

# Clustering comparison of point processes with applications to percolation

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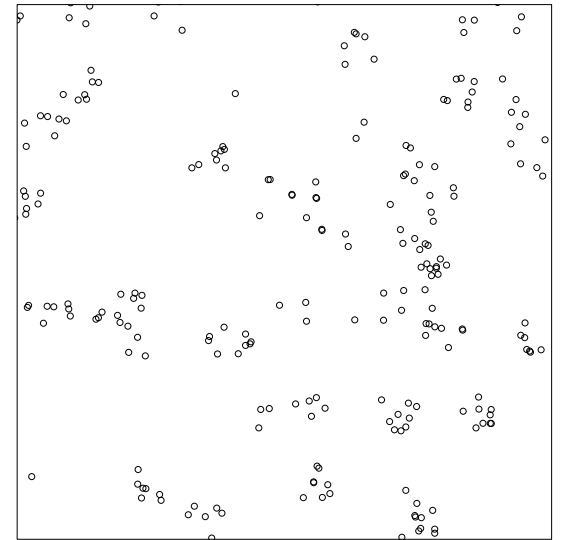
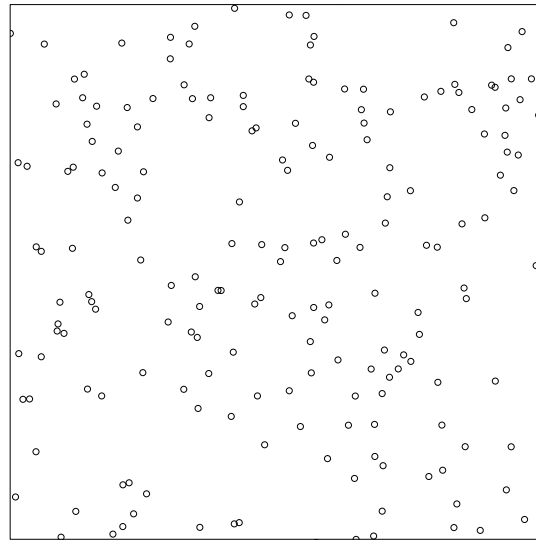
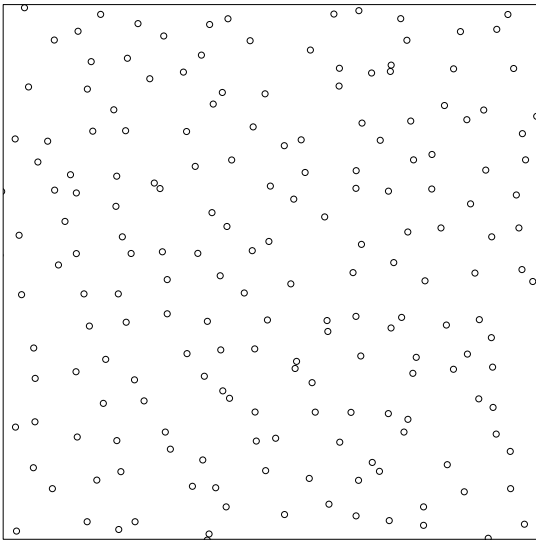
joint work with D. Yogeshwaran

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# Clustering of points

Clustering in a point pattern roughly means that the **points lie in clusters (groups) with the clusters being spaced out.**



**How to compare clustering of two point processes (pp),** say having “on average” the same number of points per unit of space? (More precisely, having the same mean measure.)  
For simplicity, we consider pp on  $\mathbb{R}^d$ .

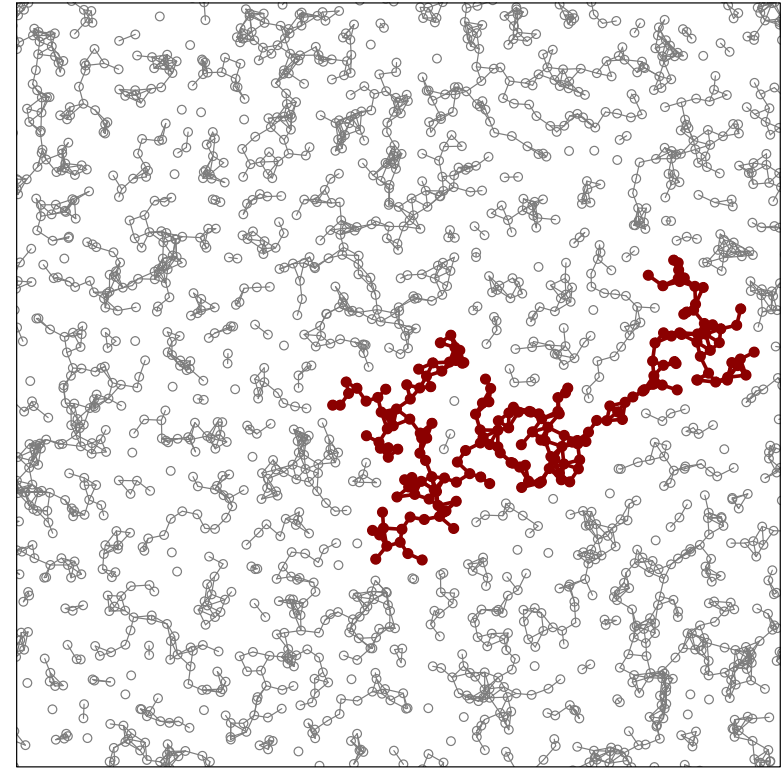
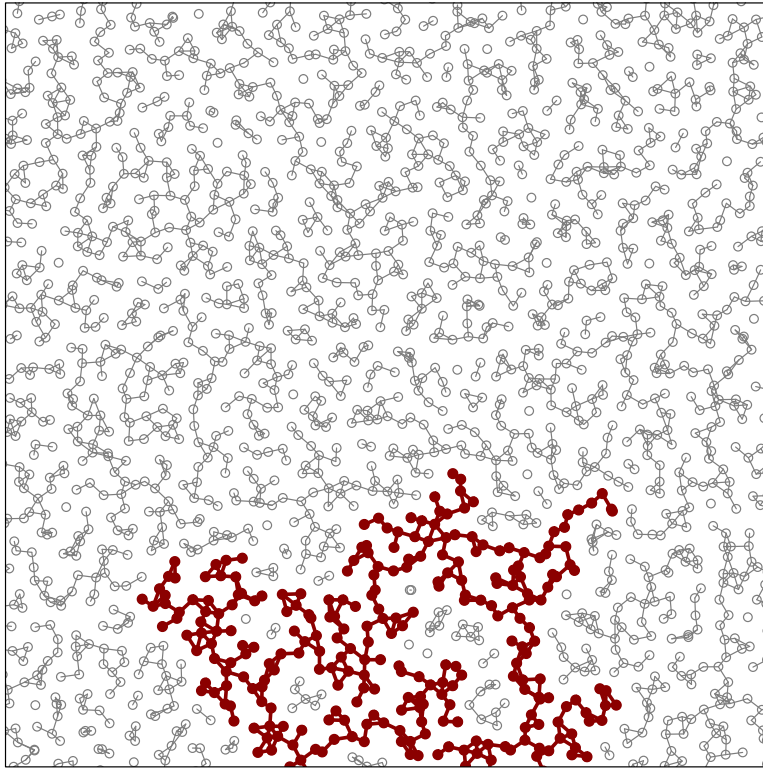
# Motivation

- Interesting methods have been developed for studying local and global functionals of geometric structures over Poisson or Bernoulli pp; experts in the audience !
- Try to carry over some results to other point processes by their “cluster-comparison” to Poisson or Bernoulli pp. In this talk we concentrate on percolation-type results.
- The “clustering-comparison” is not the usual strong (coupling) comparison as we compare pp of the same mean measure. Analog of convex comparison of random variables.

# Motivation, cont'd

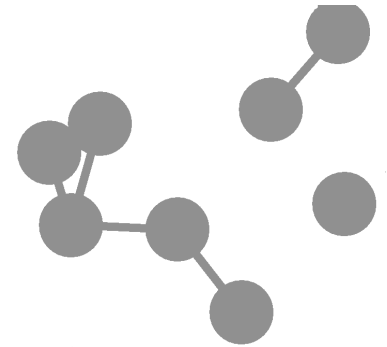
- Program can be reminiscent of **Ross-type conjectures** in queuing theory (replacing Poisson arrival process in a single-server queue by a Cox PP with the same intensity should increase the average customer delay).
- Actually, more interesting results are on the side of pp “**more regular**” pp (we call them **sub-Poisson**) with **determinantal pp** as prominent examples.
- The notion of sub- and super-Poisson distributions is used e.g. in quantum physics and denotes distributions for which the variance is smaller (respectively larger) than the mean.

