

# Polymorphic Types with Polynomial Sizes

Size tracking without dependent types

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returns (w:'T) where 'T numeric
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### Current limitations

- Redundant size annotations

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**Infer & check sizes together with types**

# Agenda

1. A sized type system
2. Inference
3. Perspectives and conclusion



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## Type safety (ML)

*'Well-typed programs cannot go wrong'*

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- First orders (FOACs): reverse, transpose, ...
- Second orders (SOACs): map, fold, ...

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\*\* under *size consistency* assumptions (map2, ...)

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## Extensions of the ML type system

Type families		Refinement types
$\tau \ i_1 \ \dots \ i_k$	Description	$\{ x : \tau \mid P(x) \}$
Polymorphism	Genericity	Dependent types
✗	Sub-typing	✓
✓	Type checking decidability	?
✓	Type erasable semantics	✗

Dimension types (1994) [5]

Sized types (1996) [3]

Indexed Types (1997) [11]

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# ML

$e ::= x \mid n \mid e e \mid \lambda x. e \mid \text{let } x=e \text{ in } e$

*Expressions*

## ML + Types

$\tau ::= \alpha \mid \text{int} \mid \tau \rightarrow \tau$

*Types*

$e ::= x \mid n \mid e e \mid \lambda x:\tau. e \mid \text{let } x:\tau=e \text{ in } e \mid e \triangleright \tau$

*Expressions*

# ML + Types + Polymorphism

$\tau ::= \alpha \mid \text{int} \mid \tau \rightarrow \tau$

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$e ::= \boxed{S}x \mid n \mid e e \mid \lambda x:\tau. e \mid \text{let } \boxed{V}x:\tau=e \text{ in } e \mid e \triangleright \tau$

*Expressions*

$V ::= \varepsilon \mid \alpha \cdot V$

*Generalization*

$S ::= \varepsilon \mid \tau \cdot S$

*Instantiation*

# ML + Types + Polymorphism + Sizes

$\eta ::= \iota \mid n \mid \eta + \eta \mid \eta * \eta$

**Sizes**

$\tau ::= \alpha \mid \text{int} \mid \tau \rightarrow \tau \mid \langle \eta \rangle \mid [\eta]$

**Types**

$e ::= S_x \mid n \mid e e \mid \lambda x : \tau. e \mid \text{let}_V x : \tau = e \text{ in } e \mid e \triangleright \tau \mid \langle \eta \rangle$

**Expressions**

$V ::= \varepsilon \mid \alpha \cdot V \mid \iota \cdot V$

**Generalization**

$S ::= \varepsilon \mid \tau \cdot S \mid \eta \cdot S$

**Instantiation**

## Integer refinements

- $\langle \eta \rangle$ : singleton type  $\{ x : \text{int} \mid x = \eta \}$  (size  $\eta$ )
- $[\eta]$ : interval type  $\{ x : \text{int} \mid 0 \leq x < \eta \}$  (index  $\eta$ )

# ML + Types + Polymorphism + Sizes

$\eta ::= \iota$

*Sizes*

$\tau ::= \alpha$

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## Where are arrays?

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$S ::= \varepsilon$

*initialiation*

**Integer**

**Where are arrays?**

For typing purposes, arrays are functions on bounded domains:

$$[\eta]\tau \equiv [\eta] \rightarrow \tau$$

**Array access:** application

**Array definition:** abstraction

- $\langle \eta \rangle$ : singleton type

$\{ \wedge : \text{int} \mid \wedge = \eta \}$

(size  $\eta$ )

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$\{ x : \text{int} \mid 0 \leq x < \eta \}$

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# ML + Types + Polymorphism + Sizes

$\eta ::= \iota$

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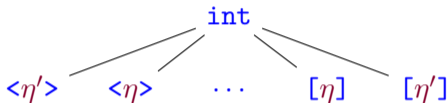
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$$\text{let length}_{\iota,\alpha} : [\iota]\alpha \rightarrow \langle \iota \rangle = \lambda x : [\iota]\alpha. \langle \iota \rangle$$

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## A flat hierarchy of types

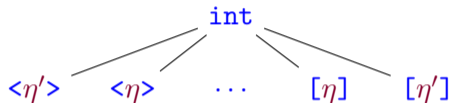
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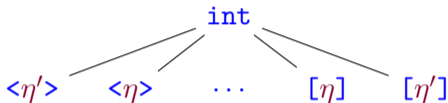


**In particular**

$$[\eta] \not\prec: [\eta + 1]$$

## A flat hierarchy of types

**Rudimentary sub-typing.** No comparison between refinements



**In particular**

$$[\eta] \not\prec: [\eta + 1]$$

**No size inequalities**

- Checking is decidable and simple (normalized polynomials)
- Inference is practical (although incomplete)

## Second Order Array Combinators

**val** map :  $\forall \iota. \alpha. \beta. (\alpha \rightarrow \beta) \rightarrow \langle \iota \rangle \rightarrow [\iota] \alpha \rightarrow [\iota] \beta$

**val** fold :  $\forall \iota. \alpha. \beta. (\alpha \rightarrow \beta \rightarrow \alpha) \rightarrow \langle \iota \rangle \rightarrow \alpha \rightarrow [\iota] \beta \rightarrow \alpha$

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## Type erasable semantics?

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let repeat =  $\lambda n:\langle \iota \rangle. \lambda a. (\lambda i:[\iota]. a)$ 
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(Error: *Unconstrained size*)

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### Remark 1. Non type-erasable semantics

- Refinements<sup>3</sup>       $(\lambda x : [\eta] . e) 8 \rightsquigarrow e\{8 \triangleright [\eta] / x\} \Rightarrow$  stops reduction
- Size expressions       $\langle \eta \rangle \rightsquigarrow \llbracket \eta \rrbracket_{\rho} \Rightarrow$  defines result

<sup>3</sup> Cormac Flanagan. "Hybrid type checking". (2006)

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*Observational semantics* does not depend on type variables

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**Simple combinators** (available in SCADE)

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**Simple combinators** (available in SCADE)

`val reverse` :  $\forall l \cdot \alpha. [l]\alpha \rightarrow [l]\alpha$

`val transpose` :  $\forall l \cdot \kappa \cdot \alpha. [l][\kappa]\alpha \rightarrow [\kappa][l]\alpha$

