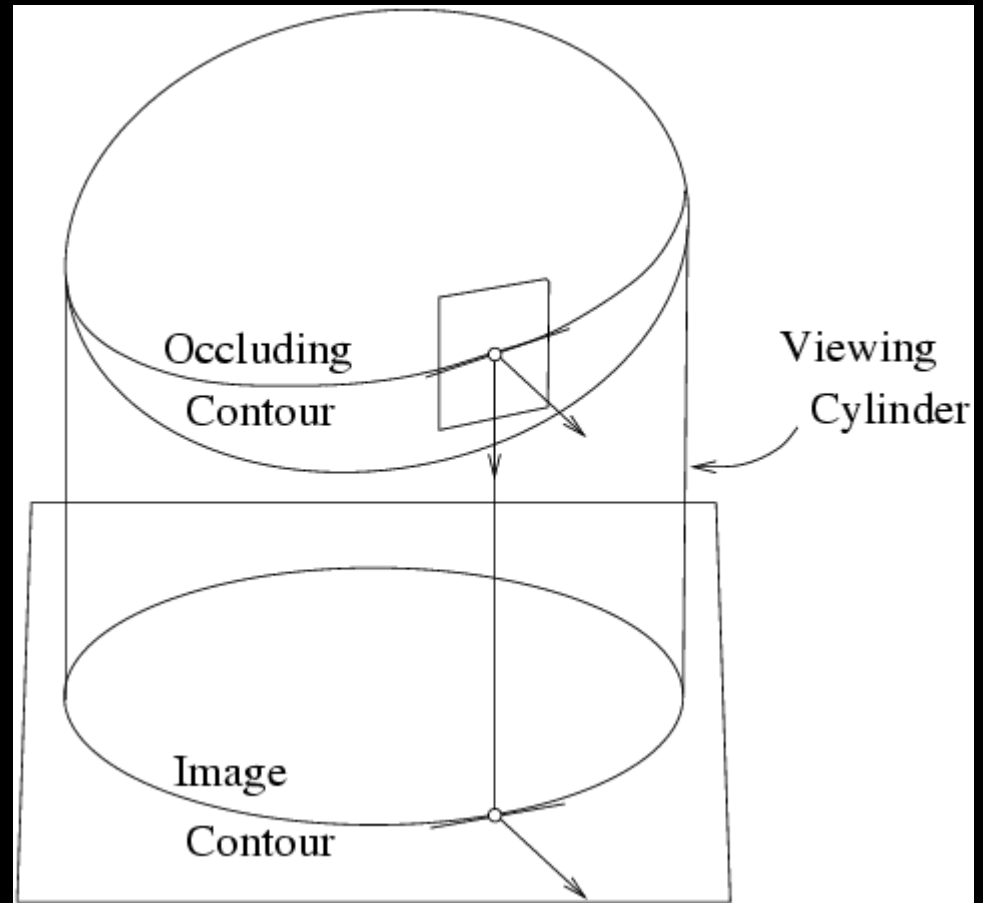
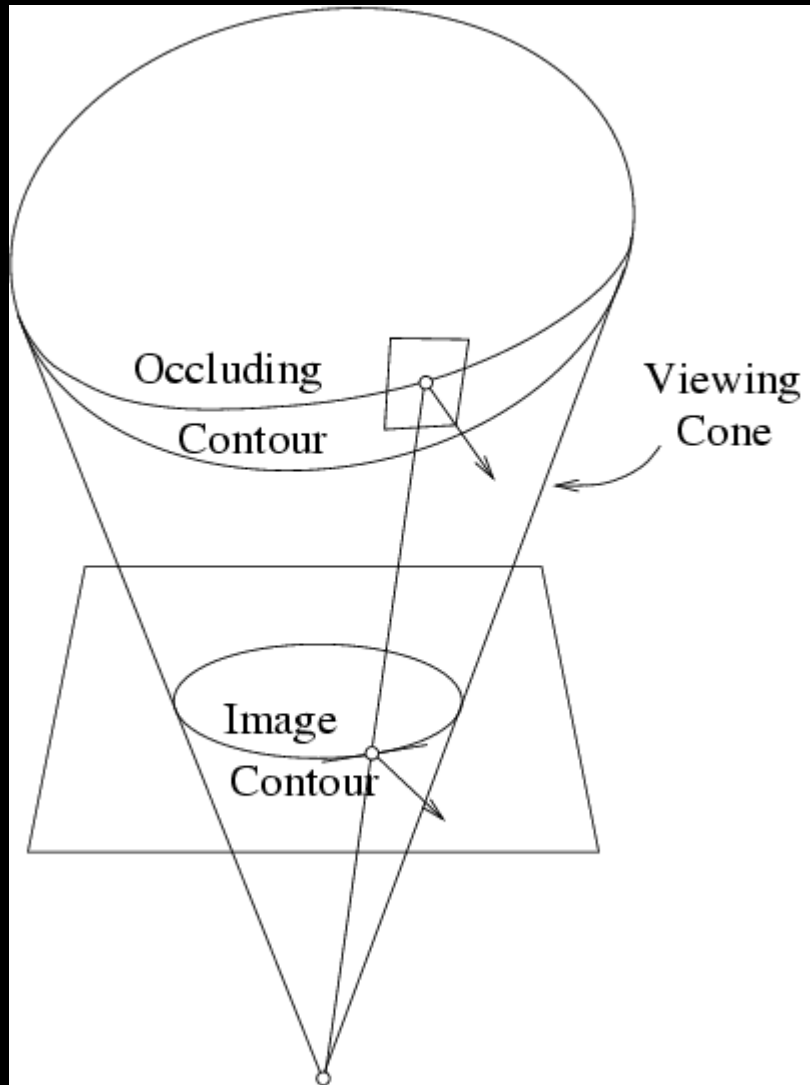


# SMOOTH SURFACES AND THEIR OUTLINES

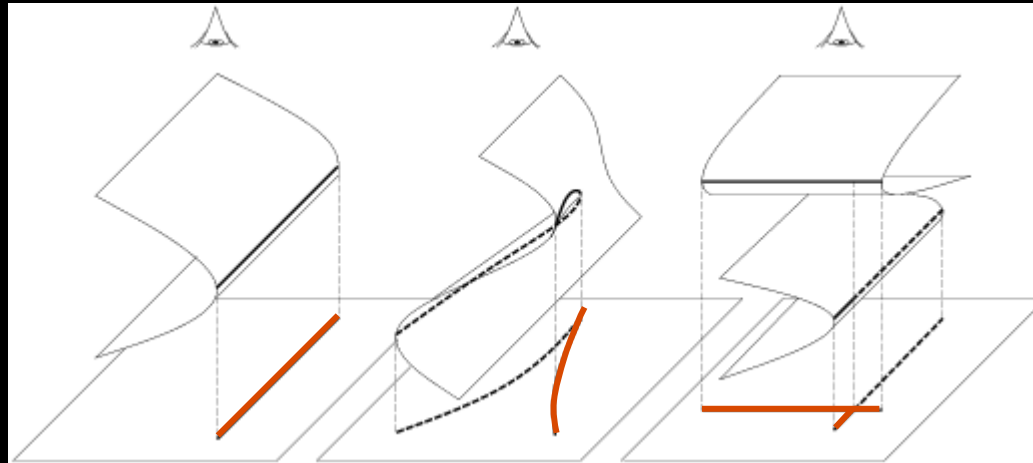
- Elements of Differential Geometry
  - The second fundamental form
  - Koenderink's Theorem
  - Aspect graphs
  - More differential geometry
  - A catalogue of visual events
  - Computing the aspect graph
- 
- <http://www.di.ens.fr/~ponce/geomvis/lect6.pptx>
  - <http://www.di.ens.fr/~ponce/geomvis/lect6.pdf>

# Smooth Shapes and their Outlines



Can we say anything about a 3D shape from the shape of its contour?

# What are the contour **stable** features??



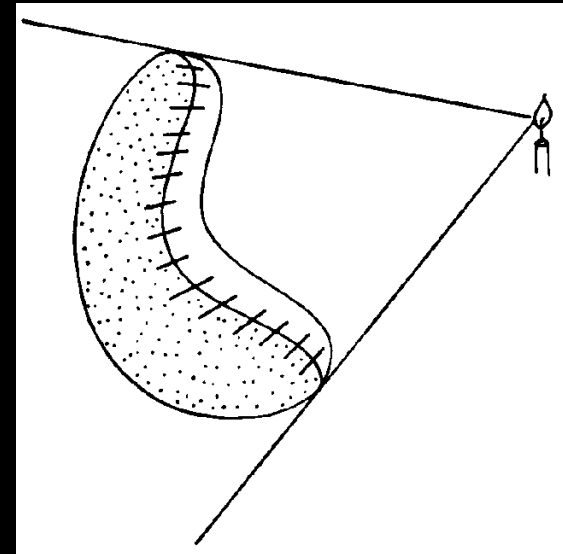
folds

cusps

T-junctions



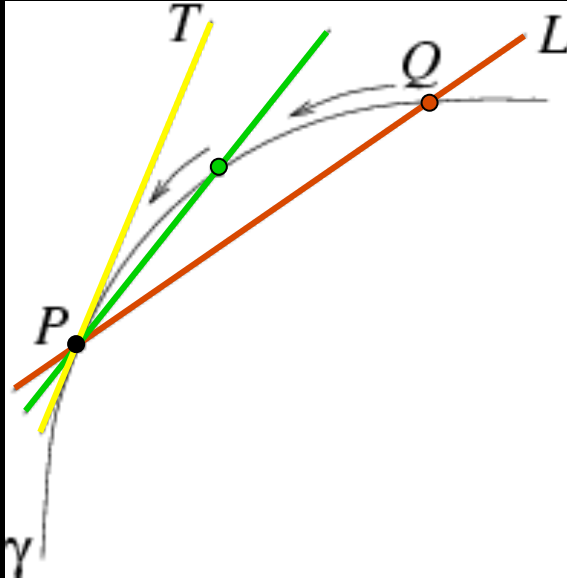
Shadows  
are like  
silhouettes..



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MIT Press (1990). © 1990 by the MIT.

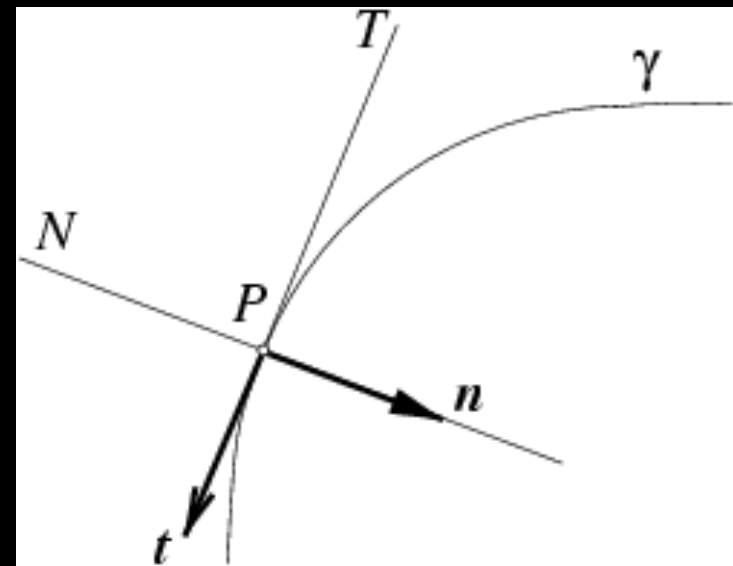
Reprinted from "Computing Exact  
Aspect Graphs of Curved Objects:  
Algebraic Surfaces," by S. Petitjean,  
J. Ponce, and D.J. Kriegman, the  
International Journal of Computer  
Vision, 9(3):231-255 (1992). © 1992  
Kluwer Academic Publishers.

# Differential geometry: geometry in the small

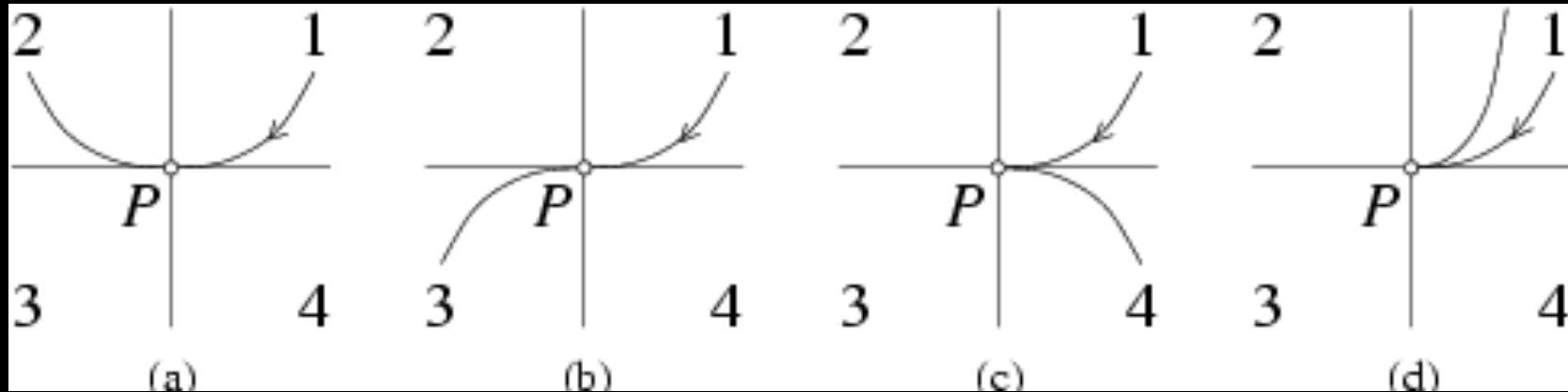


A tangent is the limit of a sequence of secants.

The normal to a curve is perpendicular to the tangent line.



What can happen to a curve in the vicinity of a point?



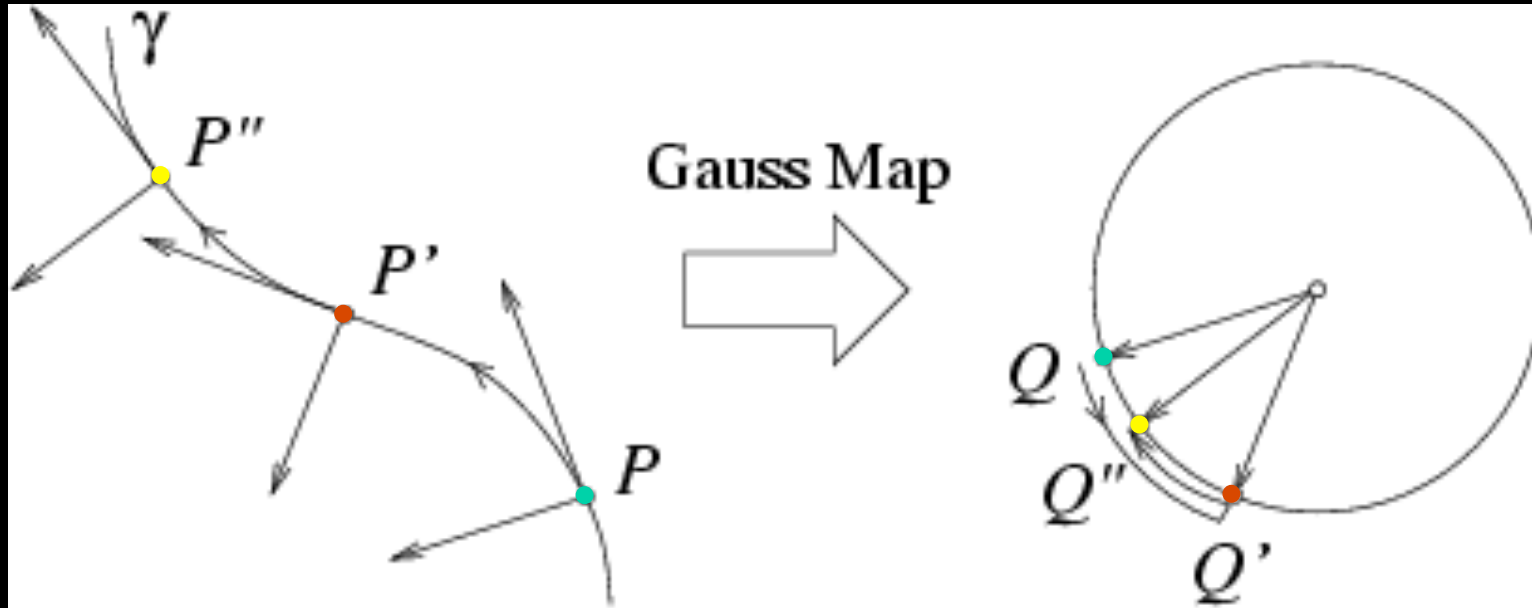
(a) Regular point;

(b) inflection;

(c) cusp of the first kind;

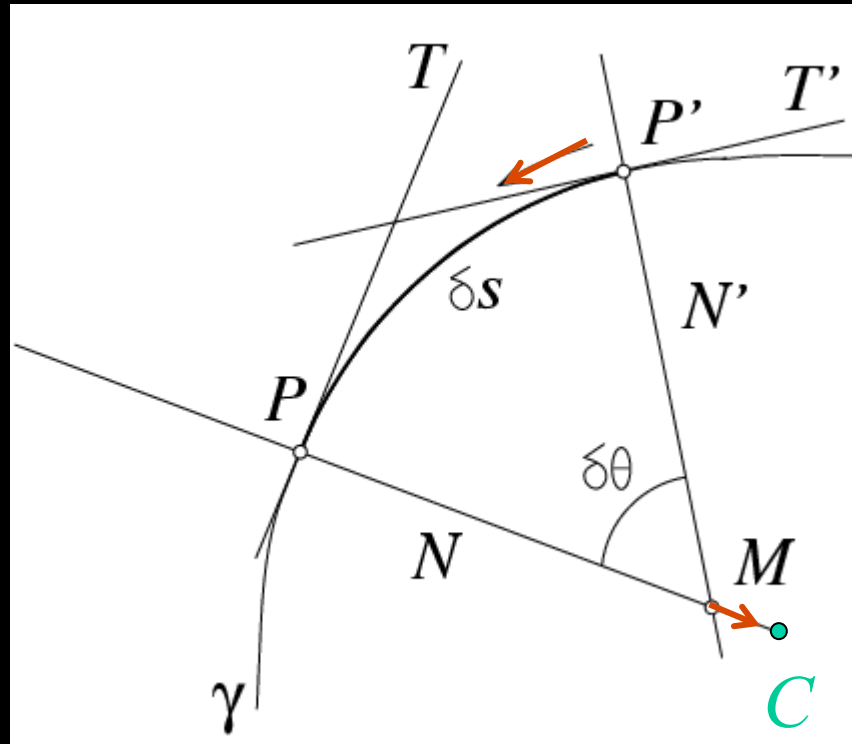
(d) cusp of the second kind.

