



Seeing 3D chairs:

**Exemplar part-based 2D-3D alignment
using a large dataset of CAD models**

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Sit on the chair!

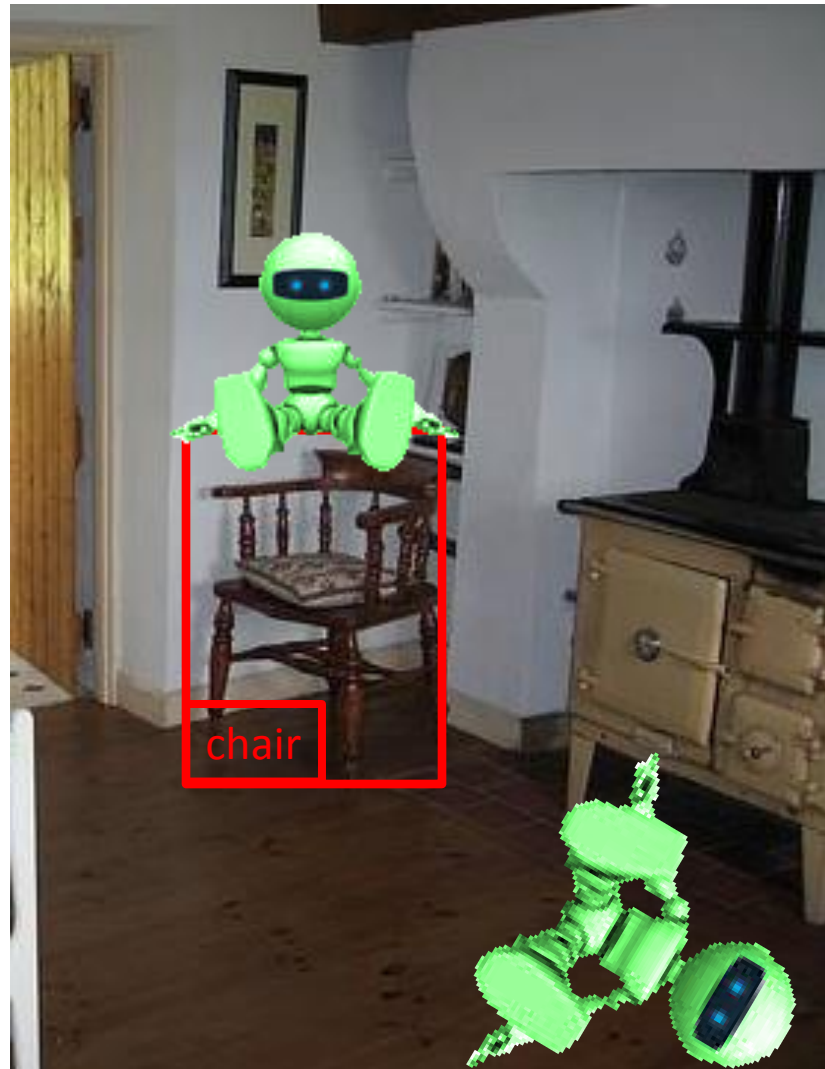


Classification



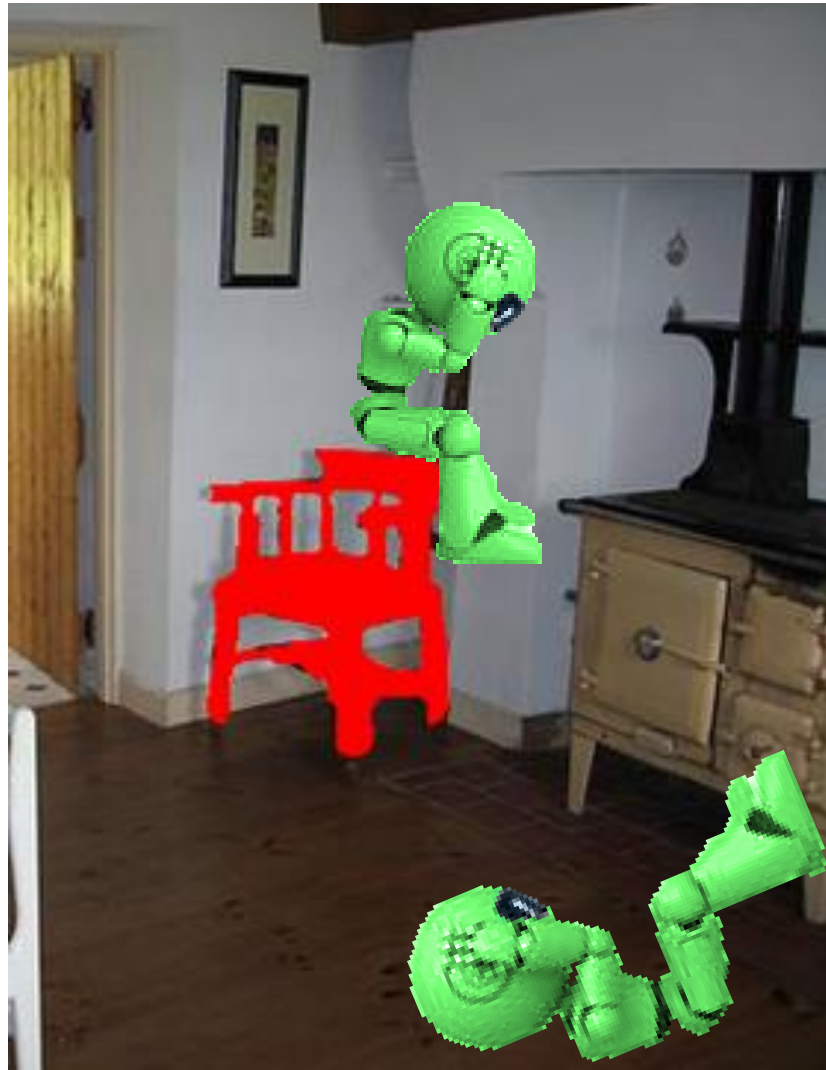
Ex: ImageNet Challenge, Pascal VOC classification.

Detection



Ex: Pascal VOC detection.

Segmentation



Ex: Pascal VOC segmentation.

