Structured sparsity-inducing norms through submodular functions

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Outline

- Introduction: Sparse methods for machine learning
 - Need for structured sparsity: Going beyond the ℓ_1 -norm
- Submodular functions
 - Lovász extension
- Structured sparsity through submodular functions
 - Relaxation of the penalization of supports
 - Examples
 - Unified algorithms and analysis
- Extensions to symmetric submodular functions
 - Shaping level sets

Sparsity in supervised machine learning

- Observed data $(x_i, y_i) \in \mathbb{R}^p \times \mathbb{R}$, $i = 1, \dots, n$
 - Response vector $y = (y_1, \dots, y_n)^\top \in \mathbb{R}^n$
 - Design matrix $X = (x_1, \ldots, x_n)^\top \in \mathbb{R}^{n \times p}$
- Regularized empirical risk minimization:

$$\min_{w \in \mathbb{R}^p} \frac{1}{n} \sum_{i=1}^n \ell(y_i, w^\top x_i) + \lambda \Omega(w) = \left[\min_{w \in \mathbb{R}^p} L(y, Xw) + \lambda \Omega(w) \right]$$

- Norm Ω to promote sparsity
 - square loss + ℓ_1 -norm \Rightarrow basis pursuit in signal processing (Chen et al., 2001), Lasso in statistics/machine learning (Tibshirani, 1996)
 - Proxy for interpretability
 - Allow high-dimensional inference: $\log p$

$$\log p = O(n)$$

Sparsity in unsupervised machine learning

• Multiple responses/signals $y = (y^1, \dots, y^k) \in \mathbb{R}^{n \times k}$

$$\min_{w^1,\dots,w^k \in \mathbb{R}^p} \sum_{j=1}^k \left\{ L(y^j, Xw^j) + \lambda \Omega(w^j) \right\}$$

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● Only responses are observed ⇒ Dictionary learning

- Learn $X = (x^1, \dots, x^p) \in \mathbb{R}^{n \times p}$ such that $\forall j, \|x^j\|_2 \leqslant 1$

$$\min_{\substack{X=(x^1,\ldots,x^p) \ w^1,\ldots,w^k \in \mathbb{R}^p}} \sum_{j=1}^k \left\{ L(y^j, Xw^j) + \lambda \Omega(w^j) \right\}$$
• Olshausen and Field (1997); Elad and Aharon (2006)

• sparse PCA: replace $||x^j||_2 \leq 1$ by $\Theta(x^j) \leq 1$

Sparsity in signal processing

• Multiple responses/signals $x = (x^1, \dots, x^k) \in \mathbb{R}^{n \times k}$

$$\min_{\alpha^1,\dots,\alpha^k \in \mathbb{R}^p} \sum_{j=1}^k \left\{ L(x^j, D\alpha^j) + \lambda \Omega(\alpha^j) \right\}$$

- Only responses are observed \Rightarrow **Dictionary learning**
 - Learn $D = (d^1, \dots, d^p) \in \mathbb{R}^{n \times p}$ such that $\forall j, \|d^j\|_2 \leqslant 1$

$$\min_{\substack{D=(d^1,\ldots,d^p) \ \alpha^1,\ldots,\alpha^k \in \mathbb{R}^p}} \sum_{j=1}^k \left\{ L(x^j, D\alpha^j) + \lambda \Omega(\alpha^j) \right\}$$
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Why structured sparsity?

• Interpretability

- Structured dictionary elements (Jenatton et al., 2009b)
- Dictionary elements "organized" in a tree or a grid (Kavukcuoglu et al., 2009; Jenatton et al., 2010; Mairal et al., 2010)



raw data

sparse PCA

 \bullet Unstructed sparse PCA \Rightarrow many zeros do not lead to better interpretability



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Structured sparse PCA

• Enforce selection of convex nonzero patterns \Rightarrow robustness to occlusion in face identification



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Modelling of text corpora (Jenatton et al., 2010)



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• Stability and identifiability