# Clustering and percolation

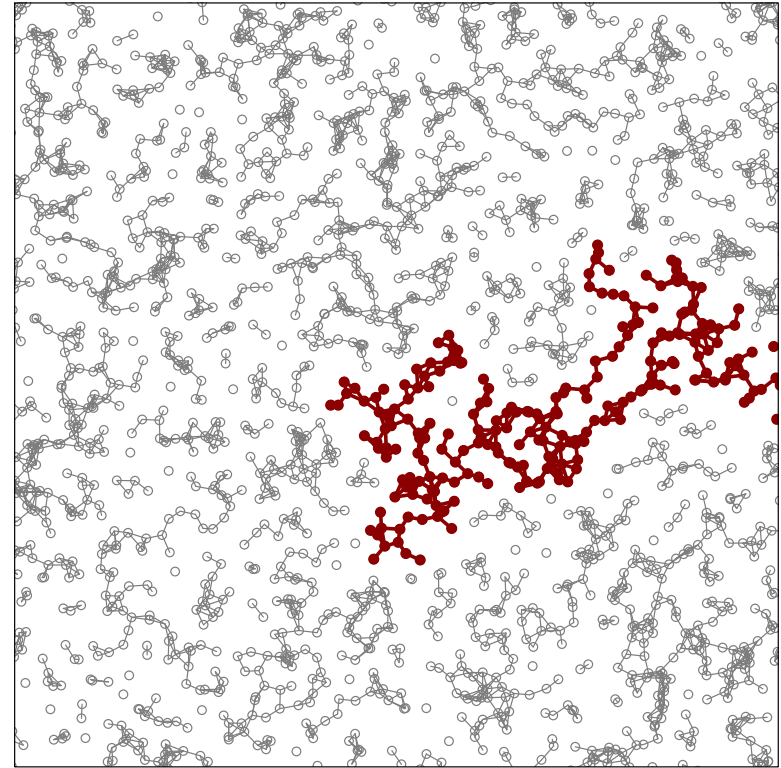
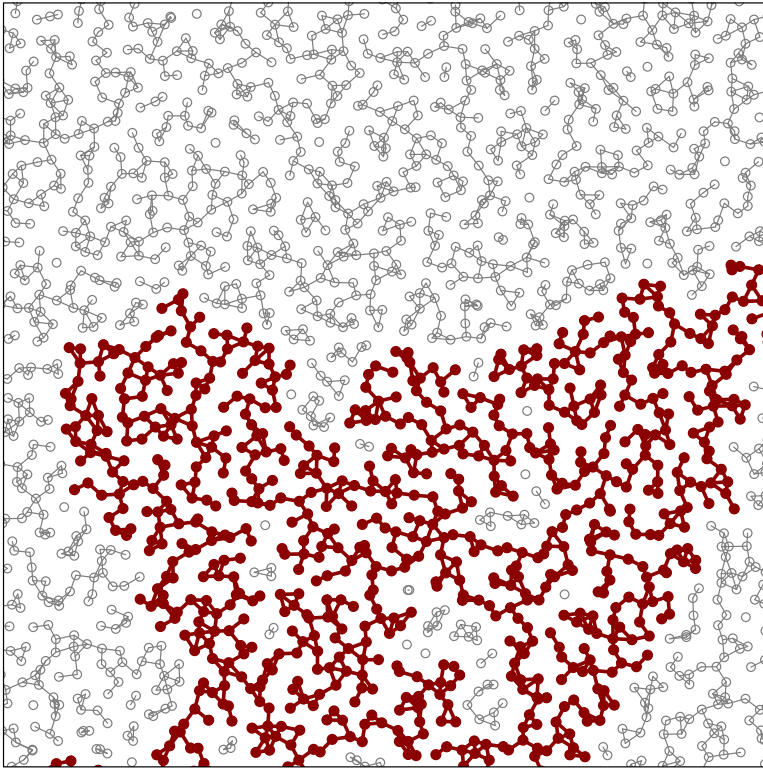


RGG with  $r = 98$ .

The largest component in the window is highlighted.



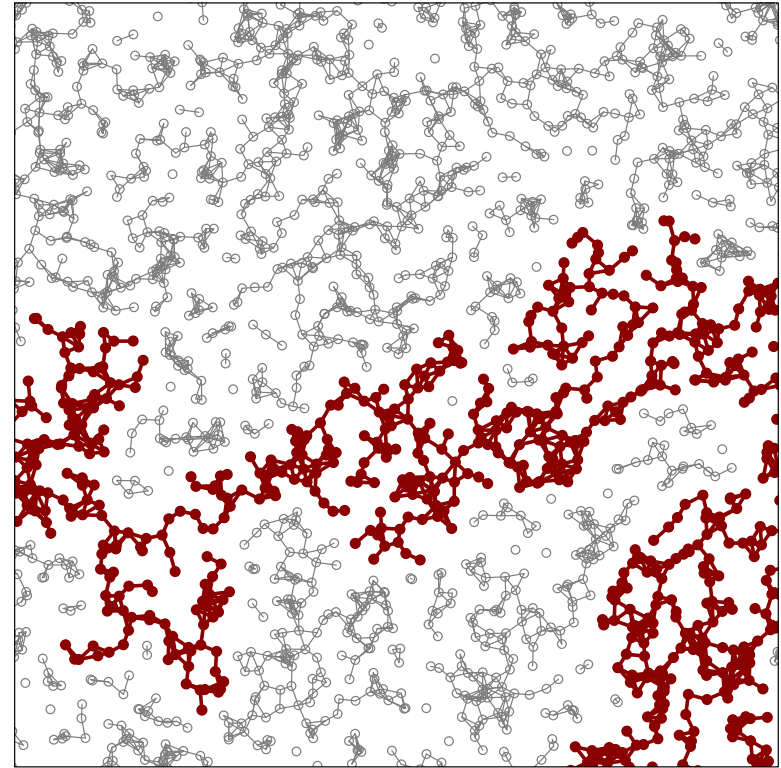
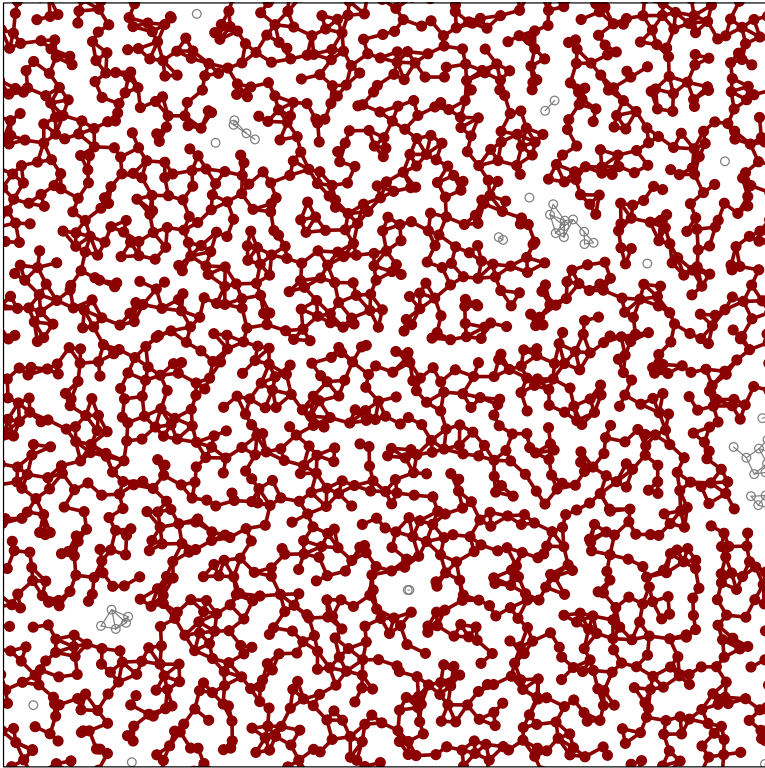
# Clustering and percolation



RGG with  $r = 100$ .

The largest component in the window is highlighted.

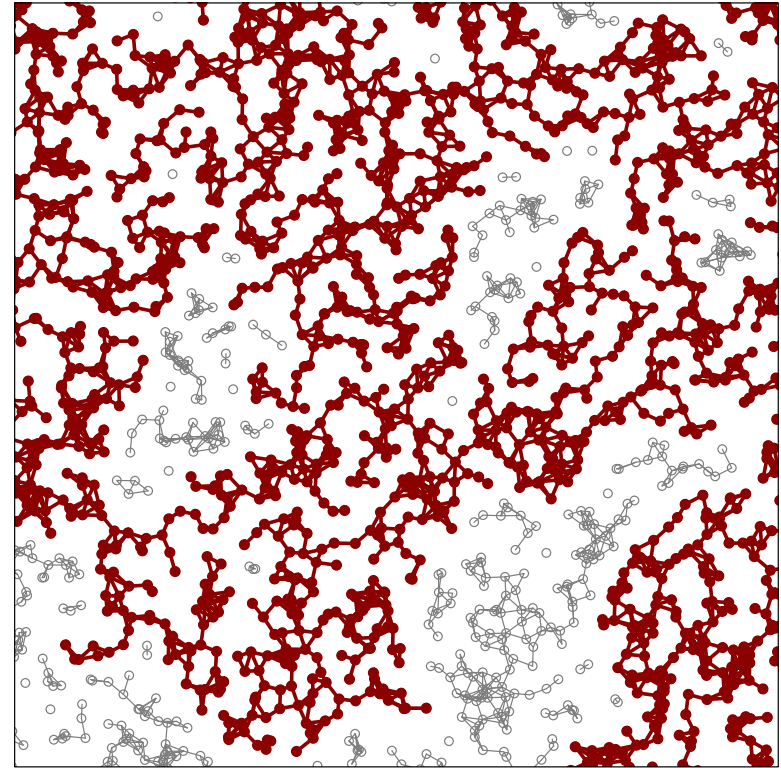
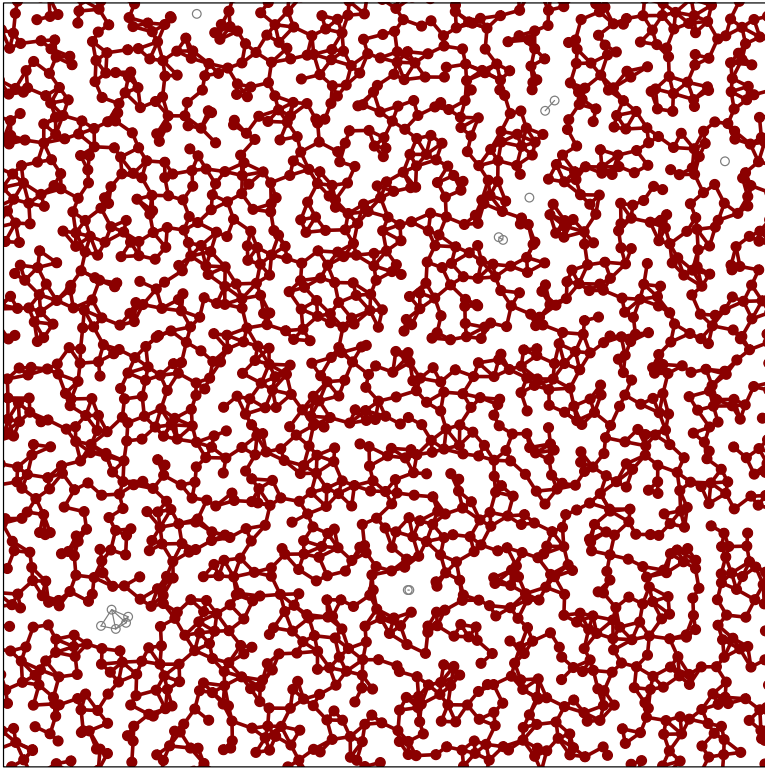
# Clustering and percolation



RGG with  $r = 108$ .

