Matrix Sparsity - Structured Sparsity

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Outline

1 Matrix Sparsity

Learning on matrices

- Forms of sparsity for matrices
- Multivariate learning and row sparsity
- Sparse spectrum
- Sparse Principal Component Analysis
- Dictionary learning, image denoising and inpainting

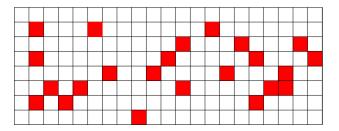
2 Structured sparsity

- Overview
- Sparsity patterns stable by union
- Sparse Structured PCA
- Hierarchical Dictionary Learning

3 Conclusion

Learning on matrices - Collaborative Filtering (CF)

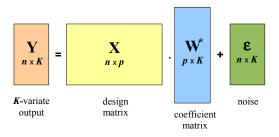
- Given $n_{\mathcal{X}}$ "movies" $\mathbf{x} \in \mathcal{X}$ and $n_{\mathcal{Y}}$ "customers" $\mathbf{y} \in \mathcal{Y}$,
- predict the "rating" $z(\mathbf{x},\mathbf{y}) \in \mathcal{Z}$ of customer \mathbf{y} for movie \mathbf{x}
- Training data: large $n_X \times n_Y$ incomplete matrix Z that describes the known ratings of some customers for some movies
- Goal: complete the matrix.



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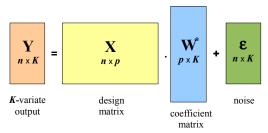
Learning on matrices - Multivariate problems

• Multivariate linear regression



Learning on matrices - Multivariate problems

• Multivariate linear regression



Multiclass classification

$$\min_{W} \sum_{i=1}^{n} \frac{1}{n} \ell(w_1^{\top} x^{(i)}, \dots, w_K^{\top} x^{(i)}, y^{(i)})$$

with

•
$$y^{(i)} \in \{0,1\}^K$$

- One parameter vector $w_k \in \mathbb{R}^p$ per class
- ℓ is e.g. the multiclass logistic loss

- k prediction tasks on same covariates $x \in \mathbb{R}^p$
 - Each model parameterized by: $w^k \in \mathbb{R}^p, \quad 1 \leq k \leq K$

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$$L_k(w^k) = \frac{1}{n} \sum_{i=1}^n \ell_k(w^k^\top x_i^k, y_i^k)$$

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 - All parameters form a matrix:

$$W = [w^1, \dots, w^K] = \begin{bmatrix} w_1^1 & \dots & w_1^K \\ \vdots & w_j^K & \vdots \\ w_p^1 & \dots & w_p^K \end{bmatrix} = \begin{bmatrix} w_1 \\ \vdots \\ w_p \end{bmatrix} \in \mathbb{R}^{p \times K}$$

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- Many applications
 - Multi-category classification (one task per class) (Amit et al., 2007)
- Share parameters between various tasks
 - similar to fixed effect/random effect models (Raudenbush and Bryk, 2002)

Learning on matrices - Image denoising

- Simultaneously denoise all patches of a given image
- Example from Mairal et al. (2009b)



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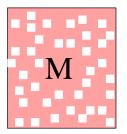
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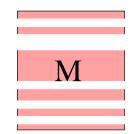
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Two types of sparsity for matrices $M \in \mathbb{R}^{n \times p}$ I - Directly on the elements of M

Many zero elements: $M_{ij} = 0$

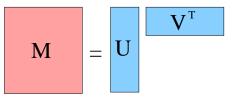


Many zero rows (or columns): $(M_{i1}, \ldots, M_{ip}) = 0$

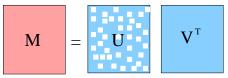


Two types of sparsity for matrices $M \in \mathbb{R}^{n \times p}$ II - Through a factorization of $M = UV^{\top}$

- $M = UV^{ op}$, $U \in \mathbb{R}^{n imes m}$ and $V \in \mathbb{R}^{n imes m}$
- Low rank: m small



• Sparse decomposition: U sparse



• Same as dictionary learning with notations M = X, V = D and $A = U^{\top}$.