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**Equivalent type schemes**

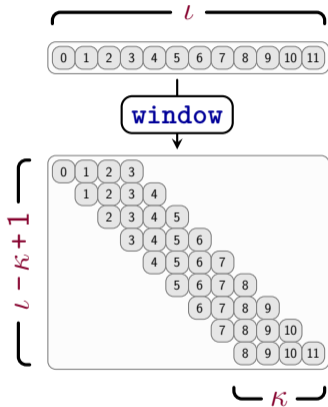
**val** concat :  $\forall l \cdot \kappa \cdot \alpha. [l]\alpha \rightarrow [\kappa - l]\alpha \rightarrow [\kappa]\alpha$

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# First Order Array Combinators

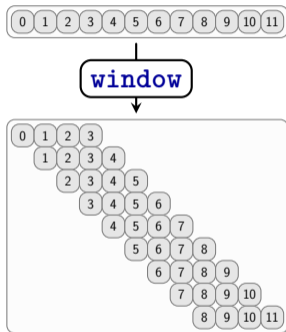


# First Order Array Combinators



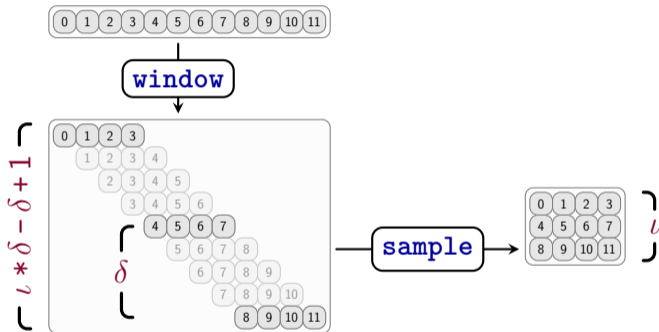
`val window :  $\forall l \cdot k \cdot \alpha . \langle k \rangle \rightarrow [l] \alpha \rightarrow [l - k + 1] [k] \alpha$`

# First Order Array Combinators



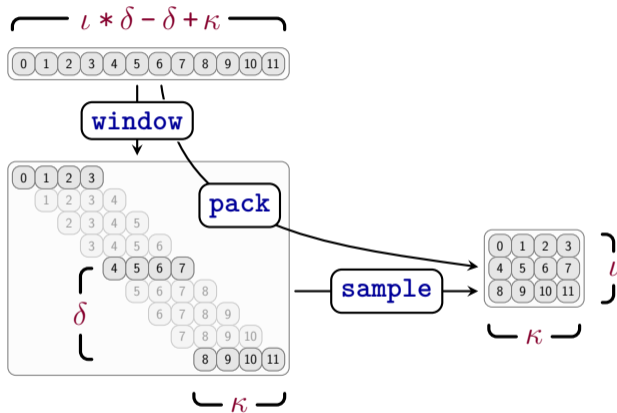
```
let convolution = λk. λi.
  map (dot <_> k) <_> (window <_> i)    [ ∀ℓ.κ. [κ]int → [ℓ + κ - 1]int → [ℓ]int ]
```

# First Order Array Combinators



`val sample :  $\forall \iota \cdot \delta \cdot \alpha . \langle \delta \rangle \rightarrow [\iota * \delta - \delta + 1] \alpha \rightarrow [\iota] \alpha$`

# First Order Array Combinators

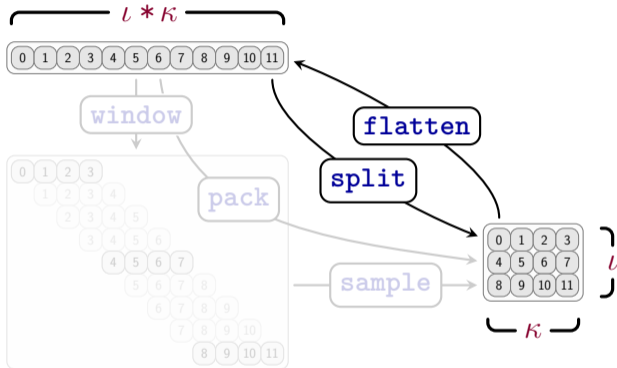


**let** pack =  $\lambda s. \lambda x.$

sample s (window  $\langle \_ \rangle$  x)

$[\forall \iota \cdot \kappa \cdot \delta \cdot \alpha. \langle \delta \rangle \rightarrow [\iota * \delta - \delta + \kappa] \alpha \rightarrow [\iota] [\kappa] \alpha]$

# First Order Array Combinators

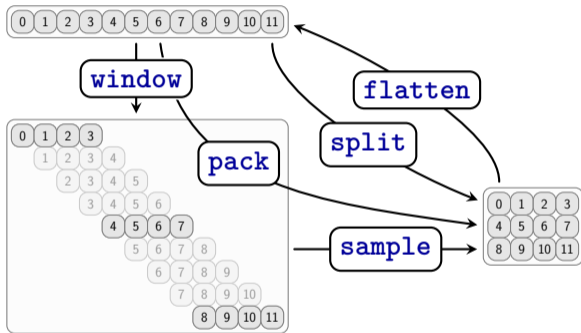


```

val split :  $\forall l \cdot k \cdot \alpha. \langle k \rangle \rightarrow [l * k] \alpha \rightarrow [l] [k] \alpha$ 
val flatten :  $\forall l \cdot k \cdot \alpha. \langle k \rangle \rightarrow [l] [k] \alpha \rightarrow [l * k] \alpha$ 

```

# First Order Array Combinators





## Principal types?

```
let mat : [_] [_] int =  
  split <_> (λi: [4]. 0)
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 [2] [2] int  
 [4] [1] int

## Principal types?

