

Denotational semantics

Semantics and Application to Program Verification

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year 2015–2016

Course 4
4 March 2016

Operational semantics (state and trace) (last two weeks)

Defined as small execution steps, *(transition relation)*
over low-level internal configurations. *(states)*

Transitions are chained to define maximal traces.

Denotational semantics (today)

Direct functions from programs to mathematical objects, *(denotations)*
defined by induction on the program syntax, *(compositional)*
ignoring intermediate steps and execution details. *(no state)*

⇒ Higher-level, more abstract, more modular.

Tries to decouple a program meaning from its execution.

Focus on the mathematical structures that represent programs.

(founded by Strachey and Scott in the 70s: [Scott-Strachey71])

“Assembly” semantics vs. **“Functional programming”** semantics.

often: semantics for practical verification vs. semantics for computer theorists

Two very different programs

Bubble sort in C

```
int swapped;
do {
  swapped = 0;
  for (int i=1; i<n; i++) {
    if (a[i-1] > a[i]) {
      swap(&a[i-1], &a[i]);
      swapped = 1;
    }
  }
} while (swapped);
```

Quick sort in OCaml

```
let rec sort = function
| [] -> []
| x::rest ->
  let lo, hi =
    List.partition
      (fun y -> y < x) rest
  in
  (sort lo) @ [x] @ (sort hi)
```

- different **languages** (C / OCaml)
- different **algorithms** (bubble sort / quick sort)
- different **programming principles** (loop / recursion)
- different **data-types** (array / list)

Can we give them the same semantics?

- **imperative programs**

effect of a program: mutate a memory state

natural denotation: **input/output function**

domain $\mathcal{D} \simeq \text{memory} \rightarrow \text{memory}$

challenge: build a whole program denotation

from denotations of atomic language constructs (**modularity**)

- **functional programs**

effect of a program: return a value (without any side-effect)

model a program of type $a \rightarrow b$ as a **function in $\mathcal{D}_a \rightarrow \mathcal{D}_b$**

challenge: choose \mathcal{D} to allow **polymorphic** or **untyped** languages

- other paradigms: parallel, probabilistic, etc.

\implies very rich theory of mathematical structures

Scott domains, cartesian closed categories, coherent spaces, event structures, game semantics, etc. We will not present them in this overview!

- **Imperative programs**
 - **IMP**: **deterministic** programs
 - **NIMP**: handling **non-determinism**
 - **linking** denotational and operational semantics
- **Higher-order programs**
 - **PCF** : monomorphic **typed** programs
 - linking denotational and operational semantics: **full abstraction**
 - **untyped λ -calculus**: **recursive domain equations**
- **Practical session** (room INFO 4)
 - **program** the denotational semantics of a simple imperative (non-)deterministic language (IMP, NIMP)

Deterministic imperative programs

A simple imperative language: IMP

IMP expressions

$expr$	$::=$	X	(variable)
		c	(constant)
		$\diamond expr$	(unary operation)
		$expr \diamond expr$	(binary operation)

- variables in a fixed set $X \in \mathbb{V}$
- constants $\mathbb{I} \stackrel{\text{def}}{=} \mathbb{B} \cup \mathbb{Z}$:
 - booleans $\mathbb{B} \stackrel{\text{def}}{=} \{\text{true}, \text{false}\}$
 - integers \mathbb{Z}
- operations \diamond :
 - integer operations: $+$, $-$, \times , $/$, $<$, \leq
 - boolean operations: \neg , \wedge , \vee
 - polymorphic operations: $=$, \neq

A simple imperative language: IMP

Statements

<i>stat</i>	::=	skip	(<i>do nothing</i>)
		$X \leftarrow expr$	(<i>assignment</i>)
		<i>stat</i> ; <i>stat</i>	(<i>sequence</i>)
		if <i>expr</i> then <i>stat</i> else <i>stat</i>	(<i>conditional</i>)
		while <i>expr</i> do <i>stat</i>	(<i>loop</i>)

(inspired from the presentation in [Benton96])

Expression semantics

$E[\text{expr}] : \mathcal{E} \rightarrow \mathbb{V}$

- environments $\mathcal{E} \stackrel{\text{def}}{=} \mathbb{V} \rightarrow \mathbb{V}$ map variables in \mathbb{V} to values in \mathbb{V}
- $E[\text{expr}]$ returns a value in \mathbb{V}
- \rightarrow denotes partial functions (as opposed to \rightarrow)
necessary because some operations are undefined
 - $1 + \text{true}$, $1 \wedge 2$ (type mismatch)
 - $3/0$ (invalid value)
- defined by structural induction on abstract syntax trees
(next slide)

when we use the notation $X[\text{y}]$, y is a syntactic object; X serves to distinguish between different semantic functions with different signatures, often varying with the kind of syntactic object y (expression, statement, etc.);
 $X[\text{y}]z$ is the application of the function $X[\text{y}]$ to the object z

Expression semantics

$E[\text{expr}] : \mathcal{E} \rightarrow \mathbb{I}$

$E[c] \rho$	$\stackrel{\text{def}}{=} c$	$\in \mathbb{I}$	
$E[V] \rho$	$\stackrel{\text{def}}{=} \rho(V)$	$\in \mathbb{I}$	
$E[-e] \rho$	$\stackrel{\text{def}}{=} -v$	$\in \mathbb{Z}$	if $v = E[e] \rho \in \mathbb{Z}$
$E[\neg e] \rho$	$\stackrel{\text{def}}{=} \neg v$	$\in \mathbb{B}$	if $v = E[e] \rho \in \mathbb{B}$
$E[e_1 + e_2] \rho$	$\stackrel{\text{def}}{=} v_1 + v_2$	$\in \mathbb{Z}$	if $v_1 = E[e_1] \rho \in \mathbb{Z}, v_2 = E[e_2] \rho \in \mathbb{Z}$
$E[e_1 - e_2] \rho$	$\stackrel{\text{def}}{=} v_1 - v_2$	$\in \mathbb{Z}$	if $v_1 = E[e_1] \rho \in \mathbb{Z}, v_2 = E[e_2] \rho \in \mathbb{Z}$
$E[e_1 \times e_2] \rho$	$\stackrel{\text{def}}{=} v_1 \times v_2$	$\in \mathbb{Z}$	if $v_1 = E[e_1] \rho \in \mathbb{Z}, v_2 = E[e_2] \rho \in \mathbb{Z}$
$E[e_1/e_2] \rho$	$\stackrel{\text{def}}{=} v_1/v_2$	$\in \mathbb{Z}$	if $v_1 = E[e_1] \rho \in \mathbb{Z}, v_2 = E[e_2] \rho \in \mathbb{Z} \setminus \{0\}$
$E[e_1 \wedge e_2] \rho$	$\stackrel{\text{def}}{=} v_1 \wedge v_2$	$\in \mathbb{B}$	if $v_1 = E[e_1] \rho \in \mathbb{B}, v_2 = E[e_2] \rho \in \mathbb{B}$
$E[e_1 \vee e_2] \rho$	$\stackrel{\text{def}}{=} v_1 \vee v_2$	$\in \mathbb{B}$	if $v_1 = E[e_1] \rho \in \mathbb{B}, v_2 = E[e_2] \rho \in \mathbb{B}$
$E[e_1 < e_2] \rho$	$\stackrel{\text{def}}{=} v_1 < v_2$	$\in \mathbb{B}$	if $v_1 = E[e_1] \rho \in \mathbb{Z}, v_2 = E[e_2] \rho \in \mathbb{Z}$
$E[e_1 \leq e_2] \rho$	$\stackrel{\text{def}}{=} v_1 \leq v_2$	$\in \mathbb{B}$	if $v_1 = E[e_1] \rho \in \mathbb{Z}, v_2 = E[e_2] \rho \in \mathbb{Z}$
$E[e_1 = e_2] \rho$	$\stackrel{\text{def}}{=} v_1 = v_2$	$\in \mathbb{B}$	if $v_1 = E[e_1] \rho \in \mathbb{I}, v_2 = E[e_2] \rho \in \mathbb{I}$
$E[e_1 \neq e_2] \rho$	$\stackrel{\text{def}}{=} v_1 \neq v_2$	$\in \mathbb{B}$	if $v_1 = E[e_1] \rho \in \mathbb{I}, v_2 = E[e_2] \rho \in \mathbb{I}$