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Joint variable selection (Obozinski et al., 2009)

$$\sum_{k=1}^{K} \frac{1}{n_k} \sum_{i=1}^{n_k} \ell_k(w^{k^{\top}} x_i^k, y_i^k) + \lambda \Omega(W)$$

• Joint matrix of predictors
$$W = (w_1, \dots, w_k) \in \mathbb{R}^{p \times k}$$
:
 $W = [w^1, \dots, w^K] = \begin{bmatrix} w_1^1 & \cdots & w_1^K \\ \vdots & w_j^k & \vdots \\ w_p^1 & \cdots & w_p^K \end{bmatrix} = \begin{bmatrix} w_1 \\ \vdots \\ w_p \end{bmatrix} \in \mathbb{R}^{p \times K} \to$

Select all variables that are relevant to at least one task

$$\sum_{k=1}^{K} \frac{1}{n_k} \sum_{i=1}^{n_k} \ell_k(w^{k^{\top}} x_i^k, y_i^k) + \lambda \sum_{j=1}^{p} \|w_j\|_2$$

• Can improve performance over ℓ_1 -regularization (Obozinski et al., 2008; Lounici et al., 2009)

W*

Applications for simultaneous selection

Multi-class image classification (Quattoni et al., 2008)

- $\rightarrow\,$ algorithms for the regularization by a sum of $\ell_\infty\text{-norm}\,\,(\ell_1/\ell_\infty).$
- $\rightarrow\,$ increase in performance

Multi-class tumor classification based on gene expression

- data (Obozinski et al., 2009)
- \rightarrow smaller gene signatures

Source localization in M/EEG inverse problems from several experiments (Gramfort, 2010)

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Rank constraints and sparsity of the spectrum

Rank

Given a matrix $M \in \mathbb{R}^{n \times p}$

- Singular value decomposition (SVD): $M = U \operatorname{Diag}(s) V^{\top}$ where U, V orthogonal, $s \in \mathbb{R}^m_+$ are singular values
- $Rank(M) = \|s\|_0$
- Rank of M is the minimum size m of all factorizations of M into $M = UV^{\top}$, $U \in \mathbb{R}^{n \times m}$ and $V \in \mathbb{R}^{p \times m}$

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Rank constrained Learning

$$\min_{W\in \mathbb{R}^{p imes k}} L(W)$$
 s.t. $\mathrm{rank}(W) \leq m$

Examples:

- Collaborative filtering
- Multi-task learning with task parameters assumed in a low dimensional subspace (Argyriou et al., 2009)

Low-rank via factorization

Reduced-rank multivariate regression

$$\min_{W} \|Y - XW\|_F^2$$
 s.t. $\mathrm{rank}(W) \leq k$

- Well studied (Anderson, 1951; Izenman, 1975; Reinsel and Velu, 1998)
- Is solved directly using the SVD (by OLS + SVD + projection)

General factorization

$$\min_{U\in\mathbb{R}^{p\times m},V\in\mathbb{R}^{k\times m}}L(UV^{\top})$$

- Still non-convex but convex w.r.t. U and V separately
- Optimization by alternating procedures

Trace norm relaxation

With SVD W = UDiag $(s)V^{\top}$, rank $(W) = \|s\|_0 \xrightarrow{\text{Relax}} \|s\|_1$.

- $M \mapsto ||s||_1$ is actually a *unitary invariant* norm: the trace norm, nuclear norm or unitary norm
- Write it $M \mapsto \|M\|_{tr}$
- Dual norm to the spectral norm $\|M\|_2 = \|s\|_\infty$

Trace norm regularization

$$\min_{W\in\mathbb{R}^{p\times k}}L(W)+\lambda\|W\|_{\mathrm{tr}}$$

- Convex problem
- Algorithms:
 - Proximal methods
 - Iterated Reweighted Least-Square (Argyriou et al., 2009)
 - Common bottleneck: require iterative SVD

Trace norm and collaborative filtering

$$\min_{M \in \mathbb{R}^{p \times n}} \sum_{(i,j) \in S} \|M_{ij} - M_{ij}^0\|_2^2 + \lambda \|M\|_{tr}$$

- semi-definite program (Fazel et al., 2001)
- see also max-margin approaches to CF (Srebro et al., 2005)
- Statistical results:
 - High-dimensional inference for noisy matrix completion (Srebro et al., 2005; Candès and Plan, 2009)
 - May recover entire matrix from slightly more entries than the minimum of the two dimensions

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Analysis view

Find projection $v \in \mathbb{R}^p$ maximizing variance:

 $\begin{aligned} \max_{v \in \mathbb{R}^p} & v^\top X^\top X v \\ \text{s.t.} & \|v\|_2 \leq 1 \end{aligned}$

 $\rightarrow ~$ deflate and iterate to obtain more components.

