Risk Management Methods for the Libor Market Model Using Semidefinite Programming.

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1.1 Interest rate model calibration

- All Heath, Jarrow & Morton (1992) based models are fully parametrized by the curve today and a covariance matrix.
- i.e. a positive semidefinite matrix The natural variable in the calibration problem is a covariance matrix,
- Classic calibration methods are heavily parametrized and only describe a small, often non-convex subset of the set of semidefinite matrices
- bumping the data and recalibrating. When using these techniques, sensitivity analysis has to be done by

Results on the LMM model calibration

- coefficients We can express the swap rate as a basket of Forwards with very stable
- European Caplets and Swaptions can be priced using the Black (1976) market formula with a variance that is *linear* in the coefficients of the Forward rates covariance matrix...
- naturally provides the local sensitivity to all market movements. The calibration problem is a semidefinite program and the dual solution
- hedging portfolio in the sense of El Karoui & Quenez (1991) and Avellaneda & Paras (1996). The dual solution also provides the coefficients of an upper (lower)

1.3 Related literature

- Works by Nesterov & Nemirovskii (1994) and Vandenberghe & Boyd (1996) on semidefinite programming
- the Libor market model. Brace, Gatarek & Musiela (1997) and Musiela & Rutkowski (1997) on
- on a calibration method parametrized by factors Rebonato (1998), Brace, Dun & Barton (1999) and Singleton & Umantsev (2001) on Swaps as baskets of Forwards. Rebonato (1999)
- dan Swaption. Parallel work by Brace & Womersley (2000) on the calibration of the BGM by semidefinite programming and the evaluation of the Bermu-

2 Swaption pricing

2.1 The Swap rate

We write the swap rate as a basket of Forwards:

$$swap(t, T_0, T_n) = \sum_{i=0}^{n} \omega_i(t)K(t, T_i)$$

the weights $\omega_i(t)$ are given by where $K(t,T_i)$ are the Forward Rates with maturities T_i , i=1,...,n and

$$\omega_i(t) = \frac{coverage(T_i^{float}, T_{i+1}^{float})B(t, T_{i+1}^{float})}{Level(t, T_0^{fixed}, T_n^{fixed})}$$

2.2 BGM Swaption price

strike k as a that of a Call on a Swap rate: following Jamshidian (1997), we can write the price of the Swaption with In practice, the weights $\omega_i(t)$ are very stable (see Rebonato (1998)) and

$$Ps(t) = Level(t, T, T_N) E_t^{Q_{LVL}} \left[\left(\sum_{i=0}^n \omega_i(T) K(T, T_i) - k \right)^+ \right]$$

where Q_{LVL} is the swap forward martingale probability measure

price can be very efficiently approximated by the Black (1976) formula: In fact, as detailed in Huynh (1994) or Brace et al. (1999) the Swaption

$$Swaption = Level(t, T, T_N) \left(swap(t, T, T_N) N(h) - \kappa N(h - V_T^{1/2}) \right)$$

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$$h = \frac{\left(\ln\left(\frac{swap(t,T,T_N)}{\kappa}\right) + \frac{1}{2}V_T\right)}{V_T^{1/2}}$$

where the cumulative variance is computed by:

$$V_T = \int_t^T \left\| \sum_{i=1}^N \hat{\omega}_i(t) \gamma(s, T_i - s) \right\|^2 ds \text{ and } \hat{\omega}_i(t) = \omega_i(t) \frac{K(t, T_i)}{swap(t, T, T_N)}$$

with $dK(s,T_i)=\gamma(s,T_i-s)K(s,T_i)dW_s^{Q_{T_{i+1}}}$.