Our goal

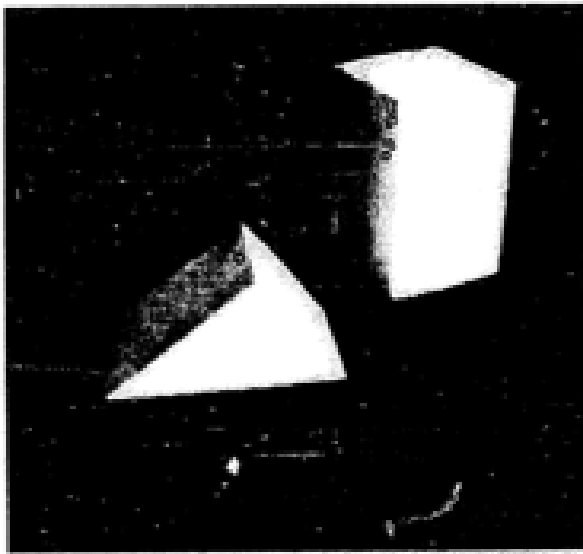


From the beginning of computer vision

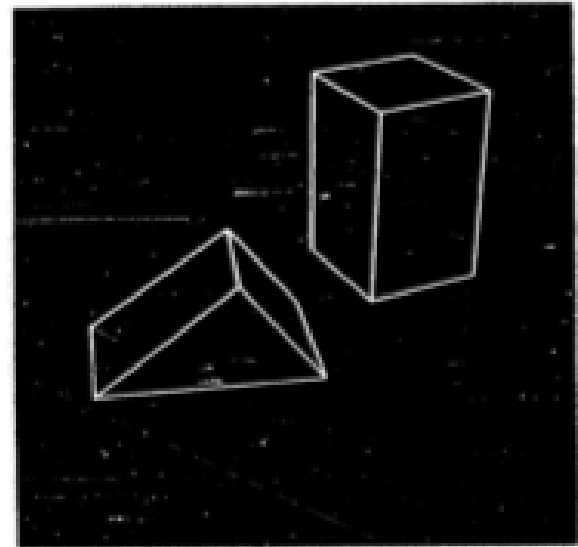
First PhD in computer vision, MIT 1963

Lawrence G. Roberts

Machine perception of three-dimensional solids

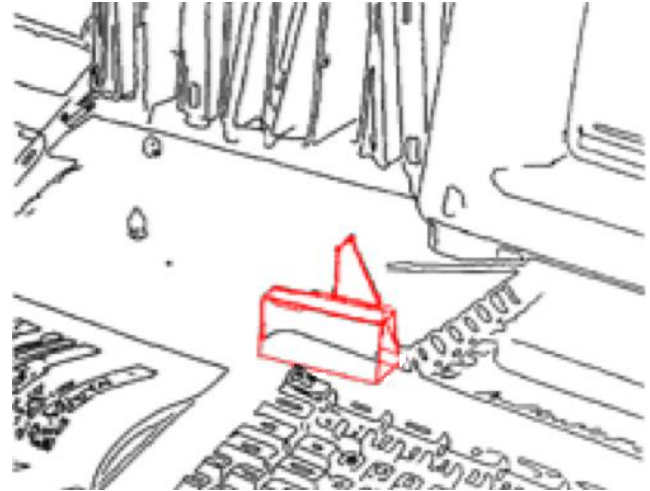


Photograph

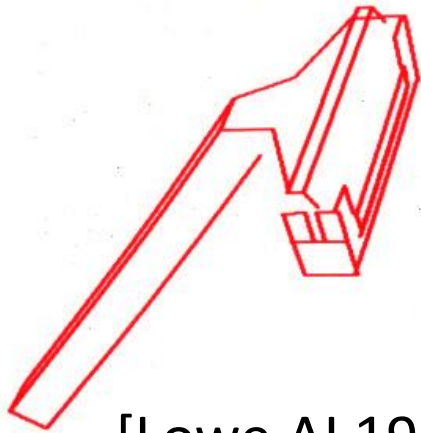


3D model

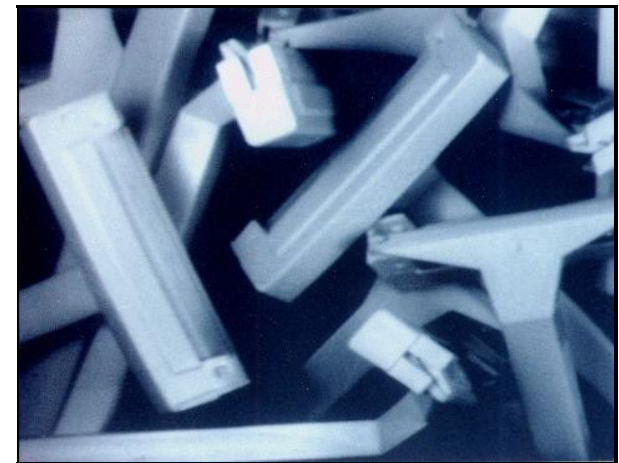
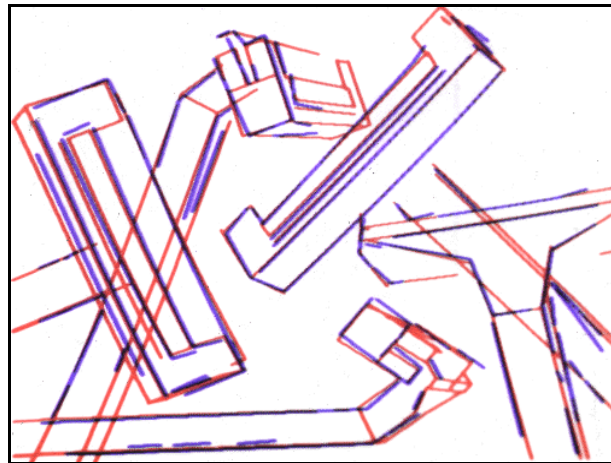
1980s: 2D-3D Alignment



[Huttenlocher and Ullman IJCV 1990]

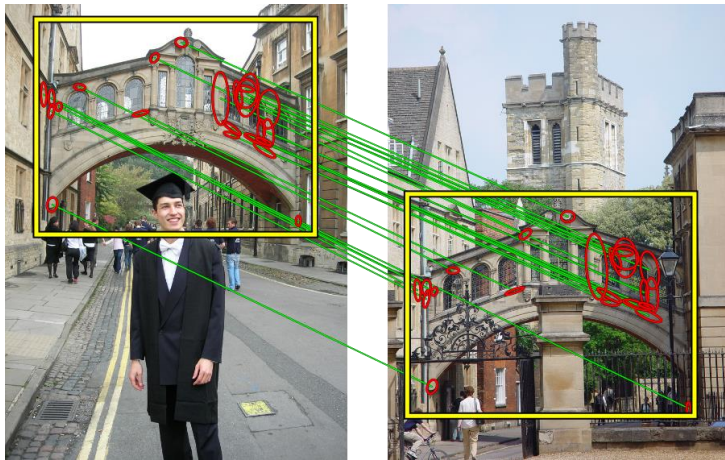


[Lowe AI 1987]



[Faugeras&Hebert'86], [Grimson&Lozano-Perez'86], ...

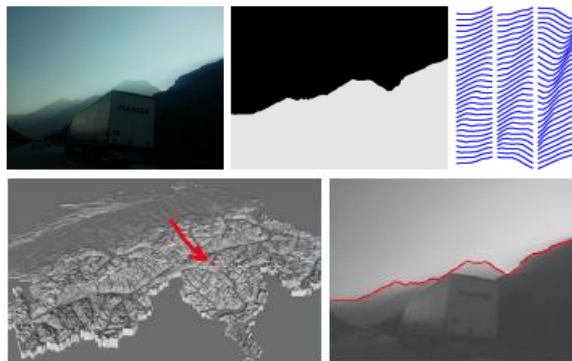
Exact Instance alignment



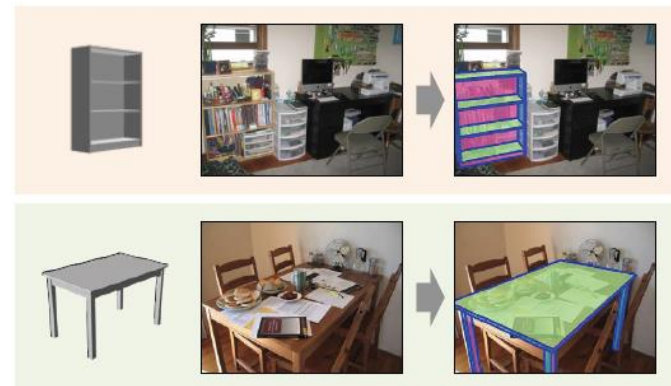
[Philbin et al. CVPR 2007]



[Sattler et al. ICCV 2011]



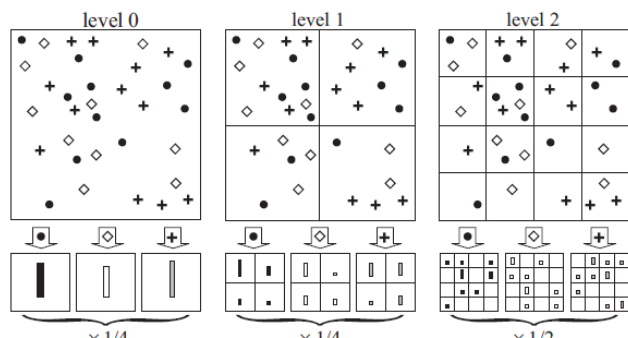
[Baatz et al. ECCV 2012]



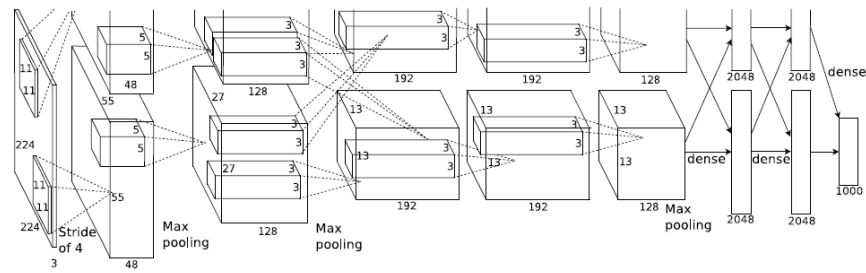
[Lim et al. ICCV 2013]

See also [Rothganger et al. CVPR 2003] ,[Arandjelović and Zisserman ICCV 2011],
[Li et al. ECCV 2012], [Snavely et al. SIGGRAPH 2006] ...