Analysis view

Find projection $v \in \mathbb{R}^{p}$ maximizing variance:

Synthesis view

Find $V = [v_1, \ldots, v_k]$ s.t. x_i have low reconstruction error on span(V):

 $\begin{aligned} \max_{v \in \mathbb{R}^p} \quad v^\top X^\top X \ v \\ \text{s.t.} \quad \|v\|_2 \leq 1 \end{aligned}$

$$\min_{u_i,v_i\in\mathbb{R}^p} \|X-\sum_{i=1}^k u_iv_i^\top\|_F^2$$

 $\rightarrow \;$ deflate and iterate to obtain more components.

Analysis view

Find projection $v \in \mathbb{R}^{p}$ maximizing variance:

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 $\min_{u_i, v_i \in \mathbb{R}^p} \|X - \sum_{i=1}^{\kappa} u_i v_i^\top\|_F^2$

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Analysis view

Find projection $v \in \mathbb{R}^p$ maximizing variance:

Synthesis view

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 $\rightarrow \;$ deflate and iterate to obtain more components.

• For regular PCA, the two views are equivalent!

• Not true if constraints on *u*, *v* change

Sparse PCA - Analysis view

Add sparsity constraint:

$$\max_{\|v\|_2=1, \|v\|_0 \leqslant k} v^\top X^\top X v$$

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Sparse PCA - Analysis view

Add sparsity constraint:

$$\max_{\|\boldsymbol{v}\|_2=1, \|\boldsymbol{v}\|_0 \leqslant k} \boldsymbol{v}^\top \boldsymbol{X}^\top \boldsymbol{X} \boldsymbol{v}$$

Convex relaxation DSPCA (d'Aspremont et al., 2007)

relaxed into
$$\max_{\|v\|_2=1, \|v\|_1 \leqslant k^{1/2}} v^\top X^\top X v$$

then relaxed into
$$\max_{M \succeq 0, \operatorname{tr}(M)=1, \mathbf{1}^\top |M| \mathbf{1} \leqslant k} \operatorname{tr}(X^\top XM), \quad \text{using } M = v v^\top.$$

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$$\max_{\|v\|_2=1, \|v\|_0 \leqslant k} v^\top X^\top X v$$

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- Requires deflation for multiple components (Mackey, 2009)
- More refined convex relaxation (d'Aspremont et al., 2008)
- Analysis of non-convex formulation (Moghaddam et al., 2006)

Sparse PCA - Synthesis view Find $V = [v_1, ..., v_m] \in \mathbb{R}^{p \times n}$ sparse and $U = [u_1, ..., u_m] \in \mathbb{R}^{n \times n}$ s.t. $\sum_{i=1}^n \left\| x_i - \sum_{i=1}^m u_{ij} v_j \right\|_2^2 \text{ is small } \Leftrightarrow \quad \|X - UV^\top\|_F^2, \text{ is small}$

Sparse matrix factorization (Witten et al., 2009; Bach et al., 2008)

- Penalize columns v_i of V by the ℓ_1 -norm for sparsity
- Penalize columns u_i of U by the ℓ_2 -norm to avoid trivial solutions

$$\min_{U,V} \|X - UV^{\top}\|_{F}^{2} + \frac{\lambda}{2} \sum_{i=1}^{m} \{\|u_{i}\|_{2}^{2} + \|v_{i}\|_{1}^{2} \}$$

$$\min_{U,V} \|X - UV^{\top}\|_{F}^{2} + \lambda \sum_{i} \|u_{i}\|_{2} \|v_{i}\|_{1}$$

$$\min_{U,V} \|X - UV^{\top}\|_{F}^{2} + \lambda \sum_{i} \|v_{i}\|_{1} \quad \text{s.t.} \|u_{i}\|_{2} \le 1$$

yield the same solutions for $u_j v_i^{\top}$ (Bach et al., 2008).

Efficient algorithms for sparse matrix factorization Focus on previous formulation:

$$\min_{U,V} \|X - UV^{\top}\|_{F}^{2} + \lambda \sum_{j} \|v_{j}\|_{1} \quad \text{s.t.} \|u_{j}\|_{2} \le 1$$

• Problem is convex in U and V separately, but not jointly.