2.3 BGM approximation precision

- zero approximation using enough steps to make the 95% confidence margin of error always We plot the difference between two distinct sets of Swaption prices in the Libor Market Model. One is obtained by Monte-Carlo simulation less than 1bp. The second set of prices is computed using the order
- volatilities and the following Swaptions: 2Y into 5Y, 5Y into 5Y, 5Y 2Y, 1Y into 9Y. into 2Y, 10Y into 5Y, 7Y into 5Y, 10Y into 2Y, 10Y into 7Y, 2Y into EURO Swaption prices on November 6 2000. We have used all Cap The plots are based on the prices obtained by calibrating the model to

Absolute pricing error (in basis points)

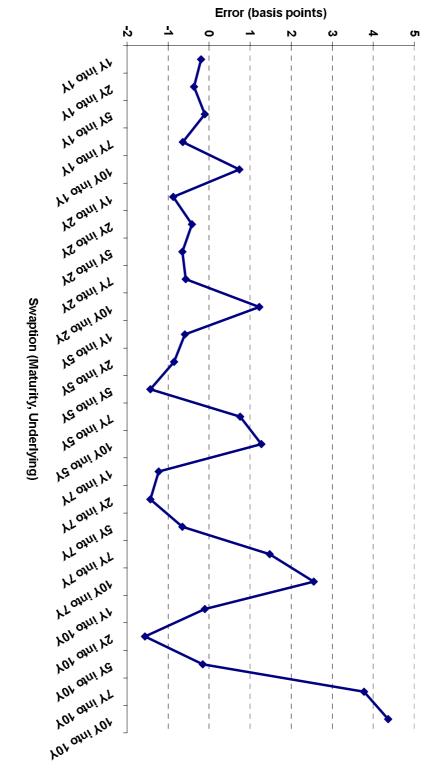


Figure 1: Absolute error (in bp) for various ATM Swaptions.

Error in the 10Y into 2Y Swaption price vs moneyness

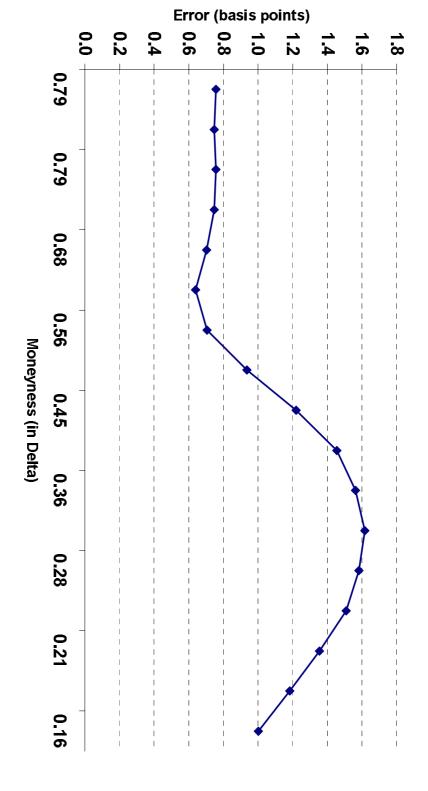


Figure 2: Absolute error (in bp) on the 10Y into 2Y.

Error in the 10Y into 7Y Swaption price vs moneyness

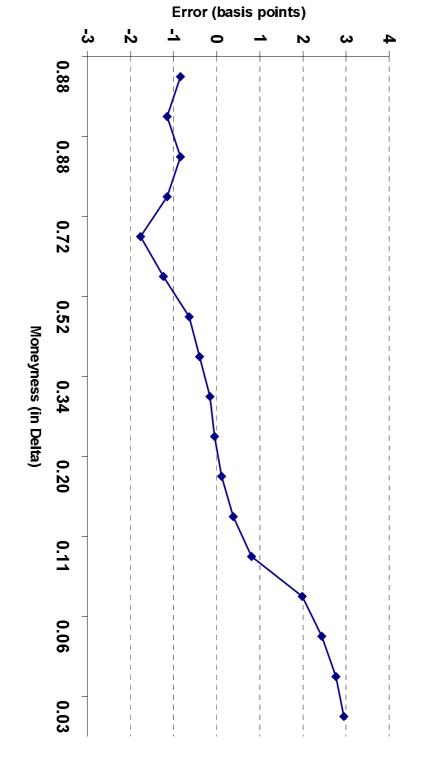


Figure 3: Absolute error (in bp) on the 10Y into 7Y.