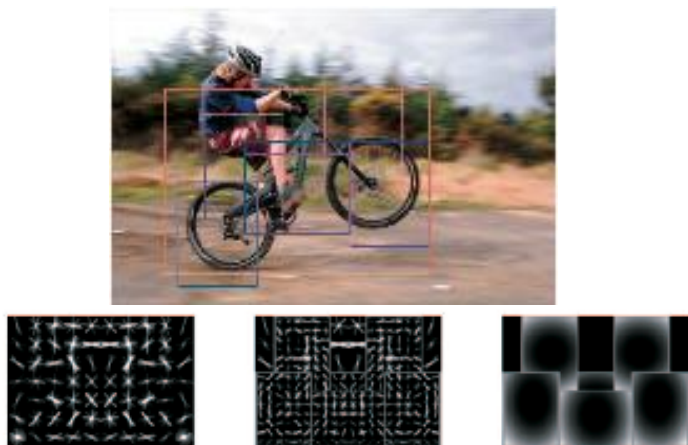
2D category recognition



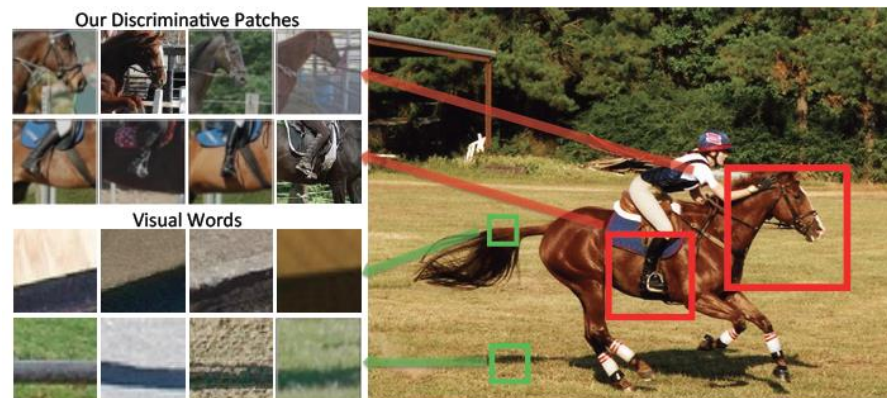
[Lazebnik et al. CVPR 2006]



[Krizhevsky et al. NIPS 2012]



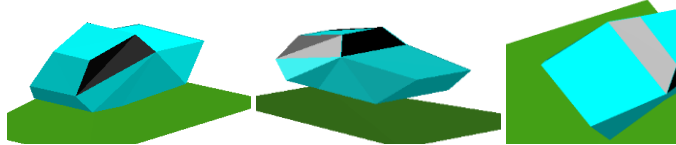
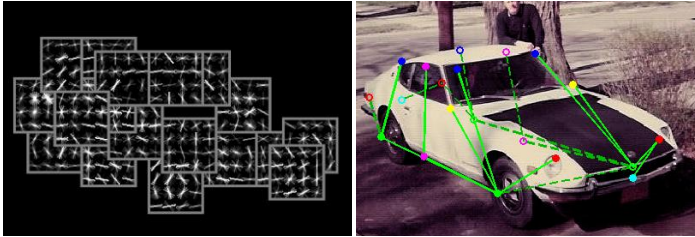
[Felzenszwalb et al. PAMI 2010]



[Singh et al. ECCV 2012]

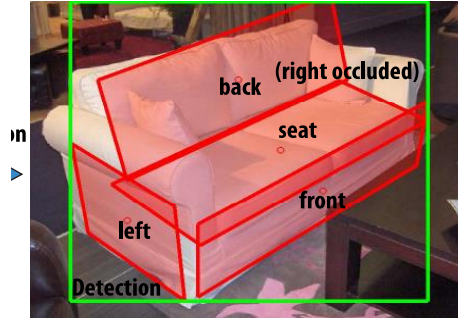
See also : [Dalal and Triggs CVPR 2005], [Bourdev and Malik ICCV 2009], [Malisiewicz et al. ICCV 2011] ...

3D category recognition

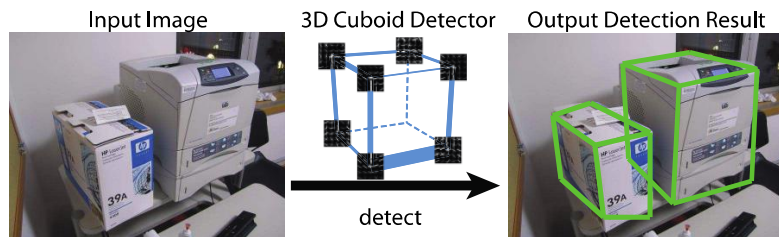


3D DPMs: [Herjati&Ramanan'12], [Pepik et al.12], [Zia et al.'13], ...

Viewpoint: Azimuth 315°, Elevation 30°, Distance 2



Simplified part models: [Xiang&Savarese'12], [Del Pero et al.'13]



Cuboids: [Xiao et al.'12] [Fidler et al.'12]



Blocks world revisited: [Gupta et al.'12]

See also: [Glasner et al.'11], [Fouhey et al.'13], [Satin&Hebert'13], [Choi et al. '13], [Hejrati and Ramanan '14], [Savarese and Fei-Fei '07]...

Why chairs?