```
let mat : [_] [_] int =  
  split <_> ( $\lambda i : [4]. 0$ )
```

```
let slope =  $\lambda f. \lambda i : [\_]. \lambda j : [\_].$   
  ( $f\ i - f\ j$ ) / ( $i - j$ )
```

{  
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 [2] [2] int  
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$$\left\{ \begin{array}{l} [1] [4] \text{ int} \\ [2] [2] \text{ int} \\ [4] [1] \text{ int} \end{array} \right.$$

```
let slope = λf. λi: [_]. λj: [_].
  (f i - f j) / (i - j)
```

$$\left\{ \begin{array}{l} \forall \iota. ([\iota] \rightarrow \text{int}) \rightarrow [\iota] \rightarrow [\iota] \rightarrow \text{int} \\ \forall \iota, \kappa. (\text{int} \rightarrow \text{int}) \rightarrow [\iota] \rightarrow [\kappa] \rightarrow \text{int} \end{array} \right.$$

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### Remark 2. No principal types

- Polynomial sizes constraints
- Simple polymorphism

$$\iota * \kappa - 4 = 0$$

Extra refinements add size constraints

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let mat : [ ] [ ] int =
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### Remark 2. No principal types

- Polynomial sizes constraints
- Simple polymorphism

$$\iota * \kappa - 4 = 0$$

Extra refinements add size constraints

### Constrained polymorphism<sup>4</sup>

⇒ delayed size resolution

$$\forall \iota, \kappa, \alpha \mid [\iota], [\kappa] <: \alpha. (\alpha \rightarrow \text{int}) \rightarrow [\iota] \rightarrow [\kappa] \rightarrow \text{int}$$

<sup>4</sup> John C. Mitchell. "Coercion and Type Inference". (1984)



# Agenda

1. A sized type system
2. Inference
3. Perspectives and conclusion

## Inference

**Purpose.** Fill missing *redundant* information

💡 Non type-erasable semantics

💡 No principal types



## Inference

**Purpose.** Fill missing *redundant* information

$t^*$

*Untyped term*

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## Inference

**Purpose.** Fill missing *redundant* information

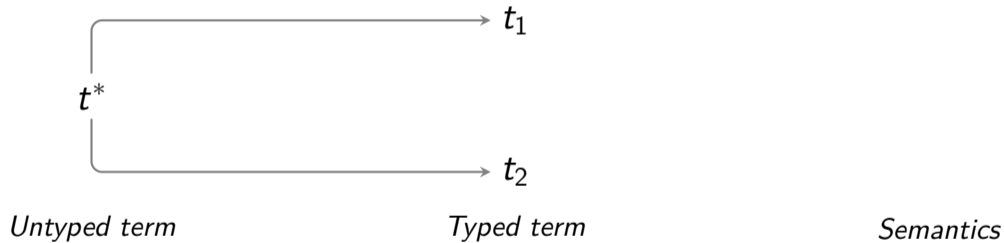
$t^*$

*Untyped term*

*Typed term*

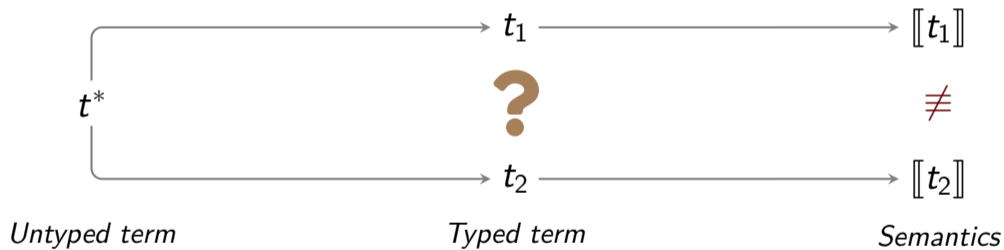
## Inference

**Purpose.** Fill missing *redundant* information



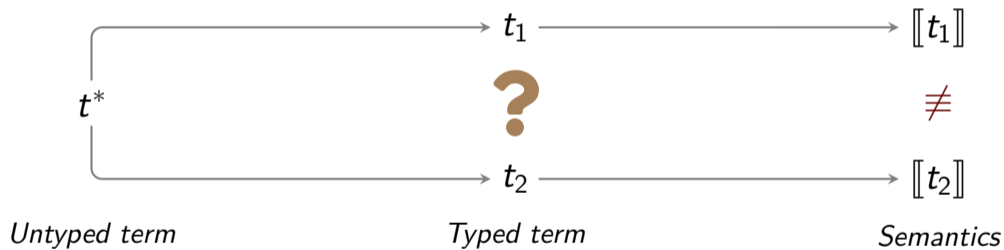
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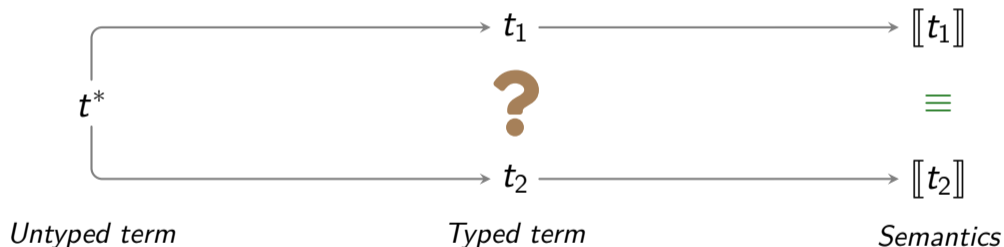
# Inference

**Purpose.** Fill missing *redundant* information



## Inference

**Purpose.** Fill missing *redundant* information, i.e. **without specializing terms**



**No arbitrary size substitutions**

## Algorithm

### One-pass resolution.

1. Collect sub-typing constraints:  $\{ \tau_1 <: \tau_2 \}$
2. At `let` declarations, solve them and generalize size and type variables

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*Type  
unification*

*Refinement  
propagation*

*Size  