undefined otherwise

Statement semantics

$$\underline{S[\textit{stat}] : \mathcal{E} \rightarrow \mathcal{E}}$$

- maps an environment before the statement to an environment after the statement
- partial function due to
 - errors in expressions
 - non-termination
- also defined by structural induction

Statement semantics

$$\underline{S[\textit{stat}] : \mathcal{E} \rightarrow \mathcal{E}}$$

- **skip**: do nothing

$$S[\mathbf{skip}] \rho \stackrel{\text{def}}{=} \rho$$

- **assignment**: evaluate expression and mutate environment

$$S[X \leftarrow e] \rho \stackrel{\text{def}}{=} \rho[X \mapsto v] \quad \text{if } E[e] \rho = v$$

- **sequence**: function composition

$$S[s_1; s_2] \stackrel{\text{def}}{=} S[s_2] \circ S[s_1]$$

- **conditional**

$$S[\mathbf{if } e \mathbf{ then } s_1 \mathbf{ else } s_2] \rho \stackrel{\text{def}}{=} \begin{cases} S[s_1] \rho & \text{if } E[e] \rho = \text{true} \\ S[s_2] \rho & \text{if } E[e] \rho = \text{false} \\ \text{undefined} & \text{otherwise} \end{cases}$$

$f[x \mapsto y]$ denotes the function that maps x to y , and any $z \neq x$ to $f(z)$

Statement semantics: loops

How do we handle loops?

The semantics of loops must satisfy:

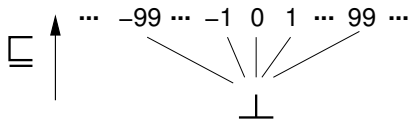
$$S[\mathbf{while\ } e \mathbf{\ do\ } s] \rho = \begin{cases} \rho & \text{if } E[e] \rho = \text{false} \\ S[\mathbf{while\ } e \mathbf{\ do\ } s] (S[s] \rho) & \text{if } E[e] \rho = \text{true} \\ \text{undefined} & \text{otherwise} \end{cases}$$

This is a **recursive definition**; we must prove that:

- the equation has solution(s);
- in case there are several solutions, there is a single “right” one;

⇒ we use **fixpoints** of operators over **partially ordered sets**.

Flat orders and partial functions



Flat ordering (\perp, \sqsubseteq) on \mathbb{I} :

- $\mathbb{I}_\perp \stackrel{\text{def}}{=} \mathbb{I} \cup \{\perp\}$ (pointed set)
- $a \sqsubseteq b \stackrel{\text{def}}{\iff} a = \perp \vee a = b$ (partial order)
- every chain is finite, and so has a **lub** \sqcup
 \implies it is a **pointed complete partial order** (cpo)

\perp denotes the value “undefined” (\sqsubseteq is an information order)

Similarly for $\mathcal{E}_\perp \stackrel{\text{def}}{=} \mathcal{E} \cup \{\perp\}$.

Note that $(\mathcal{E} \rightarrow \mathcal{E}) \simeq (\mathcal{E} \rightarrow \mathcal{E}_\perp)$

\implies we will now **use total functions only**.

Poset of continuous partial functions

Partial order structure on partial functions $(\mathcal{E}_\perp \xrightarrow{c} \mathcal{E}_\perp, \sqsubseteq)$

- $\mathcal{E}_\perp \rightarrow \mathcal{E}_\perp$ extends $\mathcal{E} \rightarrow \mathcal{E}_\perp$
 - domain = co-domain \implies allows **composition** \circ
 - $f \in \mathcal{E} \rightarrow \mathcal{E}_\perp$ extended with $f(\perp) \stackrel{\text{def}}{=} \perp$ (strictness)
 - \implies if $S[[s]]x$ is undefined, so is $(S[[s']] \circ S[[s]])x$
 - such functions are **monotonic and continuous**
 $(a \sqsubseteq b \implies f(a) \sqsubseteq f(b))$ and $f(\sqcup X) = \sqcup \{f(x) \mid x \in X\}$
 - \implies we restrict $\mathcal{E}_\perp \rightarrow \mathcal{E}_\perp$ to **continuous functions**: $\mathcal{E}_\perp \xrightarrow{c} \mathcal{E}_\perp$
- point-wise order \sqsubseteq on functions
 $f \sqsubseteq g \stackrel{\text{def}}{\iff} \forall x: f(x) \sqsubseteq g(x)$
- $\mathcal{E}_\perp \xrightarrow{c} \mathcal{E}_\perp$ has a **least element**: $\perp \stackrel{\text{def}}{=} \lambda x. \perp$
- by point-wise lub \sqcup of chains, it is also **complete** \implies a **cpo**
 $\sqcup F = \lambda x. \sqcup \{f(x) \mid f \in F\}$

Fixpoint semantics of loops

To solve the semantic equation, we use a **fixpoint** of a functional.