The largest component in the window is highlighted.

# Clustering and percolation

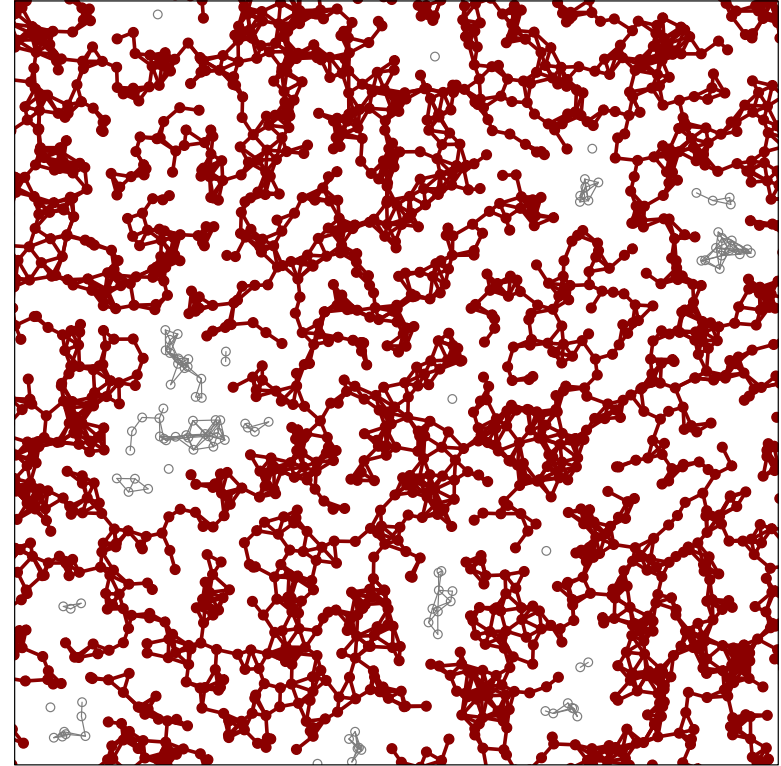
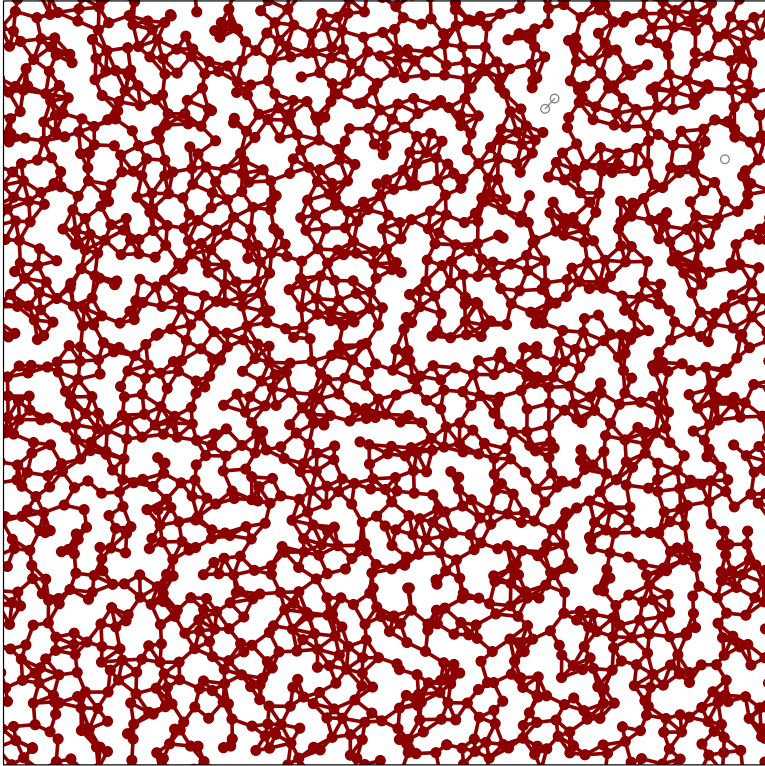


RGG with  $r = 112$ .

The largest component in the window is highlighted.



# Clustering and percolation



RGG with  $r = 120$ .

The largest component in the window is highlighted.

# Conjecture: Clustering worsens percolation

Point processes exhibiting more clustering should have larger **critical radius**  $r_c$  for the percolation of their continuum percolation models.

$$\Phi_1 \text{ "clusters less than" } \Phi_2 \Rightarrow r_c(\Phi_1) \leq r_c(\Phi_2),$$

where  $r_c(\Phi) = \inf\{r > 0 : P(C(\Phi, r) \text{ percolates}) > 0\}$

**Heuristic:** Interconnecting well spaced-out clusters (necessary to obtain an infinite connected component) requires large  $r$ . Spreading points from clusters "more homogeneously" should result in a decrease  $r$  for which the percolation takes place.

# Ways of comparing clustering — outline of the talk

Smaller in one of the following ways indicates less clustering:

- **Second-order statistics** (Ripley's  $K$ ,  $L$ , pair correlation function)  $\Rightarrow$  variance comparisons
- **Comparisons of void probabilities** and all higher-order factorial moment measures.  
 $\Rightarrow$  concentration inequalities and percolation results
- **Positive and negative association** of pp.  
 $\Rightarrow$  comparison to Poisson pp
- ***dcx* ordering of pp**  
 $\Rightarrow$  the strongest (on this list) comparison tool
- examples, counterexamples and conclusions

# Second-order statistics

# Ripley's $K$ and $L$ function

- Ripley's  $K$  function: for a stationary isotropic pp  $\Phi$  of intensity  $\lambda$  on  $\mathbb{R}^d$

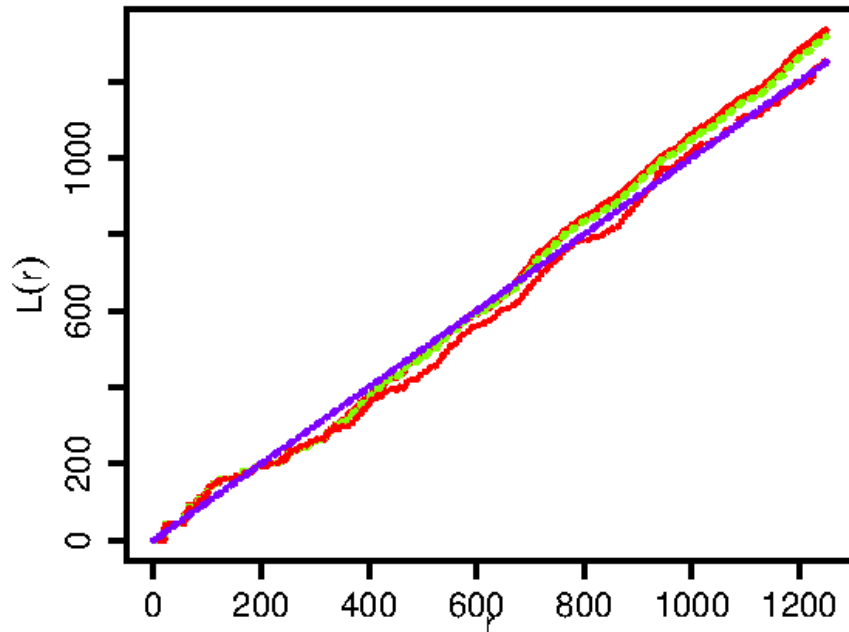
$$K(r) = \frac{1}{\lambda} \mathbb{E}^0[\Phi(\{x : |x| \leq r\}) - 1]$$

(expected number of points of  $\Phi$  within the distance  $r$  of its typical point)

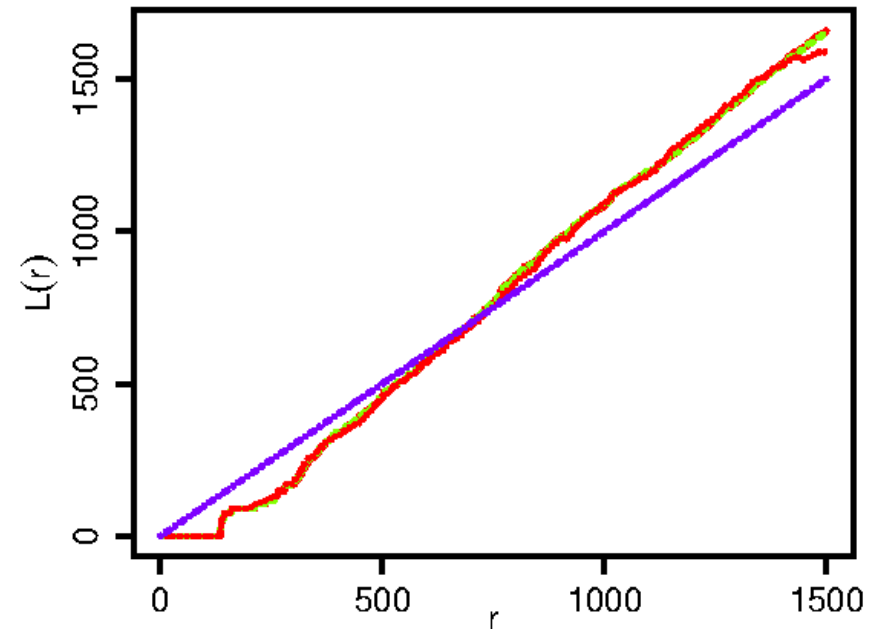
- Ripley's  $L$  function:  $L(r) = (K(r)/\kappa_d)^{1/d}$ , where  $\kappa_d$  volume of the unit ball in  $\mathbb{R}^d$ .