# The Gauss Map



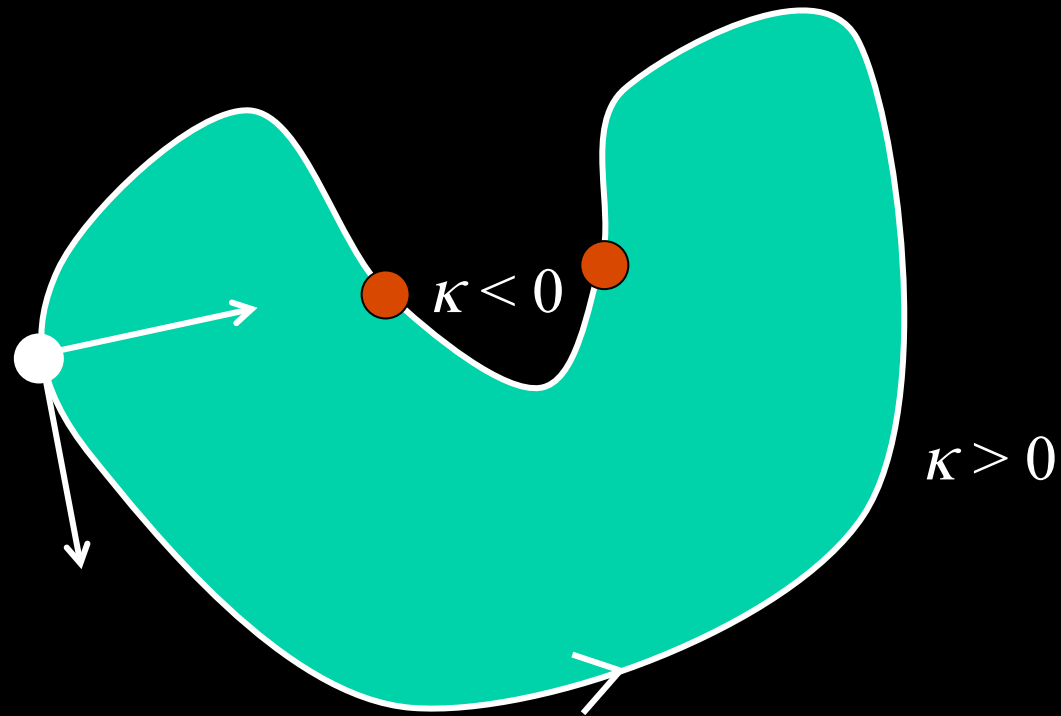
- It maps points on a curve onto points on the unit circle.
- The direction of traversal of the Gaussian image reverses at inflections: it folds there.

## The curvature



- $C$  is the center of curvature;
- $R = CP$  is the radius of curvature;
- $\kappa = \lim \delta\theta/\delta s = 1/R$  is the curvature.

Closed curves admit a canonical orientation..

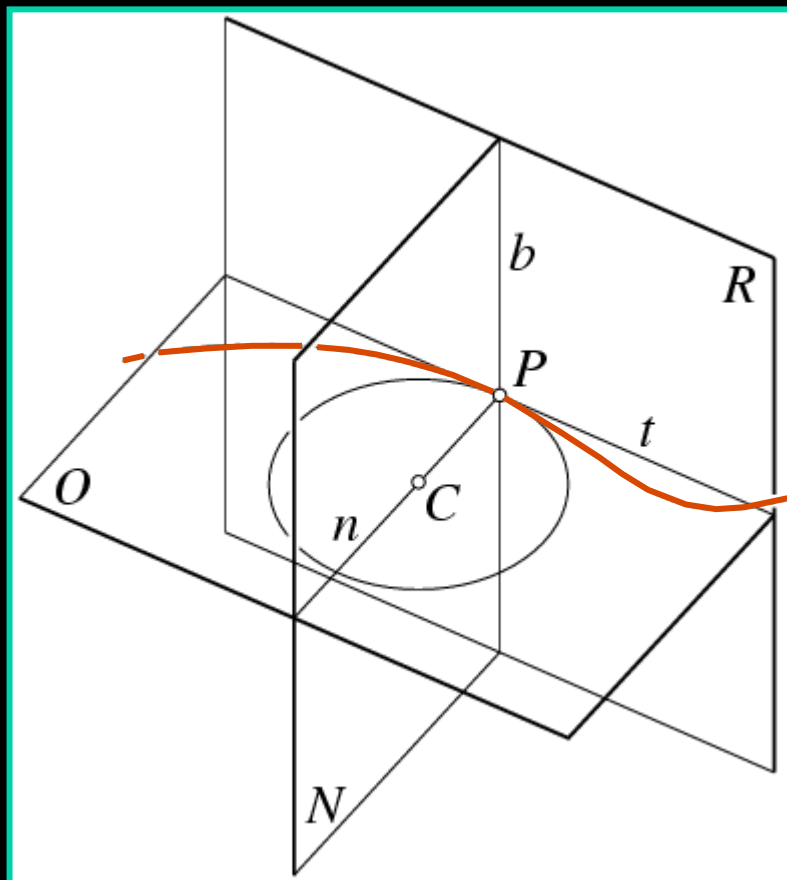


$$\kappa = d\theta / ds$$
$$dt/ds = \kappa \mathbf{n}$$

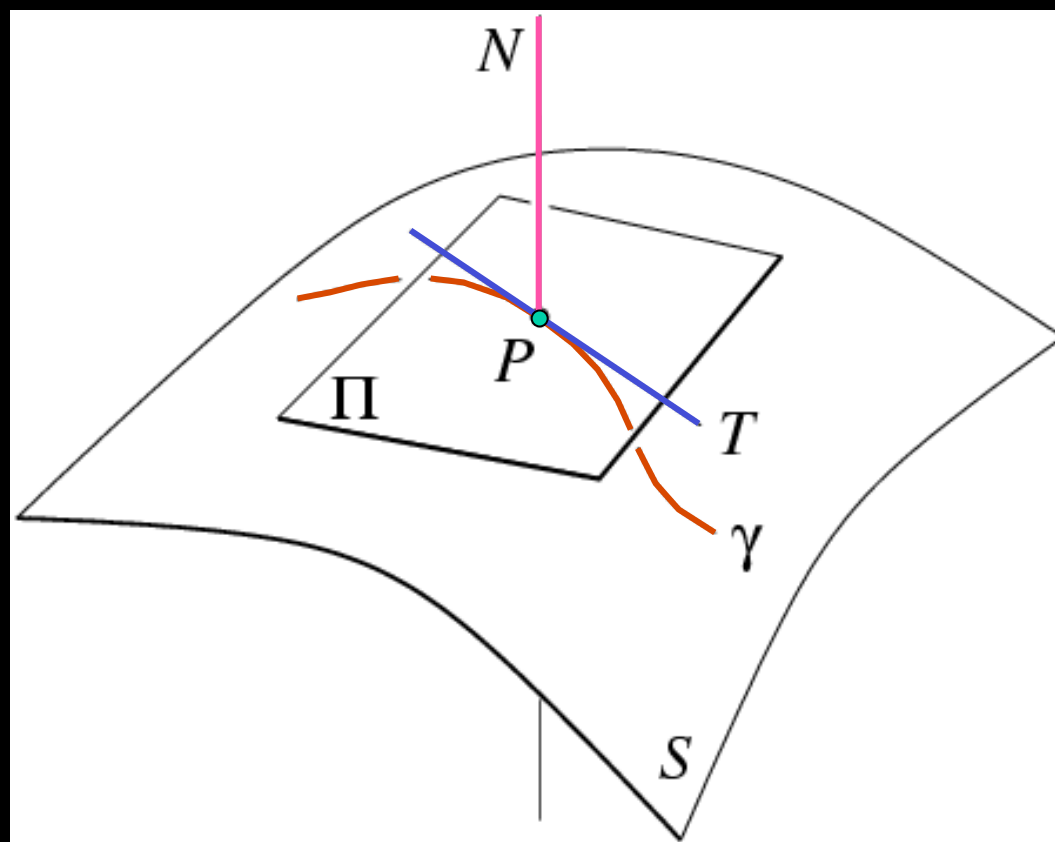
← derivative of the Gauss map



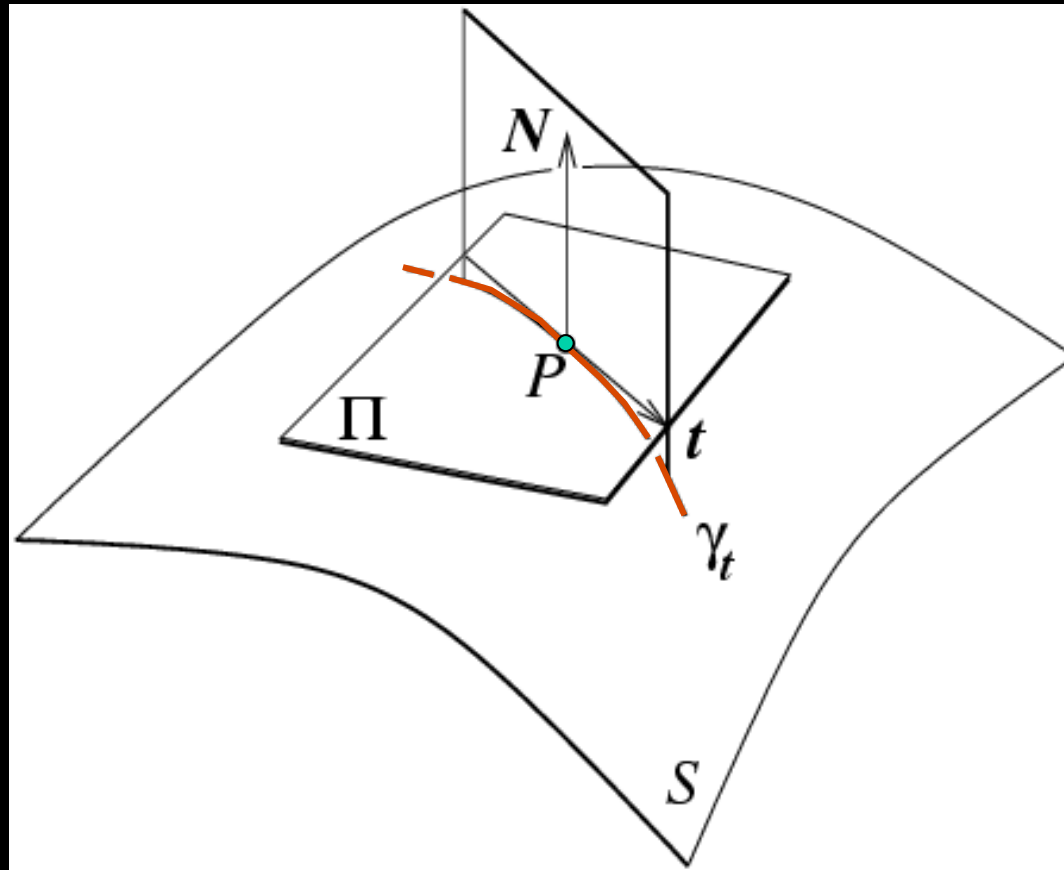
Twisted curves are more complicated animals..



A smooth surface, its tangent plane and its normal.



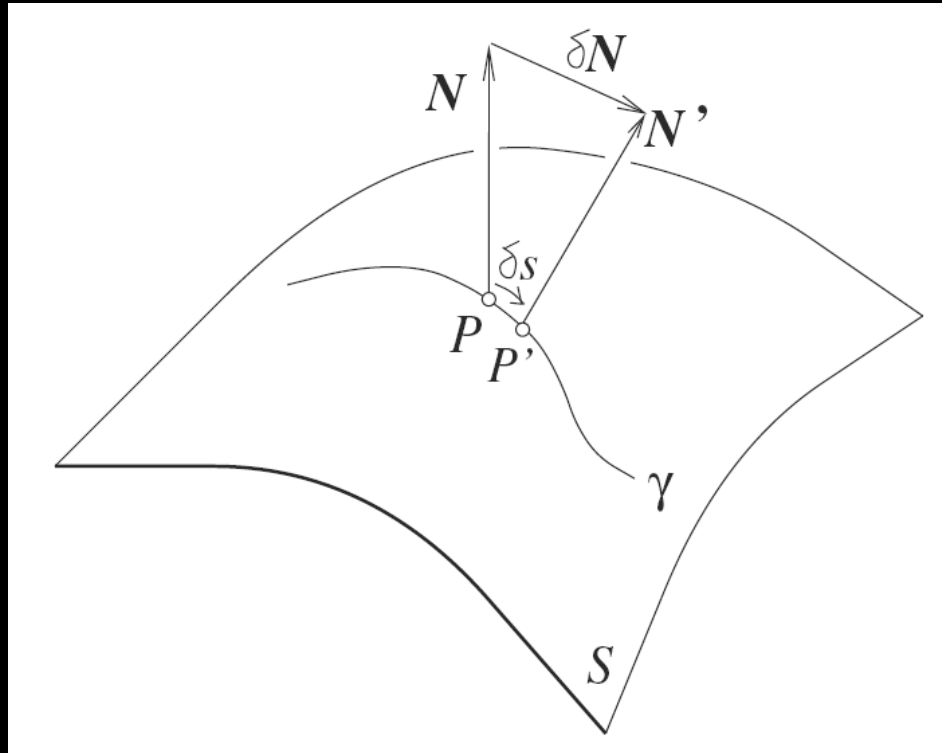
## Normal sections and normal curvatures



Principal curvatures:  
minimum value  $\kappa_1$   
maximum value  $\kappa_2$

Gaussian curvature:  
 $K = \kappa_1 \kappa_2$

## The differential of the Gauss map

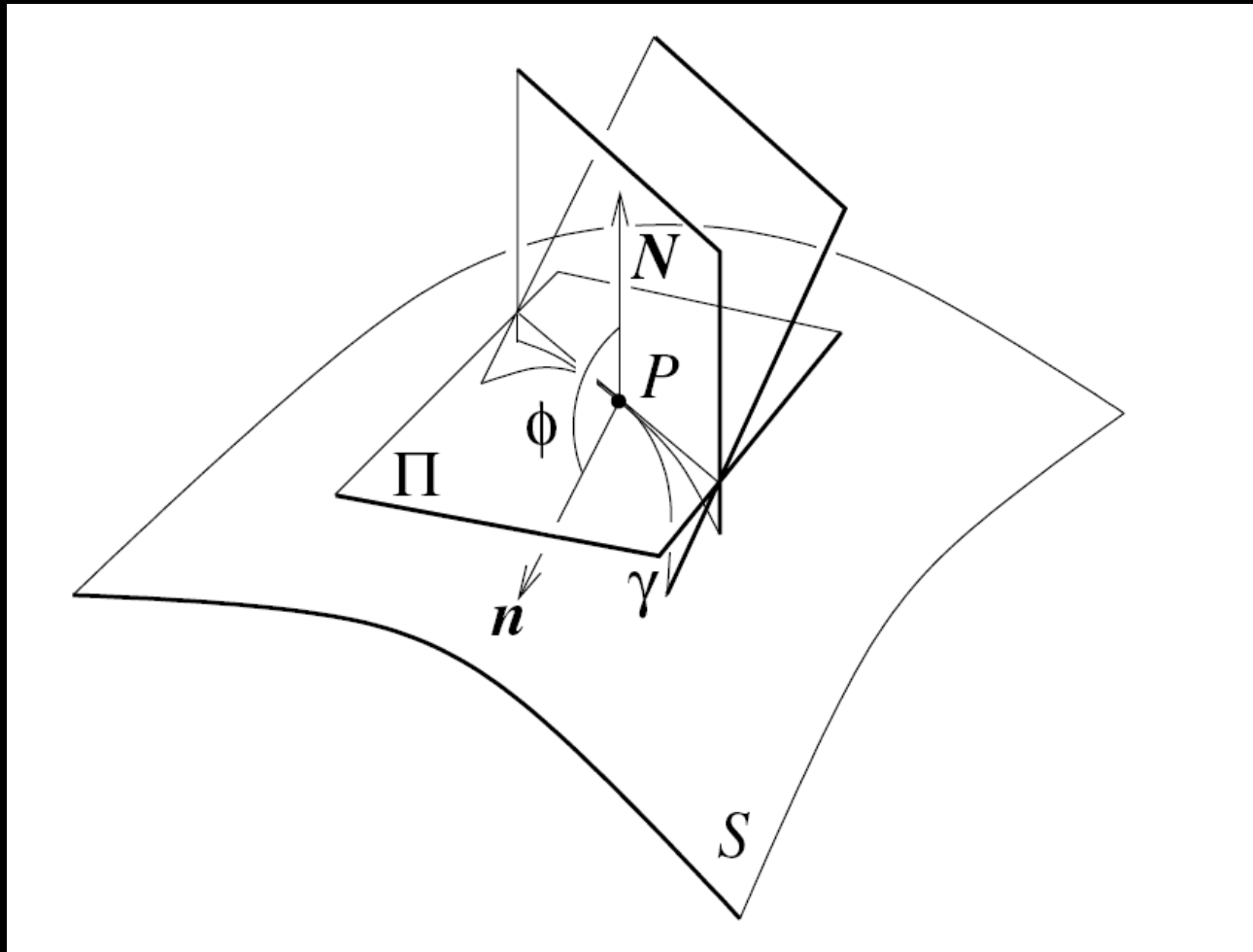


$$d\mathbf{N}(\mathbf{t}) = \lim_{\delta s \rightarrow 0} \frac{1}{\delta s} \delta \mathbf{N}$$

Second fundamental form:  
 $\text{II}(\mathbf{u}, \mathbf{v}) = \mathbf{u}^T d\mathbf{N}(\mathbf{v})$

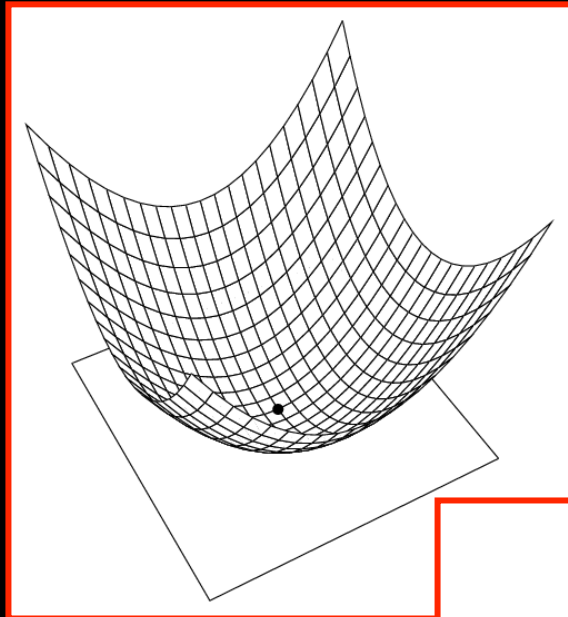
(II is symmetric.)