- Optimization problem $\min_{w \in \mathbb{R}^p} L(y, Xw) + \lambda \|w\|_1$ is unstable
- "Codes" w^j often used in later processing (Mairal et al., 2009)

• Prediction or estimation performance

 When prior knowledge matches data (Haupt and Nowak, 2006; Baraniuk et al., 2008; Jenatton et al., 2009a; Huang et al., 2009)

• Numerical efficiency

- Non-linear variable selection with 2^p subsets (Bach, 2008)

ℓ_1 -norm = convex envelope of cardinality of support

- Let $w \in \mathbb{R}^p$. Let $V = \{1, \ldots, p\}$ and $\operatorname{Supp}(w) = \{j \in V, w_j \neq 0\}$
- Cardinality of support: $||w||_0 = Card(Supp(w))$
- Convex envelope = largest convex lower bound (see, e.g., Boyd and Vandenberghe, 2004)



• ℓ_1 -norm = convex envelope of ℓ_0 -quasi-norm on the ℓ_∞ -ball $[-1,1]^p$

Convex envelopes of general functions of the support (Bach, 2010)

- Let $F: 2^V \to \mathbb{R}$ be a set-function
 - Assume F is non-decreasing (i.e., $A \subset B \Rightarrow F(A) \leqslant F(B)$)
 - Explicit prior knowledge on supports (Haupt and Nowak, 2006; Baraniuk et al., 2008; Huang et al., 2009)
- Define $\Theta(w) = F(\operatorname{Supp}(w))$: How to get its convex envelope?
 - 1. Possible if F is also **submodular**
 - 2. Allows **unified** theory and algorithm
 - 3. Provides new regularizers

• $F: 2^V \to \mathbb{R}$ is **submodular** if and only if

 $\forall A, B \subset V, \quad F(A) + F(B) \ge F(A \cap B) + F(A \cup B)$

 $\Leftrightarrow \ \forall k \in V, \quad A \mapsto F(A \cup \{k\}) - F(A) \text{ is non-increasing}$

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 – Example: F : A → g(Card(A)) is submodular if g is concave

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 - Polynomial-time minimization, conjugacy theory

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- Intuition 2: behave like convex functions
 - Polynomial-time minimization, conjugacy theory
- Used in several areas of signal processing and machine learning
 - Total variation/graph cuts (Chambolle, 2005; Boykov et al., 2001)
 - Optimal design (Krause and Guestrin, 2005)

Submodular functions - Lovász extension

- Subsets may be identified with elements of $\{0,1\}^p$
- Given any set-function F and w such that $w_{j_1} \ge \cdots \ge w_{j_p}$, define:

$$f(w) = \sum_{k=1}^{p} w_{j_k}[F(\{j_1, \dots, j_k\}) - F(\{j_1, \dots, j_{k-1}\})]$$

- If $w = 1_A$, $f(w) = F(A) \Rightarrow$ extension from $\{0, 1\}^p$ to \mathbb{R}^p - f is piecewise affine and positively homogeneous
- F is submodular if and only if f is convex
 - Minimizing f(w) on $w \in [0,1]^p$ equivalent to minimizing F on 2^V

Submodular functions and structured sparsity

- Let $F: 2^V \to \mathbb{R}$ be a non-decreasing submodular set-function
- **Proposition**: the convex envelope of $\Theta : w \mapsto F(\operatorname{Supp}(w))$ on the ℓ_{∞} -ball is $\Omega : w \mapsto f(|w|)$ where f is the Lovász extension of F

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- Sparsity-inducing properties: Ω is a polyhedral norm



- A if stable if for all $B \supset A$, $B \neq A \Rightarrow F(B) > F(A)$
- With probability one, stable sets are the only allowed active sets

Polyhedral unit balls



Submodular functions and structured sparsity Examples

- From $\Omega(w)$ to F(A): provides new insights into existing norms
 - Grouped norms with overlapping groups (Jenatton et al., 2009a)

$$\Omega(w) = \sum_{G \in \mathcal{G}} \|w_G\|_{\infty}$$

- ℓ_1 - ℓ_∞ norm \Rightarrow sparsity at the group level
- Some w_G 's are set to zero for some groups G

$$(\operatorname{Supp}(w))^c = \bigcup_{G \in \mathcal{H}} G \text{ for some } \mathcal{H} \subseteq \mathcal{G}$$