# Ripley's $K$ and $L$ function; cont'd

**Fact:** For Poisson pp  $K(r) = \kappa_d r^d$ ,  $L(r) = r$  (Slivnyak-Mecke).



“Poisson-like network”



“not so Poisson network”

Empirical Ripley's  $L$  function for real positioning of BS in some big European city ( Jovanovic&Karray [Orange Labs]).

Allow for local clustering comparison at different scales  $r$ .

# Pair correlation function

Probability of finding a point at a given position with respect to another point

$$g(x, y) = g(x - y) := \frac{\rho^{(2)}(x, y)}{\lambda^2},$$

where  $\rho^{(2)}$  is the density of the 2'nd order moment measure.

**Also a local comparison.** Too weak to capture global (percolation-like) properties.

# Ripley's $K$ function and variance comparison

A forerunner in this theory

**Fact (Stoyan'83):** Consider two stationary isotropic pp  $\Phi_1$  and  $\Phi_2$  of the same intensity, with the Ripley's functions  $K_1$  and  $K_2$ , respectively. If  $K_1 \leq_{dc} K_2$  i.e.,

$$\int_0^\infty f(r) K_1(dr) \leq \int_0^\infty f(r) K_2(dr)$$

for all decreasing convex  $f$  then

$$\mathbf{Var} (\Phi_1(B)) \leq \mathbf{Var} (\Phi_2(B))$$

for all compact convex  $B$ .

Stoyan'83 considers applications to some renewal, Cox, Neyman-Scott and fibre processes.



# Voids and moments & concentration inequalities via Chernoff bounds

# Voids and moments

- **probabilities**:  $\nu(B) = \mathbf{P}(\Phi(B) = 0)$ , bounded Borel sets (bBs)  $B$ .
- **Moment measures**:  
 $\alpha^k(B_1 \times \dots \times B_k) = \mathbf{E}\left(\prod_{i=1}^k \Phi(B_i)\right)$  for all (not necessarily disjoint) bBs  $B_i$ .
- **Factorial moment measures**:  $\alpha^{(k)}(\cdot)$  for simple pp, truncation of the measure  $\alpha^k(\cdot)$  to “off the diagonals”  
 $\{(x_1, \dots, x_k) \in (\mathbb{R}^d)^k : x_i \neq x_j \text{ for } i \neq j\}$
- In a general (not necessarily simple pp)  $\{\alpha^{(k)}(\cdot) : k\}$  can be expressed in terms of  $\{\alpha^k(\cdot) : k\}$  and vice versa. Each of the three families of three functionals (voids, moments and factorial moments) determine the distribution of pp.

# Clustering & concentration

- The “most spatially homogeneous” (“non-clustering”) way of spreading points of  $\Phi$ , with a given mean measure  $\alpha(\cdot)$ , would be to place them according to the (deterministic) measure  $\alpha(\cdot)$ . But this is not a point process.
- Consider the probability that  $\Phi$  deviates from  $\alpha(\cdot)$  on  $B$  by more than  $a$ :  $\mathbf{P} (|\Phi(B) - \alpha(B)| \geq a)$ .
- Smaller these probabilities indicate less clustering (more homogeneity).
- Voids and moments allow for upper bounds on these probabilities  $\rightarrow$  concentration inequalities.

# Concentration inequalities

- Chernoff's bounds:

$$\mathbf{P}(\Phi(B) - \alpha(B) \geq a) \leq e^{-t(\alpha(B)+a)} \mathbf{E}(e^{t\Phi(B)})$$

and

$$\mathbf{P}(\alpha(B) - \Phi(B) \geq a) \leq e^{t(\alpha(B)-a)} \mathbf{E}(e^{-t\Phi(B)})$$

- $\mathbf{E}(e^{t\Phi(B)})$  and  $\mathbf{E}(e^{-t\Phi(B)})$  can be expressed in terms of moments and voids of  $\Phi$ , respectively.

- Indeed:  $\mathbf{E}(e^{t\Phi(B)}) = \sum_{k=0}^{\infty} \frac{t^k}{k!} \alpha^k(B)$

- and

$$\mathbf{E}(e^{-t\Phi(B)}) = \sum_{k=0}^{\infty} e^{-tk} \mathbf{P}(\Phi(B) = k) = \mathbf{P}(\Phi'(B) = 0)$$

is the void probability of the point process  $\Phi'$  obtained from  $\Phi$  by independent thinning with retention probability  $1 - e^{-t}$ . Ordering of voids is preserved by independent thinning.

# Comparison to Poisson pp — Laplace ordering

- Consider pp  $\Phi$  having voids and moments smaller than Poisson pp (of the same mean). We call them **weakly sub-Poisson** (a weaker comparison than *dcx*).

$$\mathbf{P}(\Phi(B) = 0) \leq e^{-\mathbf{E}(\Phi(B))} \text{ for all bBs } B \quad (\text{V})$$

$$\mathbf{E}\left(\prod_{i=1}^k \Phi(B_i)\right) \leq \prod_{i=1}^k \mathbf{E}(\Phi(B_i)) \text{ for all disjoint } B_i \quad (\text{M})$$

- **Prop.** For simple pp  $\Phi$  of mean measure  $\alpha$ :  $\Phi$  has smaller voids than Poisson ((V) holds true) if and only if for all  $f \leq 0$

$$\mathbf{E}\left(\exp\left[\int_{\mathbb{R}^d} f(x) \Phi(dx)\right]\right) \leq \exp\left[\int_{\mathbb{R}^d} (e^{f(x)} - 1) \alpha(dx)\right] \quad (*)$$

- **Prop.** For simple pp  $\Phi$  of mean measure  $\alpha$ : If  $\Phi$  has smaller moments than Poisson ((M) holds true) then (\*) holds for all  $f \geq 0$ .

# Concentration inequality for sub-Poisson

Extension of a result for Poisson pp (cf Penrose (2003)):

- **Cor.** Let  $\Phi$  be an unit intensity, simple, stationary, weakly sub-Poisson point process and  $B_n$  be a set of Lebesgue measure  $n$ . Then, for any  $1/2 < a < 1$  there exist  $n(a)$  such that for  $n \geq n(a)$   
$$P(|\Phi(B_n) - n| \geq n^a) \leq 2 \exp \left[ -n^{2a-1} / 9 \right].$$

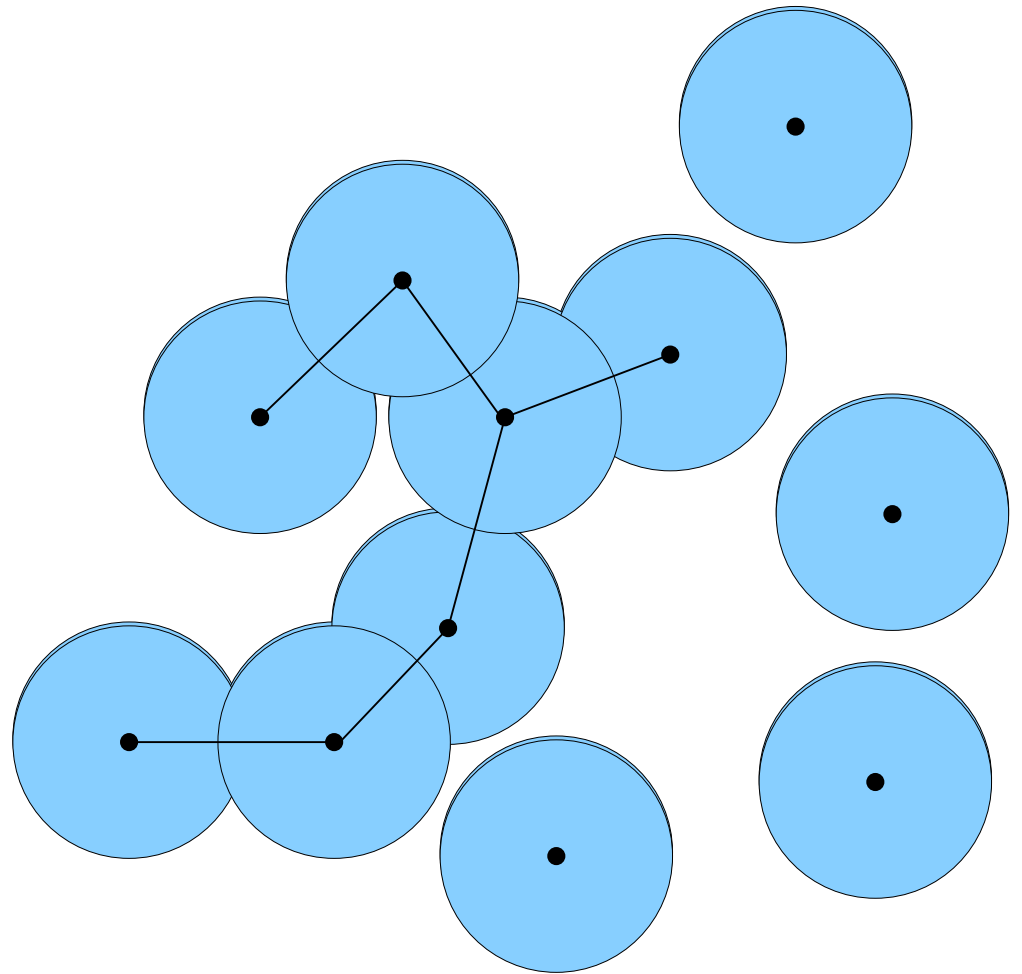
# Voids and moments & percolation

# Continuum percolation

Boolean model  $C(\Phi, 2r)$ :

germs in  $\Phi$ ,  
spherical grains of given radius  $r$ .