3 Calibration

We have approximated the Swaption (T_m, T_{u+m}) price by:

$$P = Level(t, T_m, T_{u+m})BS(T, swap(t, T_m, T_{u+m}), V(T_m, T_{u+m}))$$

where BS is the Black (1976) formula with

$$V(T_m, T_{u+m}) = \int_t^{T_m} \left\| \sum_{i=m}^u \hat{\omega}_i(t) \gamma(s, T_i - s) \right\|^2 ds$$

straints. We express these constraints in terms of the market variance Suppose that we need to impose a sequence of ${\cal M}$ market pricing coninputs σ_k^2 :

$$V(T_{m_k}, T_{u_k+m_k}) = \sigma_k^2 T_{m_k}$$
 for $k = 1, ..., M$

We can rewrite the cumulative variance:

$$\begin{aligned} & \int_{t}^{T_{m}} \left\| \sum_{i=m}^{u} \hat{\omega}_{i}(t) \gamma(s, T_{i} - s) \right\|^{2} ds \\ & = \int_{t}^{T_{m}} \sum_{i=m}^{u} \sum_{j=m}^{u} \hat{\omega}_{i}(t) \hat{\omega}_{j}(t) \left\langle \gamma(s, T_{i} - s), \gamma(s, T_{j} - s) \right\rangle ds \\ & = \int_{t}^{T_{m}} Tr \left(\Omega X_{s} \right) ds \end{aligned}$$

where Tr is the trace, X_s is the Forward rate covariance matrix, with

$$(X_s)_{i,j} = \left\langle \gamma(s,T_i-s), \gamma(s,T_j-s)
ight
angle$$
 and

and $\left(\hat{\omega}(t)\hat{\omega}^T(t)\right)$ is a rank one matrix with $\left(\hat{\omega}(t)\hat{\omega}^T(t)\right)_{i,j}=\hat{\omega}_i(t)\hat{\omega}_j(t)$.

written: This means that the calibration constraints are linear in $X_{\mathcal{S}}$ and can be

$$\int_{t}^{T_{m_{k}}}Tr\left(\Omega_{k}X_{s}
ight)ds=\sigma_{k}^{2}T_{m_{k}} \ \ ext{for } k=1,...,M$$

If we discretize in time we can write the above constraints as:

$$Tr\left(\Omega_k X\right) = \sigma_k^2 T_{m_k} \ \text{ for } k=1,...,M$$

where Ω_k is a block diagonal matrix.

3.1 Semidefinite programming

The calibration problem can finally be stated as:

find
$$X$$
 s.t. $Tr(\Omega_k X) = \sigma_k^2 T_{m_k}$ for $k=1,...,M$ $X\succeq 0$

where $X\succeq 0$ stands for "X semidefinite positive". If we choose an objective matrix Ω_0 , this becomes a semidefinite program:

$$\begin{array}{ll} \min & Tr\left(\Omega_0X\right) \\ \text{s.t.} & Tr(\Omega_kX) = \sigma_k^2 T_{m_k} \ \text{ for } k=1,...,M \\ & X \succeq 0 \end{array}$$

which can be solved very efficiently (see Nesterov & Nemirovskii (1994), Vandenberghe & Boyd (1996) for the theory and Sturm (1999) for a MAT-

