Sparse Coding and Dictionary Learning for Image Analysis

Part IV: New sparse models

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Sparse Structured Linear Model

• We focus on linear models

 $\mathbf{x} pprox \mathbf{D} \boldsymbol{lpha}.$

- $\mathbf{x} \in \mathbb{R}^m$, vector of *m* observations.
- $\mathbf{D} \in \mathbb{R}^{m \times p}$, dictionary or data matrix.
- $\pmb{lpha} \in \mathbb{R}^p$, loading vector.

Assumptions:

• α is sparse, i.e., it has a small support

$$|\Gamma| \ll p, \ \ \Gamma = \{j \in \{1, \ldots, p\}; \ \alpha_j \neq 0\}.$$

- The support, or nonzero pattern, Γ is structured:
 - $\bullet~\Gamma$ reflects spatial/geometrical/temporal. . . information about the data.
 - e.g., 2-D grid structure for features associated to the pixels of an image.

Sparsity-Inducing Norms (1/2)



Standard approach to enforce sparsity in learning procedures:

- Regularizing by a sparsity-inducing norm ψ .
- The effect of ψ is to set some α_j 's to zero, depending on the regularization parameter $\lambda \ge 0$.

The most popular choice for ψ :

- The ℓ_1 norm, $\|\boldsymbol{\alpha}\|_1 = \sum_{j=1}^p |\boldsymbol{\alpha}_j|$.
- For the square loss, Lasso [Tibshirani, 1996].
- However, the ℓ_1 norm encodes poor information, just cardinality!

Sparsity-Inducing Norms (2/2)

Another popular choice for ψ :

• The ℓ_1 - ℓ_2 norm,

 $\sum_{G \in \mathcal{G}} \|\alpha_G\|_2 = \sum_{G \in \mathcal{G}} \left(\sum_{j \in G} \alpha_j^2\right)^{1/2}, \text{ with } \mathcal{G} \text{ a partition of } \{1, \dots, p\}.$

- The l₁-l₂ norm sets to zero groups of non-overlapping variables (as opposed to single variables for the l₁ norm).
- For the square loss, group Lasso [Yuan and Lin, 2006, Bach, 2008a].
- However, the ℓ_1 - ℓ_2 norm encodes fixed/static prior information, requires to know in advance how to group the variables !

Questions:

- \bullet What happen if the set of groups ${\cal G}$ is not a partition anymore?
- What is the relationship between ${\cal G}$ and the sparsifying effect of $\psi?$

Structured Sparsity

[Jenatton et al., 2009]

Assumption: $\bigcup_{G \in \mathcal{G}} G = \{1, \dots, p\}.$

When penalizing by the ℓ_1 - ℓ_2 norm,

$$\sum_{G \in \mathcal{G}} \|\boldsymbol{\alpha}_{G}\|_{2} = \sum_{G \in \mathcal{G}} \big(\sum_{j \in G} \boldsymbol{\alpha}_{j}^{2}\big)^{1/2}$$

• The ℓ_1 norm induces sparsity at the group level:

- Some α_G 's are set to zero.
- Inside the groups, the ℓ_2 norm does not promote sparsity.
- Intuitively, the zero pattern of w is given by

$$\{j \in \{1, \dots, p\}; \ \alpha_j = 0\} = \bigcup_{G \in \mathcal{G}'} G$$
 for some $\mathcal{G}' \subseteq \mathcal{G}$.

This intuition is actually true and can be formalized (see [Jenatton et al., 2009]).

Examples of set of groups \mathcal{G} (1/3)

Selection of contiguous patterns on a sequence, p = 6.



- \mathcal{G} is the set of blue groups.
- Any union of blue groups set to zero leads to the selection of a contiguous pattern.

Examples of set of groups \mathcal{G} (2/3)

Selection of rectangles on a 2-D grids, p = 25.



- *G* is the set of blue/green groups (with their not displayed complements).
- Any union of blue/green groups set to zero leads to the selection of a rectangle.

Examples of set of groups \mathcal{G} (3/3)

Selection of diamond-shaped patterns on a 2-D grids, p = 25.



• It is possible to extent such settings to 3-D space, or more complex topologies.