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- Justification not only limited to allowed sparsity patterns

Selection of contiguous patterns in a sequence

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• G is the set of blue groups: any union of blue groups set to zero leads to the selection of a **contiguous pattern**

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- $\sum_{G \in \mathcal{G}} \|w_G\|_{\infty} \Rightarrow F(A) = p 2 + \operatorname{Range}(A) \text{ if } A \neq \emptyset$
 - Jump from 0 to p-1: tends to include all variables simultaneously
 - Add $\nu |A|$ to smooth the kink: all sparsity patterns are possible
 - Contiguous patterns are favored (and not forced)

Extensions of norms with overlapping groups

• Selection of rectangles (at any position) in a 2-D grids



• Hierarchies



Application to background subtraction (Mairal, Jenatton, Obozinski, and Bach, 2010)

Background

 ℓ_1 -norm

Structured norm



Topographic dictionaries (Mairal, Jenatton, Obozinski, and Bach, 2010)



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- Justification not only limited to allowed sparsity patterns
- From F(A) to $\Omega(w)$: provides new sparsity-inducing norms

 $- F(A) = g(Card(A)) \Rightarrow \Omega$ is a combination of **order statistics**

– Non-factorial priors for supervised learning: Ω depends on the eigenvalues of $X_A^\top X_A$ and not simply on the cardinality of A

Non-factorial priors for supervised learning

- Selection of subset A from design $X \in \mathbb{R}^{n \times p}$ with ℓ_2 -penalization
- Frequentist analysis (Mallow's C_L): tr $X_A^{\top} X_A (X_A^{\top} X_A + \lambda I)^{-1}$
 - Not submodular
- Bayesian analysis (marginal likelihood): $\log \det(X_A^{\top}X_A + \lambda I)$

- Submodular (also true for $tr(X_A^{\top}X_A)^{1/2}$)

p	n	k	submod.	ℓ_2 vs. submod.	ℓ_1 vs. submod.	greedy vs. submod.
120	120	80	40.8 ± 0.8	-2.6 ± 0.5	$\textbf{0.6}\pm\textbf{0.0}$	$\textbf{21.8} \pm \textbf{0.9}$
120	120	40	35.9 ± 0.8	$\textbf{2.4}\pm\textbf{0.4}$	$\textbf{0.3}\pm\textbf{0.0}$	$\textbf{15.8} \pm \textbf{1.0}$
120	120	20	29.0 ± 1.0	$\textbf{9.4}\pm\textbf{0.5}$	$\textbf{-0.1}\pm0.0$	$\textbf{6.7} \pm \textbf{0.9}$
120	120	10	20.4 ± 1.0	$\textbf{17.5}\pm\textbf{0.5}$	-0.2 ± 0.0	-2.8 ± 0.8
120	20	20	49.4 ± 2.0	0.4 ± 0.5	$\textbf{2.2} \pm \textbf{0.8}$	$\textbf{23.5} \pm \textbf{2.1}$
120	20	10	49.2 ± 2.0	0.0 ± 0.6	1.0 ± 0.8	$\textbf{20.3} \pm \textbf{2.6}$
120	20	6	43.5 ± 2.0	$\textbf{3.5} \pm \textbf{0.8}$	$\textbf{0.9}\pm\textbf{0.6}$	$\textbf{24.4} \pm \textbf{3.0}$
120	20	4	41.0 ± 2.1	4.8 ± 0.7	-1.3 ± 0.5	$\textbf{25.1} \pm \textbf{3.5}$

Unified optimization algorithms

- Polyhedral norm with $O(3^p)$ faces and extreme points
 - Not suitable to linear programming toolboxes
- Subgradient ($w \mapsto \Omega(w)$ non-differentiable)
 - subgradient may be obtained in polynomial time \Rightarrow too slow