- The normal curvature is  $\kappa_t = \text{II}(\mathbf{t}, \mathbf{t})$ .
- Two directions are said to be conjugated when  $\text{II}(\mathbf{u}, \mathbf{v}) = 0$ .



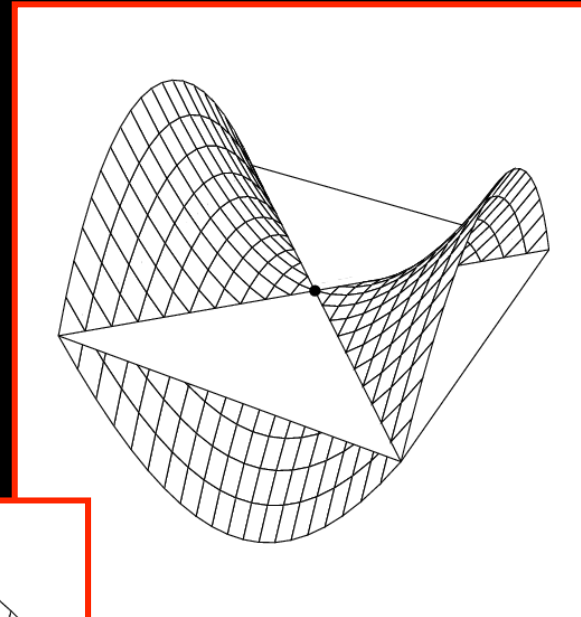
Meusnier's theorem:  $\kappa_t = -\kappa \cos\phi$ .

# The local shape of a smooth surface



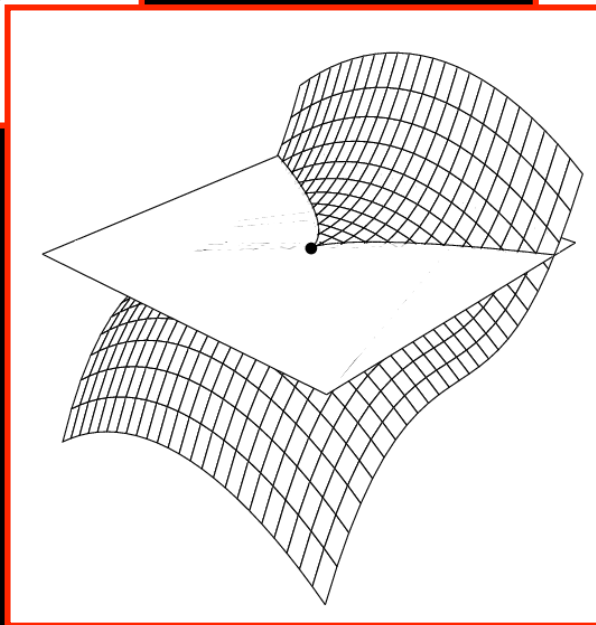
Elliptic point

$$K > 0$$



Hyperbolic point

$$K < 0$$

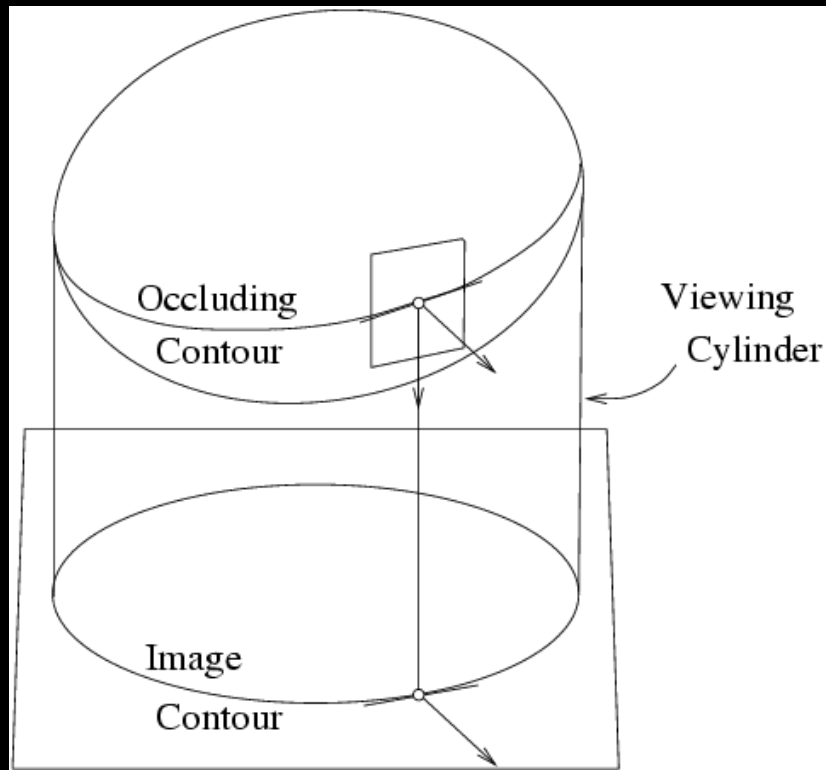


Parabolic point  $K = 0$

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By S. Pae and J. Ponce, the  
International Journal of Computer  
Vision, 43(2):113-131 (2001).  
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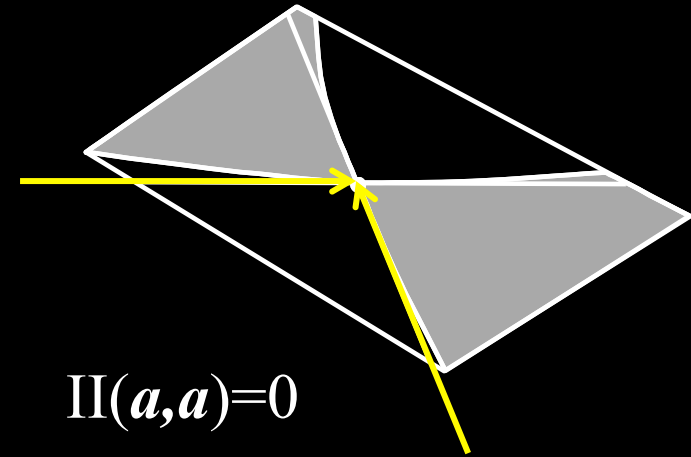


Parabolic lines marked on the Apollo Belvedere by Felix Klein



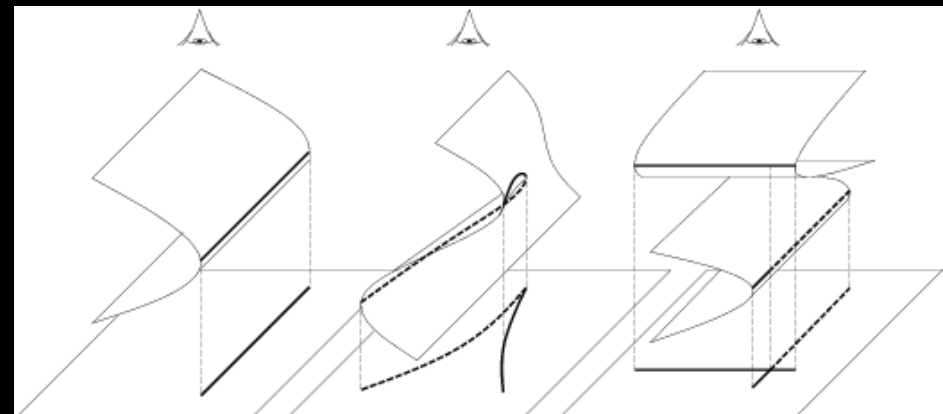
$$N \cdot v = 0 \Rightarrow \Pi(t, v) = 0$$

Asymptotic directions:



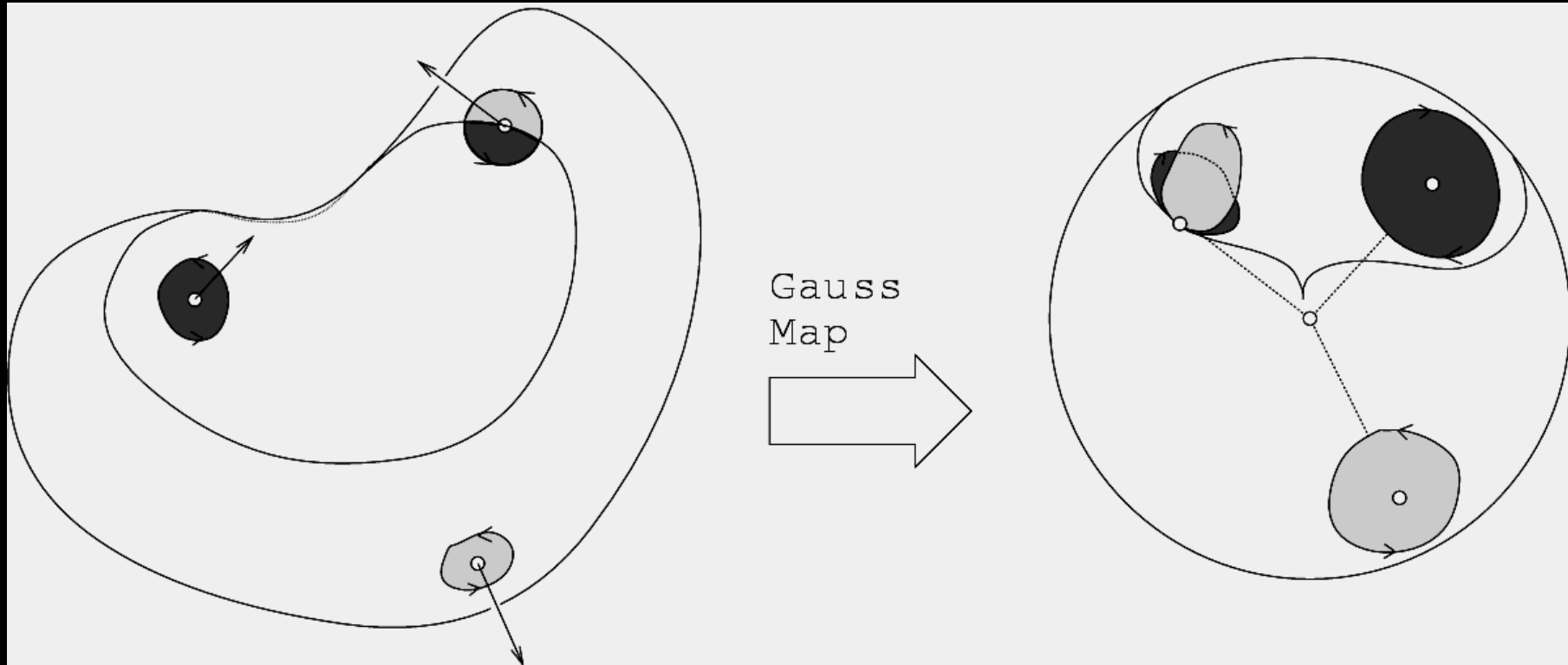
$$\Pi(a, a) = 0$$

The contour cusps when  
when a viewing ray grazes  
the surface along an  
asymptotic direction  $v=a$ .





# The Gauss map

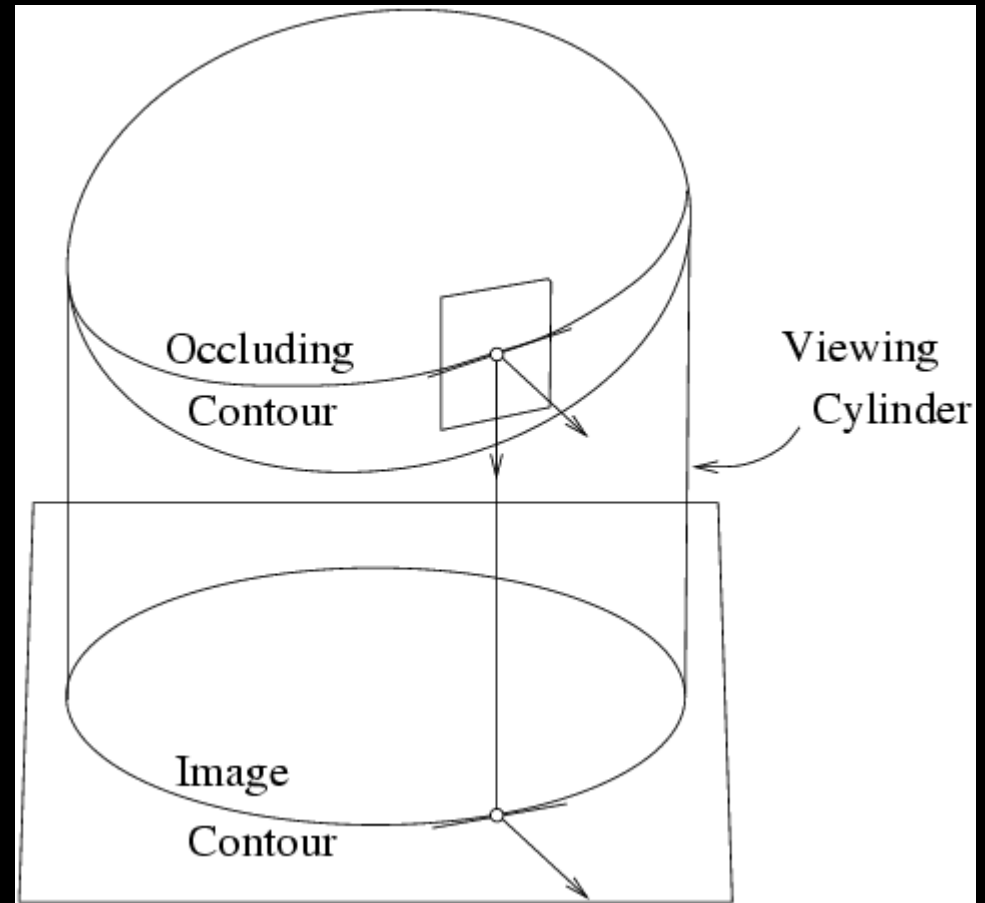
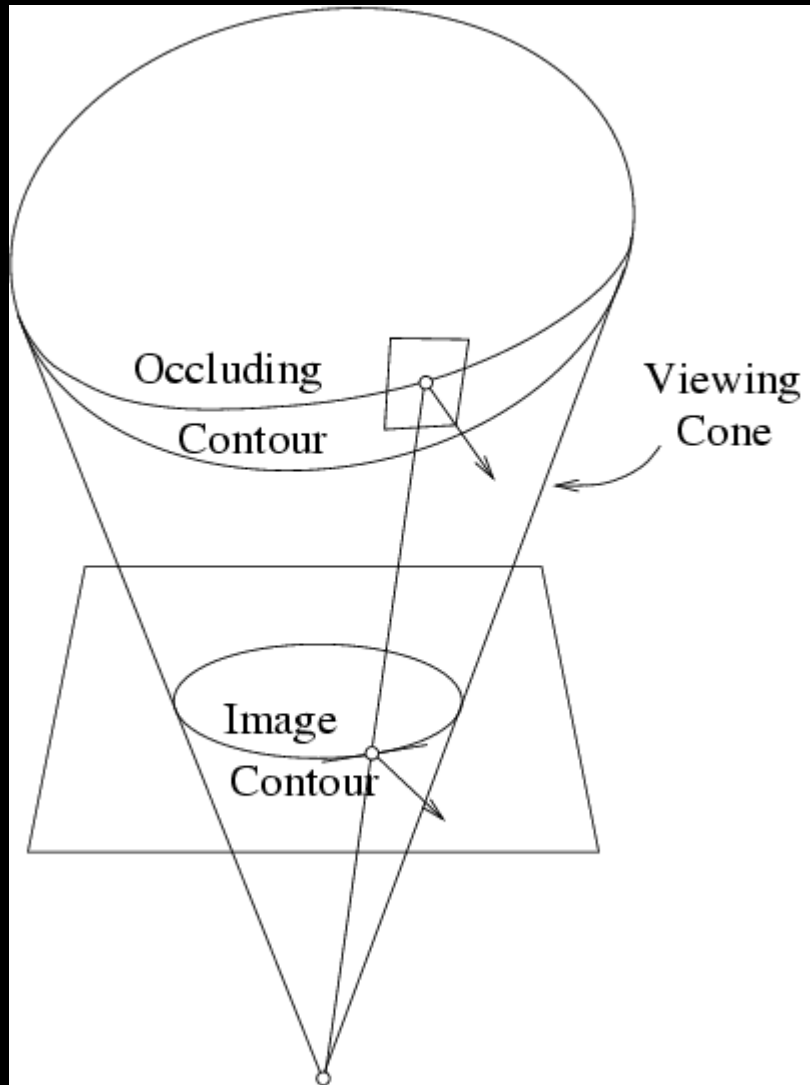


The Gauss map folds at parabolic points.