Joining germs whose grains intersect one gets  
**Random Geometric Graph (RGG)**.

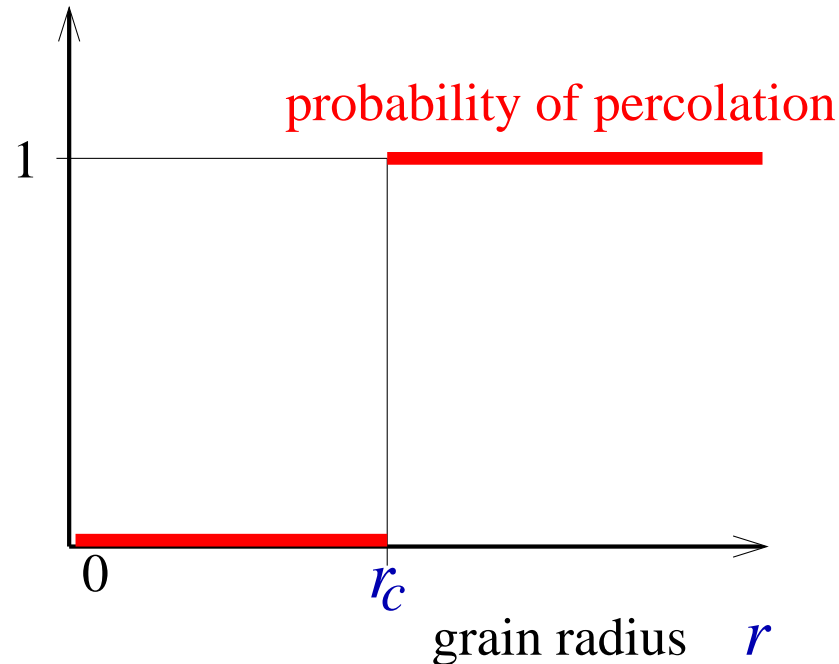


**percolation**  $\equiv$  existence of an infinite connected subset (component).



# Critical radius for percolation

- **Critical radius** for the percolation in the Boolean Model with germs in  $\Phi$ :  
$$r_c(\Phi) = \inf\{r > 0 : P(C(\Phi, r) \text{ percolates}) > 0\}$$
- In the case when  $\Phi$  is stationary and ergodic



- If  $0 < r_c < \infty$  the **phase transition is non-trivial**.

# Voids & percolation — a sufficient condition

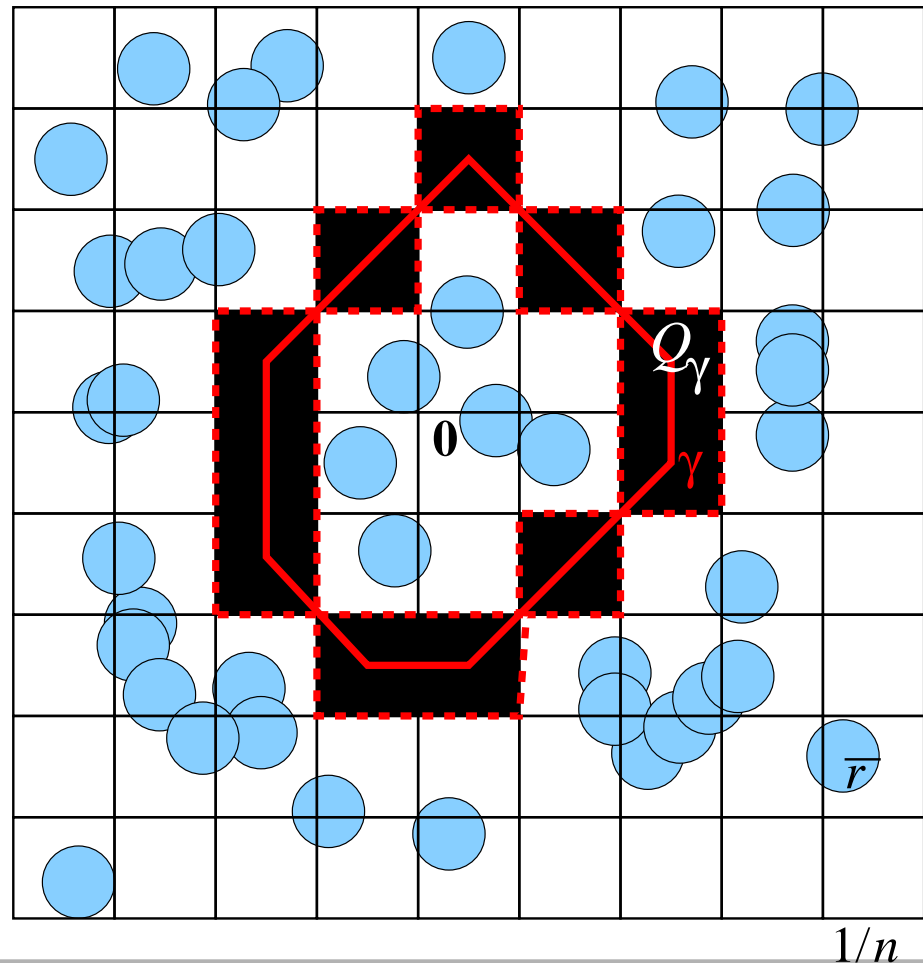
An upper bound on  $r_c$  using voids

$$\bar{r}_c = \inf \left\{ r > 0 : \forall n \geq 1, \sum_{\gamma \in \Gamma_n} \mathbf{P} (C(\Phi, r) \cap Q_\gamma = \emptyset) < \infty \right\}.$$

By Peierls argument

$$r_c(\Phi) \leq \bar{r}_c(\Phi).$$

Smaller voids imply  
smaller  $\bar{r}_c(\Phi)$



# Moments & percolation — a necessary cond.

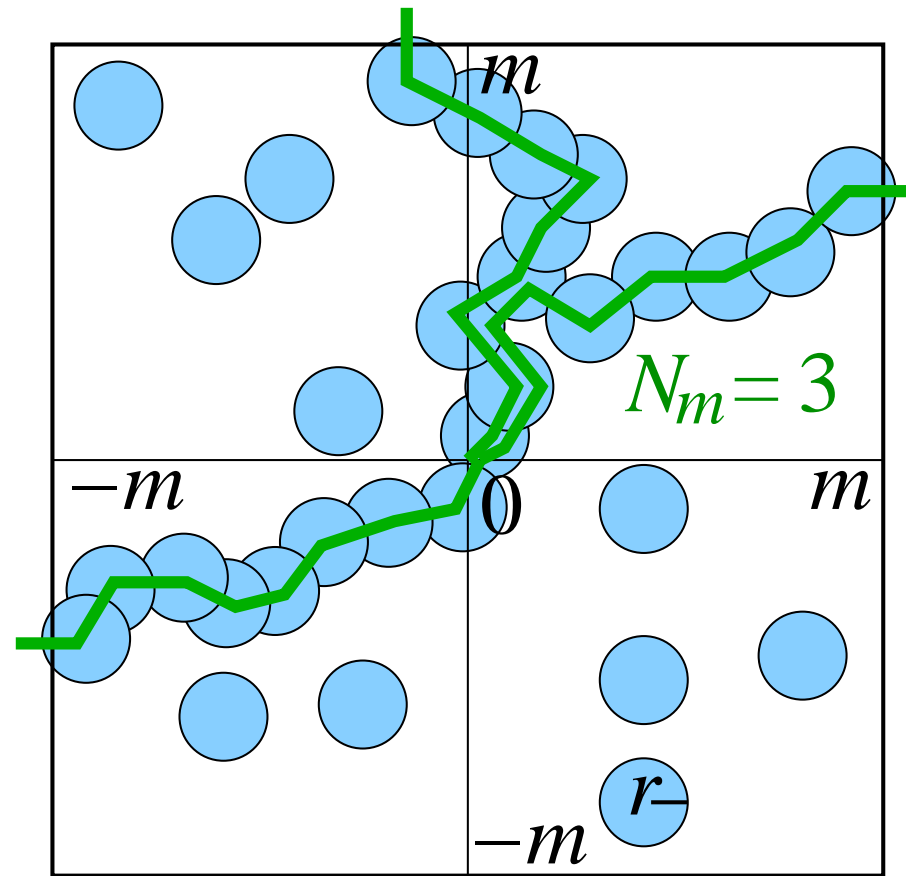
A lower bound on  $r_c$  related to moments measures

$$\underline{r}_c(\Phi) := \inf \left\{ r > 0 : \liminf_{m \rightarrow \infty} \mathbf{E}(N_m(\Phi, r)) > 0 \right\} .$$

By Markov inequality

$$\underline{r}_c(\Phi) \leq r_c(\Phi).$$

Smaller moments imply  
larger(!)  $\underline{r}_c(\Phi)$



# Non-trivial phase transition for sub-Poisson

Extension of the well known result for Poisson pp:

- **Prop.** Let  $\Phi$  be a stationary, weakly sub-Poisson pp with intensity  $\lambda$ . Then

$$0 < \frac{1}{(\kappa_d \lambda)^{1/d}} \leq r_c(\Phi) \leq \sqrt{d} \left( \frac{\log(3^d - 2)}{\lambda} \right)^{1/d} < \infty.$$

All weakly sub-Poisson point processes exhibit a non-trivial phase transition in the percolation of their Boolean models. Bounds are uniform over all processes of a given intensity!