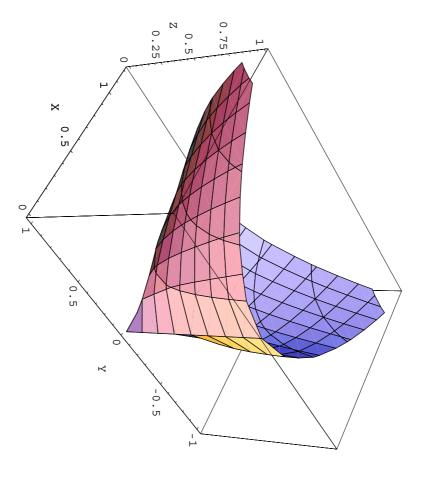


Figure 4: The semidefinite cone in dim 3: $\{\min(\text{eig}[x,y;y,z])=0\}$

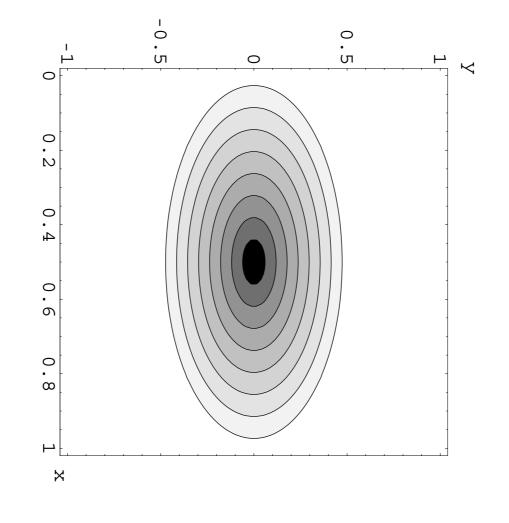


Figure 5: A typical SDP feasible set in dimension 3.

3.2 Definite advantages

- time, with a certificate of optimality or infeasibility. The calibration program has a unique solution computed in polynomial
- the inputs and objective Bid-Ask spread data, smoothness or other prices can be included in
- gives the calibrated Forward rate covariance matrix, while the dual provides local sensitivity results. The algorithms provide both primal and dual solutions. The primal

3.3 Smooth calibration

We calibrate the model to EURO Swaption prices on November 6

We use all Caplet volatilities and the following Swaptions: 2Y into 5Y, 5Y into 5Y, 5Y into 2Y, 10Y into 5Y, 7Y into 5Y, 10Y into 2Y 10Y into 7Y, 2Y into 2Y, 1Y into 9Y (data courtesy of BNP Paribas London).

number of numerical hedging transactions We add a smoothness constraint (minimum surface), this acts as a Tikhonov (1963) stabilization of the solution and reduces purely the

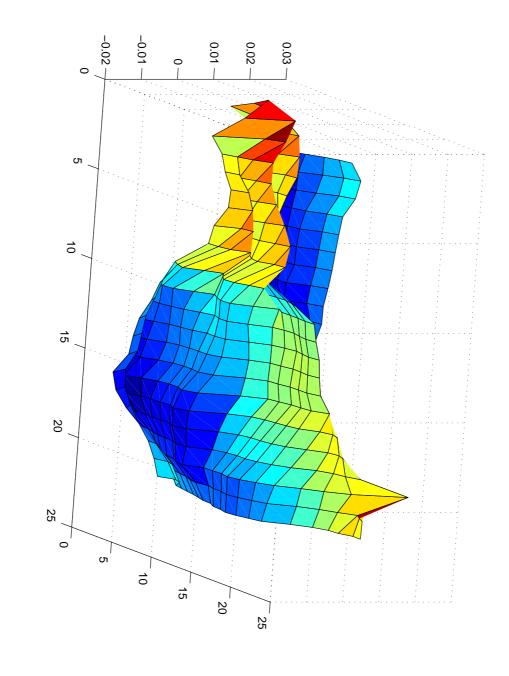


Figure 6: Forward rates covariance matrix

3.4 The dual program

When the original program is given by:

$$\begin{array}{ll} \max & Tr\left(\Omega_0 X\right) \\ \text{s.t.} & Tr(\Omega_k X) = \sigma_k^2 T_{m_k} \quad \text{for } k=1,...,M \\ X \succeq 0 \end{array}$$

the dual becomes:

$$\min \ -\sum_{k=1}^M y_k \sigma_k^2 T_{m_k}$$

s.t.
$$\Omega_0 \preceq \sum_{k=1}^M y_k \Omega_k$$

pute both solutions at the same time most S.D.P. solvers (such as SEDUMI by Sturm (1999) for example) com-

3.4.1 Local sensitivity

conditions given by u_k for k=1,...,M, the calibration program becomes: We can study the impact on the solution of a (small) change in market

maximize
$$Tr(CX)$$
 s.t. $Tr(\Omega_k X) = \sigma_k^2 T_k + u_k$ for $k=1,...,M$ $X \succeq 0$

Using Todd & Yildirim (1999) we can compute the new calibrated matrix

$$\Delta X = E^{-1} F A^* \left[\left(A E^{-1} F A^* \right)^{-1} u \right]$$

where E,F and A are linear operators computed from (X^st,y^st) the primal and dual solutions to the original calibration program (with $u_k=0$).

