Discriminative Clustering for Image Co-segmentation

Armand Joulin Francis Bach Jean Ponce

INRIA Ecole Normale Supérieure, Paris

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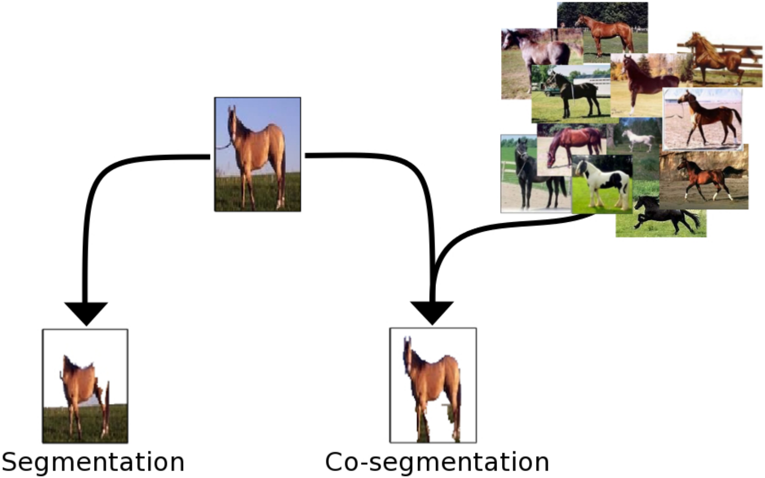
Introduction

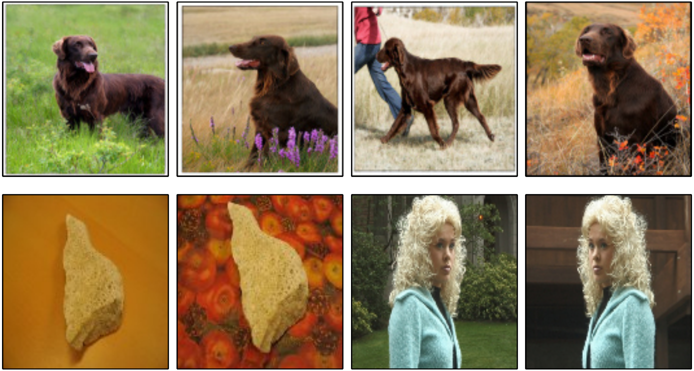


Introduction

- **Task**: dividing simultaneously q images in k different segments
  - When $k = 2$, this reduces to dividing images into foreground and background regions.
- Our approach considers simultaneously the object recognition and the segmentation problems
  - **Semi-supervised discriminative clustering**
- Well-adapted to segmentation problems for 2 reasons :
  - Re-use existing features for supervised classification
  - Introduce spatial and local color-consistency constraints.

Prior work

- Rother et al. (2006), Hochbaum and Singh (2009)
- Identical or similar objects



- **Goal**: objects are different instances from same object class

Problem Notations

- Input: q images.
  - Each image i is reduced to a subsampled grid of n_i pixels
- For the j-th pixel (among the $\sum_{i=1}^{q} n_i$ pixels), we denote by :
  - $c^j \in \mathbb{R}^3$ its color,
  - $p^j \in \mathbb{R}^2$ its position within the corresponding image,
  - x^j an additional k-dimensional feature vector.

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   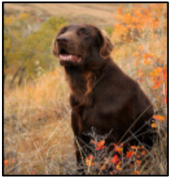

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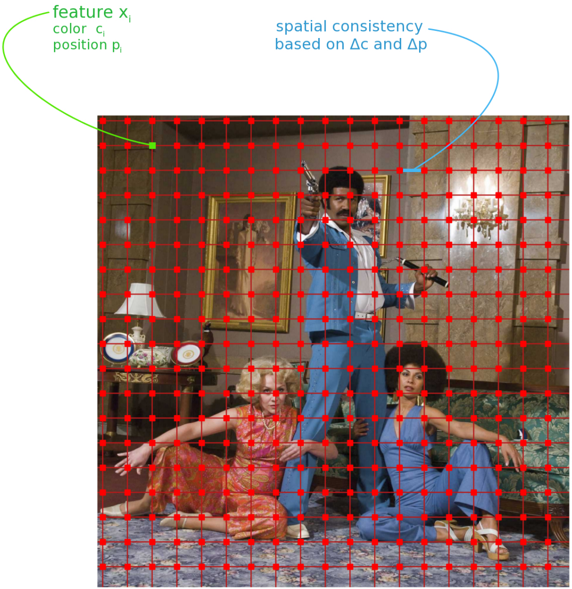
  - $p^j \in \mathbb{R}^2$ its position within the corresponding image,
  - x^j an additional k-dimensional feature vector.
- **Goal**: find y = vector of size $\sum_{i=1}^{q} n_i$ such that
  - $y_j = 1$ if the i-th pixel is in the foreground
  - -1 otherwise.