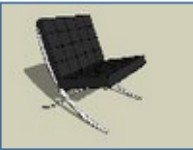
Difficulty: style



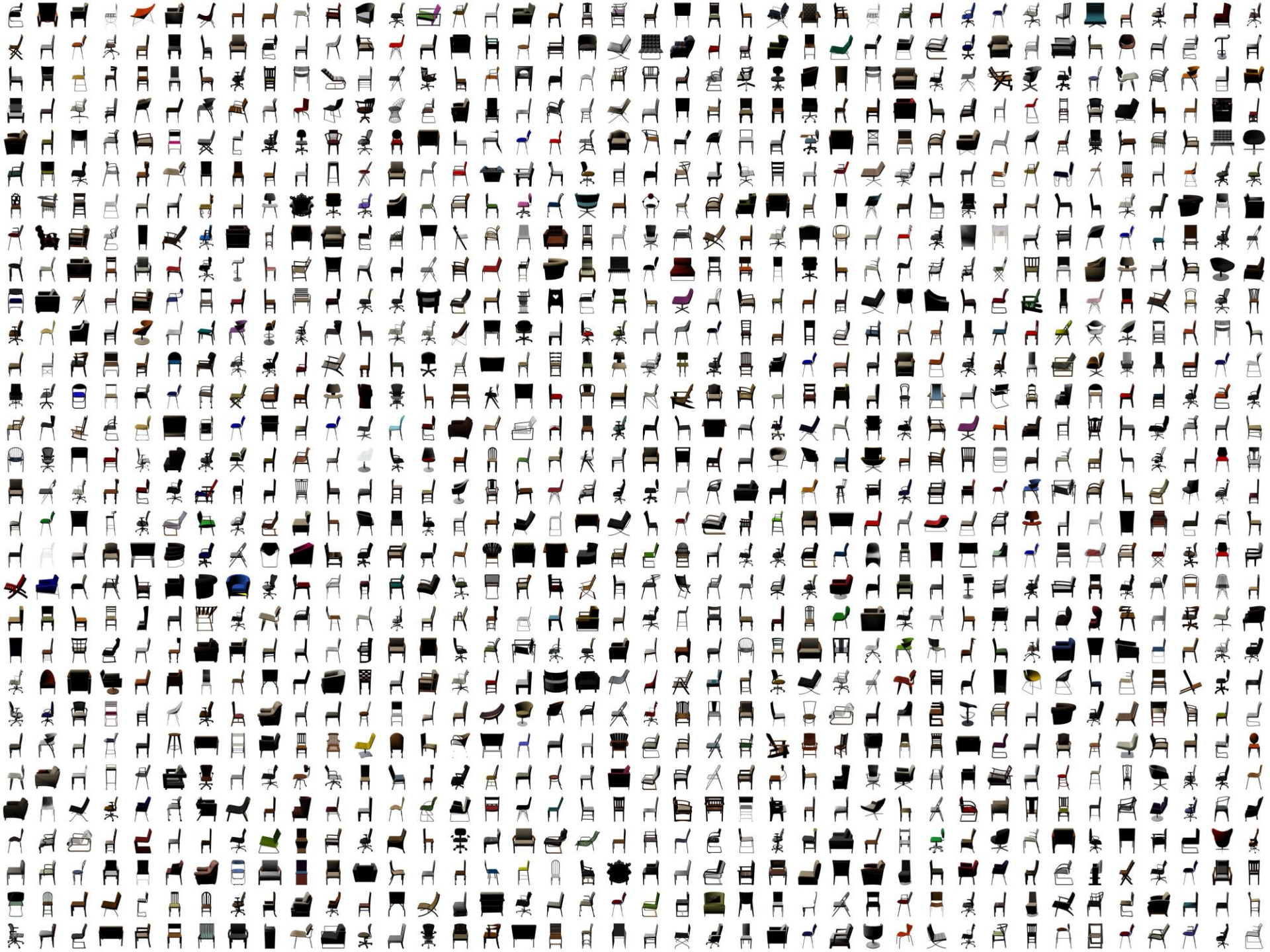
Approach: data-driven

Trimble 3D Warehouse Models ▾ Search [Advanced Search](#)
powered by **Google**

3D Warehouse Results Sorted by relevance ▾

 ★★★★★	Chair - Barcelona Chair by Adam Barcelona Chair 1929 Ludwig... Download to SketchUp 5	 ★★★★★	Eames Lounge Chair by Mart Lounge Chair and Ottoman by... Download to SketchUp 6	 ★★★★★	LC-2 (Chair) by Archi Maniac One of the most famous modern... Download to SketchUp 5
 ★★★★★	Barcelona Chair by acad whiz EDITED: Added the support... History Download to SketchUp 6	 ★★★★★	Egg Chair by Mart Egg Chair by Arne Jacobsen... Download to SketchUp 6	 ★★★★★	Eames Lounge Chair & Ottoman... by SmartFurniture.com The Eames Lounge Chair and... History Download to SketchUp 8
 ★★★★★	chair silla by ketchup silla classica——classic... Download to SketchUp 6	 ★★★★★	BKF Chair and the BKF 2000 by ArqDirk The BKF 2000 chair or bench... Download to SketchUp 6	 ★★★★★	Wassily Chair, Model B3 chair by Darrell Smith Deducing Moon's import Stuhl... Download to SketchUp 6

