
 - Richardson extrapolation restores linear convergence

Averaged gradient descent - III

• Experiments on logistic regression

- Data $(a_i, b_i) \in \mathbb{R}^d \times \{-1, 1\}$, with d = 400 and n = 4000 $\min_{x \in \mathbb{R}^d} f(x) = \frac{1}{n} \sum_{i=1}^n \log(1 + \exp(-b_i x^\top a_i))$

– Covariance matrix of inputs with eigenvalues 1/j , $j=1,\ldots,d$



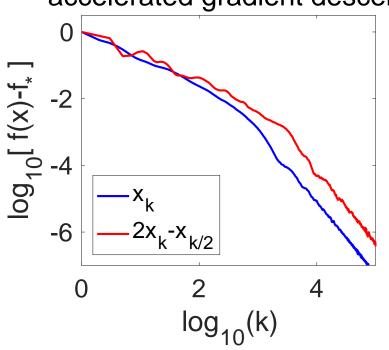
Accelerated gradient descent

• Nesterov acceleration (Nesterov, 1983)

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Accelerated gradient descent

- Nesterov acceleration (Nesterov, 1983)
 - Convergence in $O(1/k^2)$ instead of O(1/k) for convex functions
 - Iterates x_k oscillate around the optimum (see, e.g., Su et al., 2016; Flammarion and Bach, 2015)



accelerated gradient descent

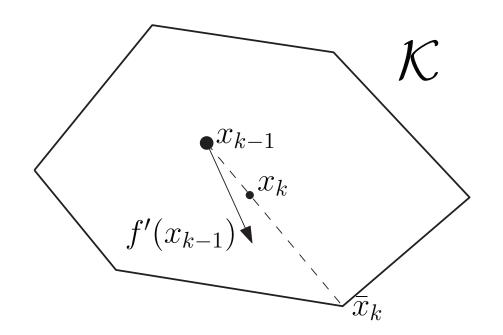
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Frank-Wolfe algorithms - I

• Minimizing function f on a compact set ${\mathcal K}$

$$\bar{x}_{k} \in \arg\min_{x \in \mathcal{K}} f(x_{k-1}) + f'(x_{k-1})^{\top} (x - x_{k-1})$$
$$x_{k} = (1 - \rho_{k}) x_{k-1} + \rho_{k} \bar{x}_{k}$$

- $\rho_k=1/k$, $\rho=2/(k+1)$ or with line search
- Convergence rate: $f(x_k) f(x_*) = O(1/k)$ or $O((\log k)/k)$
- Dunn and Harshbarger (1978); Jaggi (2013)

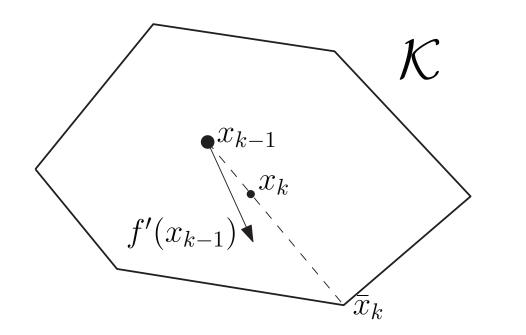


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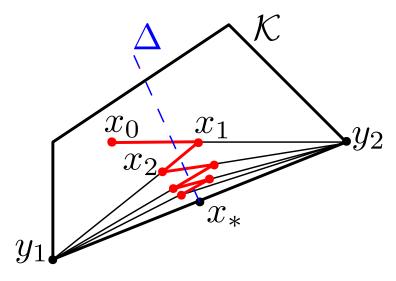
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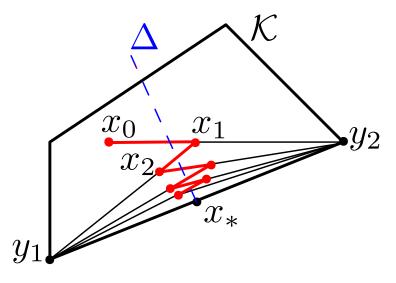
Frank-Wolfe algorithms - II