- \rightarrow Alternating scheme: optimize U and V in turn.
- Even better: use simple column updates (Lee et al., 2007; Witten et al., 2009):

With
$$\widetilde{X} = X - \sum_{j' \neq j} u_j v_j^{\top}$$
, we have
either $u_j \leftarrow \frac{\widetilde{X}v_j}{\|\widetilde{X}v_j\|}$ or $v_j \leftarrow \operatorname{argmin}_v \|X^{\top}u_j - v\|_2^2 + \lambda \|v\|_1$

- requires no matrix inversion
- ullet + can take advantage of efficient algorithms for Lasso
- can use warm start + active sets

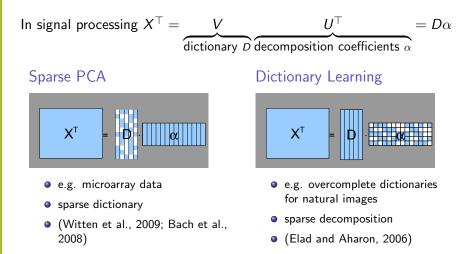
Sparse PCA - Synthesis view II

"Sparse projector" (Zou et al., 2006) Find $\widetilde{V} = [\widetilde{v}_1, \dots, \widetilde{v}_m] \in \mathbb{R}^{p \times n}$ and $V = [v_1, \dots, v_m] \in \mathbb{R}^{p \times n}$ such that

$$\begin{split} \min_{\widetilde{V},V} & \sum_{i=1}^n \|x_i - \widetilde{V}V^\top x_i\|_2^2 + \lambda_1 \|V\|_1 + \lambda_2 \|V\|_F^2 \\ \text{such that} & \widetilde{V}^\top \widetilde{V} = I_p \end{split}$$

- The data should be reconstructed from sparse projections
- \bullet Non-convex formulation \rightarrow alternating minimization

Sparse PCA vs Dictionary Learning a.k.a. Sparse Coding



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Dictionary Learning

$$\min_{\substack{\mathbf{A}\in\mathbb{R}^{k\times n}\\\mathbf{D}\in\mathbb{R}^{p\times k}}}\sum_{i=1}^{n}\left(\|\mathbf{x}_{i}-\mathbf{D}\boldsymbol{\alpha}_{i}\|_{2}^{2}+\lambda\|\boldsymbol{\alpha}_{i}\|_{1}\right) \quad \text{s.t.} \quad \forall j, \ \|\mathbf{d}_{j}\|_{2} \leq 1.$$

• As before not jointly convex but convex in each \mathbf{d}_j and $lpha_j$

• Alternating scheme becomes slow for large signal databases ...

 $[\rightarrow]$ use Stochastic Optimization / Online learning (Mairal et al., 2009a)

- can handle potentially infinite datasets
- can adapt to dynamic training sets

THE SALINAS VALLEY is in Northern California. It is a long narrow swale between two ranges of mountains, and the Salinas River winds and twists up the center until it falls at last into Monterey Bay.

I ramember my childhood names for grosses and secar flowers. I genember where a toad may live and whill time the birds awaken in the summer and what trees and seasons smelled like-how people looked and walked and smalled aven. The memory stodors is very rich

Tremember that the Galilan Moustains forthe eart of the vality were limit as imbinities folloop sum and laveliness and a kind of invitation, so that you wanted to climb into their warm foothills almost as you want to climb into the lab balo of a bioloved matter. They ware becoming meuntains with a brown grass love. The Santa-Lucias stand, up against the sky to the west and kept the value, from the apart see. and they were bark and brooding-unitinely and dimensions. Lathways found in may if aparts and love of east. Where I ever got such an idea i cannot say, unless it could be that the monthly dame over the peaks of the Gabilans and the night drifted bark from the sidess of the Santa Lucius. It bar for that the bith and death of the day had some part in my fealing about the two ranges of mount must.

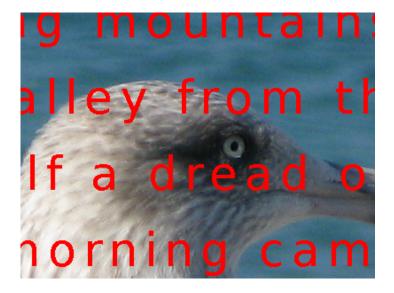
From both sides of the valley little stream slipped out of the hir canyons and fall into the bed of the Salinas River. In the winter of wet years the streams and full infected, and they swelled the river until sametimes it raged and bolled, bank full, and they they as a destroyer. The river fore the edges of the farm lands and mashed whole acres down, it toppled barry and houses into itself way floating and bobbing away. It trapped cows and

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The floor of the Salinas Vallow, between the runnes and of low the foothills, it revelopecause this valley used to be the battern of a hundredware rifet from the twee, the over mouth at Moss Landing was eventuries ago the e trace to a this long inland water. Once, first will solve the vallow, my father roads a well, the deriv and up first with to use any the mouth in well and then with white sea since the shifts and even plus.