3.4.2 Super hedging price

in terms of hedging portfolio As expected, we can interpret the dual solution to the calibration program

- a dynamic super-replication strategy. uncertain and we hedge by mixing a static portfolio of derivatives with As in Avellaneda & Paras (1996) we suppose that the volatility is
- The price is obtained by solving the following (formal) program:

 $Price = Min \{Value of static hedge + Max(PV of residual liability)\}$

3.4.3 Super hedging portfolio

Suppose we study an upper hedging price on a particular Swaption (Ω_0, T_0) . the following problem: We can find an approximate solution to the previous problem by solving

$$\inf_{\lambda} \left\{ \sum_{k=1}^{M} \lambda_k C_k + \sup_{X \succeq 0} \left(BS(Tr(\Omega_0 X)) - \sum_{k=1}^{M} \lambda_k BS\left(Tr(\Omega_k X)\right) \right) \right\}$$

or its dual:

maximize
$$BS_0(Tr(\Omega_0X))$$
 s.t. $BS_k\left(Tr(\Omega_kX)\right) = C_k$ for $k=1,...,M$ $X\succeq 0$

We can write the KKT optimality conditions on this problem:

$$\begin{cases} Z = \frac{\partial BS_0(\Omega_0 X)}{\partial v} \Omega_0 + \sum_{k=1}^M \lambda_k \frac{\partial BS_k(\Omega_k X)}{\partial v} \Omega_k \\ XZ = 0 \\ BS_k \left(Tr(\Omega_k X) \right) = C_i \text{ for } k = 1, ..., M \\ 0 \leq X, Z \end{cases}$$

hence if y_i^* solves the dual S.D.P:

then

$$\lambda_k^* = -y_i^* \frac{\partial BS_0 \left(Tr(\Omega_0 X) \right) / \partial v}{\partial BS_k \left(Tr(\Omega_k X) \right) / \partial v}$$

will be the coefficients of a super replicating portfolio in the Swaptions (Ω_k, T_k)

Sydney Opera House Effect

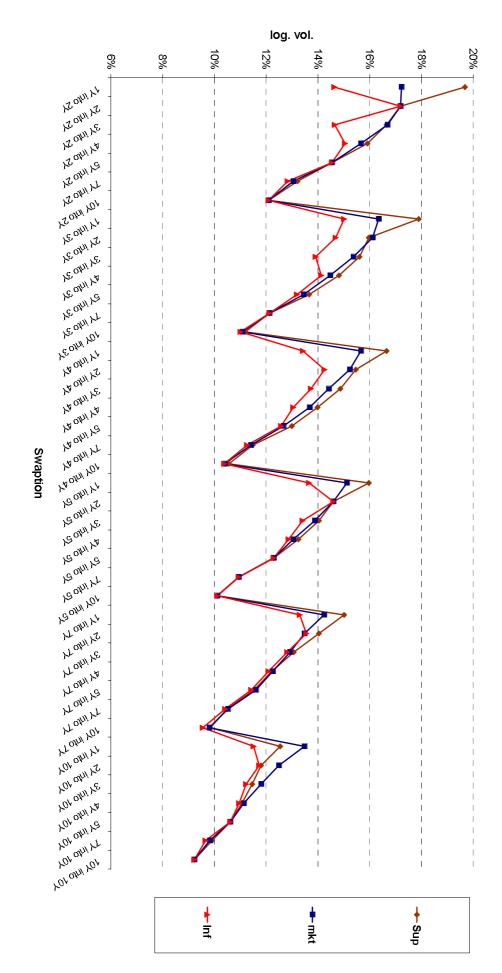


Figure 7: Upper and lower bounds for various Swaption (EUR, 11/6/2000)