- Assumptions: \mathcal{K} polytope + "constraint qualification"
- Step-size $\rho_k = 1/k$
 - Asymptotic expansion: $x_k = x_* + \frac{1}{k}\Delta_1 + O(1/k^2)$ With Δ_1 orthogonal the facet of x_* in \mathcal{K}



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- Function values: $f(x_k) f(x_*) = \frac{1}{k} \Delta_1^{\top} f'(x_*) + O(1/k^2)$
- Richardson: $f(2x_k x_{k/2}) f(x_*) = O(1/k^2)$
- Richardson extrapolation transforms O(1/k) to $O(1/k^2)$

Frank-Wolfe algorithms - III

- Step-size $\rho_k = 1/k$
- Experiments on constrained logistic regression

- Data $(a_i, b_i) \in \mathbb{R}^d \times \{-1, 1\}$, with d = 400 and n = 400 $\min_{\|x\|_1 \leqslant c} \quad \frac{1}{n} \sum_{i=1}^n \log(1 + \exp(-b_i x^\top a_i))$ step 1/k 0 -x_k $-2x_k - x_{k/2}$ -6 2 0 4

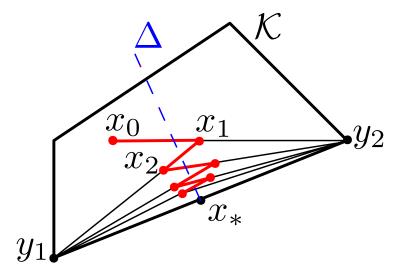
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Frank-Wolfe algorithms - IV

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$$\rho_k = 2/(k+1)$$

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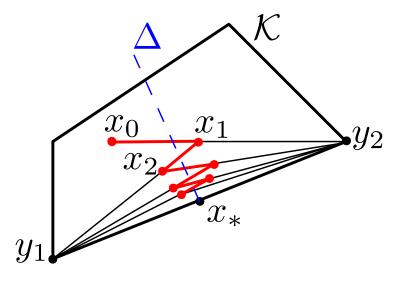


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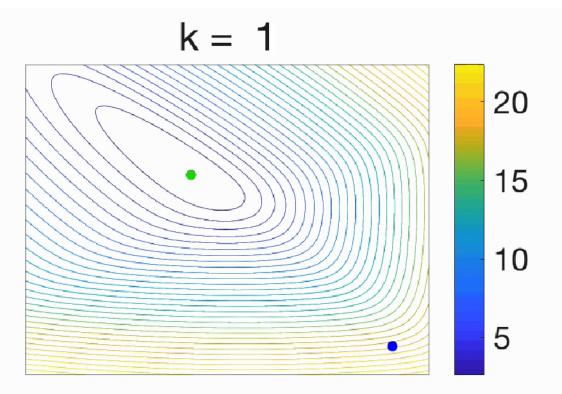
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• Averaged SGD, with stochastic gradients $g'(x_{k-1}, z_k)$

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 and $y_k = \frac{1}{k} \sum_{i=0}^{\kappa-1} x_i$

1, 1

- with expectation $\mathbb{E}_{z_k}g'(x_{k-1}, z_k) = f'(x_{k-1})$ - y_k converges to $y_*^{(\gamma)} \neq x_* = \arg\min f$ (Dieuleveut et al., 2017)



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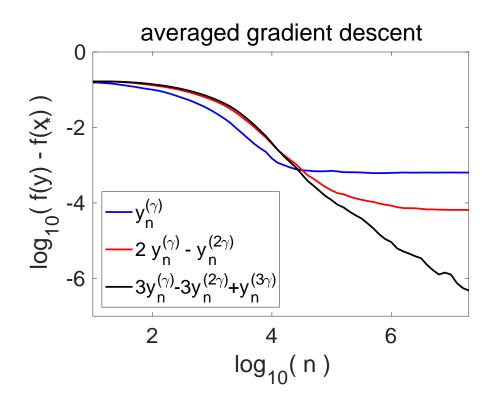
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- Can go up to order m...