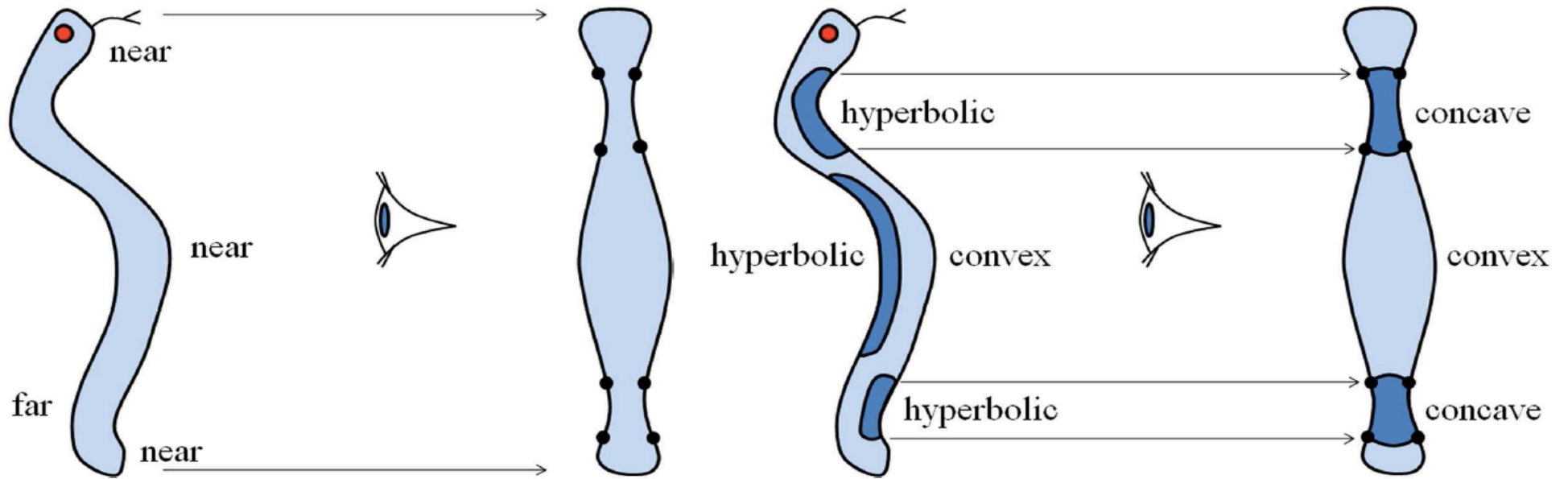
$$K = dA'/dA$$

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International Journal of Computer  
Vision, 43(2):113-131 (2001).  
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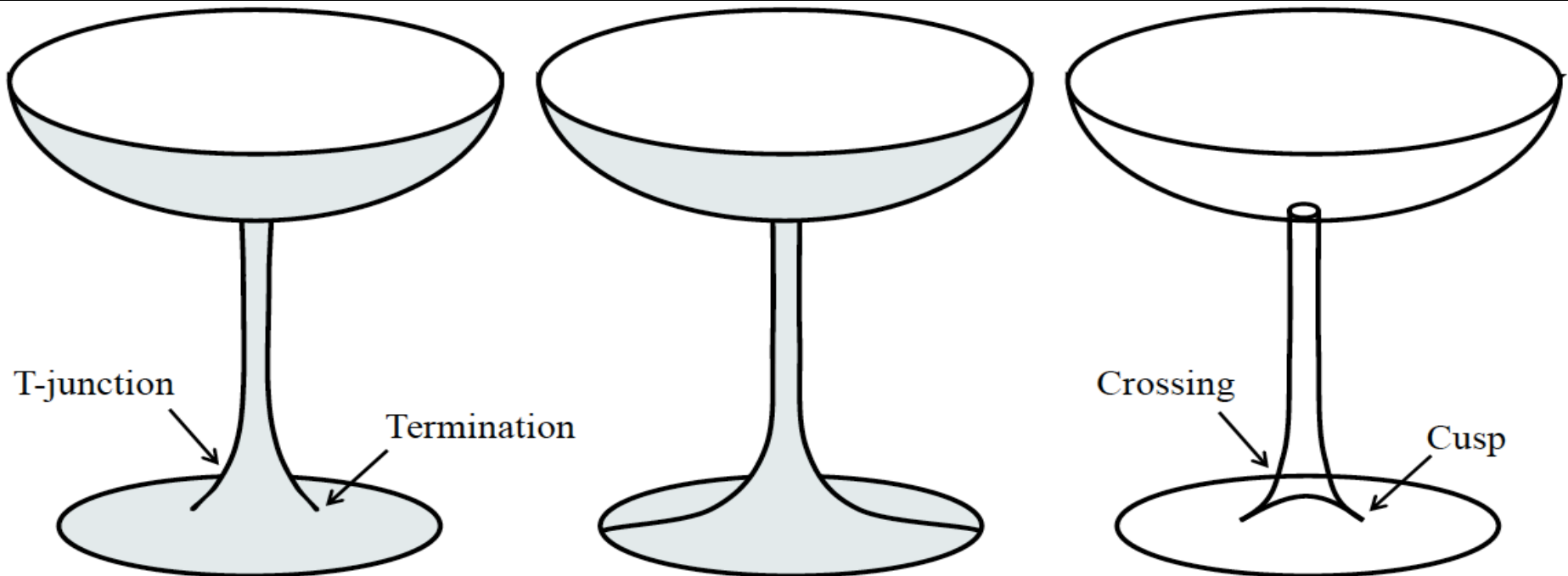
# Smooth Shapes and their Outlines

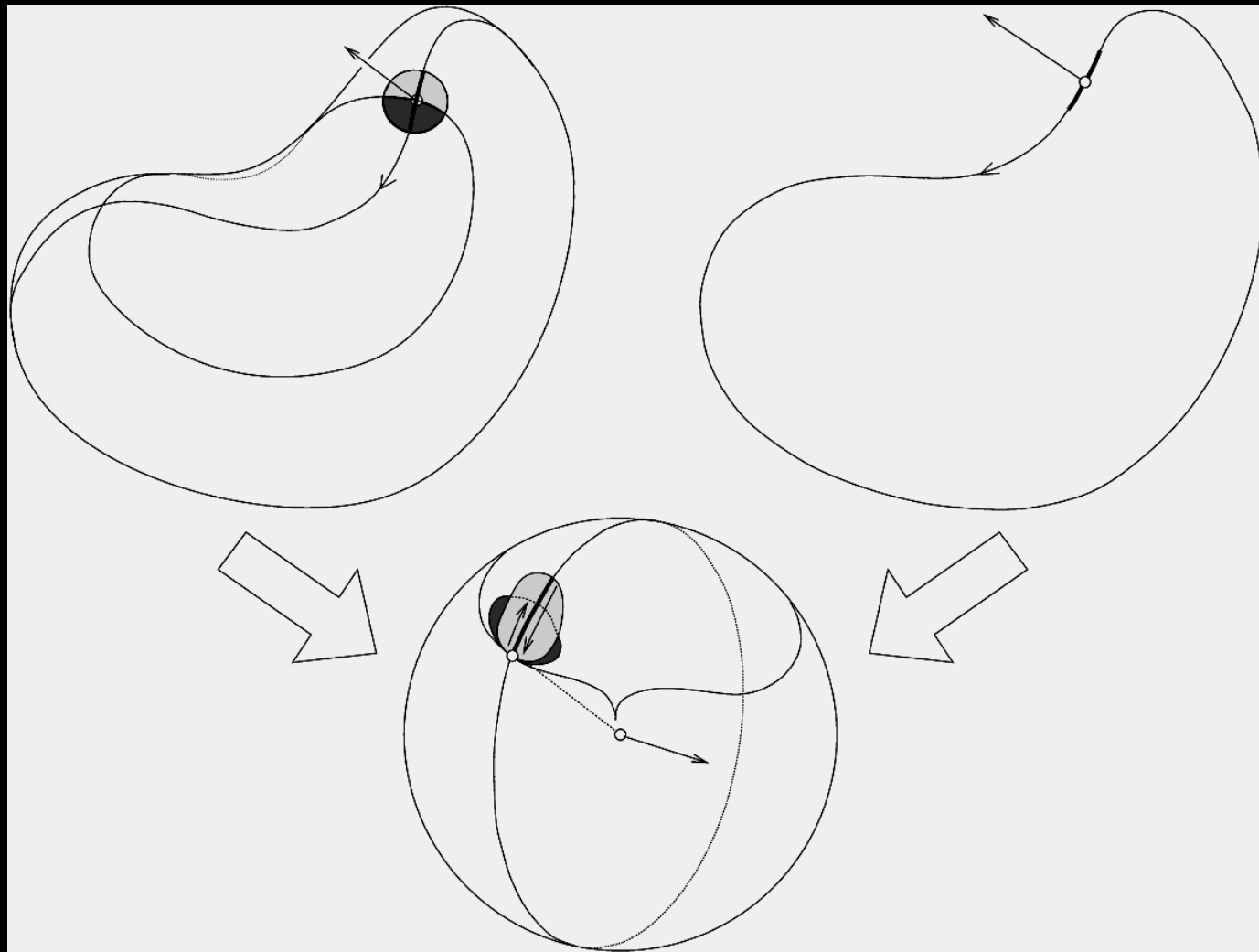


Can we say anything about a 3D shape from the shape of its contour?



After Marr (1977) and Koenderink (1984).





Theorem [Koenderink, 1984]: the inflections of the silhouette are the projections of parabolic points.

# Koenderink's Theorem (1984)

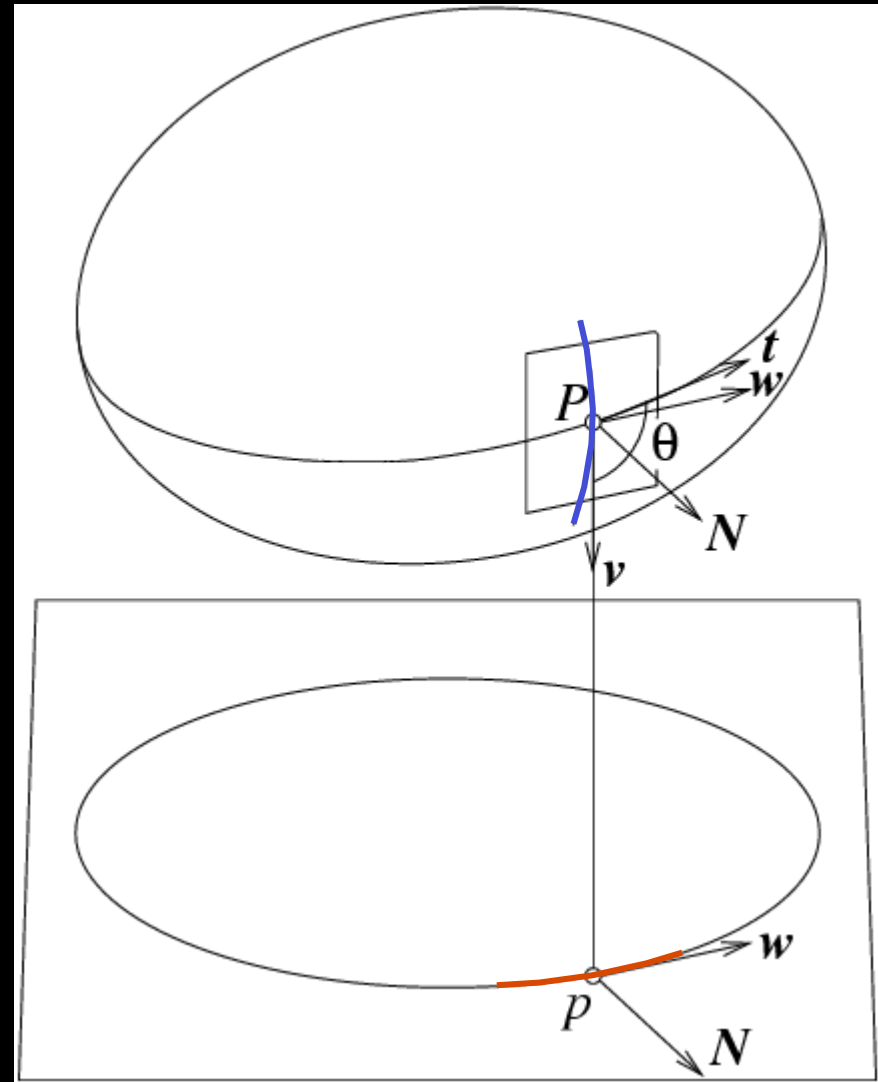
$$K = \kappa_r \kappa_c$$

Note:  $\kappa_r > 0$ .

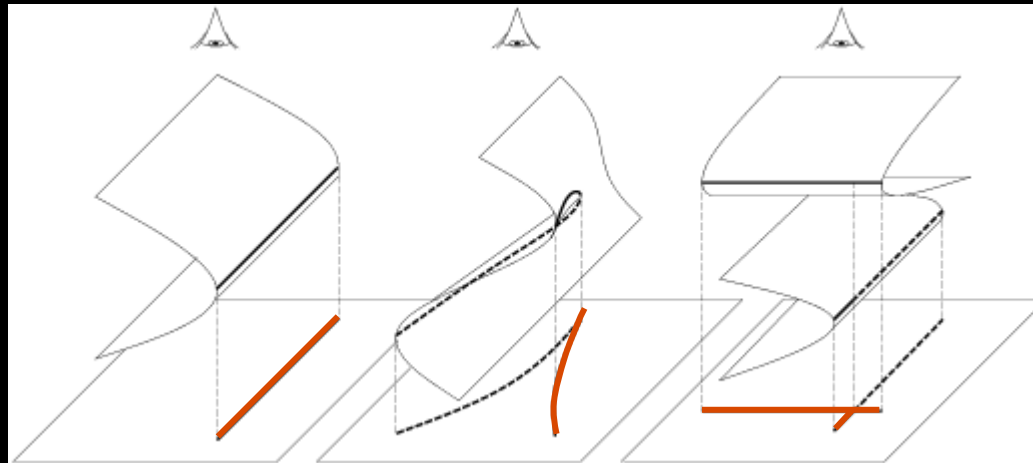
Corollary:  $K$  and  $\kappa_c$  have the same sign!

Proof: Based on the idea that, given two conjugated directions,

$$K \sin^2\theta = \kappa_u \kappa_v$$



# What are the contour **stable** features??



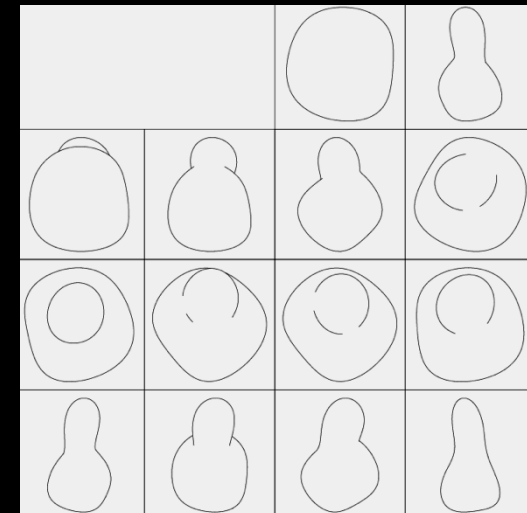
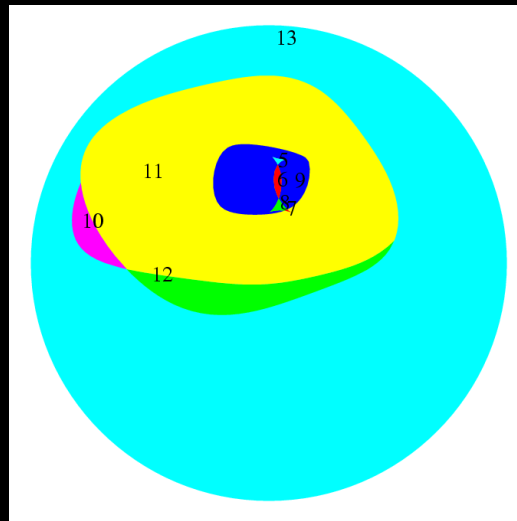
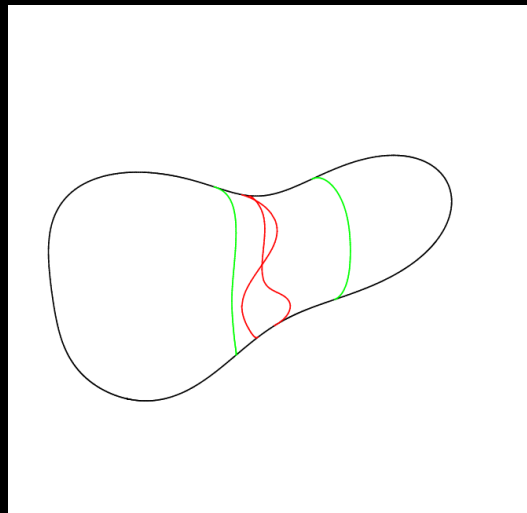
folds