Problem Notations



Local consistency and discriminative clustering

- Co-segmenting images relies on two tasks :
  1. Within an image: maximize local spatial and appearance consistency **(normalized cuts)**
  2. Over all images: maximize the separability of two classes between different images **(semi-supervised SVMs)**

Local consistency through Laplacian matrices

(Shi and Malik, 2000)

- Spatial consistency *within* an image i is enforced through a similarity matrix W^i
  - W^i is based on color features (c^j) and spatial position (p^j)
  - Similarity between two pixels l and m within an image i:

$$W^i_{lm} = \exp(-\lambda_p \|p^m - p^l\|^2 - \lambda_c \|c^m - c^l\|^2), \qquad (1)$$

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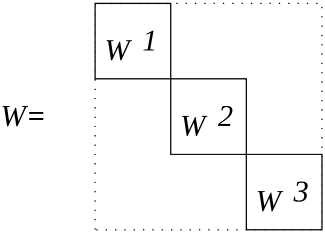
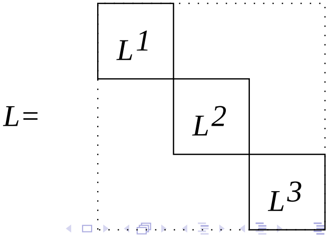
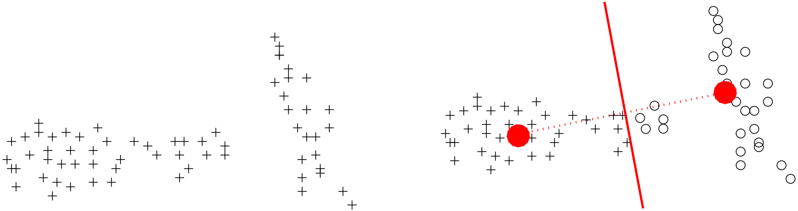
- Concatenate all similarity matrices into a block-diagonal matrix W (with W_i on its diagonal)
- Normalized Laplacian matrix $L = I_n - D^{-1/2} W D^{-1/2}$





Discriminative clustering

- Generative clustering (e.g., K-means)



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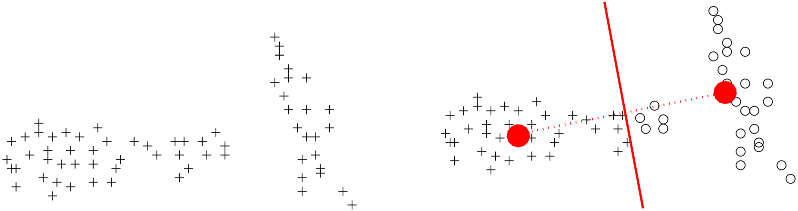
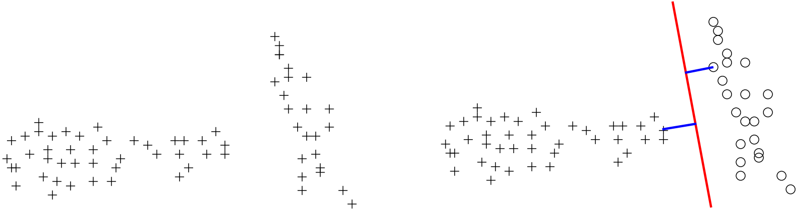


- Discriminative clustering (Xu et al., 2002, Bach and Harchaoui, 2007)



Discriminative clustering

- Discriminative clustering framework based on positive definite kernels
- Histograms of features ⇒ kernel matrix K based on the χ^2-distance:

$$K_{lm} = \exp\left(- \lambda_h \sum_{d=1}^{k} \frac{(x_d^l - x_d^m)^2}{x_d^l + x_d^m} \right), \qquad (2)$$

- Equivalent to mapping each of our n k-dimensional vectors x^j, $j = 1, \dots, n$ into a high-dimensional Hilbert space $\mathcal{F}$ through a feature map Φ, so that $K_{ml} = \Phi(x^m)^T \Phi(x^l)$

Discriminative clustering

- Minimize with respect to both the predictor f and the labels y (Xu et al., 2002):

$$\frac{1}{n}\sum_{j=1}^{n}\ell(y_j, f^T\Phi(x^j)) + \lambda_k\|f\|^2, \tag{3}$$

where ℓ is a loss function.