- Experiments on logistic regression in dimension 20
 - Dieuleveut, Durmus, and Bach (2017)



- See also Durmus, Simsekli, Moulines, Badeau, and Richard (2016)

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 - Example: smooth $\max\{x, y\}$ by $\lambda \log(\exp(x/\lambda) + \exp(y/\lambda))$
- Optimization of $h + g_{\lambda}$ by accelerated gradient descent
 - Error rate of $O(\lambda + 1/(\lambda k^2))$
 - With $\lambda \propto 1/k$, rate of O(1/k)
 - Better than subgradient method in $O(1/\sqrt{k})$

Nesterov smoothing - II

- Assumptions: (1) polyhedral function g
 (2) smoothing by entropic or quadratic dual penalty
- Asymptotic expansion
 - If x_{λ} is the minimizer of $h + g_{\lambda}$
 - If x_* the global minimizer of f = h + g

$$x_{\lambda} = x_* + \lambda \Delta + O(\lambda^2)$$

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- Then $x_{\lambda}^{(1)} = 2x_{\lambda} x_{2\lambda} = x_* + O(\lambda^2)$ and $f(x_{\lambda}^{(1)}) = f(x_*) + O(\lambda^2)$
- Error rate of $O(\lambda^2 + 1/(\lambda k^2))$
- With $\lambda \propto k^{-2/3}$, overall convergence rate of $k^{-4/3}$

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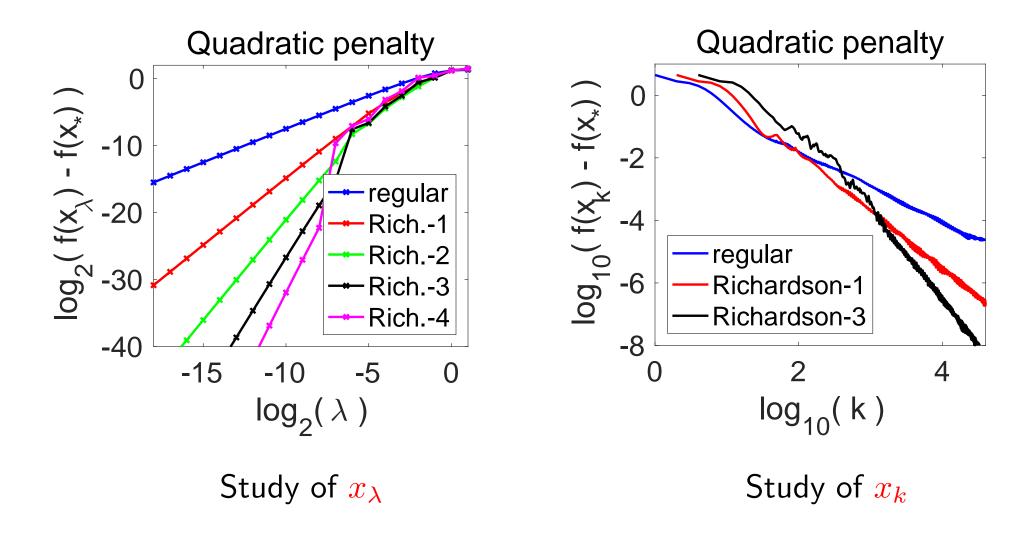
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- With $\lambda \propto k^{-2/3}$, overall convergence rate of $k^{-4/3}$
- High-order expansions have rate $O(k^{-2(m+1)/(m+2)})$

Nesterov smoothing - III

• Experiments on penalized Lasso problem



- Iteration of an optimization algorithm: $t = k \rightarrow +\infty$
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- Other problems?

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