We use actually the **least fixpoint**. (most precise for the information order)

$$S[\mathbf{while} \ e \ \mathbf{do} \ s] \stackrel{\text{def}}{=} \text{lfp } F$$

where : $F : (\mathcal{E}_{\perp} \rightarrow \mathcal{E}_{\perp}) \rightarrow (\mathcal{E}_{\perp} \rightarrow \mathcal{E}_{\perp})$

$$F(f)(\rho) = \begin{cases} \rho & \text{if } E[e] \rho = \text{false} \\ f(S[s] \rho) & \text{if } E[e] \rho = \text{true} \\ \perp & \text{otherwise} \end{cases}$$

Theorem

$\text{lfp } F$ is well-defined

remember our equation on $S[\mathbf{while} \ e \ \mathbf{do} \ s]$?

it can be rewritten exactly as: $S[\mathbf{while} \ e \ \mathbf{do} \ s] = F(S[\mathbf{while} \ e \ \mathbf{do} \ s])$

Fixpoint semantics of loops (proof sketch)

Recall **Kleene's** theorem:

Kleene's theorem

A continuous function on a cpo has a least fixpoint

To use the theorem we prove that $S[[stat]]$ is **continuous** (and is well-defined) by induction on the syntax of $stat$:

- base cases: $S[[skip]]$ and $S[[X \leftarrow e]]$ are continuous
- $S[[if\ e\ then\ s_1\ else\ s_2]]$: by induction hypothesis, as $S[[s_1]]$ and $S[[s_2]]$ are continuous
- $S[[s_1; s_2]]$: by induction hypotheses and because \circ respects continuity
- F is continuous in $(\mathcal{E}_\perp \xrightarrow{c} \mathcal{E}_\perp) \xrightarrow{c} (\mathcal{E}_\perp \xrightarrow{c} \mathcal{E}_\perp)$ by induction hypotheses $\implies \text{lfp } F$ exists by Kleene's theorem

moreover, $\text{lfp } F$ is continuous (simple consequence of Kleene's proof)
 $\implies S[[while\ e\ do\ s]]$ is continuous

Join semantics of loops

Recall another fact about Kleene's fixpoints: $\text{lfp } F = \bigsqcup_{n \in \mathbb{N}} F^n(\perp)$

- $F^0(\perp) = \perp$ is completely **undefined** (no information)

- $F^1(\perp)(\rho) = \begin{cases} \rho & \text{if } E[e] \rho = \text{false} \\ \perp & \text{otherwise} \end{cases}$
environment if the loop is **never entered** (partial information)

- $F^2(\perp)(\rho) = \begin{cases} \rho & \text{if } E[e] \rho = \text{false} \\ S[s] \rho & \text{else if } E[e] (S[s] \rho) = \text{false} \\ \perp & \text{otherwise} \end{cases}$
environment if the loop is iterated **at most once**

- $F^n(\perp)(\rho)$
environment if the loop is iterated **at most $n - 1$ times**

- $\bigsqcup_{n \in \mathbb{N}} F^n(\perp)$
environment when exiting the loop
whatever the number of iterations (total information)

Error vs. non-termination

In our semantics $S[[stat]]\rho = \perp$ can mean:

- either *stat* starting on input ρ loops for ever
- or it stops prematurely with an error

Note : we could distinguish between the two cases by :

- adding an **error value** Ω , distinct from \perp
- propagating it in the semantics, bypassing computations (no further computation after an error)

Summary

Rewriting the semantics using total functions on cpos with \perp :

- $E[\![\text{expr}]\!] : \mathcal{E}_\perp \xrightarrow{c} \mathbb{I}_\perp$
returns \perp for an error or if its argument is \perp
- $S[\![\text{stat}]\!] : \mathcal{E}_\perp \xrightarrow{c} \mathcal{E}_\perp$
 - $S[\![\text{skip}]\!] \rho \stackrel{\text{def}}{=} \rho$
 - $S[\![e_1; e_2]\!] \stackrel{\text{def}}{=} S[\![e_2]\!] \circ S[\![e_1]\!]$
 - $S[\![X \leftarrow e]\!] \rho \stackrel{\text{def}}{=} \begin{cases} \perp & \text{if } E[\![e]\!] \rho = \perp \\ \rho[X \mapsto E[\![e]\!] \rho] & \text{otherwise} \end{cases}$
 - $S[\![\text{if } e \text{ then } s_1 \text{ else } s_2]\!] \rho \stackrel{\text{def}}{=} \begin{cases} S[\![s_1]\!] \rho & \text{if } E[\![e]\!] \rho = \text{true} \\ S[\![s_2]\!] \rho & \text{if } E[\![e]\!] \rho = \text{false} \\ \perp & \text{otherwise} \end{cases}$
 - $S[\![\text{while } e \text{ do } s]\!] \stackrel{\text{def}}{=} \text{lfp } F$
where $F(f)(\rho) = \begin{cases} \rho & \text{if } E[\![e]\!] \rho = \text{false} \\ f(S[\![s]\!] \rho) & \text{if } E[\![e]\!] \rho = \text{true} \\ \perp & \text{otherwise} \end{cases}$

Non-determinism

Why non-determinism?

It is useful to consider non-deterministic programs, to:

- model partially **unknown** environments (user input)
- abstract away **unknown** program parts (libraries)
- abstract away **too complex** parts (rounding errors in floats)
- handle a **set of programs** as a single one (parametric programs)

Kinds of non-determinism

- data non-determinism: $expr ::= \mathbf{random}()$
- control non-determinism: $stat ::= \mathbf{either } s_1 \mathbf{ or } s_2$
but we can write “**either** s_1 **or** s_2 ” as “**if** $\mathbf{random}() = 0$ **then** s_1 **else** s_2 ”

Consequence on semantics and verification

we want to verify **all** the possible executions

\implies the semantics should express **all** the possible executions

Modified language

We extend **IMP** to **NIMP**,
an imperative language with non-determinism.

NIMP language

$expr$	$::=$	X	(variable)
		c	(constant)
		$[c_1, c_2]$	(constant interval)
		$\diamond expr$	(unary operation)
		$expr \diamond expr$	(binary operation)

NIMP has the same statements as **IMP**

$c_1 \in \mathbb{Z} \cup \{-\infty\}$, $c_2 \in \mathbb{Z} \cup \{+\infty\}$

$[c_1, c_2]$ means: return a fresh random value between c_1 and c_2 each time the expression is evaluated

Question: is $[0, 1] = [0, 1]$ true or false?