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*Refinement  
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let slope :  $\alpha$  =  
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# Algorithm

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1. Collect sub-typing constraints:  $\{ \tau_1 <: \tau_2 \}$

2. First order unification (Hindley-Milner)

$\tau = \tau$

Cons

*Type  
unification*

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```
let slope : (int → int) → int → int → int =  
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# Algorithm

## One-pass resolution.

1. Collect sub-typing constraints:  $\{ \tau_1 <: \tau_2 \}$

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$r <: r$

Cons

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```
let slope : ( $\alpha^+ \rightarrow \alpha^-$ )  $\rightarrow$  [ $\_$ ]  $\rightarrow$  [ $\_$ ]  $\rightarrow$  int =  
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# Algorithm

## One-pass resolution.

1. Collect sub-typing constraints:  $\{ \tau_1 <: \tau_2 \}$

2.

Simplify polynomial system (keeping all solutions)

$\eta = \eta$

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let slope : ( $\alpha^+ \rightarrow \alpha^-$ )  $\rightarrow$  [ $\iota$ ]  $\rightarrow$  [ $\kappa$ ]  $\rightarrow$  int =  
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# Algorithm

## One-pass resolution.

1. Collect sub-typing constraints:  $\{ \tau_1 <: \tau_2 \}$

2. Propagate refinements if sizes match

$\tau <: \tau$

Cons

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```

## Generalization. Variables must...

- ... not appear in any remaining constraints (simple polymorphism)
- ... appear in the type of the declaration (implicit instantiation)

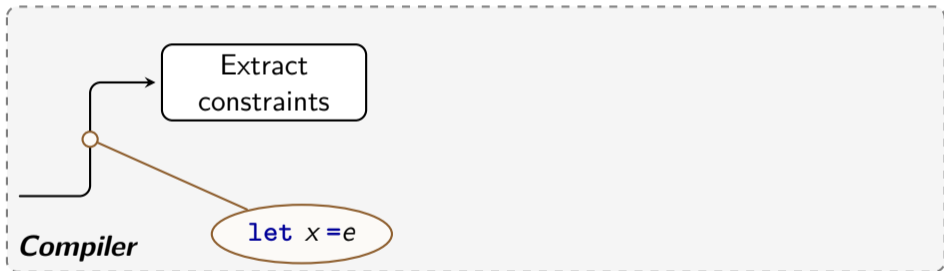
## Using solvers

***Solver***

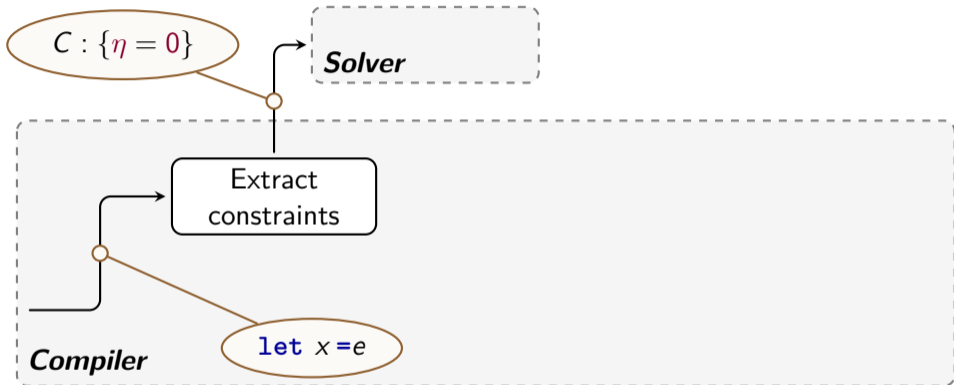
***Compiler***

## Using solvers

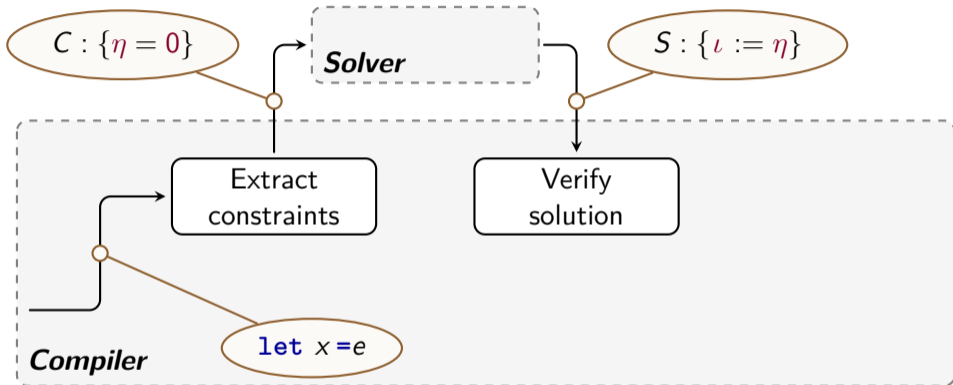
*Solver*



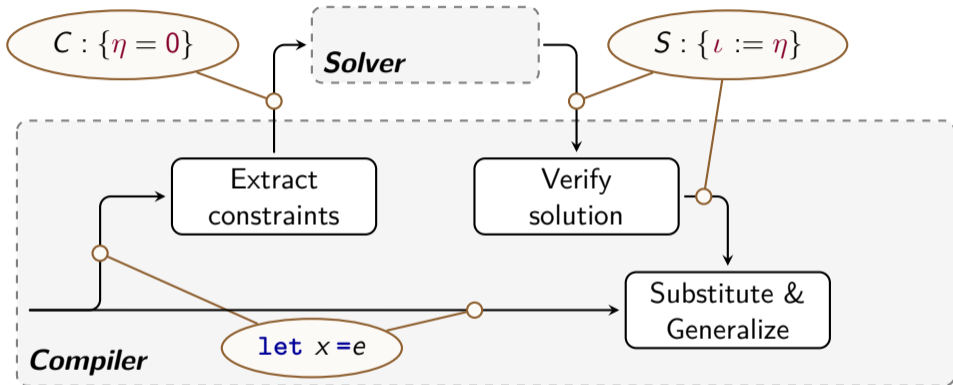
## Using solvers



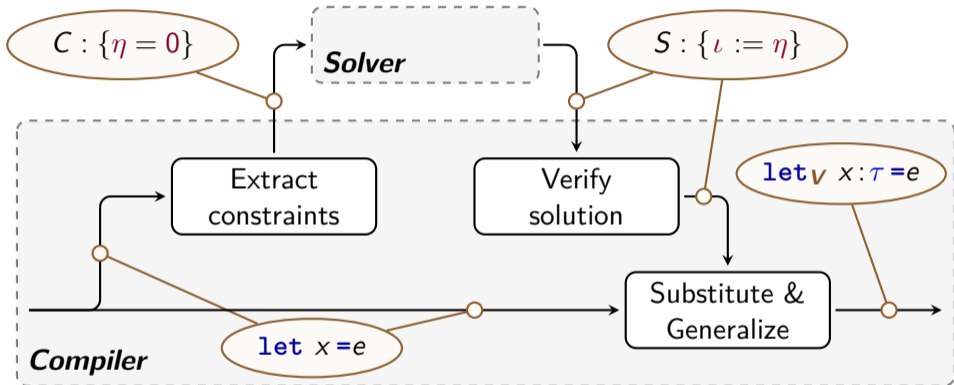
## Using solvers



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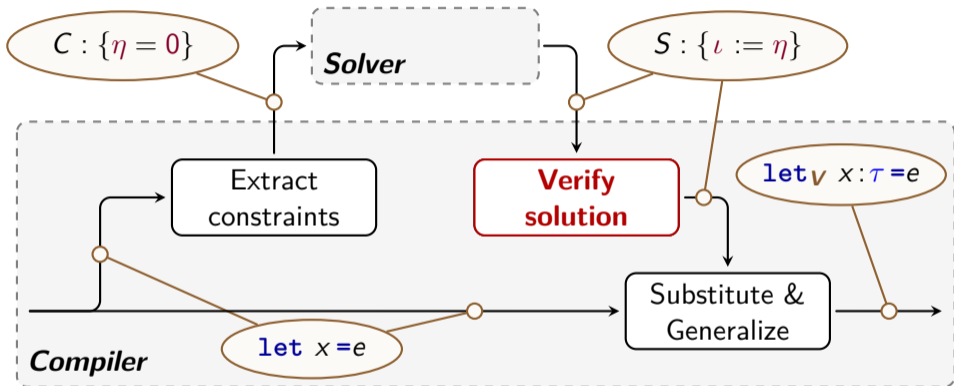


## Using solvers





## Using solvers



### Solution checks

- *Soundness*

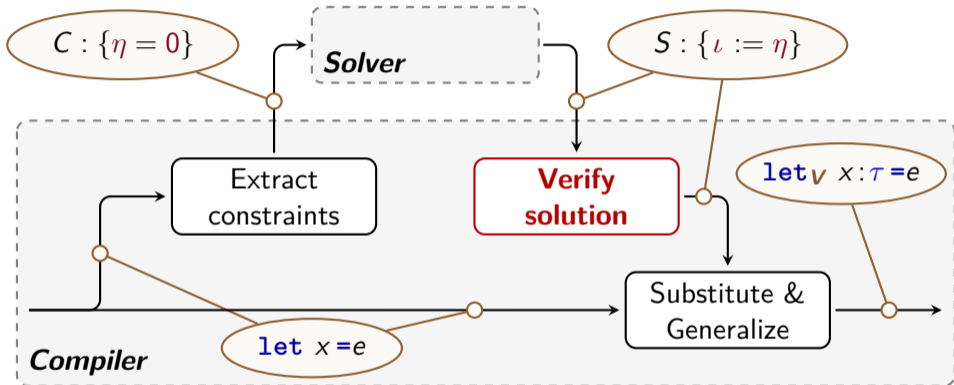
$\vdash C\{S\}$

$S$  solves  $C$



(Correction)

## Using solvers



### Solution checks

- |                       |                 |                  |   |               |
|-----------------------|-----------------|------------------|---|---------------|
| • <i>Soundness</i>    | $\vdash C\{S\}$ | $S$ solves $C$   | ✓ | (Correction)  |
| • <i>Completeness</i> | $C \implies S$  | $S$ is necessary | ✗ | (Determinism) |

# Agenda

1. A sized type system
2. Inference
3. Perspectives and conclusion

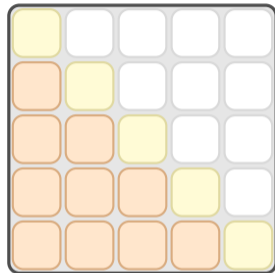