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Sparsity with Structure

Notion emerged very recently through the work of several authors: Yuan and Lin (2006), Zhao et al. (2009), Baraniuk et al. (2008), Bach (2008), Jacob et al. (2009), Jenatton et al. (2009), Jenatton et al. (2010b), He and Carin (2009), Huang et al. (2009).

The support is sparse but we have prior information about its structure.

- The variables should be selected in groups.
- The variables lie in a hierarchy.
- The variables lie on a graph or network and the support should be localized or densely connected on the graph.
- The variables are pixels of an image and form rectangles or convex shapes.

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Biological markers for cancer

Metastasis prognosis: Predict if a tumor will produce metastases.



Gene expression in tumor	Metastasis?
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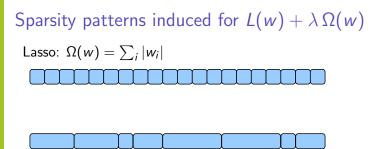
• Can we predict metastasis and identify few predictive genes?

Biological pathways as relevant groups of genes

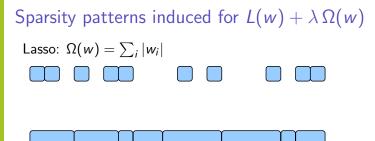
Predictive genes are naturally grouped in *biological pathways*

- Correspond to genes participating in same biological mechanisms
- Contain often very correlated genes
- The pathways form overlapping groups
- Ultimately relevant to the biologist
- \Rightarrow Instead of selecting genes individually, select entire pathways.

The support is a union of overlapping groups.



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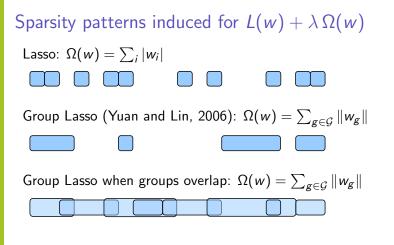
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Sparsity patterns induced for $L(w) + \lambda \Omega(w)$ Lasso: $\Omega(w) = \sum_{i} |w_{i}|$ Group Lasso (Yuan and Lin, 2006): $\Omega(w) = \sum_{g \in \mathcal{G}} ||w_{g}||$

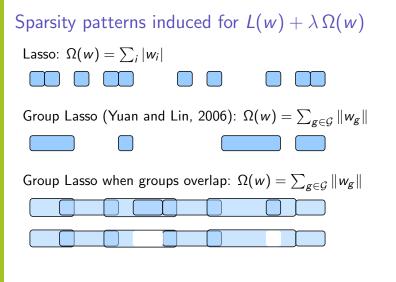
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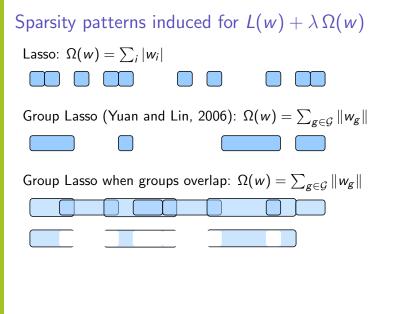
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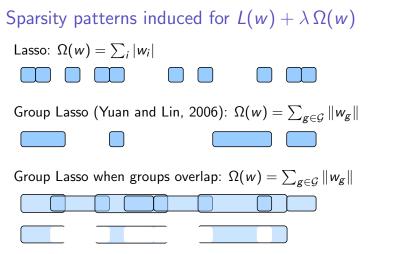
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The support obtained is

- An intersection of the complements of the groups set to 0 (cf. Jenatton et al. (2009))
- Not a union of groups

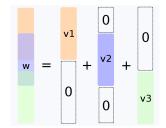
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New formulation

(Jacob, Obozinski and Vert (2009))

Introducing latent variables v_g :

$$\begin{cases} \min_{w,v} L(w) + \lambda \sum_{g \in \mathcal{G}} \|v_g\|_2 \\ w = \sum_{g \in \mathcal{G}} v_g \\ \operatorname{supp}(v_g) \subseteq g. \end{cases}$$



Properties

- Resulting support is a *union* of groups in \mathcal{G} .
- Possible to select one variable without selecting all the groups containing it.