Expression semantics

$$E[\text{expr}] : \mathcal{E} \rightarrow \mathcal{P}(\mathbb{I})$$

$E[V] \rho$	$\stackrel{\text{def}}{=}$	$\{\rho(V)\}$
$E[c] \rho$	$\stackrel{\text{def}}{=}$	$\{c\}$
$E[[c_1, c_2]] \rho$	$\stackrel{\text{def}}{=}$	$\{c \in \mathbb{Z} \mid c_1 \leq c \leq c_2\}$
$E[-e] \rho$	$\stackrel{\text{def}}{=}$	$\{-v \mid v \in E[e] \rho \cap \mathbb{Z}\}$
$E[\neg e] \rho$	$\stackrel{\text{def}}{=}$	$\{\neg v \mid v \in E[e] \rho \cap \mathbb{B}\}$
$E[e_1 + e_2] \rho$	$\stackrel{\text{def}}{=}$	$\{v_1 + v_2 \mid v_1 \in E[e_1] \rho \cap \mathbb{Z}, v_2 \in E[e_2] \rho \cap \mathbb{Z}\}$
$E[e_1/e_2] \rho$	$\stackrel{\text{def}}{=}$	$\{v_1/v_2 \mid v_1 \in E[e_1] \rho \cap \mathbb{Z}, v_2 \in E[e_2] \rho \cap \mathbb{Z} \setminus \{0\}\}$
$E[e_1 < e_2] \rho$	$\stackrel{\text{def}}{=}$	$\{\text{true} \mid \exists v_1 \in E[e_1] \rho, v_2 \in E[e_2] \rho: v_1 \in \mathbb{Z}, v_2 \in \mathbb{Z}, v_1 < v_2\} \cup$ $\{\text{false} \mid \exists v_1 \in E[e_1] \rho, v_2 \in E[e_2] \rho: v_1 \in \mathbb{Z}, v_2 \in \mathbb{Z}, v_1 \geq v_2\}$
...		

- we output a **set** of values, to account for non-determinism
- we can have $E[e] \rho = \emptyset$ due to **errors**
 (no need for a special Ω nor \perp element)

Statement semantic domain

Semantic domain:

- a statement can output a **set** of environments
 \implies use $\mathcal{E} \rightarrow \mathcal{P}(\mathcal{E})$
- to allow composition, extend it to $\mathcal{P}(\mathcal{E}) \rightarrow \mathcal{P}(\mathcal{E})$
- non-termination and errors can be modeled by \emptyset
(no need for a special Ω nor \perp element)

Statement semantics

$$S[\textit{stat}] : \mathcal{P}(\mathcal{E}) \rightarrow \mathcal{P}(\mathcal{E})$$

- $S[\textit{skip}] R \stackrel{\text{def}}{=} R$
- $S[s_1; s_2] \stackrel{\text{def}}{=} S[s_2] \circ S[s_1]$
- $S[X \leftarrow e] R \stackrel{\text{def}}{=} \{ \rho[X \mapsto v] \mid \rho \in R, v \in E[e] \rho \}$
 - pick an environment ρ
 - pick an expression value v in $E[e] \rho$
 - generate an updated environment $\rho[X \mapsto v]$
- $S[\textit{if } e \textit{ then } s_1 \textit{ else } s_2] R \stackrel{\text{def}}{=} S[s_1] \{ \rho \in R \mid \textit{true} \in E[e] \rho \} \cup S[s_2] \{ \rho \in R \mid \textit{false} \in E[e] \rho \}$
 - filter environments according to the value of e
 - execute **both** branch **independently**
 - **join** them with \cup

Statement semantics

- $S[\text{while } e \text{ do } s] R \stackrel{\text{def}}{=} \{\rho \in \text{lfp } F \mid \text{false} \in E[e] \rho\}$
 where $F(X) \stackrel{\text{def}}{=} R \cup S[s] \{\rho \in X \mid \text{true} \in E[e] \rho\}$

Justification: $\text{lfp } F$ exists

- $(\mathcal{P}(\mathcal{E}), \subseteq, \cup, \cap, \emptyset, \mathcal{E})$ forms a **complete lattice**
- all semantic functions and F are **monotonic** and **continuous**

in fact, they are strict complete join morphisms

$$S[s] (\cup_{i \in \Delta} X_i) = \cup_{i \in \Delta} S[s] X_i \text{ and } S[s] \emptyset = \emptyset$$

which we write as $S[s] \in \mathcal{P}(\mathcal{E}) \xrightarrow{\cup} \mathcal{P}(\mathcal{E})$

it is really the *image function* of a function in $\mathcal{E} \rightarrow \mathcal{P}(\mathcal{E})$

$$S[s] X = \cup \{S[s] \{x\} \mid x \in X\}$$

- we can apply both Kleene's and Tarski's fixpoint theorems

Join semantics of loops

- $S[\text{while } e \text{ do } s] R \stackrel{\text{def}}{=} \{\rho \in \text{lfp } F \mid \text{false} \in E[e] \rho\}$
 where $F(X) \stackrel{\text{def}}{=} R \cup S[s] \{\rho \in X \mid \text{true} \in E[e] \rho\}$

(F applies a loop iteration to X and adds back the environments R before the loop)

Recall that $\text{lfp } F = \bigcup_{n \in \mathbb{N}} F^n(\emptyset)$

- $F^0(\emptyset) = \emptyset$
- $F^1(\emptyset) = R$
 environments before entering the loop
- $F^2(\emptyset) = R \cup S[s] \{\rho \in R \mid \text{true} \in E[e] \rho\}$
 environments after zero or one loop iteration
- $F^n(\emptyset)$: environments after at most $n - 1$ loop iterations
 (just before testing the condition to determine if we should iterate a n -th time)
- $\bigcup_{n \in \mathbb{N}} F^n(\emptyset)$: **loop invariant**

“Angelic” non-determinism and termination

If *stat* is **deterministic** (no $[c_1, c_2]$ in expressions)

the semantics is **equivalent** to our semantics on $\mathcal{E}_\perp \xrightarrow{c} \mathcal{E}_\perp$

Justification: $(\{E \subseteq \mathcal{E} \mid |E| \leq 1\}, \subseteq, \cup, \emptyset)$ is isomorphic to $(\mathcal{E}_\perp, \sqsubseteq, \sqcup, \perp)$

In general, we can have several outputs for $S[\![stat]\!] \{\rho\} \subseteq \mathcal{E} \cup \{\Omega\}$:

- \emptyset : the program never terminates at all
- $\{\Omega\}$: the program never terminates correctly
- $R \subseteq \mathcal{E} \setminus \{\Omega\}$: when the program terminates, it terminates correctly, in an environment in R

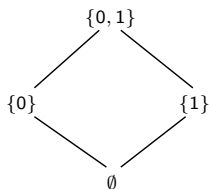
\implies we cannot express that a program always terminates!

This is called the “**Angelic**” semantics, useful for **partial correctness**.