Locally abstract sizes (or types)

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### Local existential sizes.

Construct matrix lines by assembling arrays of varying size

*Example:* The Cholesky decomposition



## Locally abstract sizes (or types)

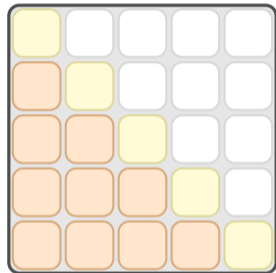
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### First class polymorphism.<sup>5</sup>

Handle dynamically sized arrays with existential sizes.



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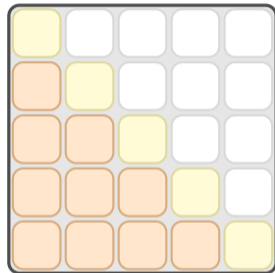
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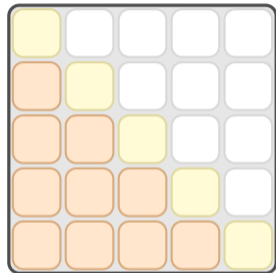
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### Size resolution.

Polynomial decomposition



$$\eta_1 * \kappa + \eta_2 = 0 \quad \overset{?}{\iff} \quad \begin{cases} \eta_1 = 0 \\ \eta_2 = 0 \end{cases}$$

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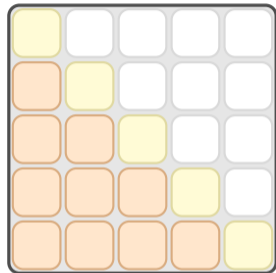
### Polymorphic recursion.

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### Size resolution.

Polynomial decomposition

$$\left\{ \begin{array}{l} \eta_1 * \kappa + \eta_2 = 0 \\ \text{if } \eta_2 \text{ cannot capture } \kappa \end{array} \right. \stackrel{\checkmark}{\iff} \left\{ \begin{array}{l} \eta_1 = 0 \\ \eta_2 = 0 \end{array} \right.$$



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## Take-away

### **A modest extension of ML**

- A restricted form of sub-typing
- Polymorphism is extended to sizes
- Polynomial sizes: trade-off between expressiveness, verification and inference

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- Improved memory placement

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map i  
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## Take-away

### A modest extension of ML

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- Polynomial sizes: trade-off between expressiveness, verification and inference

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**Thanks for your attention**

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**Negative sizes.** Type  $[\eta]$  is empty if  $\eta \leq 0$

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`let magic =  $\lambda a.$   
    flatten <-1> (map ( $\lambda e. \lambda \_ : [-1]. e) <\_> a)$`



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`let magic =  $\lambda a.$`   
`flatten  $\langle -1 \rangle$  (map ( $\lambda e. \lambda \_ : [-1]. e$ )  $\langle \_ \rangle a$ )`       $[\forall \iota. \alpha. [\iota] \alpha \rightarrow [-\iota] \alpha]$

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**Add post-typing constraints.** Check...

- ... at run-time (exceptions)
- ... at instantiation, when sizes get constant values
- ... at declaration, with advanced formal tools

## Constraint solving