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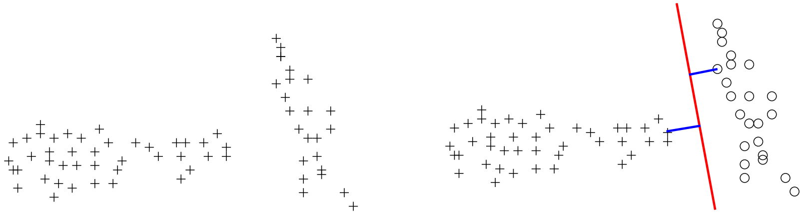
  where ℓ is a loss function.
- Square loss function ($\ell(a,b) = (a-b)^2$), solution in closed form (Bach and Harchaoui, 2007)

$$g(y) = \min_f \frac{1}{n}\sum_{j=1}^{n}\ell(y_j, f^T\Phi(x^j)) + \lambda_k\|f\|^2 = \mathrm{tr}(Ayy^T)$$

  where $A = \lambda_k(I_n - \frac{1}{n}1_n1_n^T)(n\lambda_k I_n + K)^{-1}(I_n - \frac{1}{n}1_n1_n^T)$.
- **Linear in $Y = yy^\top \in \mathbb{R}^{n\times n}$**

Cluster size constraints



- Putting all pixels into a single class leads to perfect separation
  - Constrain the number of elements in each class (Xu et al., 2002)

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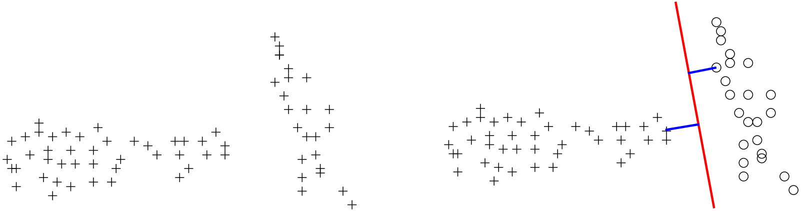

- Putting all pixels into a single class leads to perfect separation
  - Constrain the number of elements in each class (Xu et al., 2002)
- Multiple images:
  - constrain the number of elements of each class in each image to be upper bounded by λ_1 and lower bounded by λ_0.
  - Denote $\delta_i \in \mathbb{R}^n$ the indicator vector of the i-th image

Problem formulation

- Combining:
  - spatial consistency through Laplacian matrix L
  - discriminative cost through matrix A and cluster size constraints

$$\min_{y \in \{-1,1\}^n} \operatorname{tr}\left(\left(A + \frac{\mu}{n} L\right) y y^T\right),$$
$$\text{subject to} \quad \forall i,\ \lambda_0 1_n \leqslant (yy^\top + 1_n 1_n^T)\delta_i \leqslant \lambda_1 1_n.$$

- Combinatorial optimization problem
  - Convex relaxation with semi-definite programming (Goemans and Williamson, 1995)

Optimization - Convex Relaxation

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- Reparameterize problem with $Y = yy^T$
- Y referred to as the equivalence matrix
  - $Y_{ij} = 1$ if points i and j belong to the same cluster
  - $Y_{ij} = -1$ if points i and j do not belong to the same cluster
- Y is symmetric, positive semidefinite, with diagonal equal to one, and unit rank.