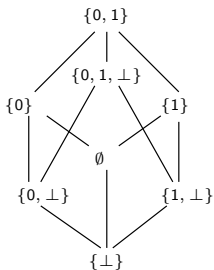
Note on non-determinism and termination

Other (more complex) ways to mix non-termination and non-determinism exist

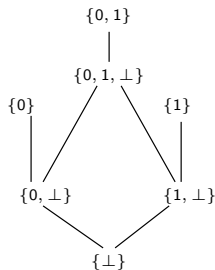
Based on **distinguishing \emptyset and \perp** , and on **different order relations \sqsubseteq**



powerset order
angelic semantics



mixed order
natural semantics



Egli-Milner order
natural semantics

(this is a complex subject, we will say no more)

Link between operational and denotational semantics

Motivation

Are the operational and denotational semantics consistent with each other?

Note that:

- systems are actually described **operationally**
(previous courses)
- the denotational semantics is a **more abstract** representation
(more suitable for some reasoning on the system)

⇒ the denotational semantics must be proven faithful
(in some sense) to the operational model to be of any use

Transition systems for our non-deterministic language

Labelled syntax

$$\begin{array}{l}
 {}^{\ell}stat^{\ell} ::= {}^{\ell}skip \\
 \quad | \quad {}^{\ell}X \leftarrow expr^{\ell} \\
 \quad | \quad {}^{\ell}if\ expr\ then\ {}^{\ell}stat\ else\ {}^{\ell}stat^{\ell} \\
 \quad | \quad {}^{\ell}while\ {}^{\ell}expr\ do\ {}^{\ell}stat^{\ell} \\
 \quad | \quad {}^{\ell}stat; {}^{\ell}stat^{\ell}
 \end{array}$$

$\ell \in \mathcal{L}$: control labels

- statements are decorated with **unique control labels** $\ell \in \mathcal{L}$
- program configurations in $\Sigma \stackrel{\text{def}}{=} \mathcal{L} \times \mathcal{E}$
(lower-level than \mathcal{E} : we must track program locations)
- transition relation $\tau \subseteq \Sigma \times \Sigma$
models atomic execution steps

Transition systems for our language

τ is defined by induction on the syntax of statements
 $(\sigma, \sigma') \in \tau$ is denoted as $\sigma \rightarrow \sigma'$

$$\tau[\ell^1 \text{skip } \ell^2] \stackrel{\text{def}}{=} \{(\ell^1, \rho) \rightarrow (\ell^2, \rho) \mid \rho \in \mathcal{E}\}$$

$$\tau[\ell^1 X \leftarrow e \ell^2] \stackrel{\text{def}}{=} \{(\ell^1, \rho) \rightarrow (\ell^2, \rho[X \mapsto v]) \mid \rho \in \mathcal{E}, v \in \mathbb{E}[\![e]\!] \rho\}$$

$$\begin{aligned} \tau[\ell^1 \text{if } e \text{ then } \ell^2_{s_1} \text{ else } \ell^3_{s_2} \ell^4] &\stackrel{\text{def}}{=} \\ &\{(\ell^1, \rho) \rightarrow (\ell^2, \rho) \mid \rho \in \mathcal{E}, \text{true} \in \mathbb{E}[\![e]\!] \rho\} \cup \\ &\{(\ell^1, \rho) \rightarrow (\ell^3, \rho) \mid \rho \in \mathcal{E}, \text{false} \in \mathbb{E}[\![e]\!] \rho\} \cup \\ &\tau[\ell^2_{s_1} \ell^4] \cup \tau[\ell^3_{s_2} \ell^4] \end{aligned}$$

$$\begin{aligned} \tau[\ell^1 \text{while } \ell^2 e \text{ do } \ell^3_{s_1} \ell^4] &\stackrel{\text{def}}{=} \\ &\{(\ell^1, \rho) \rightarrow (\ell^2, \rho) \mid \rho \in \mathcal{E}\} \cup \\ &\{(\ell^2, \rho) \rightarrow (\ell^3, \rho) \mid \rho \in \mathcal{E}, \text{true} \in \mathbb{E}[\![e]\!] \rho\} \cup \\ &\{(\ell^2, \rho) \rightarrow (\ell^4, \rho) \mid \rho \in \mathcal{E}, \text{false} \in \mathbb{E}[\![e]\!] \rho\} \cup \tau[\ell^3_{s_1} \ell^4] \end{aligned}$$

$$\tau[\ell^1 s_1; \ell^2 s_2 \ell^3] \stackrel{\text{def}}{=} \tau[\ell^1 s_1 \ell^2] \cup \tau[\ell^2 s_2 \ell^3]$$

Defines the **small-step** semantics of a statement

(the semantics of expressions is still in denotational form)

Special states

Given a labelled statement ${}^{l_e}S^{l_x}$ and its transition system, we define:

- **initial states:** $I \stackrel{\text{def}}{=} \{(l_e, \rho) \mid \rho \in \mathcal{E}\}$
note that $\sigma \rightarrow \sigma' \implies \sigma' \notin I$
- **blocking states:** $B \stackrel{\text{def}}{=} \{\sigma \in \Sigma \mid \forall \sigma' : \in \Sigma, \sigma \not\rightarrow \sigma'\}$
 - **correct termination:** $OK \stackrel{\text{def}}{=} \{(l_x, \rho) \mid \rho \in \mathcal{E}\}$
note that $OK \subseteq B$
 - **error:** $ERR \stackrel{\text{def}}{=} B \cap \{(l, \rho) \mid l \neq l_x, \rho \in \mathcal{E}\}$

$$B = ERR \cup OK$$

$$ERR \cap OK = \emptyset$$

Reminder: maximal trace semantics

Trace: in Σ^∞

(finite or infinite sequence of states)

- starting in an initial state I
- following transitions \rightarrow
- can only end in a blocking state B

(traces are maximal)

i.e.: $t[[s]] = t[[s]]^* \cup t[[s]]^\omega$ where

- **finite traces:**

$$t[[s]]^* \stackrel{\text{def}}{=} \{ (\sigma_0, \dots, \sigma_n) \mid n \geq 0, \sigma_0 \in I, \sigma_n \in B, \forall i < n: \sigma_i \rightarrow \sigma_{i+1} \}$$

- **infinite traces:**

$$t[[s]]^\omega \stackrel{\text{def}}{=} \{ (\sigma_0, \dots) \mid \sigma_0 \in I, \forall i \in \mathbb{N}: \sigma_i \rightarrow \sigma_{i+1} \}$$

From traces to big-step semantics

Big-step semantics: abstraction of traces

only remembers the input-output relations

many variants exist:

- “angelic” semantics, in $\mathcal{P}(\Sigma \times \Sigma)$:

$$A[s] \stackrel{\text{def}}{=} \{ (\sigma, \sigma') \mid \exists (\sigma_0, \dots, \sigma_n) \in t[s]^* : \sigma = \sigma_0, \sigma' = \sigma_n \}$$