- Similar results for  $k$ -coverage in Boolean model (clique percolation) and SINR percolation and some other percolation models.

# Association of point processes as comparison to Poisson pp

# Association of pp

- $\Phi$  is called **associated** if  
 $\text{Cov}(f(\Phi(B_1), \dots, \Phi(B_k)), g(\Phi(B_1), \dots, \Phi(B_k))) \geq 0$   
for bBs  $B_1, \dots, B_k$  and  $f, g$  continuous and increasing functions taking values in  $[0, 1]$  (**Burton&Waymire (1985)**).
- $\Phi$  is called **negatively associated** if  
 $\text{Cov}(f(\Phi(B_1), \dots, \Phi(B_k)), g(\Phi(B_{k+1}), \dots, \Phi(B_l))) \leq 0$   
for bBs  $B_1, \dots, B_l$  such that  
 $(B_1 \cup \dots \cup B_k) \cap (B_{k+1} \cup \dots \cup B_l) = \emptyset$  and  $f, g$   
increasing functions (**Pemantale (2000)**).

# Weak sub-poissonianity and association

- **Prop.** A negatively associated, simple point process with a Radon mean measure is weakly sub-Poisson.

A (positively) associated point process with a Radon, diffuse mean measure is weakly super-Poisson (voids and moments larger than for Poisson).

- **Cor.** Assume that  $\Phi$  is a simple point process of Radon mean measure  $\alpha$ . If  $\Phi$  is negatively associated then for all  $f$  of a fixed sign

$$\mathbf{E}\left(\exp\left[\int_{\mathbb{R}^d} f(x) \Phi(\mathrm{d}x)\right]\right) \leq \exp\left[\int_{\mathbb{R}^d} (e^{f(x)} - 1) \alpha(\mathrm{d}x)\right]$$

provided the integrals are well defined.

# **directionally-convex ordering of point processes**



# *dcx* ordering of point processes

- $\Phi_1 \leq_{dcx} \Phi_2$  if for all bounded Borel subsets  $B_1, \dots, B_n$ ,  
$$\mathbf{E}(f(\Phi_1(B_1), \dots, \Phi_1(B_n))) \leq \mathbf{E}(f(\Phi_2(B_1), \dots, \Phi_2(B_n))) .$$
for all *dcx*  $f$ . Function  $f : \mathbb{R}^d \rightarrow \mathbb{R}$  twice differentiable is *dcx* if  $\frac{\partial^2 f(x)}{\partial x_i \partial x_j} \geq 0$  for all  $x \in \mathbb{R}^d$  and  $\forall i, j$ ; extended to all functions by considering difference operators.
- *dcx* is a **partial order** (reflective, antisymmetric and transitive) of point process with locally finite mean measure (to ensure transitivity).
- If  $\Phi_1 \leq_{dcx} \Phi_2$  then  $\mathbf{E}(\Phi_1(\cdot)) = \mathbf{E}(\Phi_2(\cdot))$  (**equal mean measures**).
- *dcx* is preserved by independent thinning, marking and superpositioning of pp., creating of Cox pp.

# $d_{cx}$ and shot-noise fields

Given point process  $\Phi$  and a non-negative function  $h(x, y)$  on  $(\mathbb{R}^d, \mathcal{S})$ , measurable in  $x$ , where  $\mathcal{S}$  is some set, define **shot noise field**: for  $y \in \mathcal{S}$

$$V_{\Phi}(y) := \sum_{X \in \Phi} h(X, y) = \int_{\mathbb{R}^d} h(x, y) \Phi(dx).$$

**Prop.** If  $\Phi_1 \leq_{d_{cx}} \Phi_2$  then

$$(V_{\Phi_1}(y_1), \dots, V_{\Phi_1}(y_n)) \leq_{d_{cx}} (V_{\Phi_2}(y_1), \dots, V_{\Phi_2}(y_n))$$

for any finite subset  $\{y_1, \dots, y_n\} \subset \mathcal{S}$ , provided the RHS has finite mean. In other words,  $d_{cx}$  is preserved by the shot-noise field construction.

# *dcx* and shot-noise fields; cont'd

## Proof.

- Approximate the integral by simple functions as usual in integration theory: *a.s.* and in  $L_1$

$$\sum_{i=1}^{k_n} a_{in} \Phi(B_{in}^j) \rightarrow \int_{\mathbb{R}^d} h(x, y) \Phi(dx) = V_{\Phi}(y_j), \quad a_{in} \geq 0.$$

- Increasing linear operations preserve *dcx* hence approximating simple functions are *dcx* ordered.
- *dcx* order is preserved by *joint* weak and  $L_1$  convergence. Hence limiting shot-noise fields are *dcx* ordered.

# $dcx$ and extremal shot-noise fields

In the setting as before define for  $y \in S$

$$U_{\Phi}(y) := \sup_{X \in \Phi} h(X, y).$$

**Prop.** If  $\Phi_1 \leq_{dcx} \Phi_2$  then for all

$y_1, \dots, y_n \in S$ ;  $a_1, \dots, a_n \in \mathbb{R}$ ,

$P(U_{\Phi_1}(y_i) \leq a_i, 1 \leq i \leq m) \leq P(U_{\Phi_2}(y_i) \leq a_i, 1 \leq i \leq m)$ ;

i.e, the (joint) finite-dimensional distribution functions of the extremal shot-noise fields are ordered (**lower orthant order**).

**Cor.** One-dimensional distributions of the extremal shot-noise fields are **strongly ordered with reversed inequality**

$U_{\Phi_2}(y) \leq_{st} U_{\Phi_1}(y), \forall y \in S.$

# *dcx* and extremal shot-noise fields; cont'd

Proof.

- Reduction to an (additive) shot noise:

$$\begin{aligned} \mathbf{P} (U_{\Phi}(y_i) \leq a_i, 1 \leq i \leq n) \\ = \mathbf{E} \left( e^{-\sum_{i=1}^n \sum_{X \in \Phi} -\log 1[h(X, y_i) \leq a_i]} \right) . \end{aligned}$$

- $e^{-\sum x_i}$  is *dcx* function.

# *dcx* and voids & moments

**Prop.** If  $\Phi_1 \leq_{dcx} \Phi_2$  then  $\nu_1(B) \leq \nu_2(B)$ .

**Prop.** If  $\Phi_1 \leq_{dcx} \Phi_2$  then  $\alpha_1(\cdot) = \alpha_2(\cdot)$  and  $\alpha_1^k(\cdot) \leq \alpha_2^k(\cdot)$  for  $k \geq 1$  provided these measures are  $\sigma$ -finite.

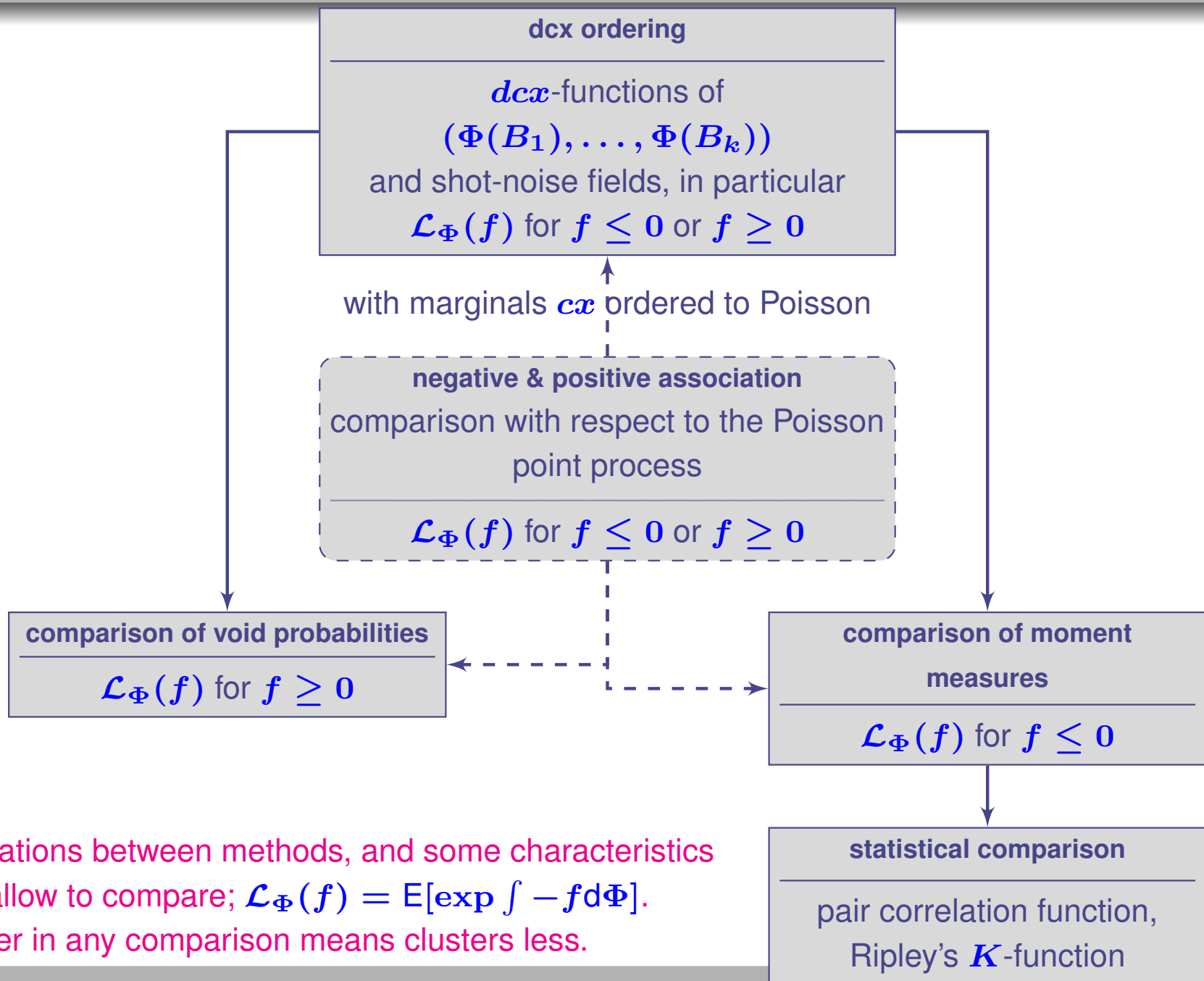
We call pp *dcx* smaller (larger) than Poisson **sub-Poisson** **super-Poisson** is (stronger) *dcx* sens.