A new "overlap" norm

Equivalent reformulation

with

$$\begin{split} \min_{w,v} L(w) + \lambda \sum_{g \in \mathcal{G}} \|v_g\|_2 \\ w &= \sum_{g \in \mathcal{G}} v_g \qquad \qquad = \min_w L(w) + \lambda \Omega_{overlap}(w) \\ \text{supp}(v_g) \subseteq g. \\ \Omega_{overlap}(w) &\triangleq \begin{cases} \min_v \sum_{g \in \mathcal{G}} \|v_g\|_2 \\ w &= \sum_{g \in \mathcal{G}} v_g \\ \supp(v_g) \subseteq g. \end{cases} \end{split}$$

Sparsity tutorial II, ECML 2010, Barcelona

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(*)

A new "overlap" norm

Equivalent reformulation

with

• $\Omega_{overlap}(w)$ is a norm of w.

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(*)

A new "overlap" norm

Equivalent reformulation

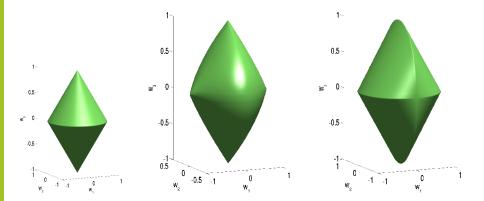
with

• $\Omega_{overlap}(w)$ is a norm of w.

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(*)

Overlap and group unity balls



Balls for $\Omega_{\text{group}}^{\mathcal{G}}(\cdot)$ (middle) and $\Omega_{\text{overlap}}^{\mathcal{G}}(\cdot)$ (right) for the groups $\mathcal{G} = \{\{1,2\},\{2,3\}\}$ where w_2 is represented as the vertical coordinate. Left: group-lasso ($\mathcal{G} = \{\{1,2\},\{3\}\}$), for comparison.

Results

Breast cancer data

- Gene expression data for 8,141 genes in 295 breast cancer tumors.
- Canonical pathways from MSigDB containing 639 groups of genes, 637 of which involve genes from our study.

Method	ℓ_1	$\Omega^{\mathcal{G}}_{overlap}(.)$
Misclassification error	0.38 ± 0.04	0.36 ± 0.03
Number of pathways involved	148, 58, 183	6, 5, 78

Outline

Matrix Sparsity

- Learning on matrices
- Forms of sparsity for matrices
- Multivariate learning and row sparsity
- Sparse spectrum
- Sparse Principal Component Analysis
- Dictionary learning, image denoising and inpainting

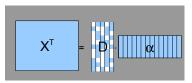
Structured sparsity

- Overview
- Sparsity patterns stable by union
- Sparse Structured PCA
- Hierarchical Dictionary Learning

3 Conclusion

Sparse PCA / Dictionary Learning

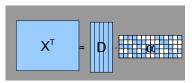
Sparse PCA



- e.g. microarray data
- sparse dictionary
- (Witten et al., 2009; Bach et al., 2008)

Other constraints

Dictionary Learning



- e.g. overcomplete dictionaries for natural images
- sparse decomposition
- (Elad and Aharon, 2006)

Structured matrix factorizations - Many instances

•
$$M = UV^ op$$
, $U \in \mathbb{R}^{n imes m}$ and $V \in \mathbb{R}^{p imes m}$

• Structure on U and/or V

- Low-rank: U and V have few columns
- Dictionary learning / sparse PCA: U or V has many zeros
- Clustering (k-means): $U \in \{0,1\}^{n \times m}$, U1 = 1
- Pointwise positivity: non negative matrix factorization (NMF)
- Specific patterns of zeros
- etc.

Many applications

 e.g., source separation (Févotte et al., 2009), exploratory data analysis

From SPCA to SSPCA

Sparse PCA:

$$\min_{\substack{\mathbf{A}\in\mathbb{R}^{k\times n}\\\mathbf{D}\in\mathbb{R}^{p\times k}}}\sum_{i=1}^{n}\|\mathbf{x}_{i}-\mathbf{D}\boldsymbol{\alpha}_{i}\|_{2}^{2}+\lambda\sum_{j=1}^{k}\|\mathbf{d}_{j}\|_{1} \quad \text{s.t.} \quad \forall j, \ \|\boldsymbol{\alpha}_{j}\|_{2} \leq 1.$$

Sparse structured PCA

$$\min_{\substack{\mathbf{A}\in\mathbb{R}^{k\times n}\\\mathbf{D}\in\mathbb{R}^{p\times k}}}\sum_{i=1}^{n}\|\mathbf{x}_{i}-\mathbf{D}\boldsymbol{\alpha}_{i}\|_{2}^{2}+\lambda\sum_{j=1}^{k}\Omega(\mathbf{d}_{j})\quad\text{s.t.}\quad\forall j,\;\|\boldsymbol{\alpha}_{j}\|_{2}\,\leq\,1.$$