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 - Not suitable to linear programming toolboxes
- Subgradient ($w \mapsto \Omega(w)$ non-differentiable)
 - subgradient may be obtained in polynomial time \Rightarrow too slow
- **Proximal methods** (e.g., Beck and Teboulle, 2009)
 - $\min_{w \in \mathbb{R}^p} L(y, Xw) + \lambda \Omega(w)$: differentiable + non-differentiable
 - Efficient when (P): $\min_{w \in \mathbb{R}^p} \frac{1}{2} ||w v||_2^2 + \lambda \Omega(w)$ is "easy"
- Proposition: (P) is equivalent to $\min_{A \subset V} \lambda F(A) \sum_{j \in A} |v_j|$ with minimum-norm-point algorithm
 - Possible complexity bound ${\cal O}(p^6)$, but empirically ${\cal O}(p^2)$ (or more)
 - Faster algorithm for special case (Mairal et al., 2010)

Proximal methods for Lovász extensions

• **Proposition** (Chambolle and Darbon, 2009): let w^* be the solution of $\min_{w \in \mathbb{R}^p} \frac{1}{2} ||w - v||_2^2 + \lambda f(w)$. Then the solutions of

$$\min_{A \subset V} \lambda F(A) + \sum_{j \in A} (\alpha - v_j)$$

are the sets A^{α} such that $\{w^* > \alpha\} \subset A^{\alpha} \subset \{w^* \ge \alpha\}$

- Parametric submodular function optimization
 - General decomposition strategy for f(|w|) and f(w) (Groenevelt, 1991)
 - Efficient only when submodular minimization is efficient
 - Otherwise, minimum-norm-point algorithm (a.k.a. Frank Wolfe) is preferable

Comparison of optimization algorithms

- Synthetic example with p = 1000 and $F(A) = |A|^{1/2}$
- ISTA: proximal method
- FISTA: accelerated variant (Beck and Teboulle, 2009)



Comparison of optimization algorithms (Mairal, Jenatton, Obozinski, and Bach, 2010) Small scale

• Specific norms which can be implemented through network flows



Comparison of optimization algorithms (Mairal, Jenatton, Obozinski, and Bach, 2010) Large scale

• Specific norms which can be implemented through network flows



Unified theoretical analysis

• Decomposability

- Key to theoretical analysis (Negahban et al., 2009)
- **Property**: $\forall w \in \mathbb{R}^p$, and $\forall J \subset V$, if $\min_{j \in J} |w_j| \ge \max_{j \in J^c} |w_j|$, then $\Omega(w) = \Omega_J(w_J) + \Omega^J(w_{J^c})$

• Support recovery

 Extension of known sufficient condition (Zhao and Yu, 2006; Negahban and Wainwright, 2008)

• High-dimensional inference

- Extension of known sufficient condition (Bickel et al., 2009)
- Matches with analysis of Negahban et al. (2009) for common cases

Support recovery - $\min_{w \in \mathbb{R}^p} \frac{1}{2n} ||y - Xw||_2^2 + \lambda \Omega(w)$

Notation

$$-\rho(J) = \min_{B \subset J^c} \frac{F(B \cup J) - F(J)}{F(B)} \in (0, 1] \text{ (for } J \text{ stable)}$$
$$-c(J) = \sup_{w \in \mathbb{R}^p} \Omega_J(w_J) / ||w_J||_2 \leq |J|^{1/2} \max_{k \in V} F(\{k\})$$

- Proposition
 - Assume $y = Xw^* + \sigma\varepsilon$, with $\varepsilon \sim \mathcal{N}(0,I)$
 - J = smallest stable set containing the support of w^*
 - Assume $\nu = \min_{j, w_j^* \neq 0} |w_j^*| > 0$ - Let $Q = \frac{1}{n} X^\top X \in \mathbb{R}^{p \times p}$. Assume $\kappa = \lambda_{\min}(Q_{JJ}) > 0$ - Assume that for $\eta > 0$, $(\Omega^J)^*[(\Omega_J(Q_{JJ}^{-1}Q_{Jj}))_{j \in J^c}] \leq 1 - \eta$ - If $\lambda \leq \frac{\kappa \nu}{2c(J)}$, \hat{w} has support equal to J, with probability larger than $1 - 3P(\Omega^*(z) > \frac{\lambda \eta \rho(J) \sqrt{n}}{2\sigma})$
 - \boldsymbol{z} is a multivariate normal with covariance matrix \boldsymbol{Q}