Optimization - Convex Relaxation

- Denote by $\mathcal{E}$ the *elliptope*, i.e., the convex set defined by:

$$\mathcal{E} = \{Y \in \mathbb{R}^{n\times n}\ ,\ Y = Y^T\ ,\ \mathrm{diag}(Y) = 1_n\ ,\ Y \succeq 0\},$$

- Reformulated optimization problem :

$$\begin{aligned} & \min_{Y\in\mathcal{E}} \mathrm{tr}\Big(Y\big(A + \frac{\mu}{n}L\big)\Big), \\ \text{subject to} \quad & \forall i,\ \lambda_0 1_n \leqslant (Y + 1_n 1_n^T)\delta_i \leqslant \lambda_1 1_n \\ & \mathrm{rank}(Y) = 1 \end{aligned}$$

- Rank constraint is not convex
- **Convex relaxation by removing the rank constraint**

Optimization

$$\min_{Y \in \mathcal{E}} \operatorname{tr}\Big(Y\big(A + \frac{\mu}{n}L\big)\Big),$$

$$\text{subject to} \quad \forall i,\ \lambda_0 1_n \leqslant (Y + 1_n 1_n^T)\delta_i \leqslant \lambda_1 1_n$$

- SDP: semidefinite program (Boyd and Vandenberghe, 2002)
- General purpose toolboxes would solve this problem in $O(n^7)$
- Bach and Harchaoui (2007) considers a partial dualization technique that scales up to thousands of data points.
- To gain another order of magnitude: optimization through low-rank matrices (Journée et al, 2008)

Efficient low-rank optimization (Journée et al, 2008)

- Replace constraints by penalization $\Rightarrow$ optimization of a convex function $f(Y)$ on the elliptope $\mathcal{E}$.
- Empirically: global solution has low rank r
- Property: a local minimum of $f(Y)$ over the rank constrained elliptope

  $$\mathcal{E}_d = \{Y \in \mathcal{E}, \mathrm{rank}(Y) = d\}$$

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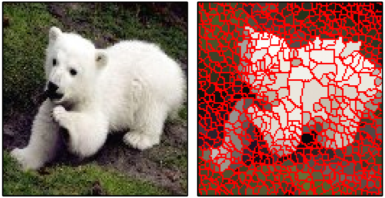
- Adaptive procedure to automatically find r
- Manifold-based trust-region method for a given d (Absil et al., 2008)

Low-rank optimization (Journée et al., 2008)

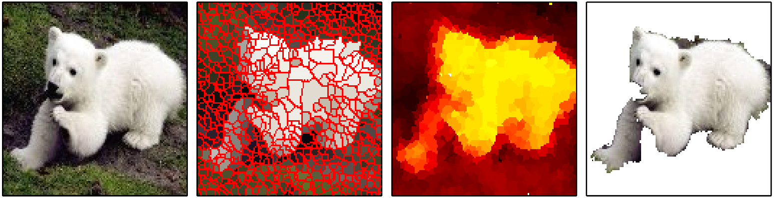
- Final (combinatorial) goal: minimize $f(Y)$ over the rank-one constrained elliptope $\mathcal{E}_1 = \{Y \in \mathcal{E}, \mathrm{rank}(Y) = 1\}$
- Convex relaxation: minimize $f(Y)$ over the unconstrained elliptope $\mathcal{E}$
- Subproblems: minimize $f(Y)$ over the rank-d constrained elliptope $\mathcal{E}_d = \{Y \in \mathcal{E}, \mathrm{rank}(Y) = d\}$ for $d \geqslant 2$
  - It is a Riemanian manifold for $d \geqslant 2$
  - If d is large enough, there is no local minima
  - Find a local minimum with trust-region method
- Adaptive procedure:
  - Start with $d = 2$
  - Find local minimum over $\mathcal{E}_d = \{Y \in \mathcal{E}, \mathrm{rank}(Y) = d\}$
  - Check global optimality condition
  - Stop or augment d

Preclustering



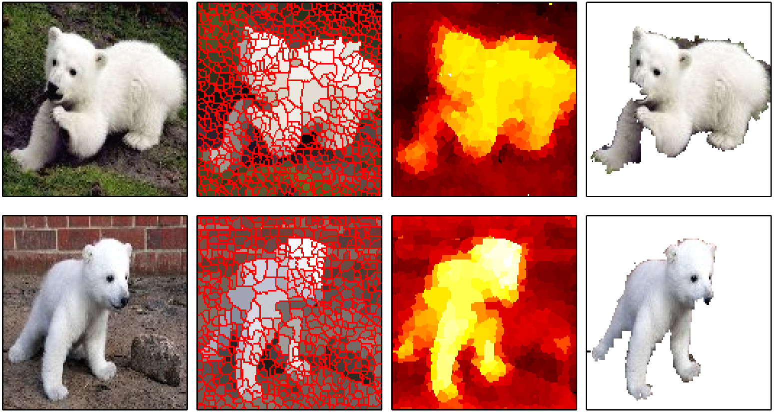
- Cost function f uses a full $n \times n$ matrix $A + (\mu/n)L$
  $\Rightarrow$ memory issues
- To reduce the total number of pixels
  - superpixels obtained from an oversegmentation of our images (watershed, Meyer, 2001)