# *dcx* versus association

**Prop.** A negatively associated point processes with convexly sub-Poisson one-dimensional marginal distributions is *dcx* sub-Poisson.

An associated point processes with convexly super-Poisson one-dimensional marginal distributions is *dcx* super-Poisson.

# Clustering comparison tools — recap.



Implications between methods, and some characteristics  
 they allow to compare;  $\mathcal{L}_\Phi(f) = E[\exp \int -fd\Phi]$ .  
 Smaller in any comparison means clusters less.



**EXAMPLES ???**

# Comparison to Poisson pp

## sub-Poisson processes

### strongly ( $dcx$ )

Voronoi perturbed lattices with replication kernel  $\mathcal{N} \leq_{cx} \text{Pois}$ , in particular binomial, **determinantal(?)**

### negatively associated

binomial, **determinantal(?)**

### weakly (voids and moments)

$dcx$  sub-Poisson, negatively associated, **determinantal**

## super-Poisson processes

### strongly ( $dcx$ )

Poisson-Poisson cluster, Lévy based Cox, mixed Poisson, Neyman-Scott with mean cluster size 1, Voronoi perturbed lattices with replication kernel  $\mathcal{N} \geq_{cx} \text{Pois}$ .

### associated

Poisson-center cluster, Neyman-Scott, Cox associated with associated intensity measure.

### weakly (voids and moments)

$dcx$  super-Poisson, associated, **permanental**

Some point processes comparable to Poisson point process according to different methods.

# **Determinantal pp**

## **— voids, moments and more**

# Determinantal pp

- Examples of weakly sub-Poisson pp? Theory fits well to **determinantal pp**  $\Phi^{det}$  defined as **having density of the  $k$ th factorial moment measure** with respect to  $\mu^{\otimes d}$ , for some  $\mu(\cdot)$ , given by  $\rho^{(k)}(x_1, \dots, x_k) = \det(K(x_i, x_j))_{1 \leq i, j \leq k}$ , where **det** stands for determinant of a matrix and  $K$  is some kernel. Assumptions on  $K$  needed!
- Assumptions: Let  $K : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{C}$  **locally square-integrable kernel** with respect to  $\mu^{\otimes 2}$ , defining **Hermitian, positive semi-definite, trace-class operator**  $\mathcal{K}_B$  on  $L^2(B, \mu)$ , for all compact  $B$ , with **all eigenvalues in  $[0, 1]$** . (cf. **Ben Hough(2009)**)

# Determinantal pp is weakly sub-Poisson

- By Hadamard's inequality,  
 $\det (K(x_i, x_j))_{1 \leq i, j \leq k} \leq \prod_{i=1}^k K(x_i, x_i)$  hence  $\Phi^{\det}$  has moments smaller than Poisson pp of mean  $K(x, x)\mu(dx)$ .
- Distribution of  $\Phi^{\det}(B)$  is equal to sum of independent Bernoulli variables with parameters given by the eigenvalues of  $\mathcal{K}_B$ . Hence  $\Phi^{\det}(B)$  is convexly smaller than Poisson which implies smaller voids.
- **Cor.** All determinantal pp exhibit non-trivial phase transition in percolation of their RGG. New result!

# Determinantal pp and dcx

- **Prop.**

$$(\Phi^{det}(B_1), \dots, \Phi^{det}(B_n))$$

$$\leq_{dcx} (\text{Pois}(B_1), \dots, \text{Pois}(B_n)),$$

for disjoint, **simultaneously observable**  $B_i$

(eigenfunctions of  $\mathcal{K}_{\cup B_i}$ , restricted to  $B_i$  are also eigenfunctions of  $\mathcal{K}_{B_i}$  for all  $i$ ).

- A partial proof of the fact that stationary **determinantal pp are negatively associated** can be found in the current version of Ghosh'12 arXiv:1211.2435.

If this is true than determinantal pp are not only **weakly sub-Poisson**, but having convexly smaller marginals are actually **dcx sub-Poisson**.

# Ginibre pp

- **Example:** Ginibre pp is the the determinantal point process on  $\mathbb{R}^2$  with kernel

$$K((x_1, x_2), (y_1, y_2)) =$$

$$\exp[(x_1 y_1 + x_2 y_2) + i(x_2 y_1 - x_1 y_2)],$$

$x_j, y_j \in \mathbb{R}, j = 1, 2$ , with respect to the measure

$$\mu(d(x_1, x_2)) = \pi^{-1} \exp[-x_1^2 - x_2^2] dx_1 dx_2.$$

- Spherical annuli are its simultaneously observable sets.
- Consequently, pp of the squared radii  $\{|X_i|^2\}$  of the Ginibre point process is  $d\mathcal{C}x$  sub-Poisson.  
Interestingly  $\{|X_i|^2\} =_{distr} \{T_n = \sum_n \sum_{i=1}^n Z_i^n\}$ , where  $Z_i^n$  are i.i.d. exponential.

# Clustering worsens percolation? — examples and ... a counterexample



# Perturbed lattices

Assume:

$\Phi$  — deterministic lattice,

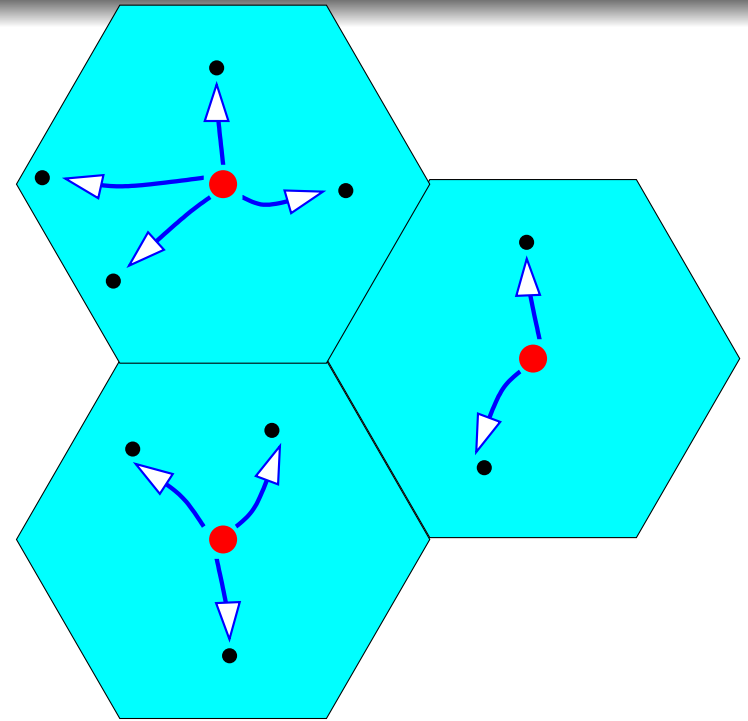
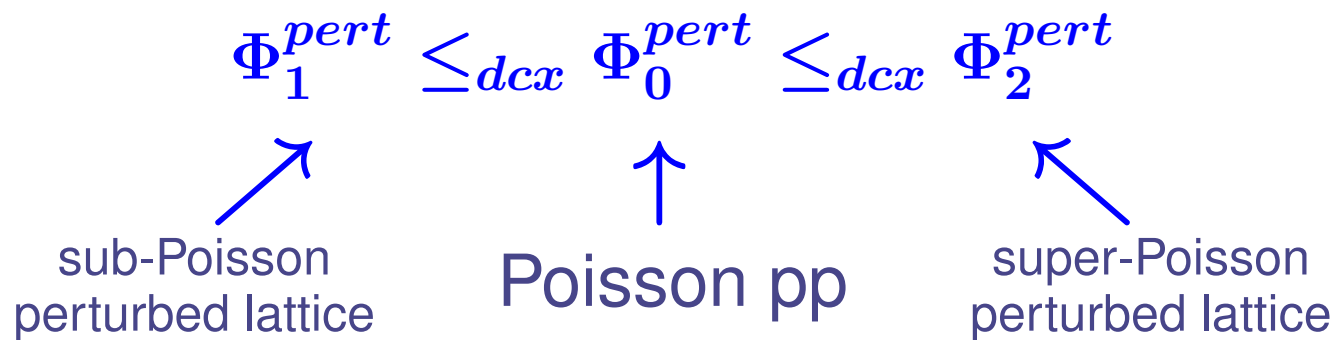
(say uniform) translation kernel inside lattice cell,

$$\mathcal{N}_0(x, \cdot) = Poi(1),$$

$$\mathcal{N}_1(x, \cdot) \leq_c Poi(1),$$

$$\mathcal{N}_2(x, \cdot) \geq_c Poi(1).$$

Then



# Perturbed lattices; cont'd

*cx* ordered families of (discrete) random variables from smaller to larger:

- **deterministic** (constant);
- **Hyer-Geometric**  $p_{HGeo(n,m,k)}(i) = \binom{m}{i} \binom{n-m}{k-i} / \binom{n}{k}$   
( $\max(k - n + m, 0) \leq i \leq m$ ).
- **Binomial**  $p_{Bin(n,p)}(i) = \binom{n}{i} p^i (1 - p)^{n-i}$  ( $i = 0, \dots, n$ )
- **Poisson**  $p_{Poi(\lambda)}(i) = e^{-\lambda} \lambda^i / i!$  ( $i = 0, 1, \dots$ )
- **Negative Binomial**  $p_{NBin(r,p)}(i) = \binom{r+i-1}{i} p^i (1 - p)^r$ .
- **Geometric**  $p_{Geo(p)}(i) = p^i (1 - p)$