- No orthogonality
- Not jointly convex but convex in each \mathbf{d}_j and α_j
- \Rightarrow efficient block-coordinate descent algorithms

Faces



Faces

- A basis to decompose faces?
- Eigenfaces
- Find parts?
- Localized components
- NMF (Lee and Seung, 1999)

Faces



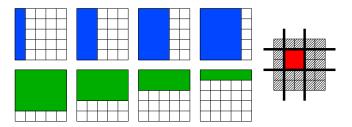
Faces



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Rectangular supports

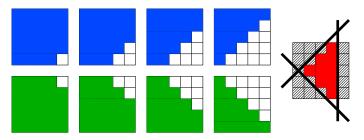
• $\Omega(\mathbf{d}) = \sum_{g \in \mathcal{G}} \|\mathbf{d}_g\|_2$: Selection of rectangles on the 2D-grid.



- *G* is the set of blue/green groups (with their not displayed complements)
- Any union of blue/green groups set to zero leads to the selection of a rectangle

General "convex" supports

• $\Omega(\mathbf{d}) = \sum_{g \in \mathcal{G}} \|\mathbf{d}_g\|_2$: Selection of "convex" patterns on a 2-D grids.



• It is possible to extend such settings to 3-D space, or more complex topologies

Sparse Structured PCA (Jenatton, Obozinski and Bach (2009))

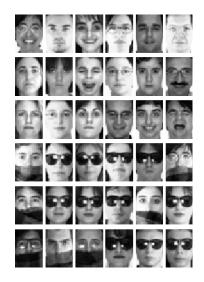
• Learning sparse and structured dictionary elements:

$$\min_{\substack{\mathbf{A} \in \mathbb{R}^{k \times n} \\ \mathbf{D} \in \mathbb{R}^{p \times k}}} \sum_{i=1}^{n} \|\mathbf{x}_i - \mathbf{D} \boldsymbol{\alpha}_i\|_2^2 + \lambda \sum_{j=1}^{p} \Omega(\mathbf{d}_j) \text{ s.t. } \forall i, \|\boldsymbol{\alpha}_i\|_2 \leq 1$$

- Structure of the dictionary elements determined by the choice of G (and thus Ω)
- Efficient learning procedures through variational formulation.

• Reweighted
$$\ell_2$$
: $\sum_{g \in \mathcal{G}} \|\mathbf{y}_g\|_2 = \min_{\eta_g \ge 0, g \in \mathcal{G}} \frac{1}{2} \sum_{g \in \mathcal{G}} \left\{ \frac{\|\mathbf{y}_g\|_2^2}{\eta_g} + \eta_g \right\}$

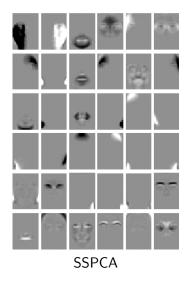
Faces



- AR Face database
- 100 individuals (50 W/50 M)
- For each
 - 14 non-occluded
 - 12 occluded
 - lateral illuminations
 - $\bullet~$ reduced resolution to 38×27 pixels

Decomposition of faces

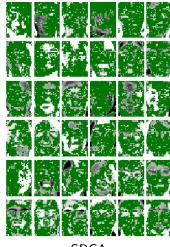




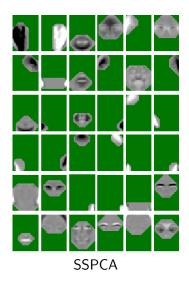
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Decomposition of faces II



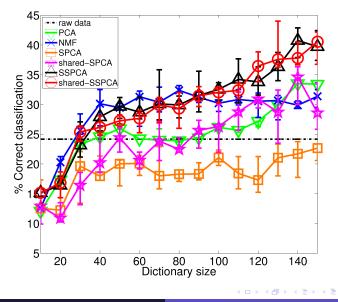
SPCA



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k-NN classification based on decompositions



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Hierarchical Topic Models for text corpora Flat Topic Model

Each document x_j is modeled through word counts: $x_{ij} =$ nb of occurrences of word *i* in document *j*, θ =topic proportions, D=topic word frequencies

$$\kappa_j^{\top} \mathbf{1} = n_j,$$

Model x_j as. $x_j \sim \mathcal{M}(D\theta, n_j)$

- Low-rank matrix factorization of word-document matrix
- Multinomial PCA (Buntine and Perttu, 2003)
- Bayesian approach: Latent Dirichlet Allocation (Blei et al., 2003)

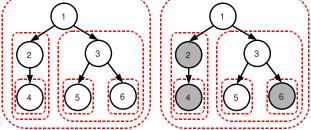
Hierarchical Model: Organise the topics in a tree ?