(only give information on the terminating behaviors;
can only prove partial correctness)

- natural semantics, in $\mathcal{P}(\Sigma \times \Sigma_{\perp})$:

$$N[s] \stackrel{\text{def}}{=} A[s] \cup \{ (\sigma, \perp) \mid \exists (\sigma_0, \dots) \in t[s]^{\omega} : \sigma = \sigma_0 \}$$

(models the terminating and non-terminating behaviors;
can prove total correctness)

Exercise: compute the semantics of “while $X > 0$ do $X \leftarrow X - [0, 1]$ ”

From big-step to denotational semantics

The angelic denotational and big-step semantics are **isomorphic**
(isomorphism between relations and strict complete join morphisms)

$S[s] = \alpha(A[s])$ where

- $\alpha(X) \stackrel{\text{def}}{=} \lambda R. \{ \rho' \mid \rho \in R, ((\ell_e, \rho), (\ell_x, \rho')) \in X \}$ *(image of a relation)*
- $\alpha^{-1}(Y) = \{ ((\ell_e, \rho), (\ell_x, \rho')) \mid \rho \in \mathcal{E}, \rho' \in Y(\{\rho\}) \}$

Proof idea: by induction on the syntax of s

\implies **our operational and denotational semantics match**

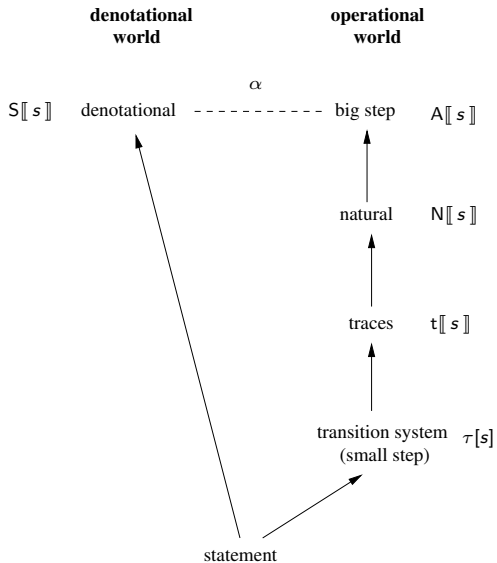
Also, the denotational semantics is an **abstraction** of the natural semantics
(it forgets about infinite computations)

Thesis

All semantics can be compared for equivalence or abstraction

this can be made formal in the **abstract interpretation theory**
(see [Cousot02])

Semantic diagram



Fixpoint formulation

Recall that traces can be expressed as fixpoints:

- $t[[s]]^* = (\text{lfp } F) \cap (I\Sigma^\infty)$ ($(\cap (I\Sigma^\infty))$ restricts to traces starting in I)
 where $F(X) \stackrel{\text{def}}{=} B \cup \{(\sigma, \sigma_0, \dots, \sigma_n) \mid \sigma \rightarrow \sigma_0 \wedge (\sigma_0, \dots, \sigma_n) \in X\}$
- $t[[s]]^\omega = (\text{gfp } F) \cap (I\Sigma^\infty)$
 where $F(X) \stackrel{\text{def}}{=} \{(\sigma, \sigma_0, \dots) \mid \sigma \rightarrow \sigma_0 \wedge (\sigma_0, \dots) \in X\}$

This also holds for the **angelic denotational semantics**:

- $S[[s]] = \alpha(\text{lfp } F)$ (α converts relations to functions)
 where $F(X) \stackrel{\text{def}}{=} (B \times B) \cup \{(\sigma, \sigma'') \mid \exists \sigma' : \sigma \rightarrow \sigma' \wedge (\sigma', \sigma'') \in X\}$

and many others: natural, denotational, big-step, denotational,...

Thesis

All semantics can be expressed through fixpoints

(again [Cousot02])

Higher-order programs

Monomorphic typed higher order language

PCF language (introduced by Scott in 1969)

<i>type</i>	$::=$	int	(integers)
		bool	(booleans)
		$type \rightarrow type$	(functions)
<i>term</i>	$::=$	X	(variable $X \in \mathbb{V}$)
		c	(constant)
		$\lambda X^{type}. term$	(abstraction)
		$term term$	(application)
		$Y^{type} term$	(recursion)
		Ω^{type}	(failure)

PCF (programming computable functions) is a λ -calculus with:

- a monomorphic type system (unlike ML)
- explicit type annotations X^{type} , Y^{type} , Ω^{type} (unlike ML)
- an explicit recursion combiner **Y** (unlike untyped λ -calculus)
- constants, including \mathbb{Z} , \mathbb{B} and a few built-in functions (arithmetic and comparisons in \mathbb{Z} , if-then-else, etc.)

Semantic domains

What should be the domain of $\llbracket \text{term} \rrbracket$?

Difficulty: *term* contains heterogeneous objects: constants, functions, second order functions, etc.

Solution: use the type information

each term m can be given a type $\text{typ}(m)$

use one semantic domain \mathcal{D}_t per type t

then $\llbracket m \rrbracket : \mathcal{E} \rightarrow \mathcal{D}_{\text{typ}(m)}$ where $\mathcal{E} \stackrel{\text{def}}{=} \mathbb{V} \rightarrow (\bigcup_{t \in \text{type}} \mathcal{D}_t)$

Domain definition by induction on the syntax of types

- $\mathcal{D}_{\text{int}} \stackrel{\text{def}}{=} \mathbb{Z}_{\perp}$
- $\mathcal{D}_{\text{bool}} \stackrel{\text{def}}{=} \mathbb{B}_{\perp}$
- $\mathcal{D}_{t_1 \rightarrow t_2} \stackrel{\text{def}}{=} (\mathcal{D}_{t_1} \xrightarrow{c} \mathcal{D}_{t_2})_{\perp}$

Order on semantic domains

Order: all domains are **cpos**

- $\mathcal{D}_{\text{int}} \stackrel{\text{def}}{=} \mathbb{Z}_{\perp}$, $\mathcal{D}_{\text{bool}} \stackrel{\text{def}}{=} \mathbb{B}_{\perp}$ use a **flat ordering**
- $\mathcal{D}_{t_1 \rightarrow t_2} \stackrel{\text{def}}{=} (\mathcal{D}_{t_1} \xrightarrow{c} \mathcal{D}_{t_2})_{\perp}$

with order $f \sqsubseteq g \iff f = \perp \vee (f, g \neq \perp \wedge \forall x: f(x) \sqsubseteq g(x))$