Rounding



- In order to retrieve $y \in \{-1, 1\}$ from our relaxed solution Y, we compute the largest eigenvector $e \in \mathbb{R}^n$ of Y.
- Final clustering is $y = \text{sign}(e)$.
- Other techniques could be used (e.g., rounding)
- Additional post-processing to remove some artefacts

Method overview (co-segmentation on two bear images)



- From left to right: input images, over-segmentations, scores obtained by our algorithm and co-segmentations.

Results

Results on two different problems :

- Simple problems: images with foreground objects which are identical or very similar in appearance and with few images to co-segment
- Hard problems: images whose foreground objects exhibit higher appearance variations and with more images to co-segment (up to 30).

Results - similar objects

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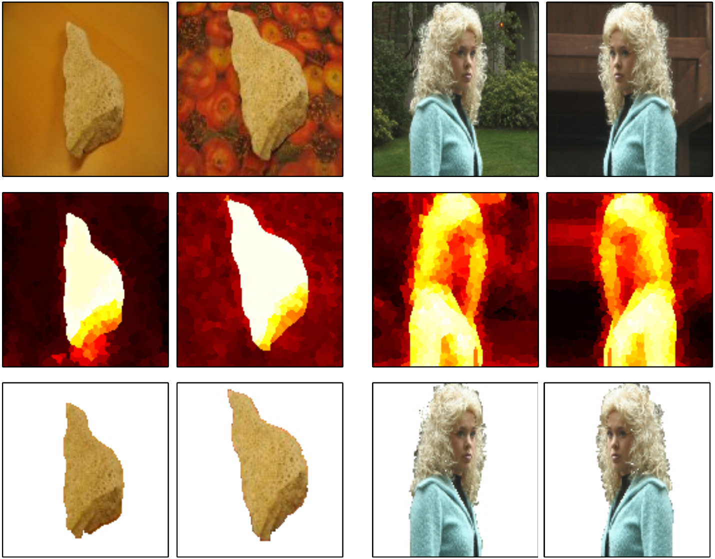

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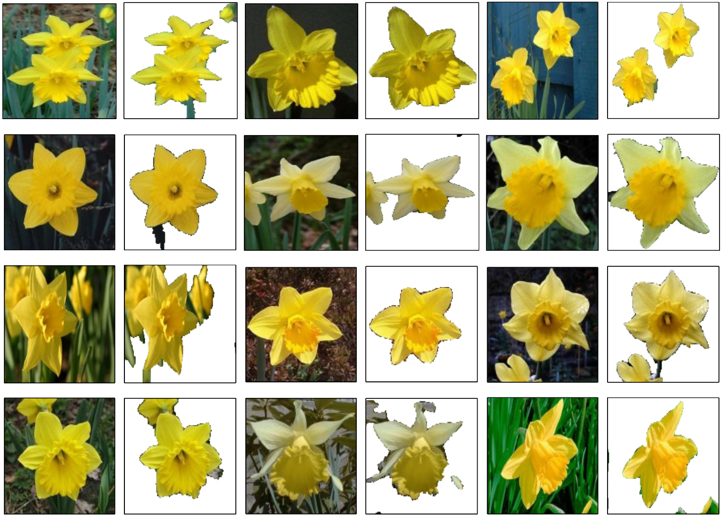
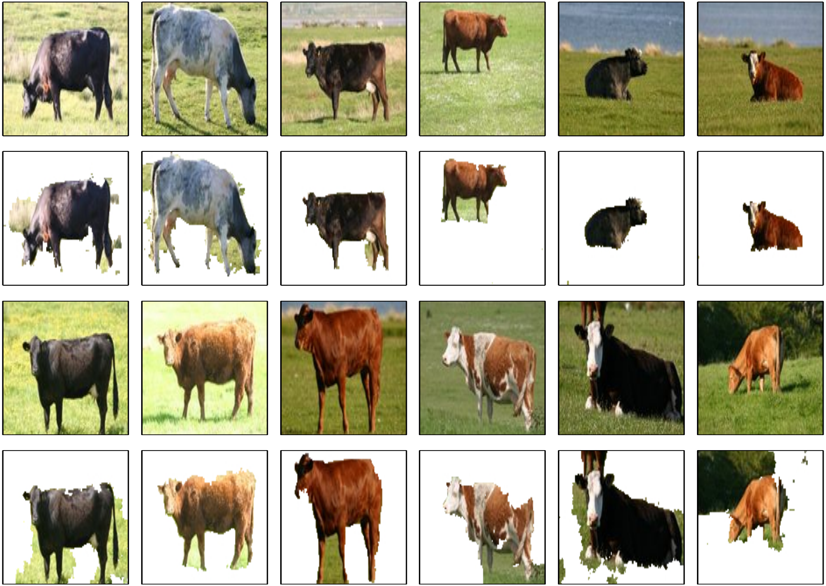