3.5 Low rank solution

in Boyd, Fazel & Hindi (2000), we can use another semidefinite positive rank. But there are some excellent heuristical methods. For example, as matrix in the objective to get a low rank solution. There is no way to efficiently guarantee that the solution will be of given

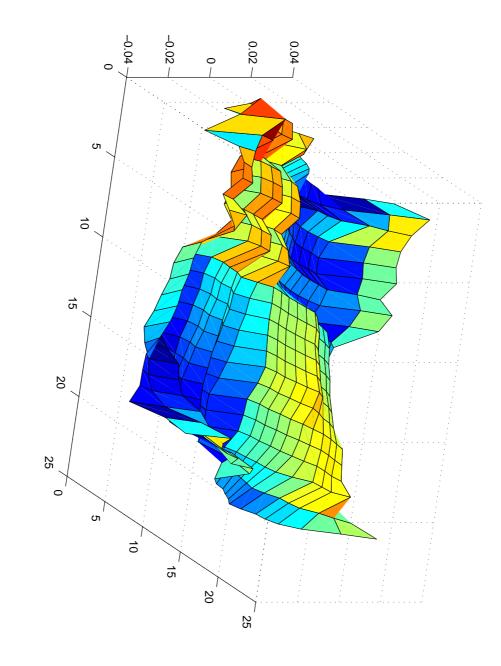


Figure 8: Low rank solution

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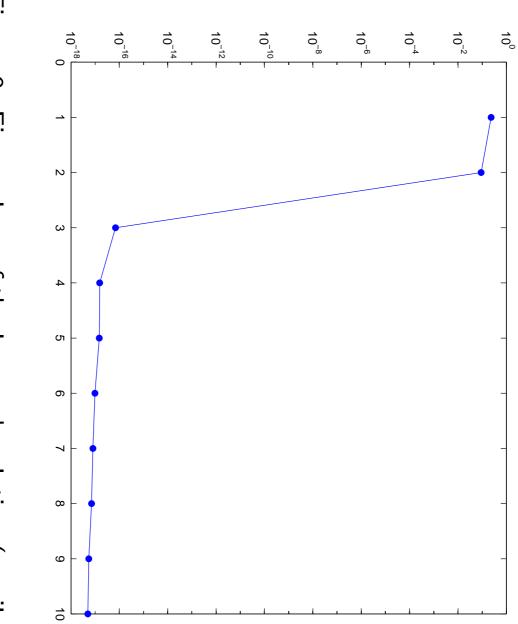


Figure 9: Eigenvalues of the low rank solution (semilog).

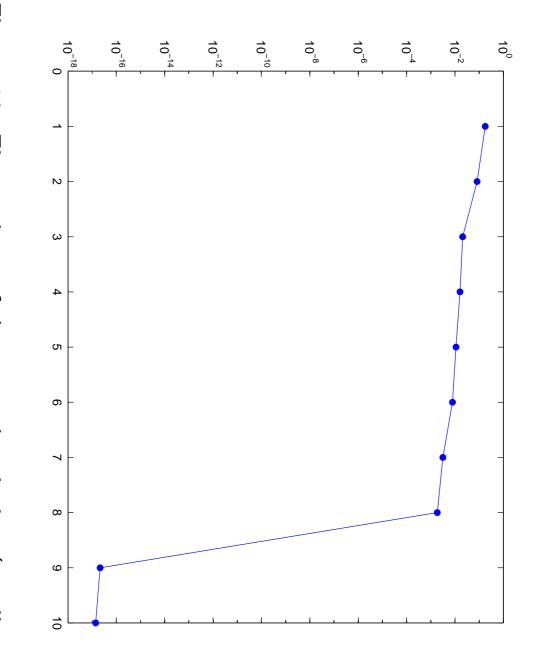


Figure 10: Eigenvalues of the smooth solution (semilog).

4 Conclusion

- Semidefinite programming provides a fast, reliable calibration method for the LMM model.
- hedging costs. The improvement in the solution's stability should reduce unnecessary
- The dual solution provides all the essential local sensitivity results.
- bility". The final trade-off in the calibration problem is "low rank" vs. "sta-

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