- $\mathcal{D}_{t_1} \xrightarrow{c} \mathcal{D}_{t_2}$ is ordered point-wise
- each domain has its fresh minimal \perp element
(to distinguish $\Omega^{\text{int} \rightarrow \text{int}}$ from $\lambda X^{\text{int}}.\Omega^{\text{int}}$)
- we restrict \rightarrow to **continuous functions**
(to be able to take fixpoints)

(see [Scott93])

Denotational semantics

Environments: $\mathcal{E} \stackrel{\text{def}}{=} \mathbb{V} \rightarrow (\bigcup_{t \in \text{type}} \mathcal{D}_t)$

Semantics: $\mathbb{T} \llbracket m \rrbracket : \mathcal{E} \rightarrow \mathcal{D}_{\text{typ}(m)}$

$$\mathbb{T} \llbracket X \rrbracket \rho \stackrel{\text{def}}{=} \rho(X)$$

$$\mathbb{T} \llbracket c \rrbracket \rho \stackrel{\text{def}}{=} c$$

$$\mathbb{T} \llbracket \lambda X^t. m \rrbracket \rho \stackrel{\text{def}}{=} \lambda x. \mathbb{T} \llbracket m \rrbracket (\rho[X \mapsto x])$$

$$\mathbb{T} \llbracket m_1 m_2 \rrbracket \rho \stackrel{\text{def}}{=} (\mathbb{T} \llbracket m_1 \rrbracket \rho)(\mathbb{T} \llbracket m_2 \rrbracket \rho)$$

$$\mathbb{T} \llbracket \mathbf{Y}^t m \rrbracket \rho \stackrel{\text{def}}{=} \text{lfp} (\mathbb{T} \llbracket m \rrbracket \rho)$$

$$\mathbb{T} \llbracket \Omega^t \rrbracket \rho \stackrel{\text{def}}{=} \perp^t$$

- program functions λ are mapped to mathematical functions λ
- program recursion \mathbf{Y} is mapped to fixpoints lfp
- errors and non-termination are mapped to (typed) \perp
- we should prove that $\mathbb{T} \llbracket m \rrbracket$ is indeed continuous (by induction) so that lfp exists, and also that $\mathbb{T} \llbracket m_1 \rrbracket$ is indeed a function (by soundness of typing)

Operational semantics

Operational semantics: based on the λ -calculus

- states are terms: $\Sigma \stackrel{\text{def}}{=} \text{term}$

- transitions correspond to **reductions**:

$$(\lambda X^t. m_1) m_2 \rightarrow m_1[X \mapsto m_2] \quad (\lambda\text{-reduction})$$

$$\Omega^t \rightarrow \Omega^t \quad (\text{failure})$$

$$\mathbf{Y}^t m \rightarrow m (\mathbf{Y}^t m) \quad (\text{iteration})$$

$$\text{plus } c_1 c_2 \rightarrow (c_1 + c_2) \quad (\text{arithmetic})$$

$$\text{if true } m_1 m_2 \rightarrow m_1 \quad (\text{if-then-else})$$

$$\text{if false } m_1 m_2 \rightarrow m_2 \quad (\text{if-then-else})$$

$$\frac{m_1 \rightarrow m'_1}{m_1 m_2 \rightarrow m'_1 m_2} \quad (\text{context rule})$$

...

- big-step semantics $m \Downarrow$: maximal reductions

$$m \Downarrow = m' \iff m \rightarrow^* m' \wedge \nexists m'' : m' \rightarrow m''$$

(PCF is deterministic)

Links between operational and denotational semantics

How do we check that operational and denotational semantics match?

check that they have the same view of “semantically equal programs”

- denotational way: we can use $T[[m_1]] = T[[m_2]]$
- we need an **operational** way to compare **functions**
 comparing the syntax is too fine grained,
Example: $(\lambda X^{\text{int}}.0) \neq (\lambda X^{\text{int}}.\text{minus } 1 \ 1)$, but they have the same denotation

Observational equivalence: observe terms **in all contexts**

- contexts c : terms with holes \square
- $c[m]$ term obtained by substituting m in hole
- *ground* is the set of terms of type **int** or **bool**
- term **equivalence** \approx :

$$m_1 \approx m_2 \stackrel{\text{def}}{\iff} (\forall c: c[m_1] \Downarrow = c[m_2] \Downarrow \text{ when } c[m_1] \in \text{ground})$$

(don't look at a function's syntax, force its full evaluation and look at the value result)

Full abstraction

Full abstraction: $\forall m_1, m_2: m_1 \approx m_2 \iff T\llbracket m_1 \rrbracket = T\llbracket m_2 \rrbracket$

Unexpected result: for PCF, \Leftarrow holds (adequacy), but **not** \Rightarrow !

(full abstraction concept introduced by Milner in 1975, proof by Plotkin 1977)

Compare with: **IMP**, **NIMP** are fully abstract

$\forall s_1, s_2 \in \text{stat}: S\llbracket s_1 \rrbracket = S\llbracket s_2 \rrbracket \iff \forall c: A\llbracket c[s_1] \rrbracket = A\llbracket c[s_2] \rrbracket$

Intuitive explanation:

Domains such as $\mathcal{D}_{t_1 \rightarrow t_2}$ contain many functions, most of them do not correspond to *any* program (this is expected: many functions are not computable).

The problem is that, if m_1, m_2 have the form $\lambda X^{t_1 \rightarrow t_2}. m$, $T\llbracket m_1 \rrbracket = T\llbracket m_2 \rrbracket$ imposes $T\llbracket m_1 \rrbracket f = T\llbracket m_2 \rrbracket f$ for all $f \in \mathcal{D}_{t_1 \rightarrow t_2}$, including many f that are not computable.

It is actually possible to construct m_1, m_2 where $T\llbracket m_1 \rrbracket f \neq T\llbracket m_2 \rrbracket f$ only for some non-program functions f , so that $m_1 \approx m_2$ actually holds

Two solutions come to mind:

- enrich the language to express more functions in $\mathcal{D}_{t_1 \rightarrow t_2}$ (next slide)
- restrict $\mathcal{D}_{t_1 \rightarrow t_2}$ to contain less non-program objects

Fruitful but complex research topic...