cusps

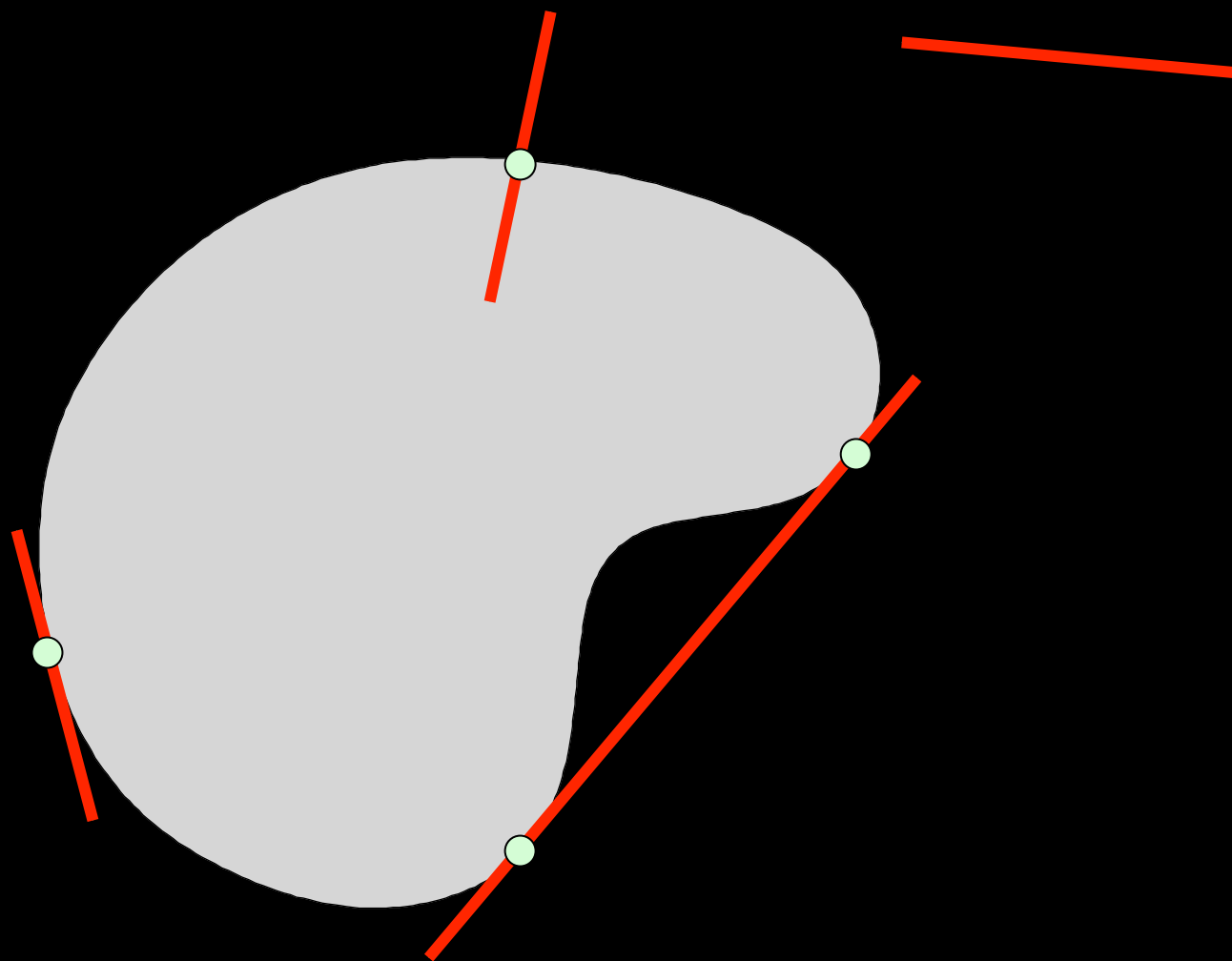
T-junctions

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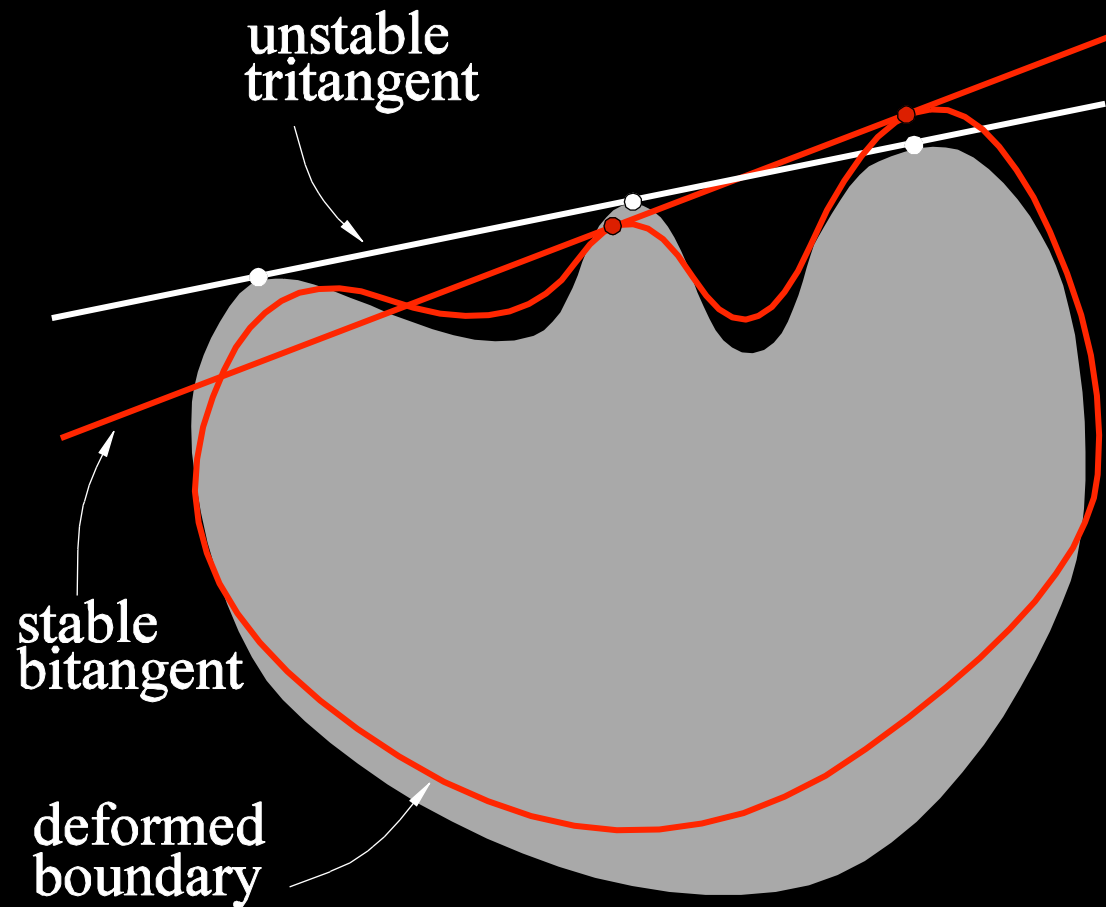
# How does the appearance of an object change with viewpoint?



# Contacts between lines and smooth curves

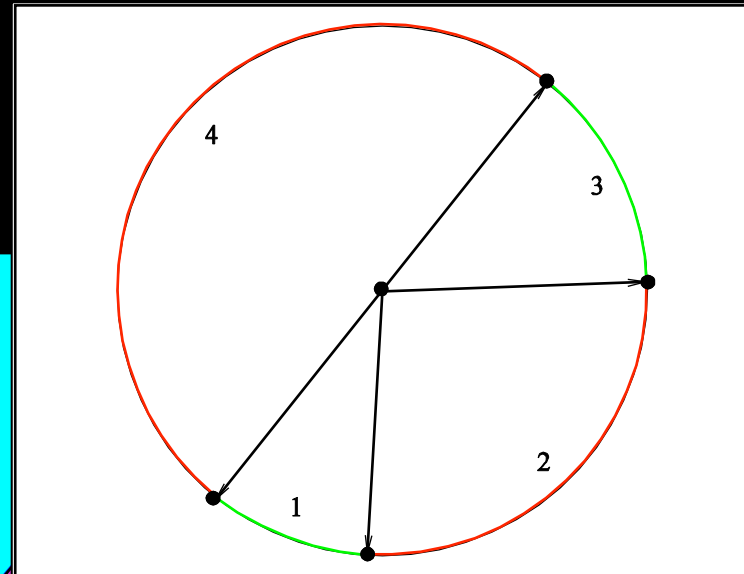
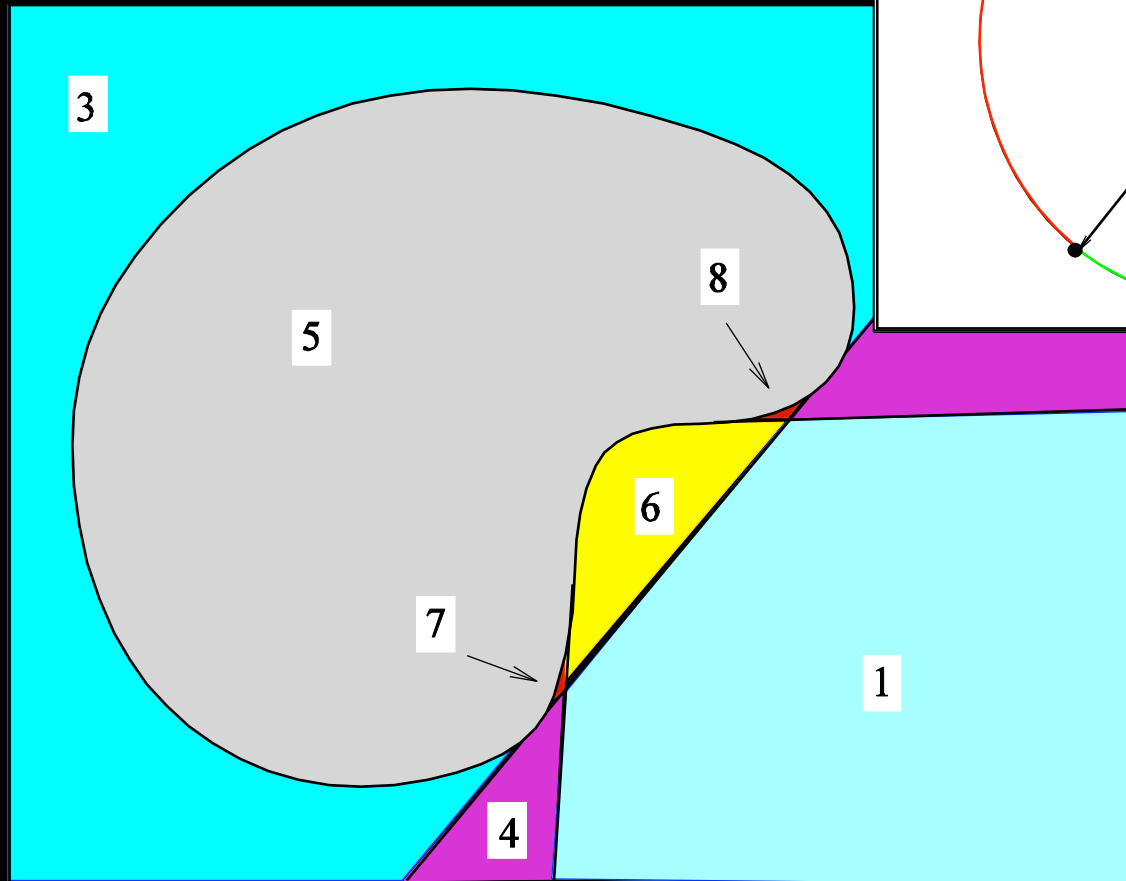


# Exceptional and Generic Curves





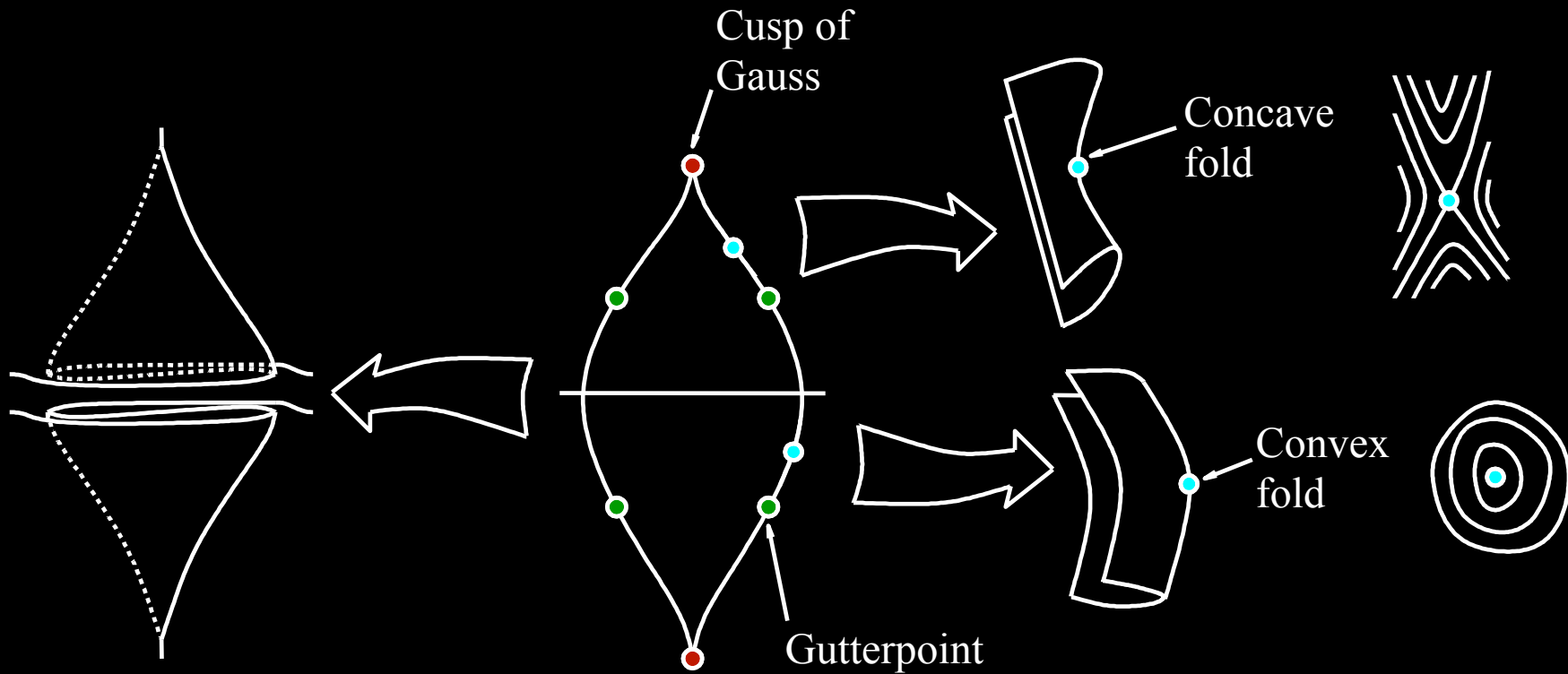
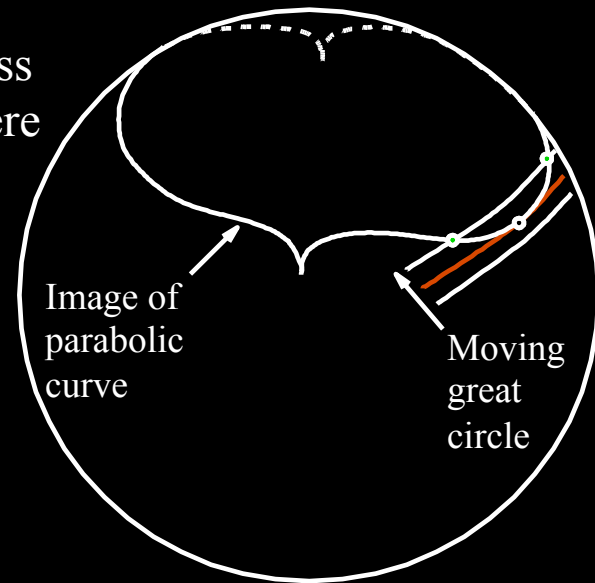
# The Aspect Graph In Flatland



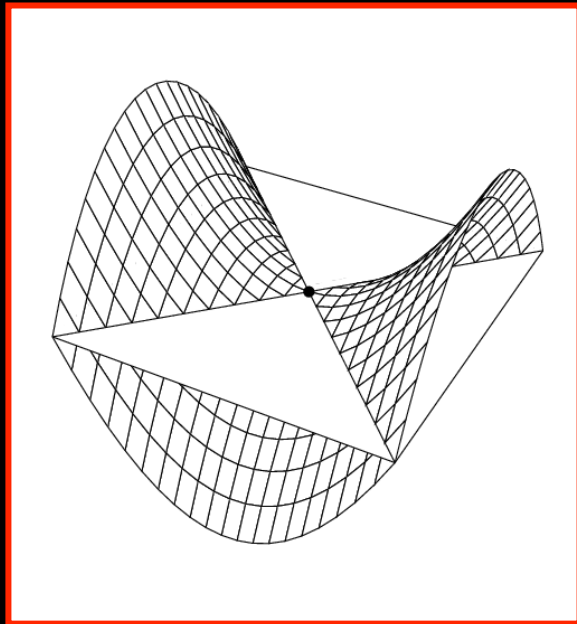
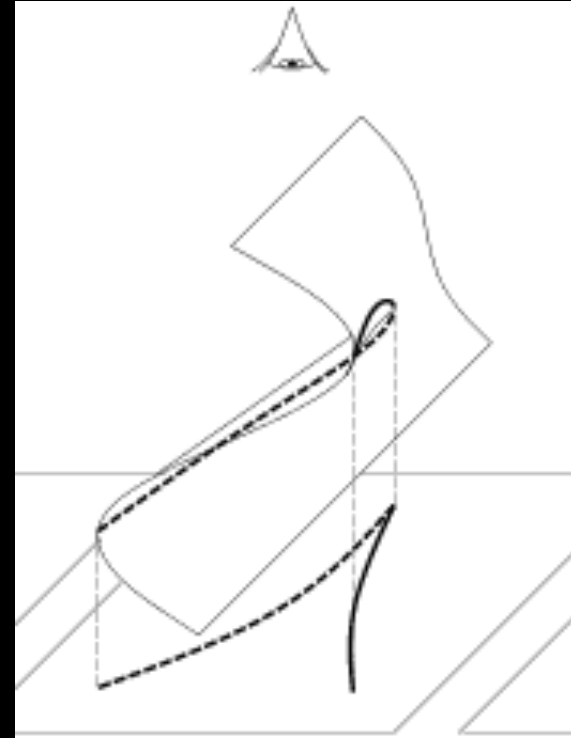
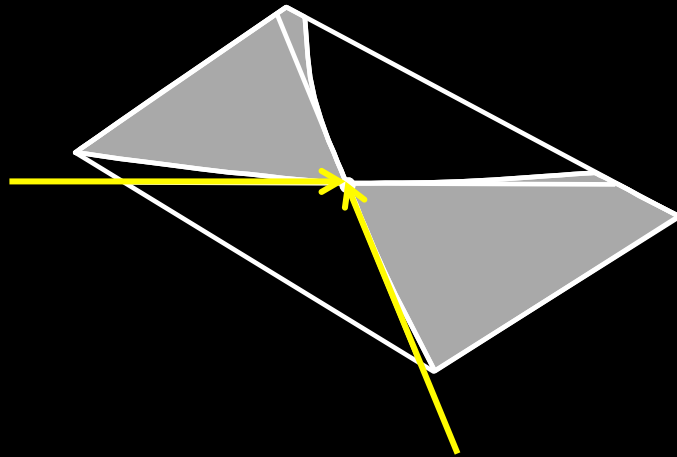
# The Geometry of the Gauss Map

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Vision, 43(2):113-131 (2001).  
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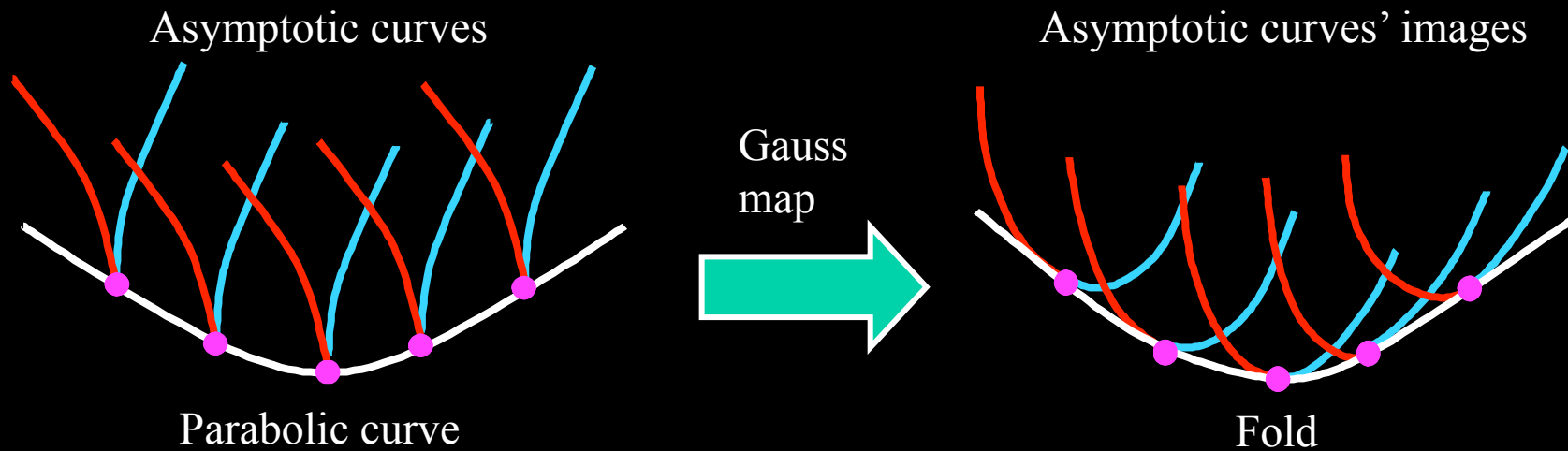
Gauss  
sphere