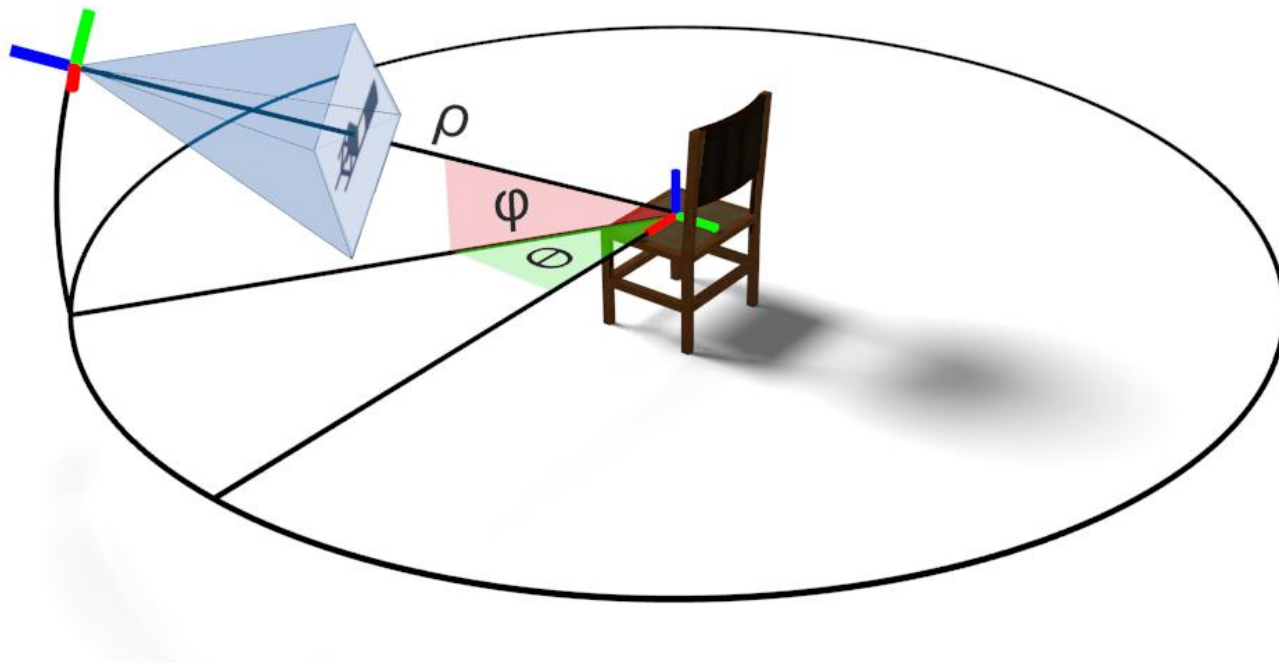
1394 3D models from internet



Difficulty: viewpoint



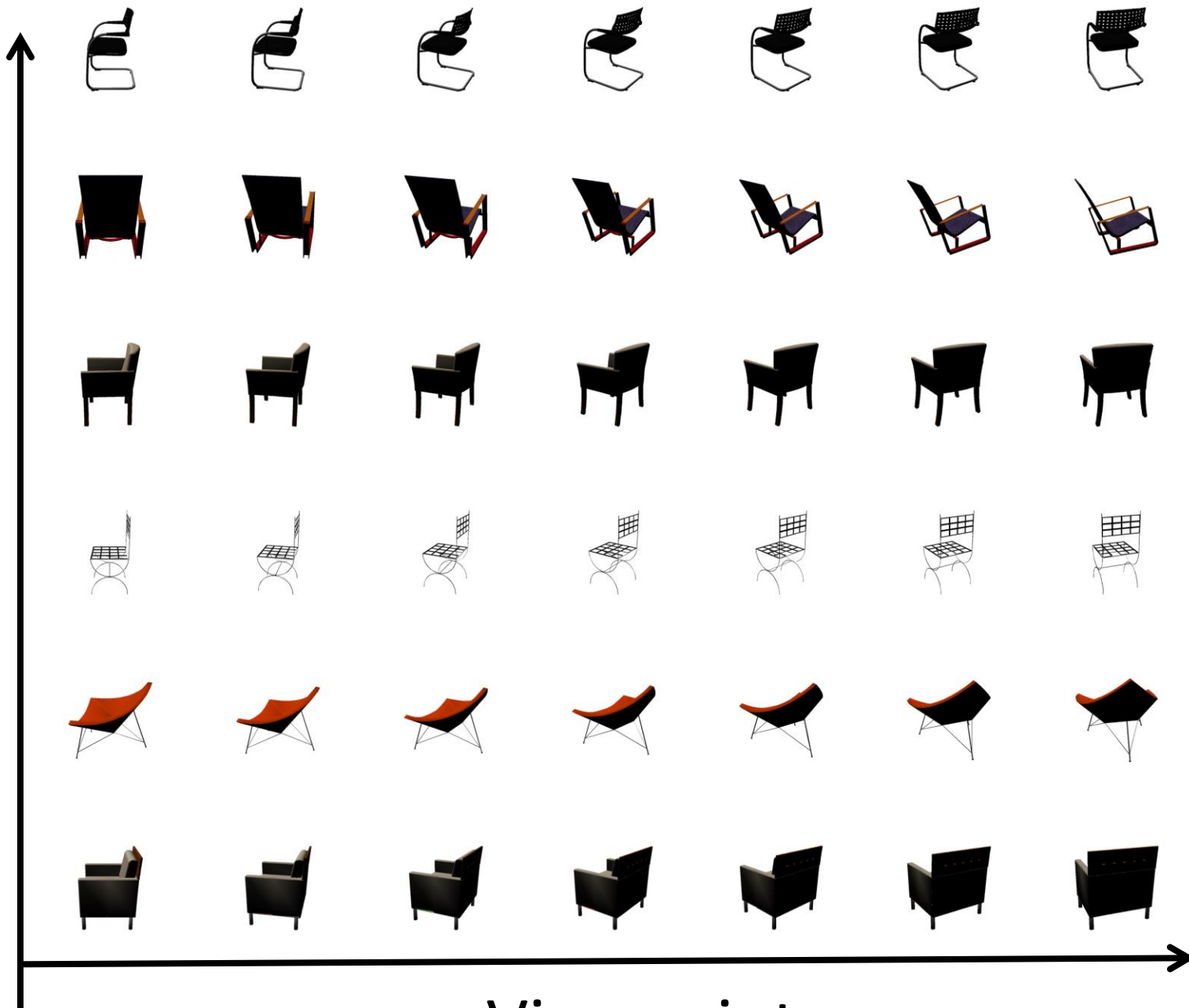
Approach: use 3D models



62 views



Style



Viewpoint

Difficulty: approximate style



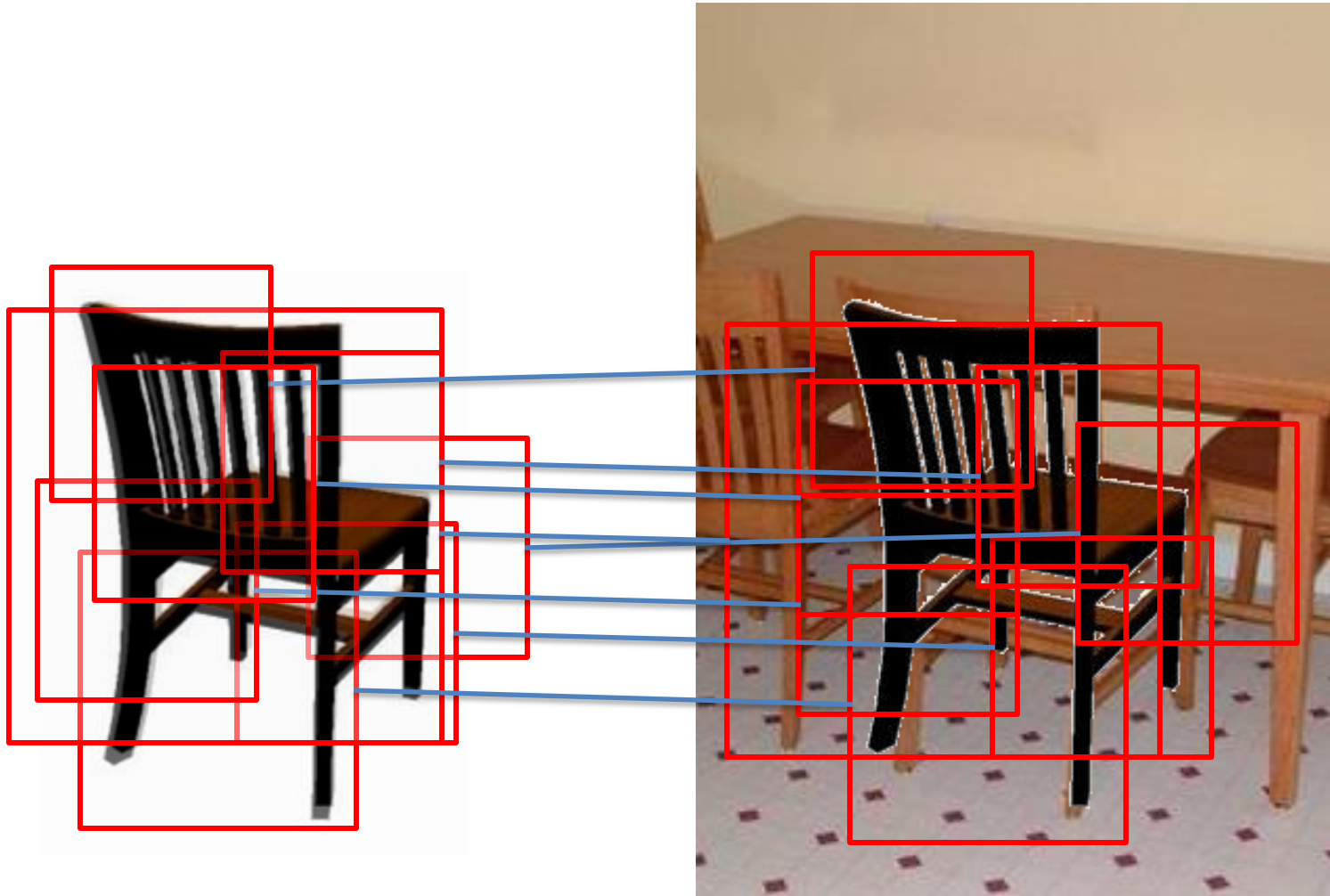
Difficulty: approximate style



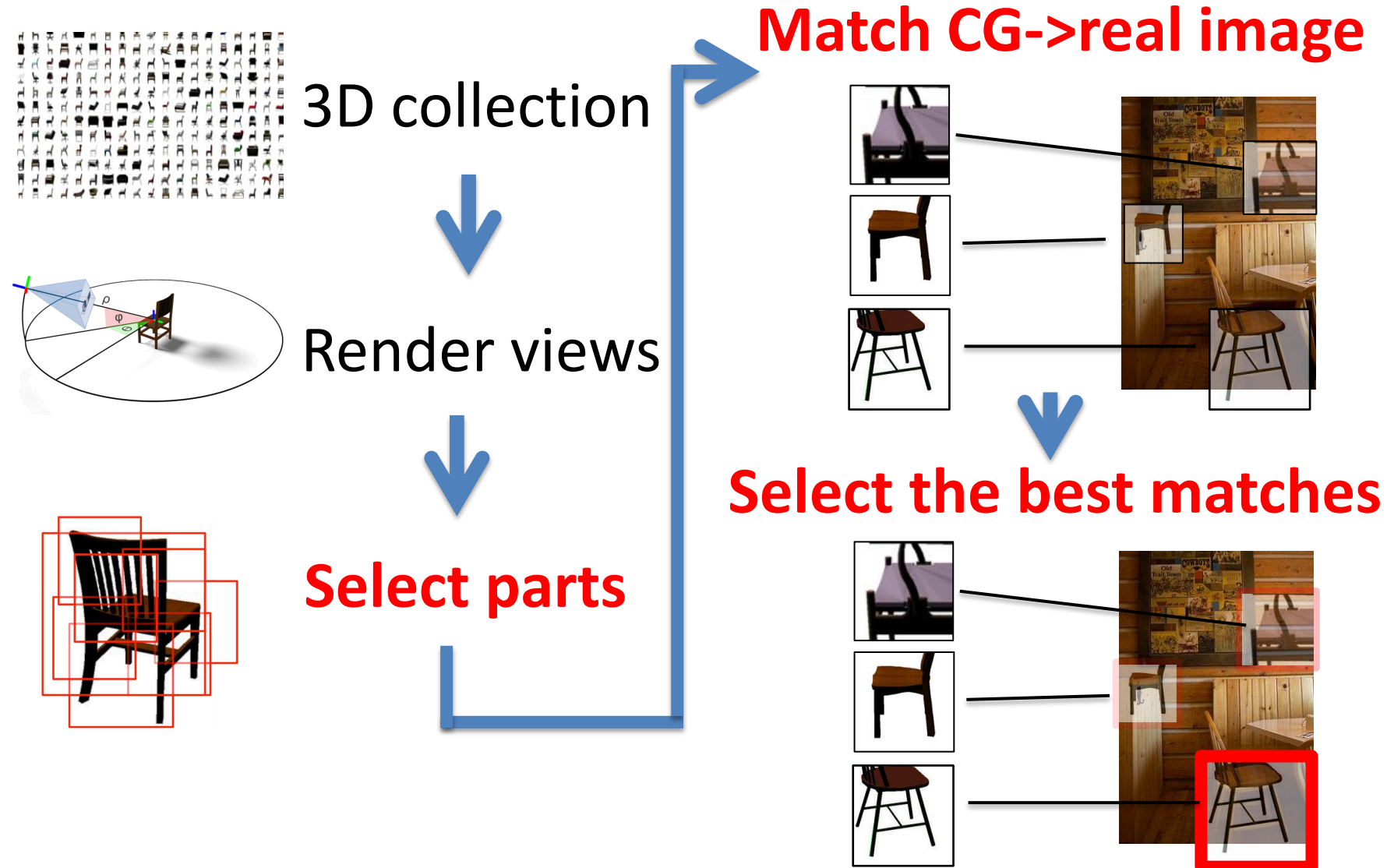
Difficulty: approximate style



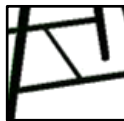
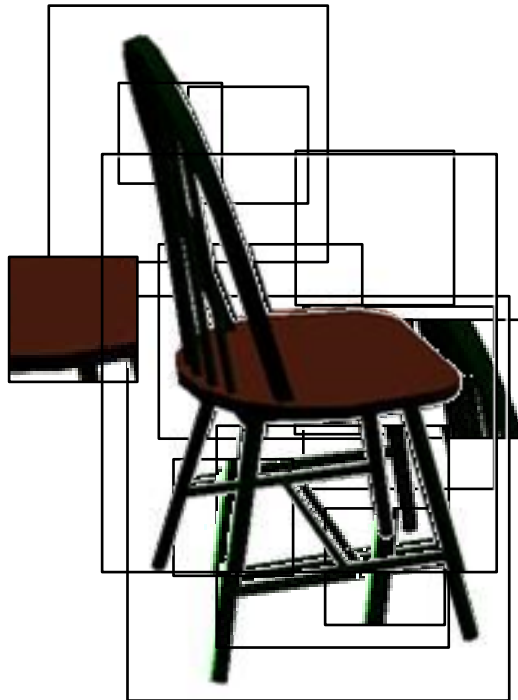
Approach: part-based model



Approach overview

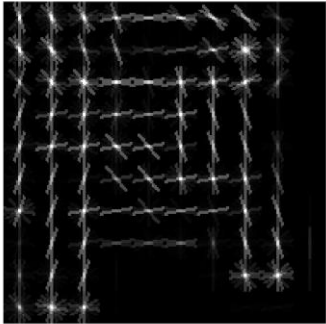


How to select discriminative parts?

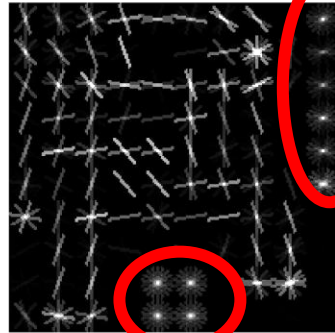


How to match CG to photograph?

HOG



Classifier



Masked classifier