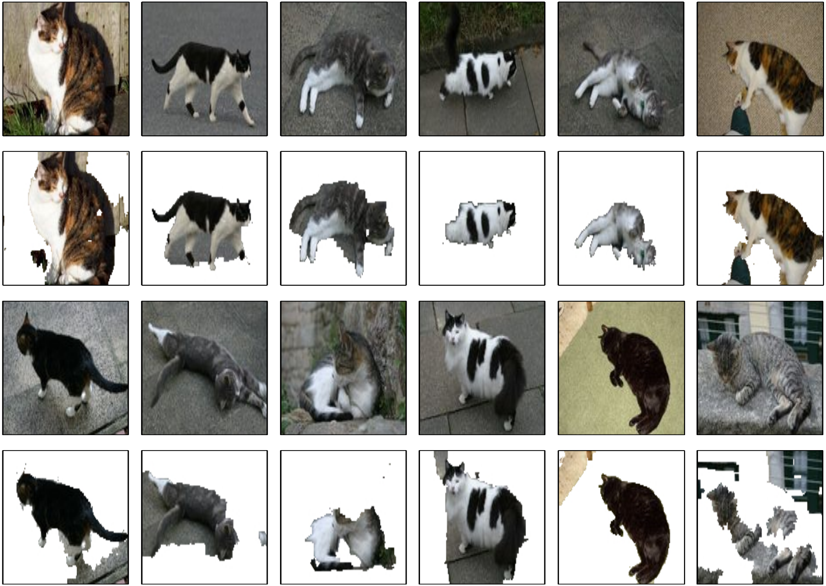
Results - similar classes - Faces

Results - similar classes - Cows



Results - similar classes - Horses

Results - similar classes - Cats



Results - similar classes - Bikes

Results - similar classes - Planes

Comparison with MN-cut (Cour, Benezit, and Shi, 2005)

- Segmentation accuracies on the Weizman horses and MSRC databases.

class	#	cosegm.	independent	Ncut	uniform
Cars (front)	6	87.65 ±0.1	**89.6 ±0.1**	51.4 ±1.8	64.0 ±0.1
Cars (back)	6	**85.1 ±0.2**	83.7 ±0.5	54.1±0.8	71.3 ±0.2
Face	30	**84.3 ±0.7**	72.4 ±1.3	67.7 ±1.2	60.4 ±0.7
Cow	30	**81.6 ±1.4**	78.5 ±1.8	60.1 ±2.6	66.3 ±1.7
Horse	30	**80.1 ±0.7**	77.5 ±1.9	50.1 ±0.9	68.6 ±1.9
Cat	24	**74.4 ±2.8**	71.3 ±1.3	59.8 ±2.0	59.2 ±2.0
Plane	30	73.8 ±0.9	62.5 ±1.9	51.9 ±0.5	**75.9 ±2.0**
Bike	30	**63.3 ±0.5**	61.1 ±0.4	60.7 ±2.6	59.0 ±0.6

Comparing co-segmentation with independent segmentations

- From left to right: original image, multiscale normalized cut, our algorithm on a single image, our algorithm on 30 images.

Conclusion

- Co-segmentation through semi-supervised discriminative clustering
  1. Within an image: maximize local spatial and appearance consistency **(normalized cuts)**
  2. Over all images: maximize the separability of two classes between different images **(semi-supervised SVMs)**

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  1. Within an image: maximize local spatial and appearance consistency **(normalized cuts)**
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- Future work
  - Add negative images
  - More than 2 classes
  - Feature selection
  - Scale up to hundred of thousands
  - Change the loss function