# Asymptotic directions at ordinary hyperbolic points



The integral curves of the asymptotic directions form two families of asymptotic curves (red and blue)

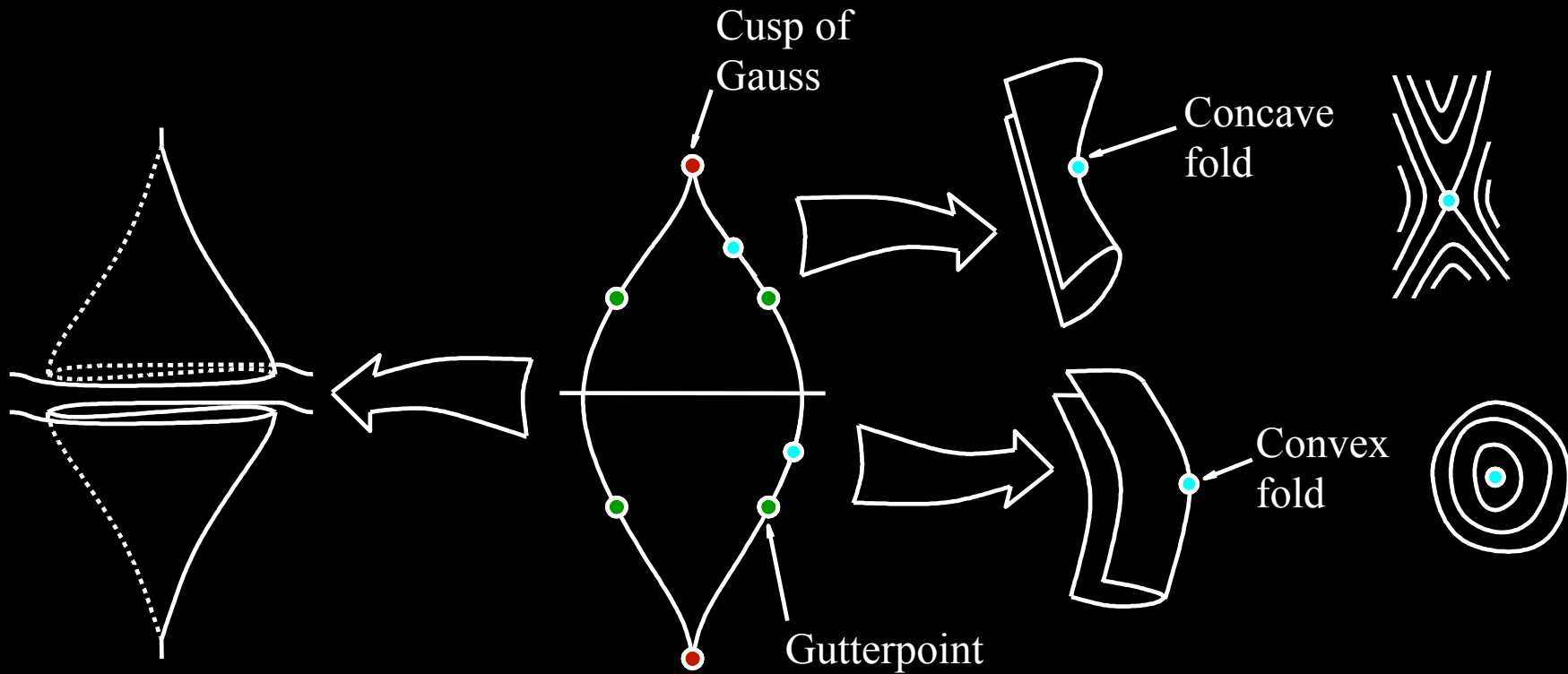
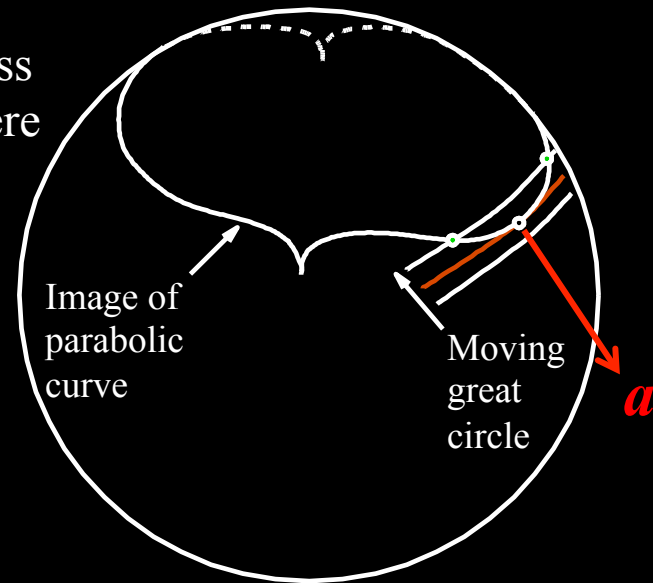


- Asymptotic directions are self conjugate:  $a \cdot dN(a) = 0$
- At a parabolic point  $dN(a) = 0$ , so for any curve  $t \cdot dN(a) = a \cdot dN(t) = 0$
- In particular, the Gaussian images of the asymptotic and parabolic curves are both orthogonal to  $a$ .

# The Geometry of the Gauss Map

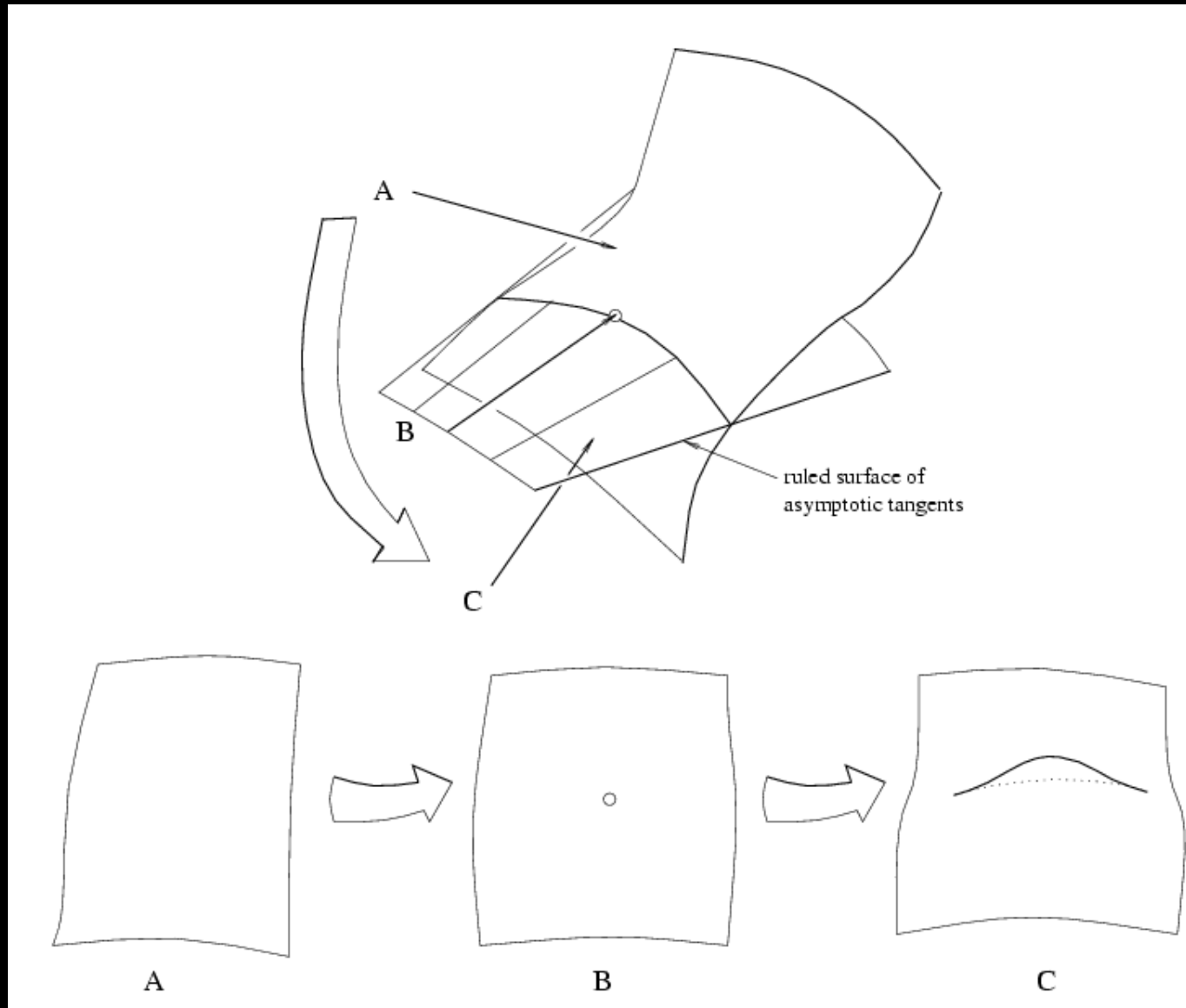
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Gauss  
sphere



# The Lip Event

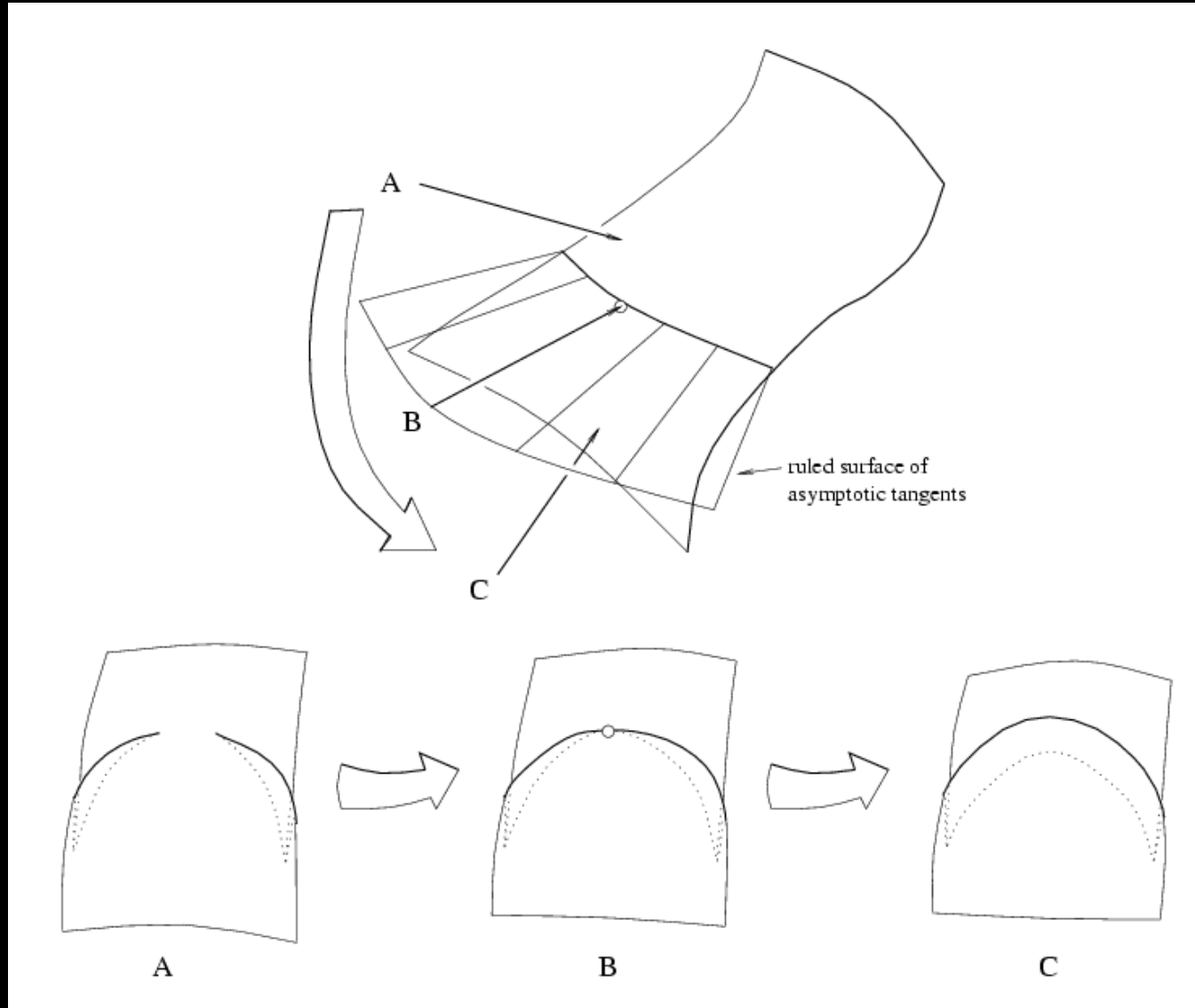
$$\mathbf{v} \cdot d\mathbf{N}(\mathbf{a}) = 0 \Rightarrow \mathbf{v} \approx \mathbf{a}$$



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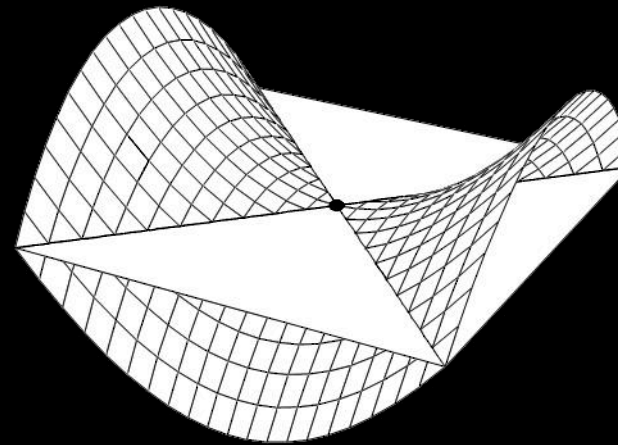
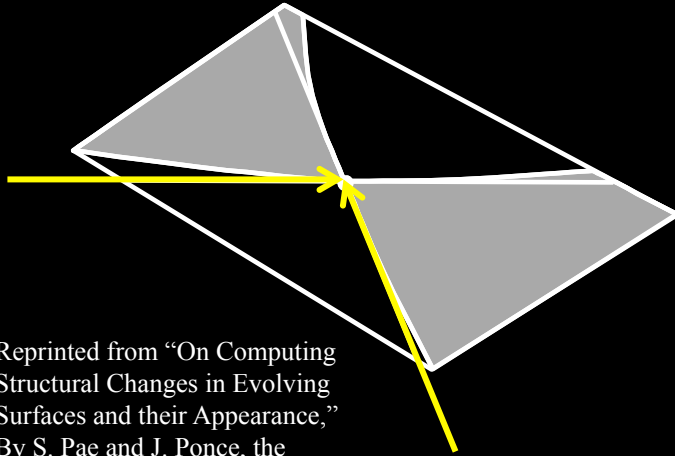
# The Beak-to-Beak Event

$$\mathbf{v} \cdot d\mathbf{N}(\mathbf{a}) = 0 \Rightarrow \mathbf{v} \approx \mathbf{a}$$

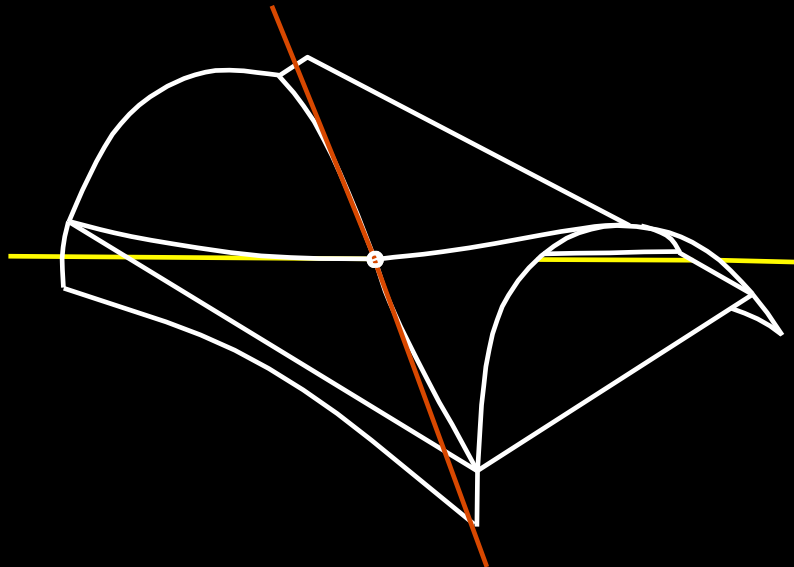


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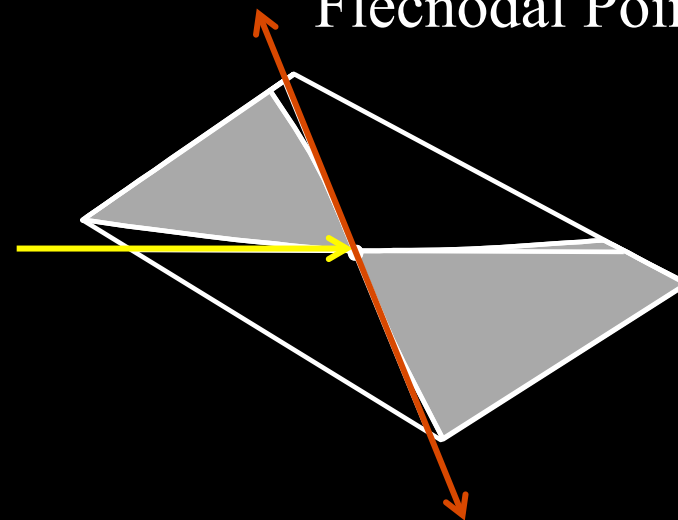
# Ordinary Hyperbolic Point