```
let slope :  $\alpha$  =  $\lambda f. \lambda i:[]. \lambda j:[]. (f\ i - f\ j) / (i - j)$ 
```

# Constraint solving

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let slope :  $\alpha$  =  $\lambda f. \lambda i: [\_]. \lambda j: [\_]. (f\ i - f\ j) / (i - j)$ 
```

## 1. Simple type unification

$\tau = \tau$

ML simple types (without refinements):

$\tau ::= \alpha \mid \text{int} \mid \tau \rightarrow \tau$

First order unification (Hindley-Milner)

### Possible failures

✗ Incompatible types

$\text{int} = \alpha \rightarrow \alpha$

✗ Recursive substitution

$\alpha = \alpha \rightarrow \alpha$

## Constraint solving

```
let slope :  $\alpha$  =  $\lambda f. \lambda i: [\_]. \lambda j: [\_]. (f\ i - f\ j) / (i - j)$ 
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1. **Simple type unification** —  $\tau = \tau$

$\alpha$

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1. Simple type unification —  $\tau = \tau$

```
(int  $\rightarrow$  int)  $\rightarrow$  int  $\rightarrow$  int  $\rightarrow$  int  $\rightarrow$  int  $\alpha$ 
```

# Constraint solving

let slope :  $\alpha$  =  $\lambda f. \lambda i: [\_]. \lambda j: [\_]. (f\ i - f\ j) / (i - j)$

1. Simj

## 2. Refinement propagation

$r <: r$

Select needed refinements (regardless sizes)

$r ::= x \mid \text{int} \mid \langle \cdot \rangle \mid [\cdot]$

$x^- <: [\cdot] \rightarrow x^- := [\cdot]$

$\text{int} <: x^+ \rightarrow x^+ := \text{int}$



$\alpha$   
 $;\rightarrow \text{int}$

Saturation is deferred after size resolution

### Possible failures

✗ Incompatible refinements

$\langle \cdot \rangle <: [\cdot]$

## Constraint solving

`let slope :  $\alpha$  =  $\lambda f. \lambda i: [\_]. \lambda j: [\_]. (f\ i - f\ j) / (i - j)$`

1. **Simple type unification** —  $\tau = \tau$

$(\text{int} \rightarrow \text{int}) \rightarrow \text{int} \rightarrow \text{int} \rightarrow \text{int}$   $\alpha$

2. **Refinement propagation** —  $r <: r$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow \alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$



## Constraint solving

`let slope :  $\alpha$  =  $\lambda f. \lambda i: [\_]. \lambda j: [\_]. (f\ i - f\ j) / (i - j)$`

1. Simple type unification —  $\tau = \tau$

$\alpha$   
`(int  $\rightarrow$  int)  $\rightarrow$  int  $\rightarrow$  int  $\rightarrow$  int`

2. Refinement propagation —  $r <: r$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$   $\alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [_]  $\rightarrow$  [_]  $\rightarrow$  int`

# Constraint solving

let slope :  $\alpha$  =  $\lambda f. \lambda i: [\_]. \lambda j: [\_]. (f\ i - f\ j) / (i - j)$

1. Simpl

### 3. Size resolution

$\eta = \eta$

Simplification of a polynomial system:  $\{ \eta_i = 0 \}_i$

$\alpha$   
;  $\rightarrow$  int

2. Refi

Isolated variable elimination:

$\rightarrow \alpha_r^+$

$\iota - \eta = 0 \rightarrow \iota := \eta$  where  $\iota \notin FV(\eta)$

|  $\rightarrow$  int

More advanced strategy using *locally abstract variables*

### Possible failures

✗ Incompatible sizes

$6 = 0$

## Constraint solving

let slope :  $\alpha$  =  $\lambda f. \lambda i: [\_]. \lambda j: [\_]. (f\ i - f\ j) / (i - j)$

1. Simple type unification —  $\tau = \tau$

$\alpha$   
 $(\text{int} \rightarrow \text{int}) \rightarrow \text{int} \rightarrow \text{int} \rightarrow \text{int}$

2. Refinement propagation —  $r <: r$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow \alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [\_] \rightarrow [\_] \rightarrow \text{int}$

3. Size resolution —  $\eta = \eta$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [k] \rightarrow \text{int}$

## Constraint solving

**let** slope :  $\alpha = \lambda f. \lambda i: [\_]. \lambda j: [\_]. (f\ i - f\ j) / (i - j)$

1. **Simple type unification** —  $\tau = \tau$

$\alpha$   
 $(\text{int} \rightarrow \text{int}) \rightarrow \text{int} \rightarrow \text{int} \rightarrow \text{int}$

2. **Refinement propagation** —  $r <: r$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow \alpha_j^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [\_] \rightarrow [\_] \rightarrow \text{int}$

3. **Size resolution** —  $\eta = \eta$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [\iota] \rightarrow [\kappa] \rightarrow \text{int}$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [\iota] \rightarrow [\kappa] \rightarrow \text{int}$

# Constraint solving

let slope :  $\alpha$  =  $\lambda f. \lambda i: [\_]. \lambda j: [\_]. (f\ i - f\ j) / (i - j)$

## 4. Refinement saturation

$\tau <: \tau$

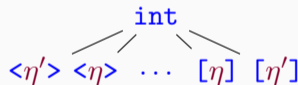
1. Simj

Propagate refinements to positive variables, if sizes match

2. Refil

$\langle \eta \rangle <: \alpha^+ \rightarrow \alpha^+ := \langle \eta \rangle$

$\left\{ \begin{array}{l} [\eta_1] <: \alpha^+ \\ [\eta_2] <: \alpha^+ \end{array} \right. \rightarrow \alpha^+ := \text{int}$



3. Size

Possible failures

$\alpha$   
→ int

→  $\alpha_r^+$   
→ int

→ int  
→ int

## Constraint solving

`let slope :  $\alpha$  =  $\lambda f. \lambda i: [\_]. \lambda j: [\_]. (f\ i - f\ j) / (i - j)$`

1. Simple type unification —  $\tau = \tau$

$\alpha$   
`(int  $\rightarrow$  int)  $\rightarrow$  int  $\rightarrow$  int  $\rightarrow$  int`

2. Refinement propagation —  $r <: r$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$   $\alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [ $\_$ ]  $\rightarrow$  [ $\_$ ]  $\rightarrow$  int`