HOG mask



$$w^T x + b$$



Implementation: exemplar-LDA

See also:
[Shrivastava et al. 2011]

Approach: CG-to-photograph



Implementation: exemplar-LDA

How to compare matches?

Patches



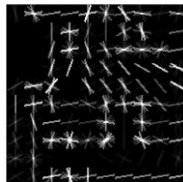
Detectors



(w_1, b_1)



(w_2, b_2)



(w_3, b_3)

Matches



How to compare matches?

Patches



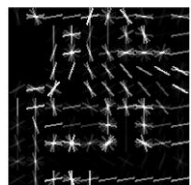
Detectors



$$(w_1, b_1)$$



$$(w_2, b_2)$$



$$(w_3, b_3)$$

Affine Calibration
with negative data



$$(\underline{a_1 w_1}, \underline{b'_1})$$

$$(\underline{a_2 w_2}, \underline{b'_2})$$

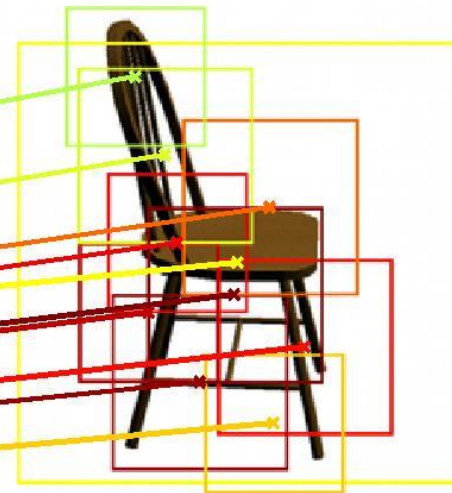
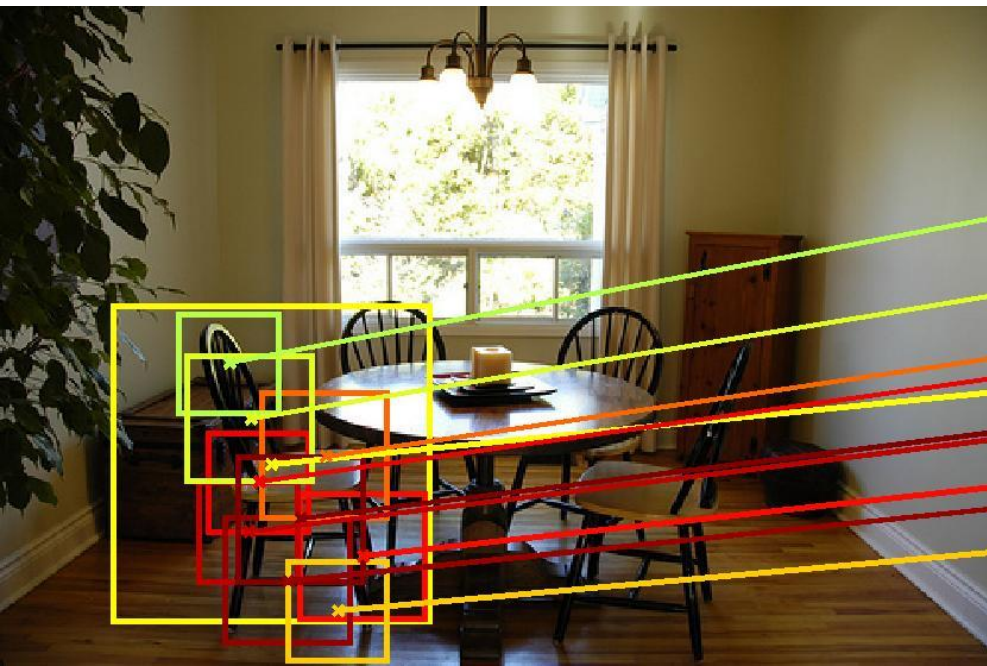
$$(\underline{a_3 w_3}, \underline{b'_3})$$