Relationship bewteen G and Zero Patterns (1/2) [Jenatton et al., 2009]

To sum up, given \mathcal{G} , the variables set to zero by ψ belong to

$$\big\{\bigcup_{G\in\mathcal{G}'}G;\ \mathcal{G}'\subseteq\mathcal{G}\big\},\ \text{i.e., are a union of elements of }\mathcal{G}.$$

In particular, the set of nonzero patterns allowed by ψ is closed under intersection.

Relationship bewteen G and Zero Patterns (2/2) [Jenatton et al., 2009]

$\mathcal{G} \rightarrow \textbf{Zero patterns}:$

 We have seen how we can go from G to the zero patterns induced by ψ (i.e., by generating the union-closure of G).

Zero patterns $\rightarrow \mathcal{G}$:

• Conversely, it is possible to go from a desired set of zero patterns to the **minimal** set of groups \mathcal{G} generating these zero patterns.

The latter property is central to our structured sparsity: we can design norms, in form of allowed zero patterns.

Overview of other work on structured sparsity

- Specific hierarchical structure [Zhao et al., 2008, Bach, 2008b].
- Union-closed (as opposed to intersection-closed) family of nonzero patterns [Baraniuk et al., 2008, Jacob et al., 2009].
- Nonconvex penalties based on information-theoretic criteria with greedy optimization [Huang et al., 2009].
- Structure expressed through a Bayesian prior, e.g., [He and Carin, 2009].

Topographic Dictionaries

"Topographic" dictionaries [Hyvarinen and Hoyer, 2001, Kavukcuoglu et al., 2009] are a specific case of dictionaries learned with a structured sparsity regularization for α .



Figure: Image obtained from [Kavukcuoglu et al., 2009]

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Dictionary Learning vs Sparse Structured PCA

• Dictionary Learning with structured sparsity for α :

$$\min_{\substack{\boldsymbol{\alpha} \in \mathbb{R}^{p \times n} \\ \mathbf{D} \in \mathbb{R}^{m \times p}}} \sum_{i=1}^{n} \frac{1}{2} \|\mathbf{x}_i - \mathbf{D}\boldsymbol{\alpha}_i\|_2^2 + \lambda \psi(\boldsymbol{\alpha}_i) \text{ s.t. } \forall j, \|\mathbf{d}_j\|_2 \leq 1.$$

• Let us transpose: Sparse Structured PCA (sparse and structured dictionary elements):

$$\min_{\substack{\boldsymbol{\alpha} \in \mathbb{R}^{p \times n} \\ \mathbf{D} \in \mathbb{R}^{m \times p}}} \sum_{i=1}^{n} \frac{1}{2} \|\mathbf{x}_{i} - \mathbf{D}\boldsymbol{\alpha}_{i}\|_{2}^{2} + \lambda \sum_{j=1}^{p} \psi(\mathbf{d}_{j}) \text{ s.t. } \forall i, \|\boldsymbol{\alpha}_{i}\|_{2} \leq 1.$$

We are interested in learning **sparse and structured** dictionary elements:

$$\min_{\substack{\boldsymbol{\alpha} \in \mathbb{R}^{p \times n} \\ \mathbf{D} \in \mathbb{R}^{m \times p}}} \sum_{i=1}^{n} \frac{1}{2} \|\mathbf{x}_{i} - \mathbf{D}\boldsymbol{\alpha}_{i}\|_{2}^{2} + \lambda \sum_{j=1}^{p} \psi(\mathbf{d}_{j}) \text{ s.t. } \forall i, \|\boldsymbol{\alpha}_{i}\|_{2} \leq 1.$$

- The columns of lpha are kept bounded to avoid degenerated solutions.
- The structure of the dictionary elements is determined by the choice of G (and ψ).

Some results (1/2)



- Application on the AR Face Database [Martinez and Kak, 2001].
- r = 36 dictionary elements.
- Left, NMF Right, our approach.
- We enforce the selection of **convex** nonzero patterns.

Some results (2/2)



- Study the dynamics of protein complexes [Laine et al., 2009].
- Find small **convex** regions in the complex that summerize the dynamics of the whole complex.
- \mathcal{G} represents the 3-D structure of the problem.

Conclusion

- We have shown how sparsity-inducing norms can encode structure.
- The structure prior is expressed in terms of allowed patterns by the regularization norm ψ .

Future directions:

- Can be used in many learning tasks, as soon as structure information about the sparse decomposition is known.
- e.g., multi-taks learning or multiple-kernel learning.

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