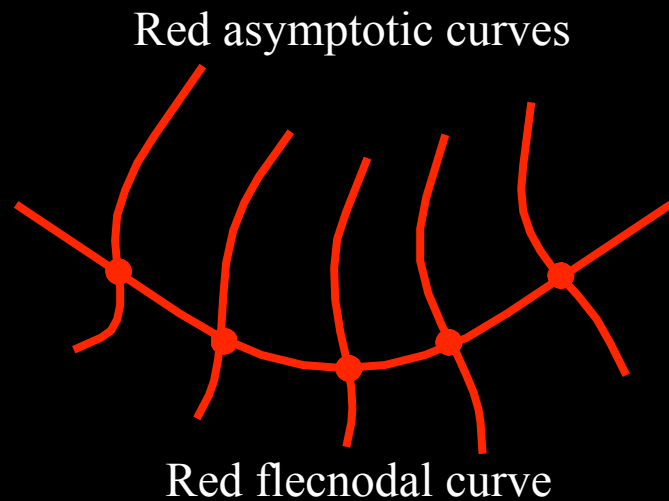
Reprinted from "On Computing Structural Changes in Evolving Surfaces and their Appearance,"  
By S. Pae and J. Ponce, the  
International Journal of Computer  
Vision, 43(2):113-131 (2001).  
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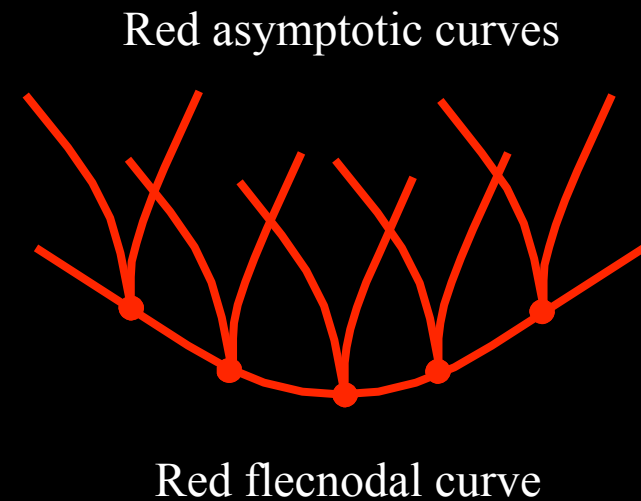
# Flecnodal Point







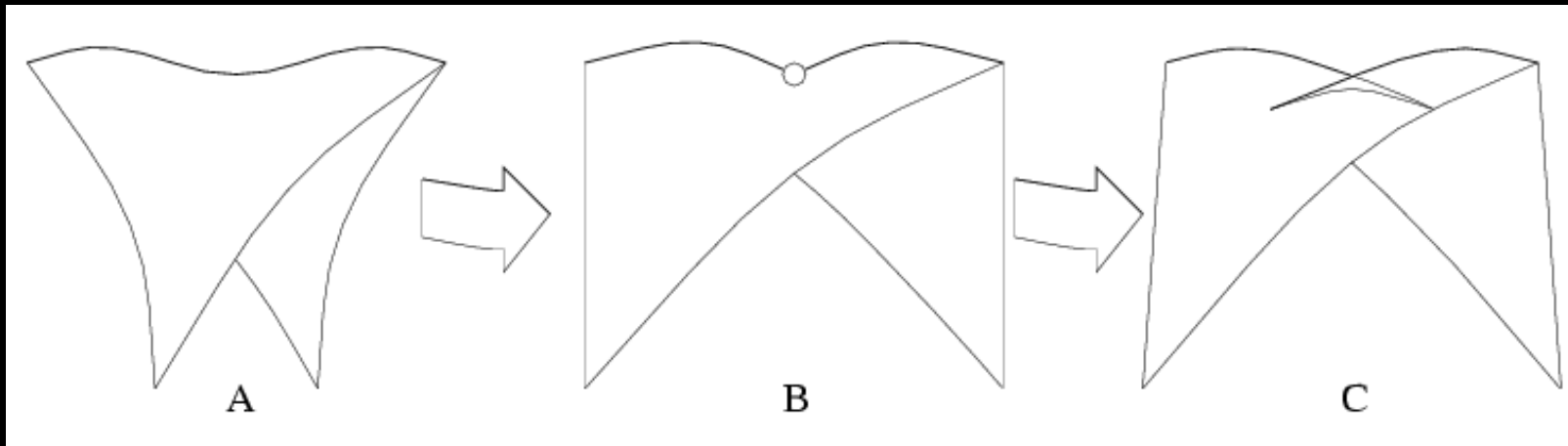
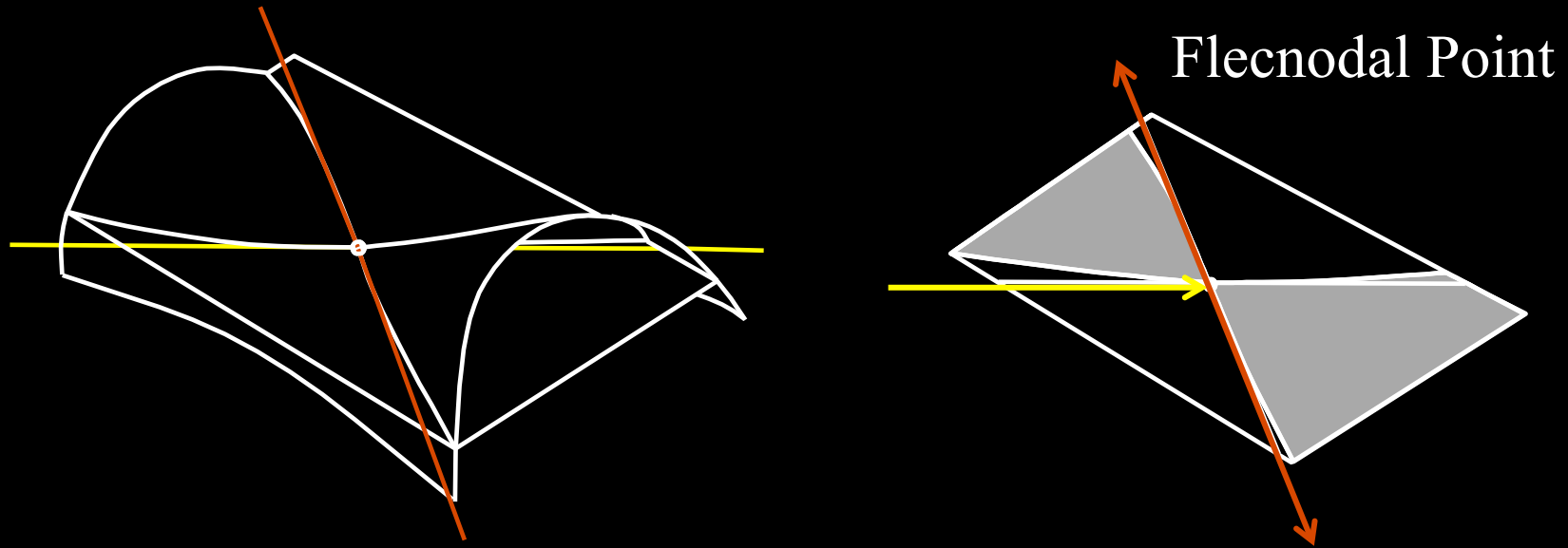
Asymptotic  
spherical  
map



Cusp pairs appear or disappear as one crosses the fold of the asymptotic spherical map.

This happens at asymptotic directions along parabolic curves, and asymptotic directions along flecnodal curves.

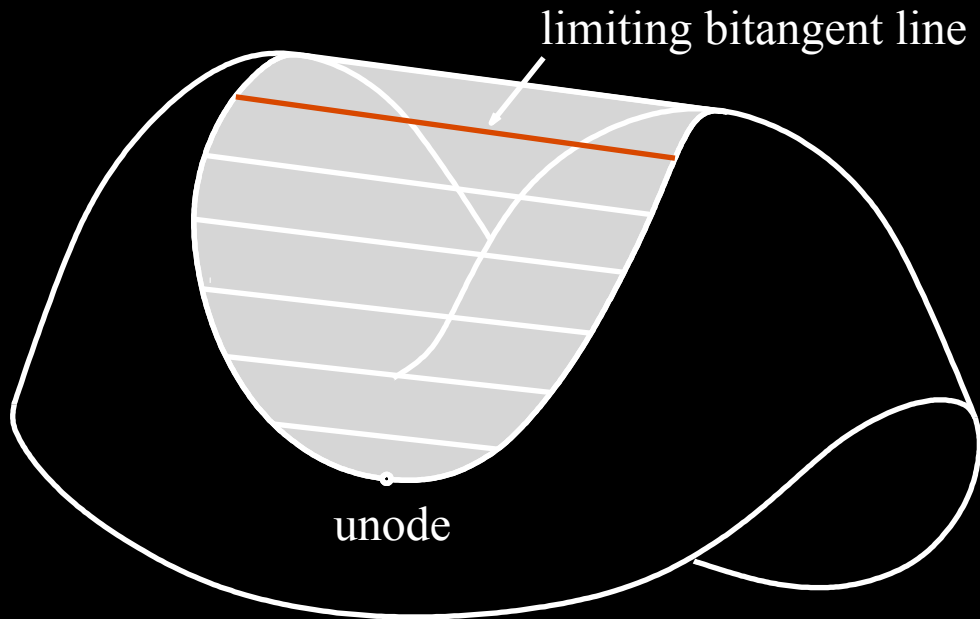
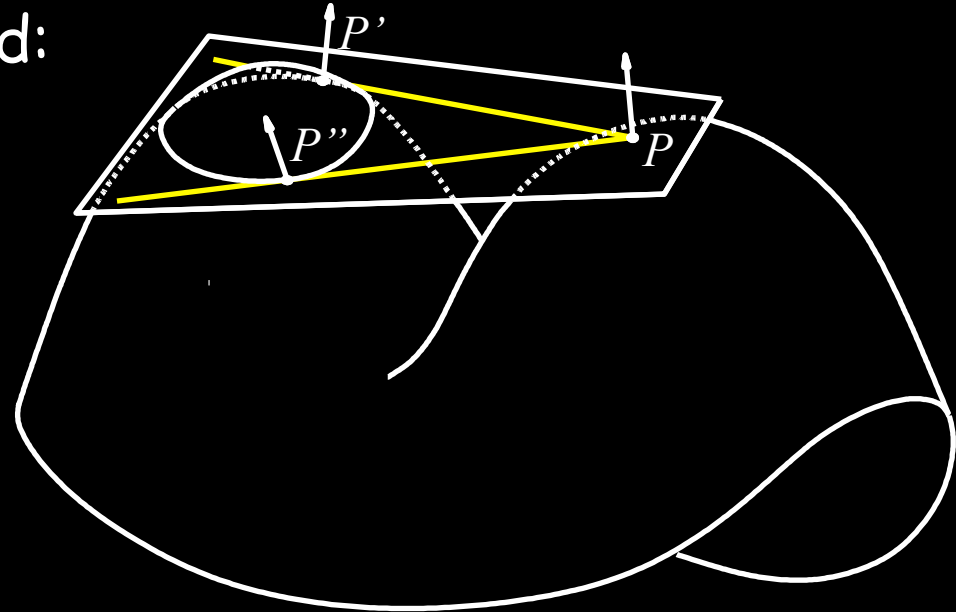
# The Swallowtail Event



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# The Bitangent Ray Manifold:

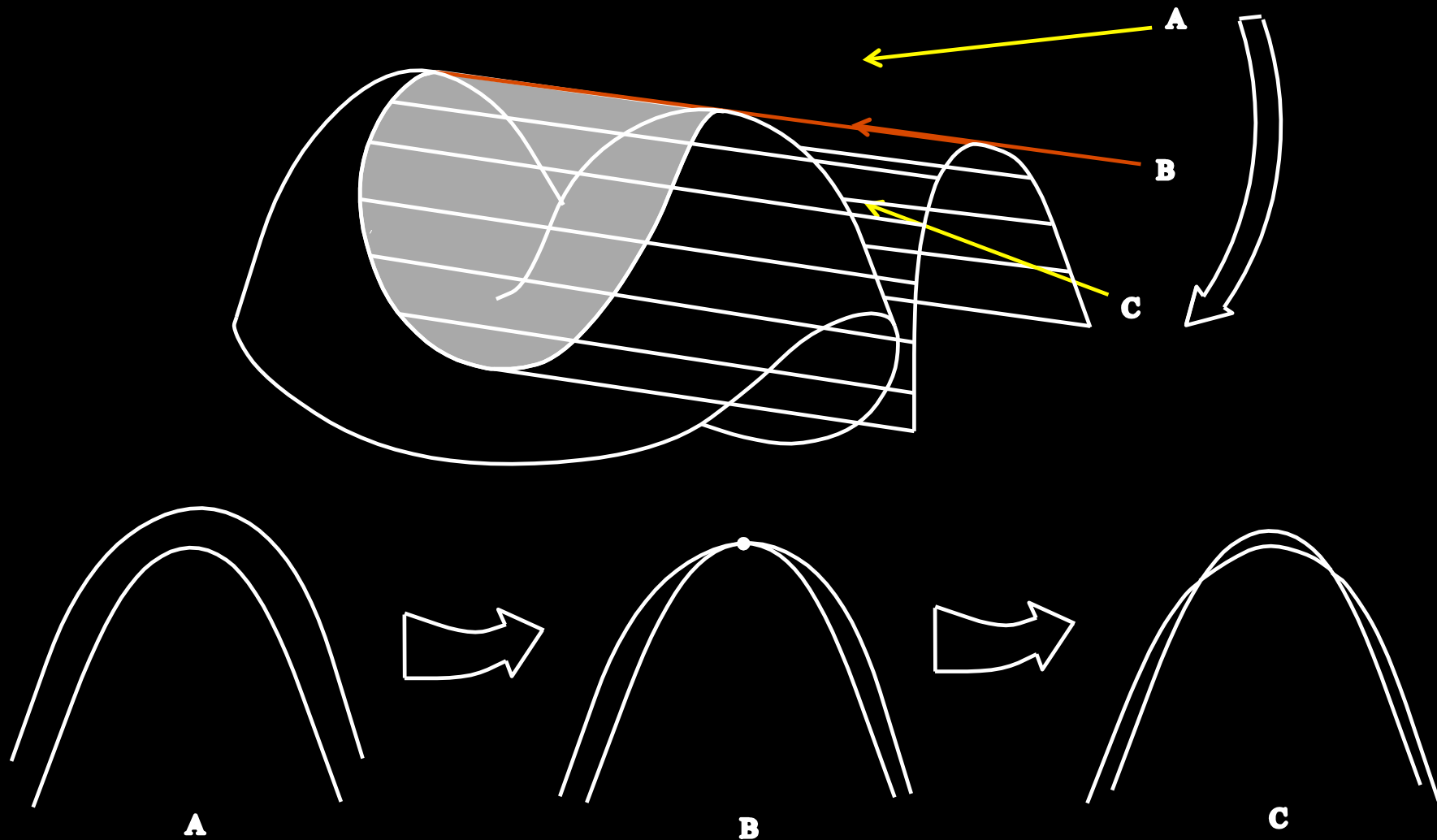
Ordinary  
bitangents..



..and exceptional  
(limiting) ones.

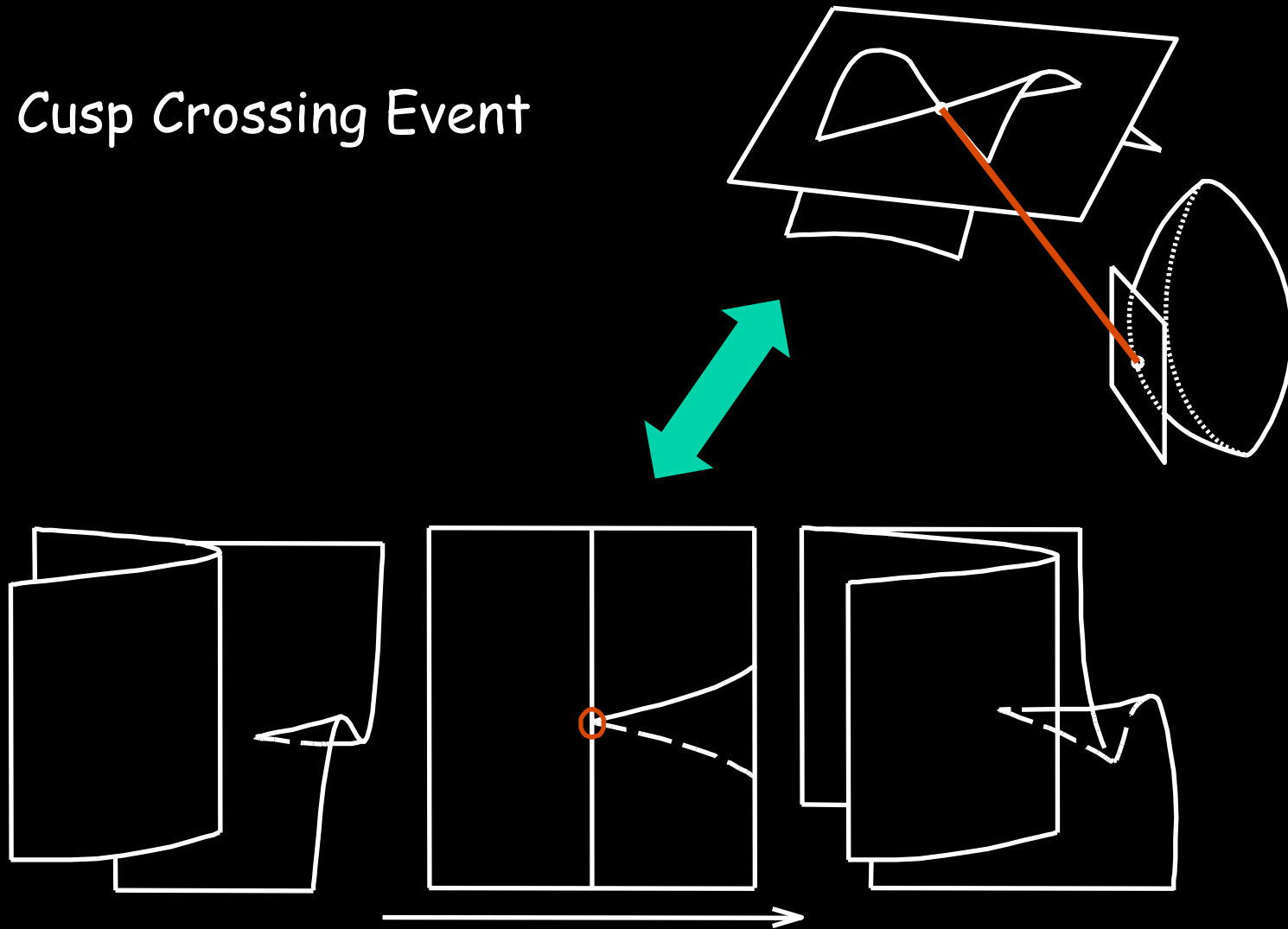
Reprinted from "Toward a Scale-Space Aspect Graph: Solids of Revolution," by S. Pae and J. Ponce, Proc. IEEE Conf. on Computer Vision and Pattern Recognition (1999). © 1999 IEEE.