Assuming parameters making equal means, we have

$const \leq_{cx} HGeo \leq_{cx} Bin \leq_{cx} Poi \leq_{cx} NBin \leq_{cx} Geo$

# Conjecture for perturbed lattices

$$\Phi_1 \leq_{dcx} \Phi_2$$

$$\Downarrow$$

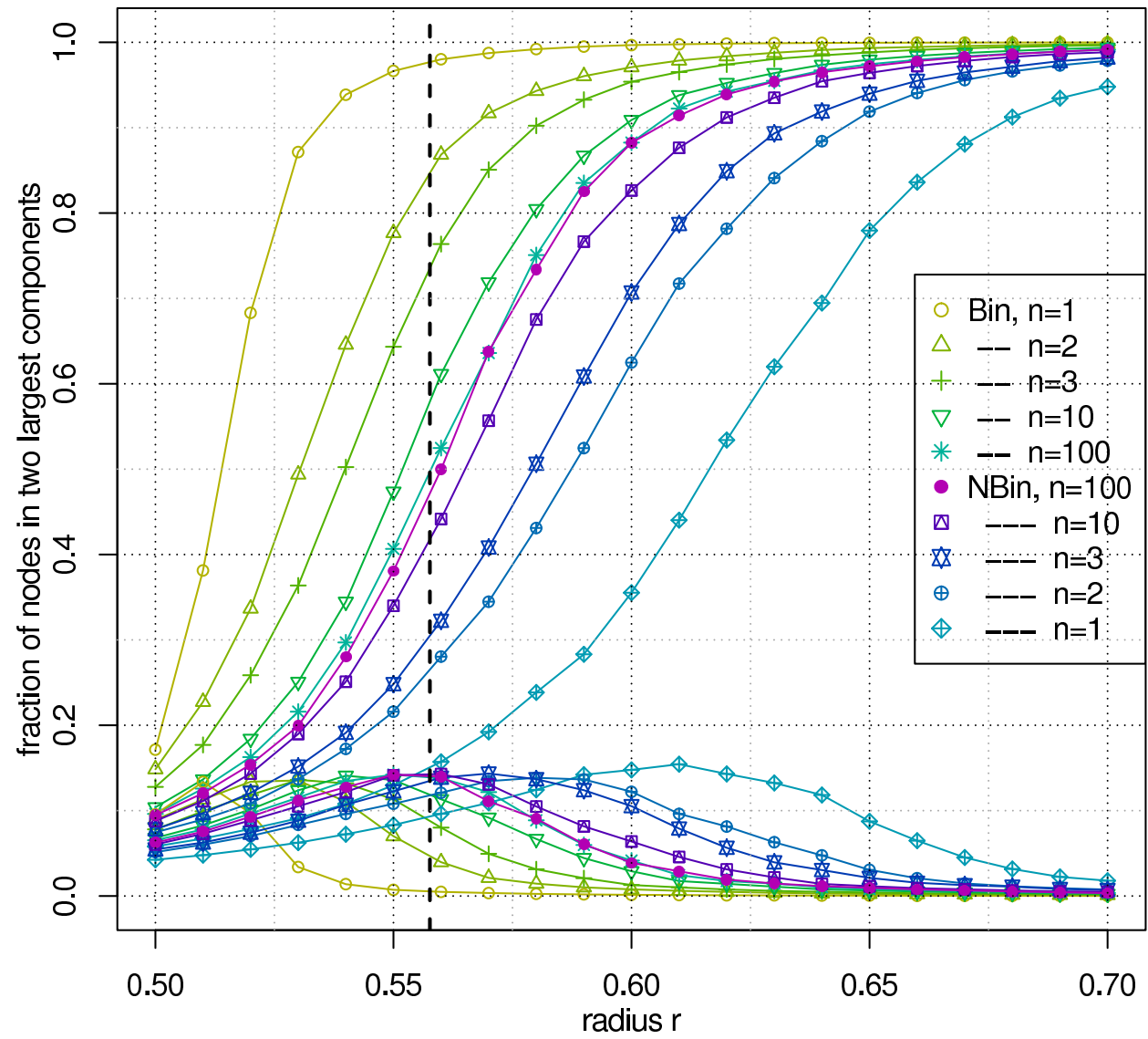
$$r_c(\Phi_1) \leq r_c(\Phi_2)$$

$$Bin(1, 1) = const$$

$$Bin(1, 1/n) \nearrow_{cx} Poi(1)$$

$$NBin(n, 1/(1+n)) \searrow_{cx} Poi(1)$$

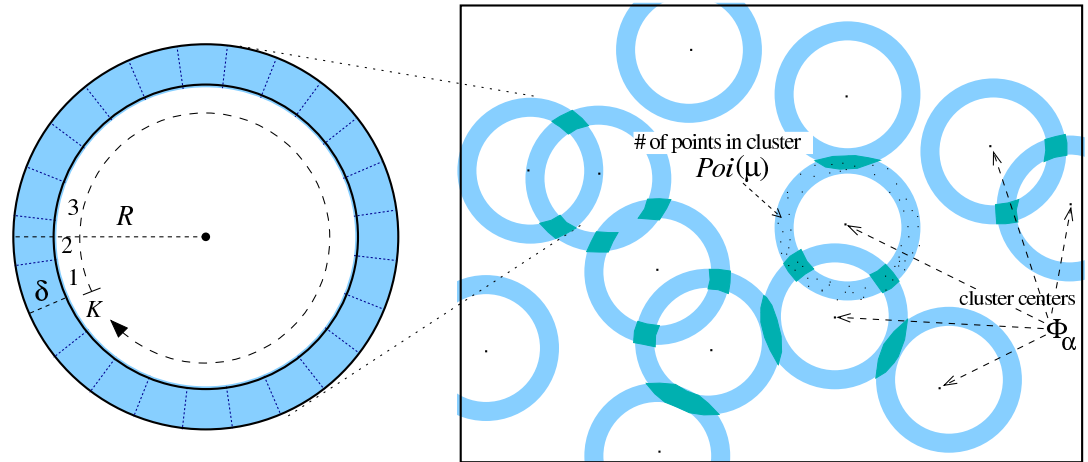
$$NBin(1, 1/2) = Geo(1/2)$$



# Counterexample: a super-Poisson pp with $r_c = 0$

Poisson-Poisson cluster pp  $\Phi_\alpha^{R,\delta,\mu}$  with annular clusters

$\Phi_\alpha$  — Poisson (parent) pp of intensity  $\alpha$  on  $\mathbb{R}^2$ , Poisson clusters of total intensity  $\mu$ , supported on annuli of radii  $R - \delta, R$ .



We have  $\Phi_\lambda \leq_{dcx} \Phi_\alpha^{R,\delta,\mu}$ , where  $\Phi_\lambda$  is homogeneous Poisson pp of intensity  $\lambda = \alpha\mu$ .

**Prop.** Given arbitrarily small  $a, r > 0$ , there exist constants  $\alpha, \mu, \delta, R$  such that  $0 < \alpha, \mu, \delta, R < \infty$ , the intensity  $\alpha\mu$  of  $\Phi_\alpha^{R,\delta,\mu}$  is equal to  $a$  and the critical radius for percolation  $r_c(\Phi_\alpha^{R,\delta,\mu}) \leq r$ . Consequently, one can construct Poisson-Poisson cluster pp of intensity  $a$  and  $r_c = 0$ .

# Conclusions

- Voids and moment measures allow for a simple comparison of comparison of clustering properties of pp.
- We believe that these tools can be used to generalize some results derived for Poisson to “more homogeneous” (less clustering) — sub-Poisson pp.
- We have seen examples regarding concentration inequalities and phase transition in percolation.
- Other clustering comparison tools?
- Conjecture restricted to sub-Poisson pp.?

# Sub-poissonianity used in

- **Daley Last** Descending chains, the lilypond model, and mutual-nearest-neighbour matching (2005)
- **Hirsch, Neuhaeuser, Schmidt** Connectivity of random geometric graphs related to minimal spanning forests (2012)
- **Yogeshwaran, Adler** On the topology of random complexes built over stationary point processes (2012).

# Other related works

- **Benjamini and Stauffer** (2011) Perturbing the hexagonal circle packing: a percolation perspective.
- **Franceschetti, Booth, Cook, Meester and Bruck** (2005) Continuum percolation with unreliable and spread-out connections. J. Stat. Phy.
- **Franceschetti, Penrose, and Rosoma** (2010) Strict inequalities of critical probabilities on Gilbert's continuum percolation graph. arXiv
- **Jonasson** (2001) Optimization of shape in continuum percolation. Ann. Probab.
- **Roy and Tanemura** (2002) Critical intensities of boolean models with different underlying convex shapes.
- **Ghosh, Krishnapur, Peres** (2012) Continuum Percolation for Gaussian zeroes and Ginibre eigenvalues.



# For mode details ...

- BB, Yogeshwaran [Directionally convex ordering of random measures, shot-noise fields ...](#) *Adv. Appl. Probab.* (2009)
- BB, Yogeshwaran [Clustering and percolation of point processes](#) *EJP* 2013.
- BB, Yogeshwaran [On comparison of clustering properties of point processes](#) *Adv. Appl. Probab.* (2014).
- BB, Yogeshwaran [Clustering comparison of point processes with applications to random geometric models](#) arXiv:1112.5285 to appear in *Stochastic Geometry, Spatial Statistics and Random Fields ...* (V. Schmidt, ed.) Lecture Notes in Mathematics Springer.

**thank you**