- Previous approaches: non-parametric Bayesian methods (Hierarchical Chinese Restaurant Process and nested Dirichlet Process): Blei et al. (2004)
- Can we obtain a similar model with **structured** matrix factorization?

Hierarchical Norm

(Jenatton, Mairal, Obozinski and Bach, 2010)

- Structure on codes α (not on dictionary **D**)
- Hierarchical penalization: $\Omega(\alpha) = \sum_{g \in \mathcal{G}} \|\alpha_g\|_2$ where groups g in \mathcal{G} are equal to set of descendants of some nodes in a tree



• Variable selected after its ancestors (Zhao et al., 2009; Bach, 2008)

Hierarchical Dictionary Learning

Efficient Optimization

$$\min_{\substack{\mathbf{A}\in\mathbb{R}^{k\times n}\\\mathbf{D}\in\mathbb{R}^{p\times k}}}\sum_{i=1}^{n}\|\mathbf{x}_{i}-\mathbf{D}\boldsymbol{\alpha}_{i}\|_{2}^{2}+\lambda\Omega(\boldsymbol{\alpha}_{i}) \text{ s.t. } \forall j, \|\mathbf{d}_{j}\|_{2} \leq 1.$$

- Proximal methods
- Requires solving min $_{\boldsymbol{\alpha}\in\mathbb{R}^p} \frac{1}{2} \|\mathbf{y}-\boldsymbol{\alpha}\|_2^2 + \lambda \Omega(\boldsymbol{\alpha})$
- Can we do this for tree-structured norms?

Tree-structured groups

Proposition (Jenatton et al., 2010a)

• If \mathcal{G} is a *tree-structured* set of groups, i.e.,

$$g\cap g'
eq \emptyset \Rightarrow g \subset g' \text{ or } g' \subset g,$$

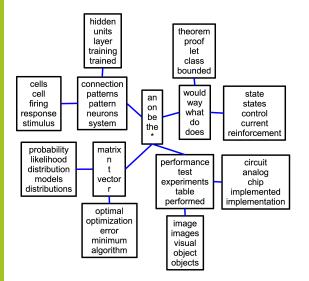
- If the groups are sorted from the leaves to the root,
- If Π_g is
 - the proximal operator $w_g\mapsto {\rm Prox}_{\mu\|\cdot\|_q}(w_g)$ on the subspace corresponding to group g and
 - the identity on the orthogonal

Then the proximal operator for Ω is the composition of all operators from the leaves to the root.

$$\mathsf{Prox}_{\mu\Omega} = \Pi_{g_m} \circ \ldots \circ \Pi_{g_1}. \tag{1}$$

 \rightarrow Tree-structured regularization : Efficient linear time algorithm

Tree of Topics



NIPS abstracts

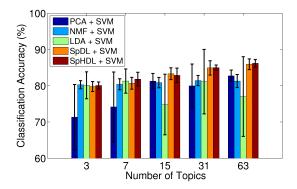
- 1714 documents
- 8274 words

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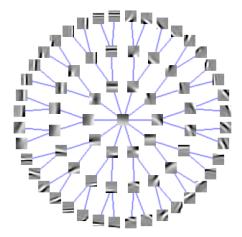
Classification based on topics

Comparison on predicting newsgroup article subjects

• 20 newsgroup articles (1425 documents, 13312 words)



Hierarchical dictionary for image patches



Summary

Sparse linear estimation with ℓ_1 -regularization

- Convex optimization and algorithms
- Theoretical results

Group sparsity

- Block norm
- Multiple Kernel Learning

Matrix Sparsity

- Row sparsity for Multivariate Learning
- Low rank, SPCA and Dictionary Learning

Structured Sparsity

- Overlapping groups and supports stable by union or intersection
- SSPCA and Hierarchical Dictionary Learning

Conclusions

Sparse methods are not limited to regression

High-dimension

- Sparse methods performs well with very many predictors:
- Can algorithms tackle log(p) = o(n) for n > 100?

Performance

- Inducing sparsity does not always improve predictive performance
- Sparsity is a prior
- "Problems are sparse if you look at them the right way"

Capture structure

- Structured sparsity enhances interpretability
- Norm design: make the right norm for your problem

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Martin M Wainwright Jo



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