3. Size resolution —  $\eta = \eta$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [ $\iota$ ]  $\rightarrow$  [ $\kappa$ ]  $\rightarrow$  int  
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [ $\iota$ ]  $\rightarrow$  [ $\kappa$ ]  $\rightarrow$  int`

4. Refinement saturation —  $\tau <: \tau$

`(int  $\rightarrow$   $\alpha_c^-$ )  $\rightarrow$  [ $\iota$ ]  $\rightarrow$  [ $\kappa$ ]  $\rightarrow$  int`

## Constraint solving

**let** slope :  $\alpha = \lambda f. \lambda i: [\_]. \lambda j: [\_]. (f\ i - f\ j) / (i - j)$

1. **Simple type unification** —  $\tau = \tau$

$\alpha$   
 $(\text{int} \rightarrow \text{int}) \rightarrow \text{int} \rightarrow \text{int} \rightarrow \text{int}$

2. **Refinement propagation** —  $r <: r$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow \alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [\_] \rightarrow [\_] \rightarrow \text{int}$

3. **Size resolution** —  $\eta = \eta$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$

4. **Refinement saturation** —  $\tau <: \tau$

$(\text{int} \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$   
 $(\text{int} \rightarrow \text{int}) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$

## Constraint solving

`let slope :  $\alpha$  =  $\lambda f. \lambda i: [6]. \lambda j: [6]. (f\ i - f\ j) / (i - j)$`

1. Simple type unification —  $\tau = \tau$

$\alpha$   
`(int  $\rightarrow$  int)  $\rightarrow$  int  $\rightarrow$  int  $\rightarrow$  int`

2. Refinement propagation —  $r <: r$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$   $\alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [ ]  $\rightarrow$  [ ]  $\rightarrow$  int`

3. Size resolution —  $\eta = \eta$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [  $\iota$  ]  $\rightarrow$  [  $\kappa$  ]  $\rightarrow$  int  
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [  $\iota$  ]  $\rightarrow$  [  $\kappa$  ]  $\rightarrow$  int`

4. Refinement saturation —  $\tau <: \tau$

`(int  $\rightarrow$   $\alpha_c^-$ )  $\rightarrow$  [  $\iota$  ]  $\rightarrow$  [  $\kappa$  ]  $\rightarrow$  int  
(int  $\rightarrow$  int)  $\rightarrow$  [  $\iota$  ]  $\rightarrow$  [  $\kappa$  ]  $\rightarrow$  int`



# Constraint solving

`let slope :  $\alpha$  =  $\lambda f. \lambda i: [6]. \lambda j: [6]. (f\ i - f\ j) / (i - j)$`

1. Simple type unification —  $\tau = \tau$

$\alpha$   
`(int  $\rightarrow$  int)  $\rightarrow$  int  $\rightarrow$  int  $\rightarrow$  int`

2. Refinement propagation —  $r <: r$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$   $\alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [ ]  $\rightarrow$  [ ]  $\rightarrow$  int`

3. Size resolution —  $\eta = \eta$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [  $\iota$  ]  $\rightarrow$  [  $\kappa$  ]  $\rightarrow$  int  
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [  $\iota$  ]  $\rightarrow$  [  $\kappa$  ]  $\rightarrow$  int`

4. Refinement saturation —  $\tau <: \tau$

`(int  $\rightarrow$   $\alpha_c^-$ )  $\rightarrow$  [  $\iota$  ]  $\rightarrow$  [  $\kappa$  ]  $\rightarrow$  int  
(int  $\rightarrow$  int)  $\rightarrow$  [  $\iota$  ]  $\rightarrow$  [  $\kappa$  ]  $\rightarrow$  int`

# Constraint solving

let slope :  $\alpha$  =  $\lambda f. \lambda i: [6]. \lambda j: [6]. (f\ i - f\ j) / (i - j)$

1. Simple type unification —  $\tau = \tau$

$\alpha$   
 $(\text{int} \rightarrow \text{int}) \rightarrow \text{int} \rightarrow \text{int} \rightarrow \text{int}$

2. Refinement propagation —  $r <: r$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow \alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [\_ ] \rightarrow [\_ ] \rightarrow \text{int}$

3. Size resolution —  $\eta = \eta$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$

4. Refinement saturation —  $\tau <: \tau$

$(\text{int} \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$   
 $(\text{int} \rightarrow \text{int}) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$

## Constraint solving

let slope :  $\alpha$  =  $\lambda f. \lambda i: [6]. \lambda j: [6]. (f\ i - f\ j) / (i - j)$

1. Simple type unification —  $\tau = \tau$

$\alpha$   
 $(\text{int} \rightarrow \text{int}) \rightarrow \text{int} \rightarrow \text{int} \rightarrow \text{int}$

2. Refinement propagation —  $r <: r$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow \alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [\_ ] \rightarrow [\_ ] \rightarrow \text{int}$

3. Size resolution —  $\eta = \eta$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$

4. Refinement saturation —  $\tau <: \tau$

$(\text{int} \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$   
 $(\text{int} \rightarrow \text{int}) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$

## Constraint solving

`let slope :  $\alpha$  =  $\lambda f. \lambda i: [6]. \lambda j: [6]. (f\ i - f\ j) / (i - j)$`

1. Simple type unification —  $\tau = \tau$

$\alpha$   
`(int  $\rightarrow$  int)  $\rightarrow$  int  $\rightarrow$  int  $\rightarrow$  int`

2. Refinement propagation —  $r <: r$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$   $\alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [  ]  $\rightarrow$  [  ]  $\rightarrow$  int`