Full abstraction

Example: the **parallel or** function *por*

$$por(a)(b) \stackrel{\text{def}}{=} \begin{cases} \text{true} & \text{if } a = \text{true} \vee b = \text{true} \\ \text{false} & \text{if } a = \text{false} \wedge b = \text{false} \\ \perp & \text{otherwise} \end{cases}$$

por can observe *a* and *b* concurrently, and return as soon as one returns true
compare with sequential *or*, where $\forall b: or(\perp)(b) = \perp$

We have the following non-obvious result:

- *por* cannot be defined in **PCF**
(*por* is a parallel construct, **PCF** is a sequential language)
- **PCF**+*por* is fully abstract

(see [Ong95], [Winskel97] for references on the subject)

Recursive domain equations

Untyped higher order language

 λ -calculus (*with arithmetic*)

<i>term</i>	::=	X	(variable $X \in \mathbb{V}$)
		c	(constants)
		$\lambda X.term$	(abstraction)
		$term term$	(application)
		Ω	(failure)

- we can write **truly polymorphic** functions: e.g., $\lambda X.X$
(in **PCF** we would have to choose a type: $\mathbf{int} \rightarrow \mathbf{int}$ or $\mathbf{bool} \rightarrow \mathbf{bool}$ or $(\mathbf{int} \rightarrow \mathbf{int}) \rightarrow (\mathbf{int} \rightarrow \mathbf{int})$ or ...)
- no need for a recursion combinator **Y**
(we can define $\mathbf{Y} \stackrel{\text{def}}{=} \lambda F.(\lambda X.F (X X))(\lambda X.F (X X))$, not typable in **PCF**)
- operational semantics based on reduction, similarly to **PCF**
- denotational semantics also similar to **PCF**, **but...**

Domain equations

How to choose the domain of denotations $\mathbb{T}[[m]]$?

- we need a unique domain \mathcal{D} for all terms
(no type information to help us)
- $\lambda X.X$ is a function
 \implies it should have denotation in $(\mathcal{X} \rightarrow \mathcal{Y})_{\perp}$ for some $\mathcal{X}, \mathcal{Y} \subseteq \mathcal{D}$
- $\lambda X.X$ is polymorphic; it accepts any term as argument
 $\implies \mathcal{D} \subseteq \mathcal{X}, \mathcal{Y}$

We have a **domain equation** to solve:

$$\mathcal{D} \simeq (\mathbb{Z} \cup \mathbb{B} \cup (\mathcal{D} \rightarrow \mathcal{D}))_{\perp}$$

Problem: no solution in set theory

($\mathcal{D} \rightarrow \mathcal{D}$ has a strictly larger cardinal than \mathcal{D})

Inverse limits

Given a **fixpoint** domain equation $\mathcal{D} = F(\mathcal{D})$
 we construct an **infinite sequence of domains**:

- $\mathcal{D}_0 \stackrel{\text{def}}{=} \{\perp\}$
- $\mathcal{D}_{i+1} \stackrel{\text{def}}{=} F(\mathcal{D}_i)$

We require the existence of **continuous retractions**:

- $\gamma_i : \mathcal{D}_i \xrightarrow{\subseteq} \mathcal{D}_{i+1}$ *(embedding)*
- $\alpha_i : \mathcal{D}_{i+1} \xrightarrow{\subseteq} \mathcal{D}_i$ *(projection)*
- $\alpha_i \circ \gamma_i = \lambda x.x$ *($\mathcal{D}_i \simeq$ a subset of \mathcal{D}_{i+1})*
- $\gamma_i \circ \alpha_i \sqsubseteq \lambda x.x$ *(\mathcal{D}_{i+1} can be approximated by \mathcal{D}_i)*

This is denoted: $\mathcal{D}_0 \begin{array}{c} \xleftarrow{\alpha_0} \\ \xrightarrow{\gamma_0} \end{array} \mathcal{D}_1 \begin{array}{c} \xleftarrow{\alpha_1} \\ \xrightarrow{\gamma_1} \end{array} \dots$

Inverse limit: $\mathcal{D}_\infty \stackrel{\text{def}}{=} \{(a_0, a_1, \dots) \mid \forall i: a_i \in \mathcal{D}_i \wedge a_i = \alpha(a_{i+1})\}$

(infinite sequences of elements; able to represent an element of any \mathcal{D}_i)

Inverse limits

Inverse limits: $\mathcal{D}_\infty \stackrel{\text{def}}{=} \{ (a_0, a_1, \dots) \mid \forall i: a_i \in \mathcal{D}_i \wedge a_i = \alpha(a_{i+1}) \}$

Theorem

\mathcal{D}_∞ is a cpo and $F(\mathcal{D}_\infty)$ is isomorphic to \mathcal{D}_∞

Application to λ -calculus

If we restrict ourself to **continuous functions**

retractions can be computed for $F(\mathcal{D}) \stackrel{\text{def}}{=} (\mathbb{Z} \cup \mathbb{B} \cup (\mathcal{D} \xrightarrow{\zeta} \mathcal{D}))_\perp$

$(\gamma_i(f) \stackrel{\text{def}}{=} \lambda x. f$

$\alpha_i(x) \stackrel{\text{def}}{=} \begin{cases} \star & \text{if } x \in \mathbb{Z} \cup \mathbb{B} \cup \{\perp\} \\ f(\perp) & \text{if } f \in \mathcal{D}_i \xrightarrow{\zeta} \mathcal{D}_i \end{cases}$

\implies we found our semantic domain!

(pioneered by [Scott-Strachey71], see [Abramsky-Jung94] for a reference)

Restrictions of function spaces

The restriction to continuous functions seems merely technical but there are some valid justifications:

- all the denotations in **IMP**, **NIMP**, **PCF** were continuous
(*this appeared naturally, not as an a priori restriction*)
- intuitively, computable functions should at least be **monotonic**
recall that \sqsubseteq is an information order
a function cannot give a more precise result with less information
e.g.: if $f(a) = \perp$ for some $a \neq \perp$, then $f(\perp) = \perp$
- **continuity** is also reasonable
given a problem on an infinite data set S
computers can only process finite parts S_i of S
continuity ensures that the solution of S is contained in that of all S_i
e.g.: if $0 \sqsubseteq 1 \sqsubseteq \dots \sqsubseteq \omega$ and $\forall i < \omega: f(i) = 0$, then $f(\omega)$ should also be 0

Domain equations for data-types

Solution domains of recursive equations can also give the semantics of a variety of inductive or polymorphic data-types

Examples:

- integer lists:

$$\mathcal{D} = (\{\text{empty}\} \cup (\mathbb{Z} \times \mathcal{D}))_{\perp}$$

- pairs:

$$\mathcal{D} = (\mathbb{Z} \cup (\mathcal{D} \times \mathcal{D}))_{\perp}$$

(allows arbitrary nested pairs, and also contains trees and lists)

- records:

$$\mathcal{D} = (\mathbb{Z} \cup (\mathbb{N} \rightarrow \mathcal{D}))_{\perp}$$

(fields are named by integer position)

- sum types:

$$\mathcal{D} = (\mathbb{Z} \cup (\{1\} \times \mathcal{D}) \cup (\{2\} \times \mathcal{D}))_{\perp}$$

(we “tag” each case of the sum with an integer)

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