# The Tangent Crossing Event



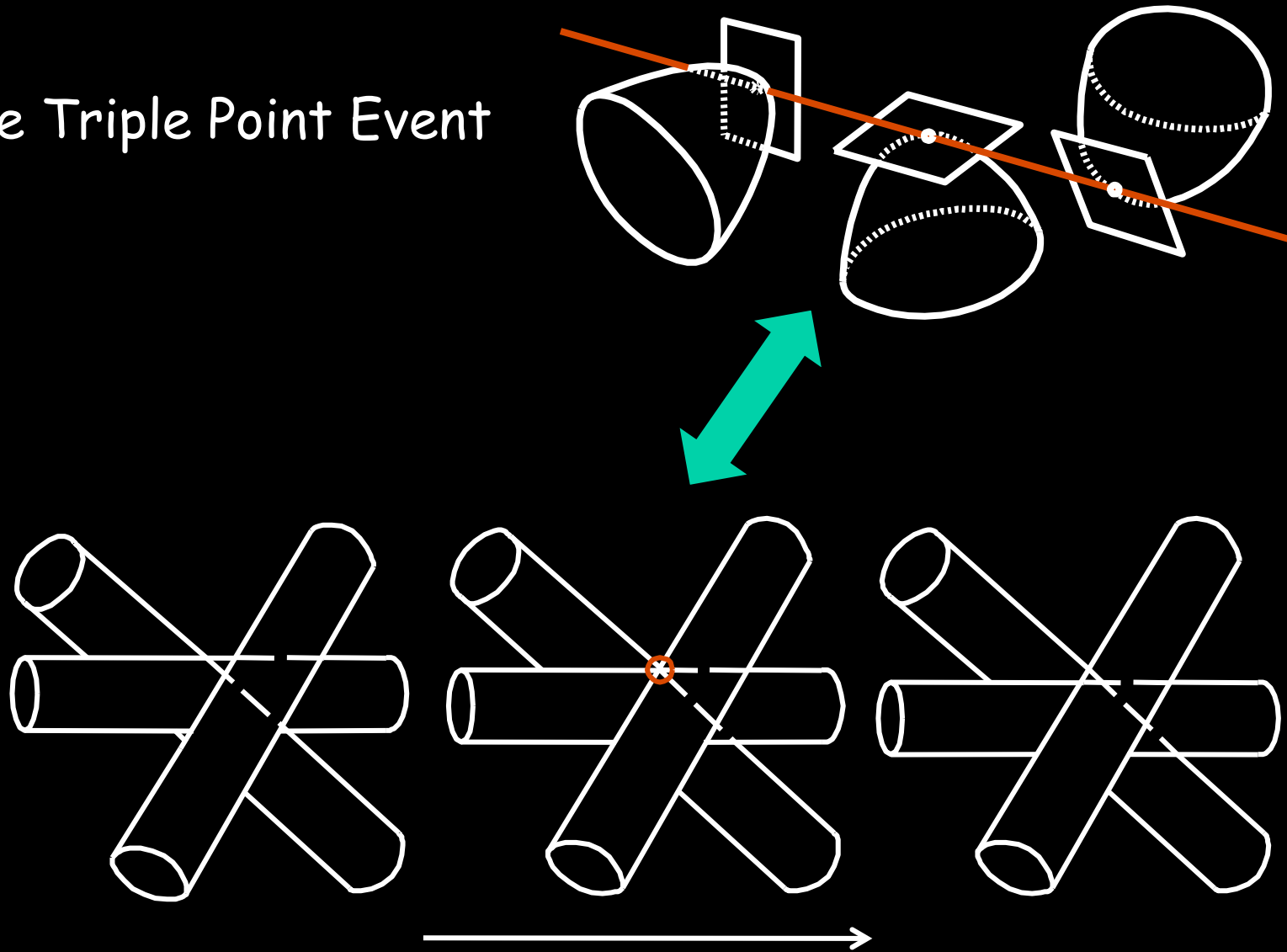
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# The Cusp Crossing Event



After "Computing Exact Aspect Graphs of Curved Objects: Algebraic Surfaces," by S. Petitjean, J. Ponce, and D.J. Kriegman, the International Journal of Computer Vision, 9(3):231-255 (1992). © 1992 Kluwer Academic Publishers.

# The Triple Point Event



After "Computing Exact Aspect Graphs of Curved Objects: Algebraic Surfaces," by S. Petitjean, J. Ponce, and D.J. Kriegman, the International Journal of Computer Vision, 9(3):231-255 (1992). © 1992 Kluwer Academic Publishers.

## Tracing Visual Events

## Computing the Aspect Graph

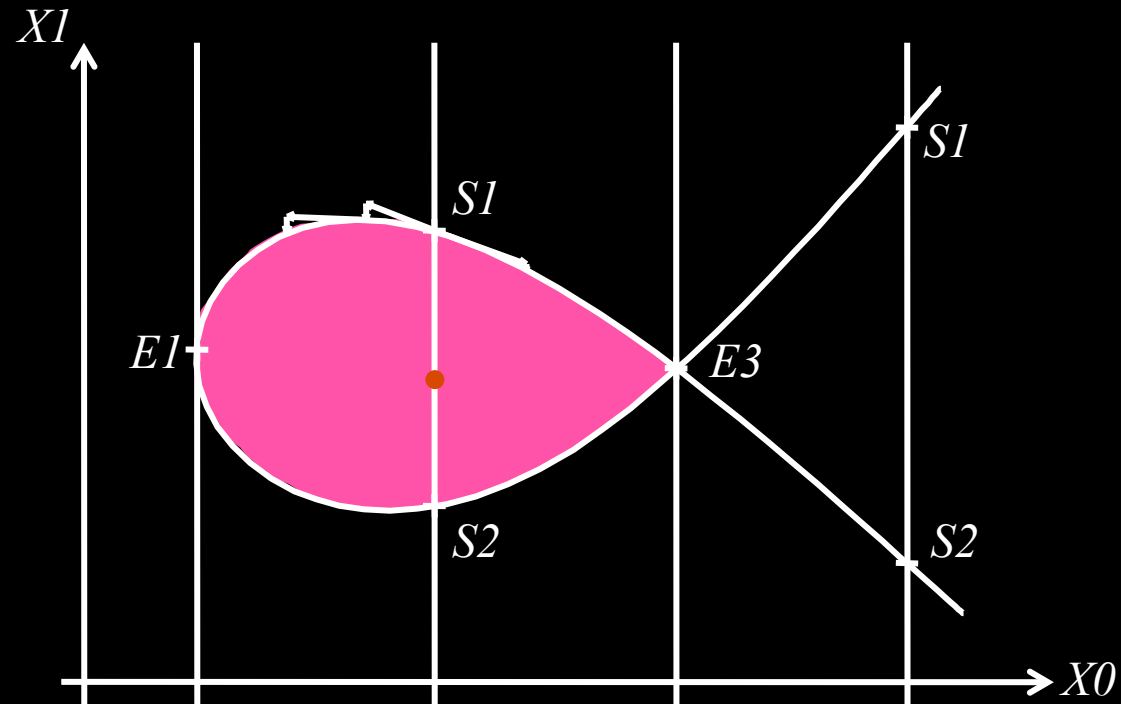
$$F(x, y, z) = 0$$



$$P_1(x_1, \dots, x_n) = 0$$

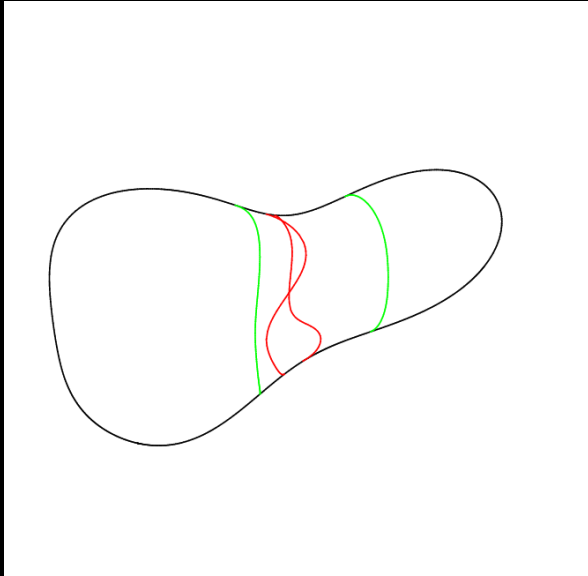
...

$$P_n(x_1, \dots, x_n) = 0$$

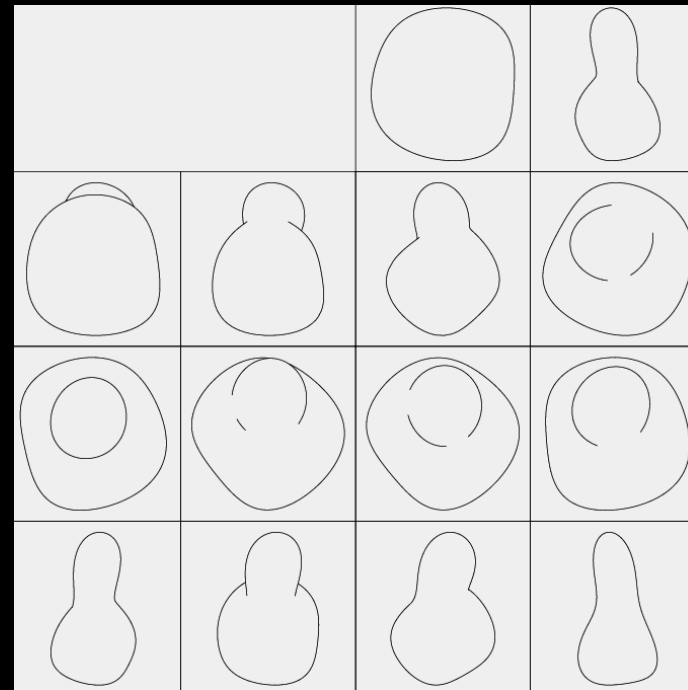
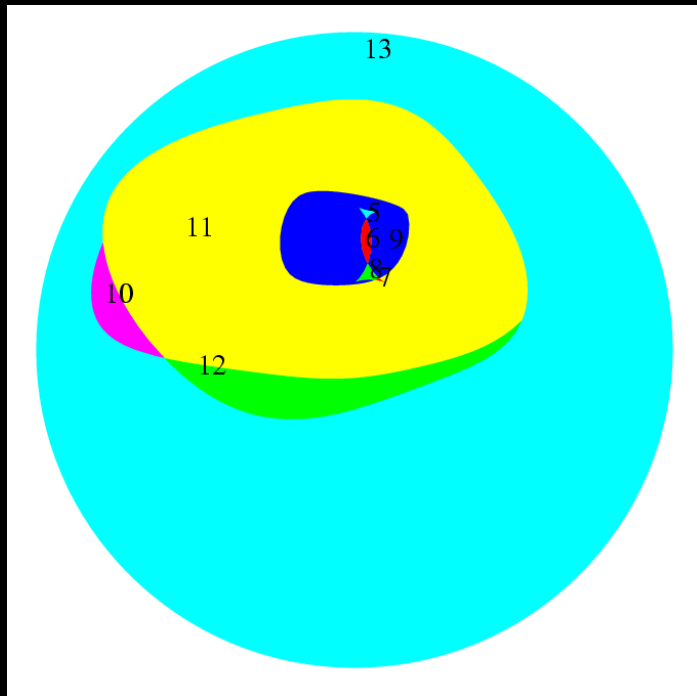
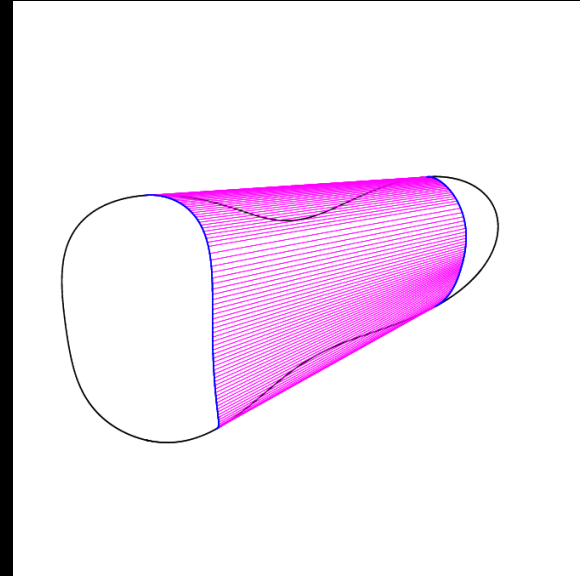


After "Computing Exact Aspect Graphs of Curved Objects: Algebraic Surfaces,"  
by S. Petitjean, J. Ponce, and D.J. Kriegman, the International Journal of Computer  
Vision, 9(3):231-255 (1992). © 1992 Kluwer Academic Publishers.

- Curve Tracing
- Cell Decomposition

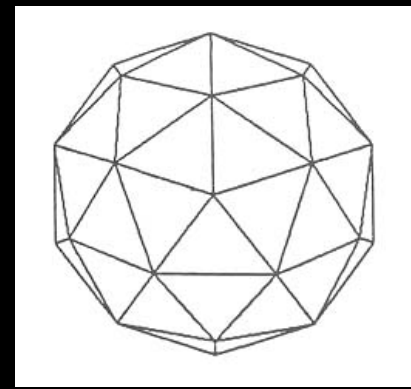
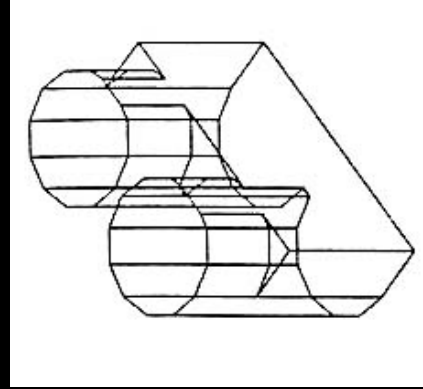
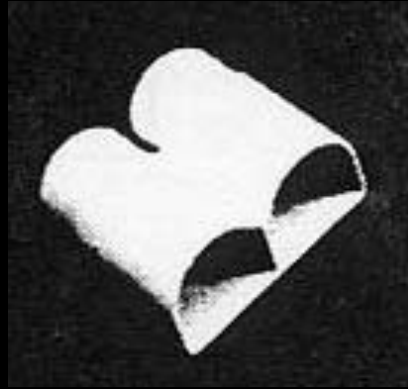


An Example





# Approximate Aspect Graphs (Ikeuchi & Kanade, 1987)



Aspect7 - 0000000  
nil

Aspect6 - 00010000  
(4)

Aspect5 - 00001100  
(5) (6)

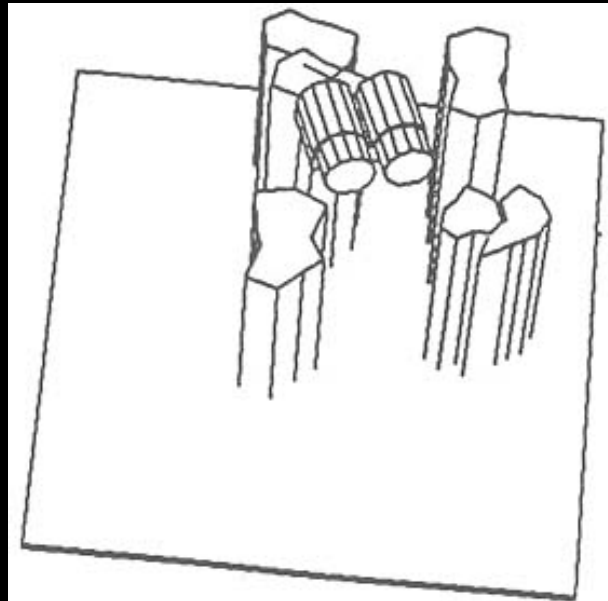
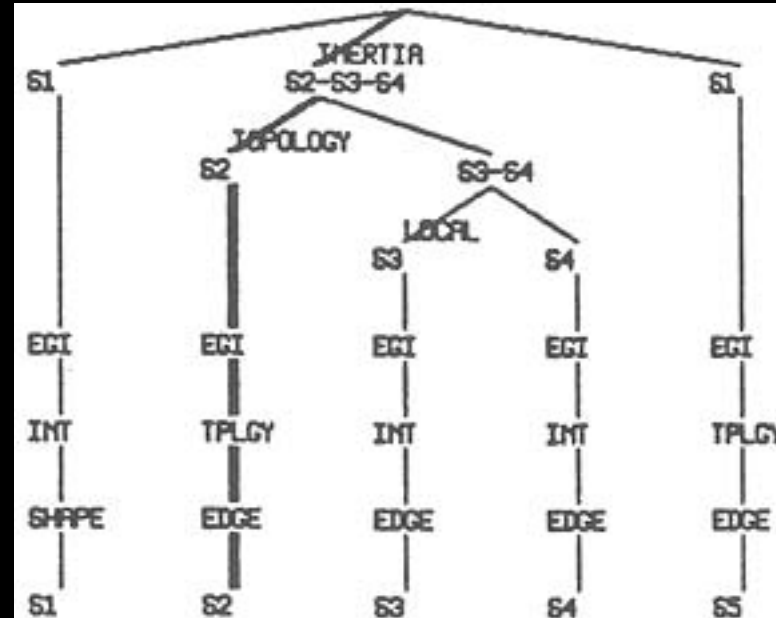
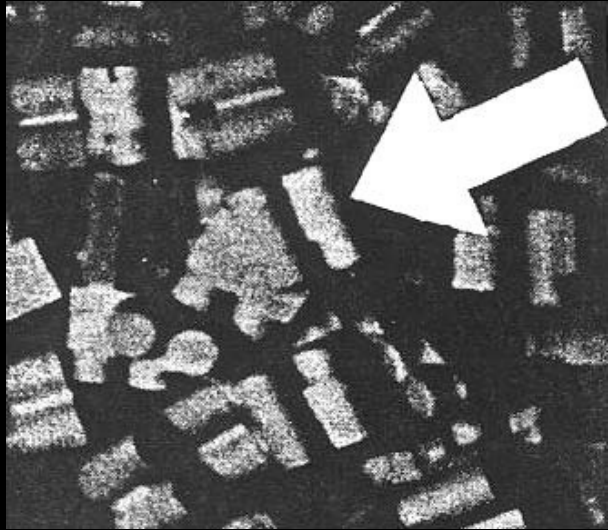
Aspect4 - 11000001  
(1) (2) (8)

Aspect3 - 11000010  
(1) (2) (7)

Aspect2 - 11000000  
(1) (2)

Aspect1 - 11100000  
(1) (2) (3)


# Approximate Aspect Graphs II: Object Localization (Ikeuchi & Kanade, 1987)



Reprinted from "Precompiling a Geometrical Model into an Interpretation Tree for Object Recognition in Bin-Picking Tasks," by K. Ikeuchi, Proc. DARPA Image Understanding Workshop, 1987.