3. Size resolution —  $\eta = \eta$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [ $\iota$ ]  $\rightarrow$  [ $\kappa$ ]  $\rightarrow$  int  
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [ $\iota$ ]  $\rightarrow$  [ $\kappa$ ]  $\rightarrow$  int`

4. Refinement saturation —  $\tau <: \tau$

`(int  $\rightarrow$   $\alpha_c^-$ )  $\rightarrow$  [ $\iota$ ]  $\rightarrow$  [ $\kappa$ ]  $\rightarrow$  int  
(int  $\rightarrow$  int)  $\rightarrow$  [ $\iota$ ]  $\rightarrow$  [ $\kappa$ ]  $\rightarrow$  int`

## Constraint solving

let slope :  $\alpha$  =  $\lambda f. \lambda i: [6]. \lambda j: [6]. (f\ i - f\ j) / (i - j)$

1. Simple type unification —  $\tau = \tau$

$\alpha$   
 $(\text{int} \rightarrow \text{int}) \rightarrow \text{int} \rightarrow \text{int} \rightarrow \text{int}$

2. Refinement propagation —  $r <: r$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow \alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [\_ ] \rightarrow [\_ ] \rightarrow \text{int}$

3. Size resolution —  $\eta = \eta$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [\iota] \rightarrow [\kappa] \rightarrow \text{int}$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [\iota] \rightarrow [\kappa] \rightarrow \text{int}$

4. Refinement saturation —  $\tau <: \tau$

$(\text{int} \rightarrow \alpha_c^-) \rightarrow [\iota] \rightarrow [\kappa] \rightarrow \text{int}$   
 $(\text{int} \rightarrow \text{int}) \rightarrow [\iota] \rightarrow [\kappa] \rightarrow \text{int}$

## Constraint solving

let slope :  $\alpha$  =  $\lambda f. \lambda i: [6]. \lambda j: [6]. (f\ i - f\ j) / (i - j)$

1. Simple type unification —  $\tau = \tau$

$\alpha$   
 $(\text{int} \rightarrow \text{int}) \rightarrow \text{int} \rightarrow \text{int} \rightarrow \text{int}$

2. Refinement propagation —  $r <: r$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow \alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [\_ ] \rightarrow [\_ ] \rightarrow \text{int}$

3. Size resolution —  $\eta = \eta$

$(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$   
 $(\alpha_d^+ \rightarrow \alpha_c^-) \rightarrow [6] \rightarrow [6] \rightarrow \text{int}$

4. Refinement saturation —  $\tau <: \tau$

$(\text{int} \rightarrow \alpha_c^-) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$   
 $(\text{int} \rightarrow \text{int}) \rightarrow [l] \rightarrow [\kappa] \rightarrow \text{int}$

## Constraint solving

`let slope :  $\alpha$  =  $\lambda f. \lambda i: [6]. \lambda j: [6]. (f\ i - f\ j) / (i - j)$`

1. Simple type unification —  $\tau = \tau$

$\alpha$   
`(int  $\rightarrow$  int)  $\rightarrow$  int  $\rightarrow$  int  $\rightarrow$  int`

2. Refinement propagation —  $r <: r$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$   $\alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [  ]  $\rightarrow$  [  ]  $\rightarrow$  int`

3. Size resolution —  $\eta = \eta$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [ $\iota$ ]  $\rightarrow$  [ $\kappa$ ]  $\rightarrow$  int  
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [6]  $\rightarrow$  [6]  $\rightarrow$  int`

4. Refinement saturation —  $\tau <: \tau$

`([6]  $\rightarrow$   $\alpha_c^-$ )  $\rightarrow$  [6]  $\rightarrow$  [6]  $\rightarrow$  int  
(int  $\rightarrow$  int)  $\rightarrow$  [ $\iota$ ]  $\rightarrow$  [ $\kappa$ ]  $\rightarrow$  int`

## Constraint solving

`let slope :  $\alpha$  =  $\lambda f. \lambda i: [6]. \lambda j: [6]. (f\ i - f\ j) / (i - j)$`

1. Simple type unification —  $\tau = \tau$

$\alpha$   
`(int  $\rightarrow$  int)  $\rightarrow$  int  $\rightarrow$  int  $\rightarrow$  int`

2. Refinement propagation —  $r <: r$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$   $\alpha_i^- \rightarrow \alpha_j^- \rightarrow \alpha_r^+$   
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [ ]  $\rightarrow$  [ ]  $\rightarrow$  int`

3. Size resolution —  $\eta = \eta$

`( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [ $\iota$ ]  $\rightarrow$  [ $\kappa$ ]  $\rightarrow$  int  
( $\alpha_d^+ \rightarrow \alpha_c^-$ )  $\rightarrow$  [6]  $\rightarrow$  [6]  $\rightarrow$  int`

4. Refinement saturation —  $\tau <: \tau$

`([6]  $\rightarrow$   $\alpha_c^-$ )  $\rightarrow$  [6]  $\rightarrow$  [6]  $\rightarrow$  int  
([6]  $\rightarrow$  int)  $\rightarrow$  [6]  $\rightarrow$  [6]  $\rightarrow$  int`



## Issue 1: Size-dependent Semantics

### Non type-erasable semantics

#### Coerced substitutions

$$(\lambda x: [\eta]. e) \delta \rightsquigarrow e\{\delta \triangleright [\eta] / x\}$$

Sizes may stop the reduction

#### Size expressions

$$\langle \eta \rangle \rightsquigarrow \llbracket \eta \rrbracket_\rho$$

Sizes define the reduction result

*Observational semantics* does not depend on type variables:

$$e\{\bar{\tau}_1 / \bar{\alpha}\} \equiv e\{\bar{\tau}_2 / \bar{\alpha}\} \quad \text{where } \bar{\alpha} = FV(e)$$

**Intuition:** Type variables...

- ... have no *computational content*
- ... may only impact the domain of definition

## Issue 2: Principal types?

```
let slope = λf. λi: [⋮]. λj: [⋮]. (f i - f j) / (i - j)
```

### 1. Simple polymorphism

⇒ no principal types

### Constrained polymorphism<sup>6</sup>

⇒ delayed size resolution

### 2. Polynomial size constraints:

$$l * \kappa - 4 = 0$$

---

<sup>6</sup> John C. Mitchell. "Coercion and Type Inference". (1984)

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