See paper for details

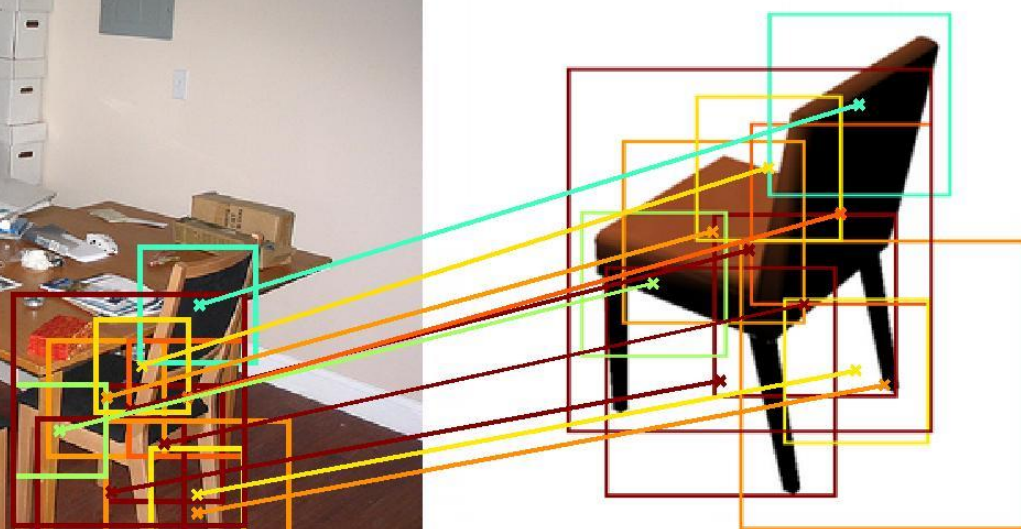
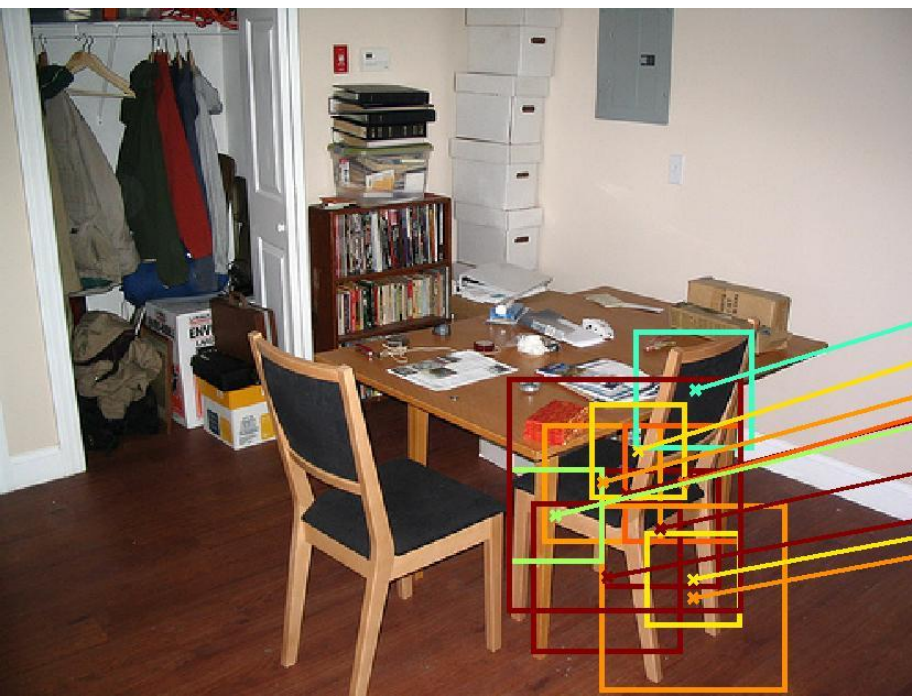
Matches



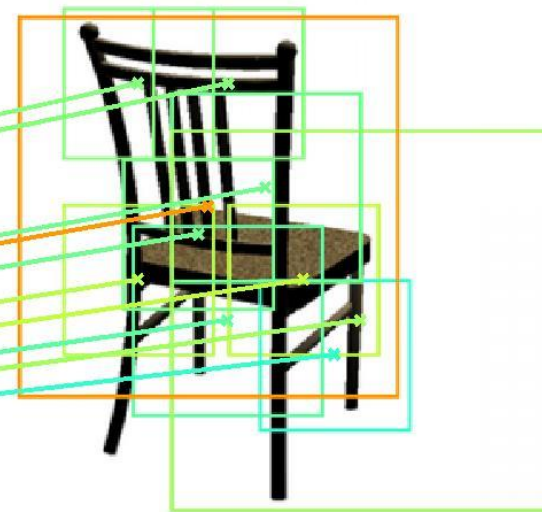
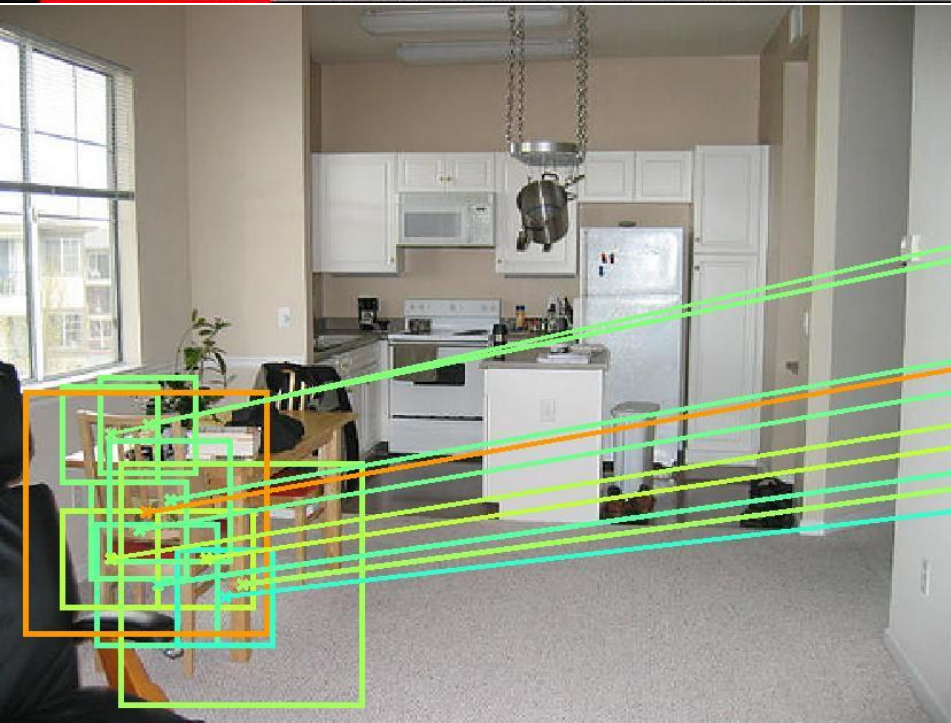
Example I.



Example II.



Example III.