Consistency - $\min_{w \in \mathbb{R}^p} \frac{1}{2n} \|y - Xw\|_2^2 + \lambda \Omega(w)$

Proposition

– Assume
$$y = Xw^* + \sigma \varepsilon$$
, with $\varepsilon \sim \mathcal{N}(0, I)$

-J = smallest stable set containing the support of w^*

- Let
$$Q = \frac{1}{n} X^{\top} X \in \mathbb{R}^{p \times p}$$

- Assume that $\forall \Delta$ s.t. $\Omega^{J}(\Delta_{J^{c}}) \leq 3\Omega_{J}(\Delta_{J}), \ \Delta^{\top}Q\Delta \geq \kappa \|\Delta_{J}\|_{2}^{2}$ - Then $\left[\Omega(\hat{w} - w^{*}) \leq \frac{24c(J)^{2}\lambda}{\kappa o(J)^{2}}\right]$ and $\left[\frac{1}{n}\|X\hat{w} - Xw^{*}\|_{2}^{2} \leq \frac{36c(J)^{2}\lambda^{2}}{\kappa \rho(J)^{2}}\right]$

- Then
$$\left| \Omega(\hat{w} - w^*) \leqslant \frac{24c(J)^2 \lambda}{\kappa \rho(J)^2} \right|$$
 and $\left| \frac{1}{n} \right|$

with probability larger than $1 - P(\Omega^*(z) > \frac{\lambda \rho(J) \sqrt{n}}{2\sigma})$

- -z is a multivariate normal with covariance matrix Q
- **Concentration inequality** (z normal with covariance matrix Q):
 - $-\mathcal{T}$ set of stable inseparable sets

- Then
$$P(\Omega^*(z) > t) \leq \sum_{A \in \mathcal{T}} 2^{|A|} \exp\left(-\frac{t^2 F(A)^2/2}{1^\top Q_{AA^1}}\right)$$

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Symmetric submodular functions (Bach, 2010a)

- Let $F: 2^V \to \mathbb{R}$ be a symmetric submodular set-function
- Proposition: The Lovász extension f(w) is the convex envelope of the function w → max_{α∈ℝ} F({w ≥ α}) on the set [0,1]^p + ℝ1_V = {w ∈ ℝ^p, max_{k∈V} w_k - min_{k∈V} w_k ≤ 1}.

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Symmetric submodular functions - Examples

- From $\Omega(w)$ to F(A): provides new insights into existing norms
 - Cuts total variation

$$F(A) = \sum_{k \in A, j \in V \setminus A} d(k, j) \quad \Rightarrow \quad f(w) = \sum_{k, j \in V} d(k, j)(w_k - w_j)_+$$



- NB: graph may be directed

Symmetric submodular functions - Examples

• From F(A) to $\Omega(w)$: provides new sparsity-inducing norms

– $F(A) = g(Card(A)) \Rightarrow$ priors on the size and numbers of clusters



 Convex formulations for clustering (Hocking, Joulin, Bach, and Vert, 2011)

Symmetric submodular functions - Examples

- From F(A) to $\Omega(w)$: provides new sparsity-inducing norms
 - Regular functions (Boykov et al., 2001; Chambolle and Darbon, 2009)



Conclusion

• Structured sparsity for machine learning and statistics

- Many applications (image, audio, text, etc.)
- May be achieved through structured sparsity-inducing norms
- Link with submodular functions
- Unified analysis and algorithms

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• On-going work on structured sparsity

- Norm design beyond submodular functions
- Links with greedy methods (Haupt and Nowak, 2006; Baraniuk et al., 2008; Huang et al., 2009)
- Extensions to matrices

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