Input image



DPM output



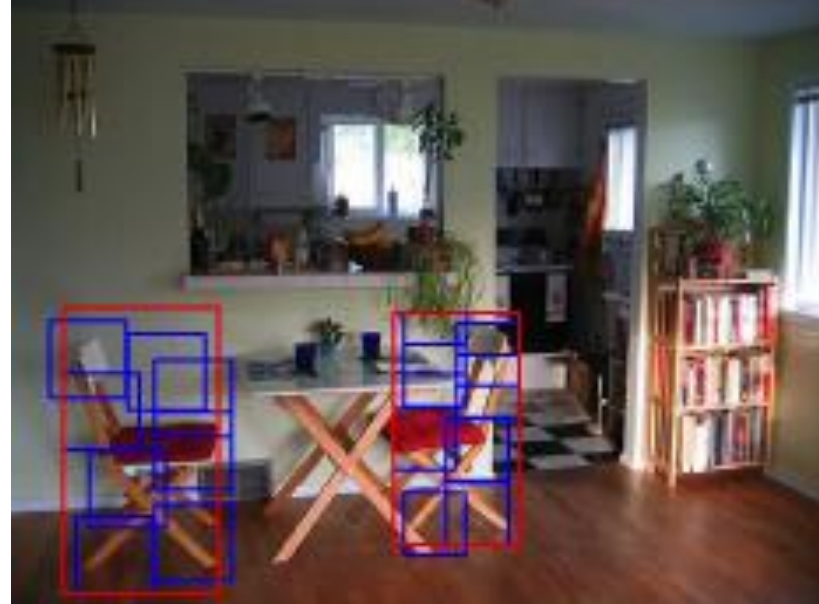
Our output



3D models



Input image



DPM output



Our output



3D models

Results

Test set:

- 179 images from Pascal VOC 2012 (subset of validation data)
- 247 annotated chair bounding boxes

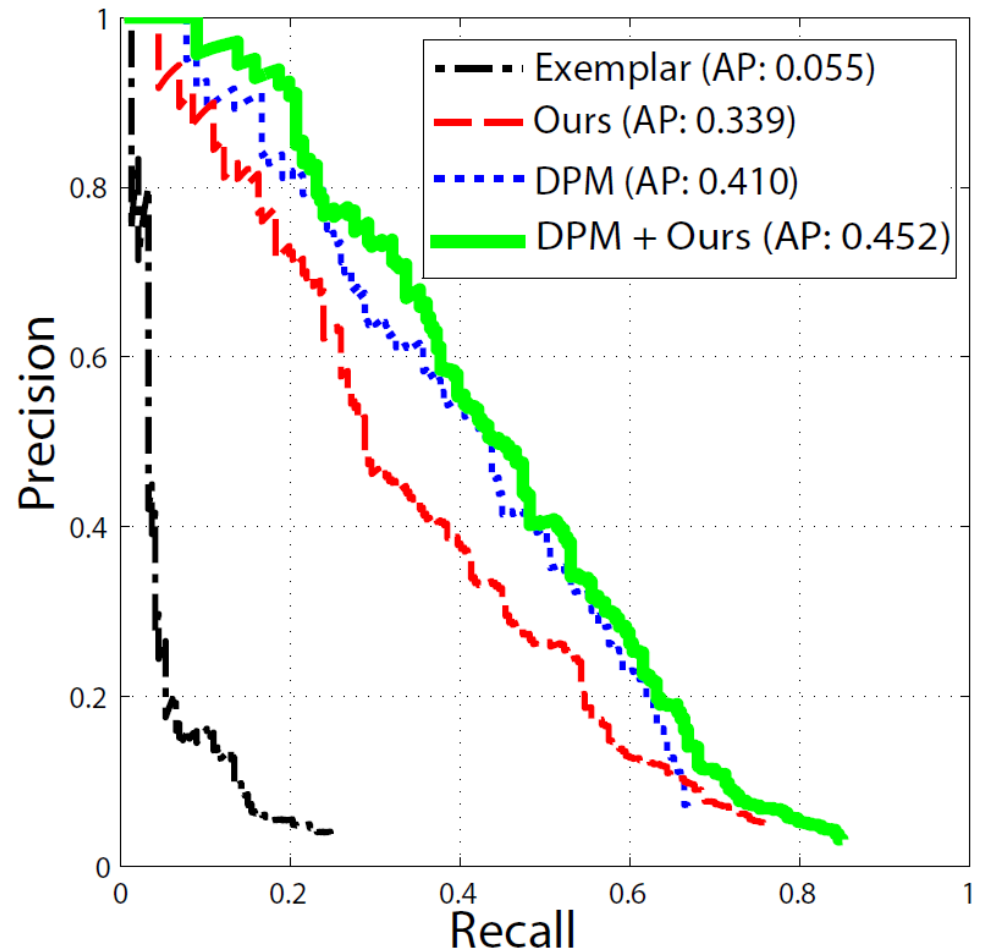
Baselines:

1. Exemplar LDA:

[Hariharan et al. 2012],
[Gharbi et al 2012],
[Malisiewicz et al 2011]

2. DPM:

[Felzenszwalb et al. 2010]



Subjective human evaluation

Orientation quality at 25% recall



	Good	Bad
Exemplar-LDA	52%	48%
Ours	90%	10%

Subjective human evaluation

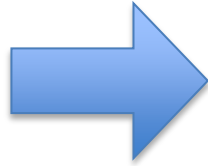
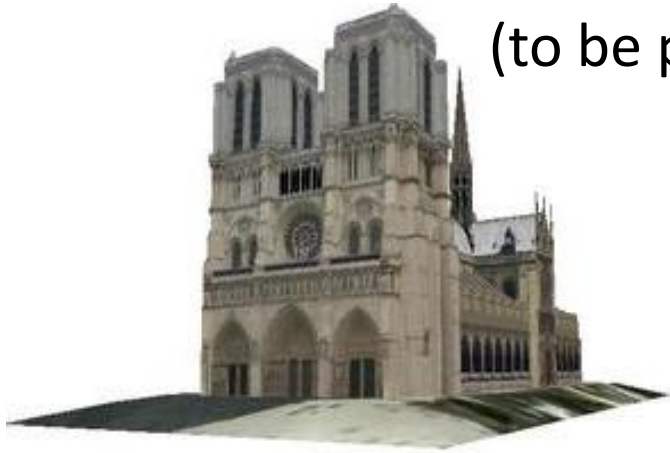
Style consistency at 25% recall



	Exact	Ok	Bad
Exemplar-LDA	3%	31%	66%
Ours	21%	64%	15%

Our related ToG 2014 paper

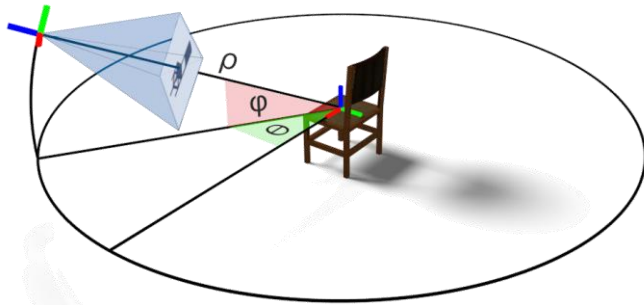
(to be presented at SIGGRAPH 14)



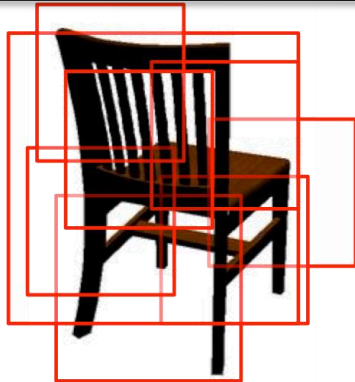
Painting-to-3D Model Alignment Via Discriminative Visual Elements
M. Aubry, B. Russell and J. Sivic

Summary

- Large collection of 3D models
 - ✓ Part score calibration



- Render views from 3D
 - ✓ CG-real matching



- Part based matching
 - ✓ Finding parts

